

A Continuum Model of Biological Transport Networks

On a PDE based modeling of biological transportation networks

Chencheng Zhang

Zhiyuan College, Shanghai Jiao Tong University

April 27, 2021

Table of contents

1. Retrospect
2. ODE based Model
3. Macroscopic Model

Previous Review

Symbols and Notations

- ▶ $G(V, E)$ is a graph with vertex set V and edge set E .

Previous Review

Symbols and Notations

- ▶ $G(V, E)$ is a graph with vertex set V and edge set E .
- ▶ The adjacency matrix of E is denoted by $A = (a_{ij})_{n \times n}$, where $n := |V|$.

Previous Review

Symbols and Notations

- ▶ $G(V, E)$ is a graph with vertex set V and edge set E .
- ▶ The adjacency matrix of E is denoted by $A = (a_{ij})_{n \times n}$, where $n := |V|$.
- ▶ The neighbour of node/vertex $i \in V$ is defined as $N(i) := \{j : j \sim i\}$.

Previous Review

Symbols and Notations

- ▶ $G(V, E)$ is a graph with vertex set V and edge set E .
- ▶ The adjacency matrix of E is denoted by $A = (a_{ij})_{n \times n}$, where $n := |V|$.
- ▶ The neighbour of node/vertex $i \in V$ is defined as $N(i) := \{j : j \sim i\}$.
- ▶ The conductivity and length of edge $i \rightarrow j$ are denoted by C_{ij} and L_{ij} correspondingly, where $C_{ij} \geq 0$ and $L_{ij} > 0$.

Previous Review

Symbols and Notations

- ▶ $G(V, E)$ is a graph with vertex set V and edge set E .
- ▶ The adjacency matrix of E is denoted by $A = (a_{ij})_{n \times n}$, where $n := |V|$.
- ▶ The neighbour of node/vertex $i \in V$ is defined as $N(i) := \{j : j \sim i\}$.
- ▶ The conductivity and length of edge $i \rightarrow j$ are denoted by C_{ij} and L_{ij} correspondingly, where $C_{ij} \geq 0$ and $L_{ij} > 0$.
- ▶ The pressure of the vertex $i \in V$ is denoted by P_i . Thus we can define the pressure drop $(\Delta P)_{ij} := P_j - P_i$ by definition.

Previous Review

Symbols and Notations

- ▶ $G(V, E)$ is a graph with vertex set V and edge set E .
- ▶ The adjacency matrix of E is denoted by $A = (a_{ij})_{n \times n}$, where $n := |V|$.
- ▶ The neighbour of node/vertex $i \in V$ is defined as $N(i) := \{j : j \sim i\}$.
- ▶ The conductivity and length of edge $i \rightarrow j$ are denoted by C_{ij} and L_{ij} correspondingly, where $C_{ij} \geq 0$ and $L_{ij} > 0$.
- ▶ The pressure of the vertex $i \in V$ is denoted by P_i . Thus we can define the pressure drop $(\Delta P)_{ij} := P_j - P_i$ by definition.
- ▶ The flow rate of an oriented flux in $i \rightarrow j$ is denoted by $Q_{ij} := \frac{C_{ij}(\Delta P)_{ij}}{L_{ij}}$.

Previous Review

Symbols and Notations

- ▶ $G(V, E)$ is a graph with vertex set V and edge set E .
- ▶ The adjacency matrix of E is denoted by $A = (a_{ij})_{n \times n}$, where $n := |V|$.
- ▶ The neighbour of node/vertex $i \in V$ is defined as $N(i) := \{j : j \sim i\}$.
- ▶ The conductivity and length of edge $i \rightarrow j$ are denoted by C_{ij} and L_{ij} correspondingly, where $C_{ij} \geq 0$ and $L_{ij} > 0$.
- ▶ The pressure of the vertex $i \in V$ is denoted by P_i . Thus we can define the pressure drop $(\Delta P)_{ij} := P_j - P_i$ by definition.
- ▶ The flow rate of an oriented flux in $i \rightarrow j$ is denoted by $Q_{ij} := \frac{C_{ij}(\Delta P)_{ij}}{L_{ij}}$.
- ▶ The strength of i , denoted by S_i , is defined as the negative summation of Q_{ij} for all $j \in N(i)$.

Formulæ

Kirchhoff first law

- Kirchhoff's first law is that the algebraic sum of currents in a network of conductors meeting at a point (or node) is zero.

$$S_i = \sum_{j \in N(i)} C_{ij} \frac{(\Delta P)_{ji}}{L_{ij}} = - \sum_{j \in N(i)} C_{ij} \frac{(\Delta P)_{ij}}{L_{ij}}$$

Formulæ

Kirchhoff first law

- Kirchhoff's first law is that the algebraic sum of currents in a network of conductors meeting at a point (or node) is zero.

$$S_i = \sum_{j \in N(i)} C_{ij} \frac{(\Delta P)_{ji}}{L_{ij}} = - \sum_{j \in N(i)} C_{ij} \frac{(\Delta P)_{ij}}{L_{ij}}$$

Global mass conservation

- The global mass conservation reveals that the algebraic sum of strength over all nodes is zero, that is, there are many sinks for many sources.

$$\sum_{i \in V} S_i = 0$$

Formulæ

Joule's law

- The kinetic energy is in proportion to both pressure drop and flow rate.

$$\mathcal{E}_1[C_{ij}] := (\Delta P)_{ij} Q_{ij} = \frac{Q_{ij}^2}{C_{ij}} L_{ij}$$

Formulæ

Joule's law

- ▶ The kinetic energy is in proportion to both pressure drop and flow rate.

$$\mathcal{E}_1[C_{ij}] := (\Delta P)_{ij} Q_{ij} = \frac{Q_{ij}^2}{C_{ij}} L_{ij}$$

Metabolic consumption (in energy form)

- ▶ The metabolic consumption is in proportion to its length and a power of its conductivity.

$$\mathcal{E}_2[C_{ij}] := \frac{\nu}{\gamma} C_{ij}^{\gamma} L_{ij}$$

The entire energy consumption

- The entire energy consumption functional is given by

$$\tilde{\mathcal{E}}[C] := \sum_{(i,j) \in E} \frac{Q_{ij}^2}{C_{ij}} L_{ij} + \sum_{(i,j) \in E} \frac{\nu}{\gamma} C_{ij}^{\gamma} L_{ij}$$

The entire energy consumption

- The entire energy consumption functional is given by

$$\tilde{\mathcal{E}}[C] := \sum_{(i,j) \in E} \frac{Q_{ij}^2}{C_{ij}} L_{ij} + \sum_{(i,j) \in E} \frac{\nu}{\gamma} C_{ij}^{\gamma} L_{ij}$$

the pumping power term

Formulæ

The entire energy consumption

- The entire energy consumption functional is given by

$$\tilde{\mathcal{E}}[C] := \sum_{(i,j) \in E} \frac{Q_{ij}^2}{C_{ij}} L_{ij} + \sum_{(i,j) \in E} \frac{\nu}{\gamma} C_{ij}^{\gamma} L_{ij}$$

the pumping power term the metabolic cost term

The entire energy consumption

- ▶ The entire energy consumption functional is given by

$$\tilde{\mathcal{E}}[C] := \sum_{(i,j) \in E} \frac{Q_{ij}^2}{C_{ij}} L_{ij} + \sum_{(i,j) \in E} \frac{\nu}{\gamma} C_{ij}^{\gamma} L_{ij}$$

the pumping power term the metabolic cost term

- ▶ Here $\nu > 0$ is so-called metabolic coefficient, γ is the effective value.

The discussion of gradient flow

The gradient flow

- ▶ The general formulation of a gradient flow of the functional $\tilde{\mathcal{E}} \circ C(t)$ is of the form

$$\frac{dC}{dt} = -\mathcal{H}[C] \cdot \nabla \tilde{\mathcal{E}}[C]$$

The discussion of gradient flow

The gradient flow

- ▶ The general formulation of a gradient flow of the functional $\tilde{\mathcal{E}} \circ C(t)$ is of the form

$$\frac{dC}{dt} = -\mathcal{H}[C] \cdot \nabla \tilde{\mathcal{E}}[C]$$

- ▶ The gradient of $\tilde{\mathcal{E}}$ on C is

$$\nabla \tilde{\mathcal{E}}[C] = \left(\cdots, \nu C_{ij}^{\gamma-1} L_{ij} - \frac{Q_{ij}^2}{C_{ij}^2} L_{ij}, \cdots \right)$$

The discussion of gradient flow

The gradient flow

- ▶ The general formulation of a gradient flow of the functional $\tilde{\mathcal{E}} \circ C(t)$ is of the form

$$\frac{dC}{dt} = -\mathcal{H}[C] \cdot \nabla \tilde{\mathcal{E}}[C]$$

- ▶ The gradient of $\tilde{\mathcal{E}}$ on C is

$$\nabla \tilde{\mathcal{E}}[C] = \left(\cdots, \nu C_{ij}^{\gamma-1} L_{ij} - \frac{Q_{ij}^2}{C_{ij}^2} L_{ij}, \cdots \right)$$

- ▶ Moreover, we have the dissipation of the energy since

$$\frac{d\tilde{\mathcal{E}}[C]}{dt} = \nabla \tilde{\mathcal{E}}[C] \cdot \frac{dC}{dt} = \left\langle \nabla \tilde{\mathcal{E}}[C], \nabla \tilde{\mathcal{E}}[C] \right\rangle_{\mathcal{H}[C]} < 0$$

The discussion of gradient flow

The duality map $\mathcal{H}[C]$

- ▶ We denote the space of tangent and cotangent vectors at $C \in \mathcal{C}$ by $\mathcal{T}_C\mathcal{C}$ and $\mathcal{T}_C^*\mathcal{C}$ respectively. Therefore $\mathcal{H}[C]$ can be regarded as a duality map

$$\mathcal{H}[C] : \mathcal{T}_C^*\mathcal{C} \rightarrow \mathcal{T}_C\mathcal{C}$$

The discussion of gradient flow

The duality map $\mathcal{H}[C]$

- ▶ We denote the space of tangent and cotangent vectors at $C \in \mathcal{C}$ by $\mathcal{T}_C\mathcal{C}$ and $\mathcal{T}_C^*\mathcal{C}$ respectively. Therefore $\mathcal{H}[C]$ can be regarded as a duality map

$$\mathcal{H}[C] : \mathcal{T}_C^*\mathcal{C} \rightarrow \mathcal{T}_C\mathcal{C}$$

- ▶ Since the effect of \mathcal{H} on the system is local $\mathcal{H}[C] = \mathcal{H}_1[C] \otimes \cdots \otimes \mathcal{H}_{|E|}[C]$ Here

$$\mathcal{H}_{ij}[C] : \partial_{C_{ij}}|_C \mapsto \varphi_{ij}(C_{ij}) \cdot dC_{ij}$$

The discussion of gradient flow

The duality map $\mathcal{H}[C]$

- ▶ We denote the space of tangent and cotangent vectors at $C \in \mathcal{C}$ by $\mathcal{T}_C\mathcal{C}$ and $\mathcal{T}_C^*\mathcal{C}$ respectively. Therefore $\mathcal{H}[C]$ can be regarded as a duality map

$$\mathcal{H}[C] : \mathcal{T}_C^*\mathcal{C} \rightarrow \mathcal{T}_C\mathcal{C}$$

- ▶ Since the effect of \mathcal{H} on the system is local $\mathcal{H}[C] = \mathcal{H}_1[C] \otimes \cdots \otimes \mathcal{H}_{|E|}[C]$ Here

$$\mathcal{H}_{ij}[C] : \partial_{C_{ij}}|_C \mapsto \varphi_{ij}(C_{ij}) \cdot dC_{ij}$$

- ▶ We usually choose $\varphi_{ij}(C_{ij}) = C_{ij}^\alpha$. Here $1 - \gamma \leq \alpha \leq 2$ is designate with respect to a weighted Euclidean distance.

On the ODE based modeling

The global existence of $C(t)$

- Consider the ODE system

$$\left\{ \begin{array}{l} \frac{dC_{ij}}{dt} = \left(\frac{Q_{ij}}{C_{ij}^2} L_{ij} - \nu C_{ij}^\gamma L_{ij} \right) C_{ij}^{\alpha-1} L_{ij} \\ \text{coupled with } S_i = - \sum_{j \in N(i)} C_{ij} \frac{(\Delta P)_{ij}}{L_{ij}} \end{array} \right.$$

On the ODE based modeling

The global existence of $C(t)$

- Consider the ODE system

$$\begin{cases} \frac{dC_{ij}}{dt} = \left(\frac{Q_{ij}}{C_{ij}^2} L_{ij} - \nu C_{ij}^\gamma L_{ij} \right) C_{ij}^{\alpha-1} L_{ij} \\ \text{coupled with } S_i = - \sum_{j \in N(i)} C_{ij} \frac{(\Delta P)_{ij}}{L_{ij}} \end{cases}$$

- Edges with initial positive conductivity are non-vanishing (in finite time) and bounded.

$$|\nabla \tilde{\mathcal{E}}|^2 = \sum_{(i,j) \in E} \left(\frac{Q_{ij}}{C_{ij}^2} L_{ij} - \nu C_{ij}^\gamma L_{ij} \right)^2 C_{ij}^{\alpha-1}$$

Form discrete parallelotopes to a continuum

What if the step size turns to zero?

Form discrete parallelotopes to a continuum

What if the step size turns to zero?

The goal of this section is to

- ▶ derive the formal macroscopic limit of the discrete model as the number of nodes and edges tends to infinity,

Form discrete parallelotopes to a continuum

What if the step size turns to zero?

The goal of this section is to

- ▶ derive the formal macroscopic limit of the discrete model as the number of nodes and edges tends to infinity,
- ▶ establish the PDE model,

Form discrete parallelotopes to a continuum

What if the step size turns to zero?

The goal of this section is to

- ▶ derive the formal macroscopic limit of the discrete model as the number of nodes and edges tends to infinity,
- ▶ establish the PDE model,
- ▶ take a glance at the weak solutions of the corresponding gradient flow.

The modeling of continuum case

The energy consumption functional on \mathbb{R}^d

- Let $(i-1)_k$ and $(i+1)_k$ denote the left and right neighbours of vertex i on the k -th spatial dimension respectively. Thus the Kirchhoff law is then written as

$$-\sum_{k=1}^d C_{(i-1)_k,i} \frac{(\Delta P)_{(i-1)_k,i}}{L_{(i-1)_k,i}} - C_{i,(i+1)_k} \frac{(\Delta P)_{i,(i+1)_k}}{L_{i,(i+1)_k}} = S_i$$

The modeling of continuum case

The energy consumption functional on \mathbb{R}^d

- ▶ Let $(i-1)_k$ and $(i+1)_k$ denote the left and right neighbours of vertex i on the k -th spatial dimension respectively. Thus the Kirchhoff law is then written as

$$-\sum_{k=1}^d C_{(i-1)_k,i} \frac{(\Delta P)_{(i-1)_k,i}}{L_{(i-1)_k,i}} - C_{i,(i+1)_k} \frac{(\Delta P)_{i,(i+1)_k}}{L_{i,(i+1)_k}} = S_i$$

- ▶ If each point has with the equal length h_k to the left or right neighbour with respect to the k -th spatial dimension, then

$$-\sum_{k=1}^d C_{(i-1)_k,i} \frac{(\Delta P)_{(i-1)_k,i}}{h_k} - C_{i,(i+1)_k} \frac{(\Delta P)_{i,(i+1)_k}}{h_k} = S_i$$

The modeling of continuum case

The energy consumption functional on \mathbb{R}^d

- ▶ Let $(i-1)_k$ and $(i+1)_k$ denote the left and right neighbours of vertex i on the k -th spatial dimension respectively. Thus the Kirchhoff law is then written as

$$-\sum_{k=1}^d C_{(i-1)_k, i} \frac{(\Delta P)_{(i-1)_k, i}}{L_{(i-1)_k, i}} - C_{i, (i+1)_k} \frac{(\Delta P)_{i, (i+1)_k}}{L_{i, (i+1)_k}} = S_i$$

- ▶ If each point has with the equal length h_k to the left or right neighbour with respect to the k -th spatial dimension, then

$$-\sum_{k=1}^d C_{(i-1)_k, i} \frac{(\Delta P)_{(i-1)_k, i}}{h_k} - C_{i, (i+1)_k} \frac{(\Delta P)_{i, (i+1)_k}}{h_k} = S_i$$

- ▶  : First difference operation(s).

The modeling of continuum case



The energy consumption functional on \mathbb{R}^d

- ▶ Let $(i-1)_k$ and $(i+1)_k$ denote the left and right neighbours of vertex i on the k -th spatial dimension respectively. Thus the Kirchhoff law is then written as

$$-\sum_{k=1}^d C_{(i-1)_k,i} \frac{(\Delta P)_{(i-1)_k,i}}{L_{(i-1)_k,i}} - C_{i,(i+1)_k} \frac{(\Delta P)_{i,(i+1)_k}}{L_{i,(i+1)_k}} = S_i$$

- ▶ If each point has with the equal length h_k to the left or right neighbour with respect to the k -th spatial dimension, then

$$-\sum_{k=1}^d C_{(i-1)_k,i} \frac{(\Delta P)_{(i-1)_k,i}}{h_k} - C_{i,(i+1)_k} \frac{(\Delta P)_{i,(i+1)_k}}{h_k} = S_i$$

- ▶  : First difference operation(s).
- ▶  : Second difference operation(s).

The modeling of continuum case

Discrete approximation of the Poisson equation

- ▶ Consider the solution $p(x)$ of the Poisson equation

$$-\nabla \cdot (c \nabla p) = S$$

The modeling of continuum case

Discrete approximation of the Poisson equation

- Consider the solution $p(x)$ of the Poisson equation

$$-\nabla \cdot (c \nabla p) = S$$

- Then the finite difference approximation is given by

$$-\sum_{k=1}^d C_{(i-1)_k, i} \frac{(\Delta P)_{(i-1)_k, i}}{L_{(i-1)_k, i}} - C_{i, (i+1)_k} \frac{(\Delta P)_{i, (i+1)_k}}{L_{i, (i+1)_k}} + O(h_k^{(d)})$$

The modeling of continuum case

Discrete approximation of the Poisson equation

- ▶ Consider the solution $p(x)$ of the Poisson equation

$$-\nabla \cdot (c \nabla p) = S$$

- ▶ Then the finite difference approximation is given by

$$-\sum_{k=1}^d C_{(i-1)_k, i} \frac{(\Delta P)_{(i-1)_k, i}}{L_{(i-1)_k, i}} - C_{i, (i+1)_k} \frac{(\Delta P)_{i, (i+1)_k}}{L_{i, (i+1)_k}} + O(h_k^{(d)})$$

- ▶ Equal $c_k(x_{(i \pm 1/2)_k})$ with $C_{i, i \pm 1}$, S_i with $S(x_i)$, P_i with $p(x_i)$ and $P_{i \pm 1}$ with $p(x_{i \pm 1})$. Here $c = \text{diag}(c_1, c_2, \dots, c_d)$ is a diagonal permeability tensor field with scalar non-negative functions $c_k \in C(\Omega)$.

The modeling of continuum case

Discrete approximation of the Poisson equation

- ▶ Consider the solution $p(x)$ of the Poisson equation

$$-\nabla \cdot (c \nabla p) = S$$

- ▶ Then the finite difference approximation is given by

$$-\sum_{k=1}^d C_{(i-1)_k, i} \frac{(\Delta P)_{(i-1)_k, i}}{L_{(i-1)_k, i}} - C_{i, (i+1)_k} \frac{(\Delta P)_{i, (i+1)_k}}{L_{i, (i+1)_k}} + O(h_k^{(d)})$$

- ▶ Equal $c_k(x_{(i \pm 1/2)_k})$ with $C_{i, i \pm 1}$, S_i with $S(x_i)$, P_i with $p(x_i)$ and $P_{i \pm 1}$ with $p(x_{i \pm 1})$. Here $c = \text{diag}(c_1, c_2, \dots, c_d)$ is a diagonal permeability tensor field with scalar non-negative functions $c_k \in C(\Omega)$.
- ▶ The rescaled Kirchhoff's law is concluded to be the discrete approximation of the Poisson function.

The modeling of continuum case

Discrete approximation of the Poisson equation

► Proof of the approximation

$$\begin{aligned} S &= -\nabla \cdot (c \nabla p) \\ &= -\sum_{k=1}^d \partial_{x_k} (c_k \partial_{x_k} p) \\ &= -\sum_{k=1}^d \frac{c_k(x_{(i+1/2)_k}) \partial_{x_k} p(x_{(i+1/2)_k}) - c_k(x_{(i-1/2)_k}) \partial_{x_k} p(x_{(i-1/2)_k})}{h_k^{(d)}} + O(h_k^{(d)}) \\ &= -\sum_{k=1}^d \frac{c_k(x_{(i+1/2)_k}) \cdot \frac{p(x_{(i+1)_k}) - p(x_{(i)_k})}{h_k^{(d)}} - c_k(x_{(i-1/2)_k}) \cdot \frac{p(x_{(i)_k}) - p(x_{(i-1)_k})}{h_k^{(d)}}}{h_k^{(d)}} + O(h_k^{(d)}) \\ &= \dots \\ &= -\sum_{k=1}^d C_{(i-1)_k, i} \frac{(\Delta P)_{(i-1)_k, i}}{L_{(i-1)_k, i}} - C_{i, (i+1)_k} \frac{(\Delta P)_{i, (i+1)_k}}{L_{i, (i+1)_k}} + O(h_k^{(d)}) \end{aligned}$$

The modeling of continuum case

Discrete approximation of the other formulæ

- The global mass conservation formula

$$\sum_{i \in V} S_i = 0 \iff \int_{\partial\Omega} S(x) dx = 0$$

The modeling of continuum case

Discrete approximation of the other formulæ

- The global mass conservation formula

$$\sum_{i \in V} S_i = 0 \iff \int_{\partial\Omega} S(x) dx = 0$$

- The metabolic term in continuum case:

$$\int_{\Omega} \frac{\nu}{\gamma} |c_k|^\gamma dx = \frac{\nu}{\gamma} W^{(d)} \sum_{i \in V} |c_k(X_{(i+1/2)_k})|^\gamma + O(h_k^{(d)})$$

Here $W^{(d)} := \prod_{k=1}^d h_k^{(d)}$ is the unit cube.

The modeling of continuum case

Discrete approximation of the other formulæ

- ▶ The global mass conservation formula

$$\sum_{i \in V} S_i = 0 \iff \int_{\partial\Omega} S(x) dx = 0$$

- ▶ The metabolic term in continuum case:

$$\int_{\Omega} \frac{\nu}{\gamma} |c_k|^\gamma dx = \frac{\nu}{\gamma} W^{(d)} \sum_{i \in V} |c_k(X_{(i+1/2)_k})|^\gamma + O(h_k^{(d)})$$

Here $W^{(d)} := \prod_{k=1}^d h_k^{(d)}$ is the unit cube.

- ▶ The pumping power term in continuum case:

$$\int_{\Omega} c_k (\partial_{x_k} p)^2 dx = W^{(d)} \sum_{i \in V} c_k(X_{(i+1/2)_k}) \left(\frac{p(X_{(i+1)_k}) - p(X_i)}{h_k^{(d)}} \right)^2 +$$

The modeling of continuum case

Discrete approximation of the other formulæ

- Thus the energy functional can be written as

$$\tilde{\mathcal{E}}[C] = \frac{1}{2} \sum_{k=1}^d \sum_{i \in V} \sum_{j \in N(i;k)} \left(\frac{Q_{ij}^2[C]}{C_{ij}} + \frac{\nu}{\gamma} C_{ij}^{\gamma} \right) h_k^{(d)}$$

The modeling of continuum case

Discrete approximation of the other formulæ

- ▶ Thus the energy functional can be written as

$$\tilde{\mathcal{E}}[C] = \frac{1}{2} \sum_{k=1}^d \sum_{i \in V} \sum_{j \in N(i;k)} \left(\frac{Q_{ij}^2[C]}{C_{ij}} + \frac{\nu}{\gamma} C_{ij}^{\gamma} \right) h_k^{(d)}$$

- ▶ Here $N(i; k)$ denotes $N(i) \cap \{(i \pm 1)_k\}$, that is, the neighbour in the k th spatial dimension.

The modeling of continuum case

Discrete approximation of the other formulæ

- ▶ Thus the energy functional can be written as

$$\tilde{\mathcal{E}}[C] = \frac{1}{2} \sum_{k=1}^d \sum_{i \in V} \sum_{j \in N(i;k)} \left(\frac{Q_{ij}^2[C]}{C_{ij}} + \frac{\nu}{\gamma} C_{ij}^{\gamma} \right) h_k^{(d)}$$

- ▶ Here $N(i; k)$ denotes $N(i) \cap \{(i \pm 1)_k\}$, that is, the neighbour in the k th spatial dimension.
- ▶ Via the discrete approximation, we deduce the energy functional

$$\mathcal{E}[c] := \int_{\Omega} \nabla p \cdot c \nabla p + \frac{\nu}{\gamma} |c|^{\gamma} dx = \tilde{\mathcal{E}}[C] + O(W^{(d)})$$

The modeling of continuum case

The formal L^2 -gradient flow of the energy

- In retrospect to how we have deduced $\frac{dC}{dt}$, we shall estimate the the formal L^2 -gradient flow of the continuum energy functional coupled with the Poisson equation. The relation between the discrete and continuum model is presented below.

$$\begin{array}{ccccc} \tilde{\mathcal{E}}[C] & + & \text{Kirchhoff law} & \Rightarrow & \text{gradient flow (discrete)} \\ \updownarrow & & \updownarrow & & \updownarrow \\ \mathcal{E}[c] & + & \text{Poisson equation} & \Rightarrow & L^2\text{-gradient flow (continuous)} \end{array}$$

The modeling of continuum case

The formal L^2 -gradient flow of the energy

- In retrospect to how we have deducted $\frac{dC}{dt}$, we shall estimate the the formal L^2 -gradient flow of the continuum energy functional coupled with the Poisson equation. The relation between the discrete and continuum model is presented below.

$$\begin{array}{ccccc} \tilde{\mathcal{E}}[C] & + & \text{Kirchhoff law} & \Rightarrow & \text{gradient flow (discrete)} \\ \updownarrow & & \updownarrow & & \updownarrow \\ \mathcal{E}[c] & + & \text{Poisson equation} & \Rightarrow & L^2\text{-gradient flow (continuous)} \end{array}$$

- The energy functional $\mathcal{E}[c] = \int_{\Omega} \nabla p \cdot c \nabla p + \frac{\nu}{\gamma} |c|^{\gamma} dx$

The modeling of continuum case

The formal L^2 -gradient flow of the energy

- ▶ In retrospect to how we have deducted $\frac{dC}{dt}$, we shall estimate the the formal L^2 -gradient flow of the continuum energy functional coupled with the Poisson equation. The relation between the discrete and continuum model is presented below.

$$\begin{array}{ccccc} \tilde{\mathcal{E}}[C] & + & \text{Kirchhoff law} & \Rightarrow & \text{gradient flow (discrete)} \\ \updownarrow & & \updownarrow & & \updownarrow \\ \mathcal{E}[c] & + & \text{Poisson equation} & \Rightarrow & L^2\text{-gradient flow (continuous)} \end{array}$$

- ▶ The energy functional $\mathcal{E}[c] = \int_{\Omega} \nabla p \cdot c \nabla p + \frac{\nu}{\gamma} |c|^{\gamma} dx$
- ▶ How shall we deduce $\frac{\partial c_k}{\partial t}$?

The modeling of continuum case

The formal L^2 -gradient flow of the energy

- We shall prove that $\partial_t c_k = (\partial_{x_k} p)^2 - \nu |c_k|^{\gamma-2} c_k$.

The modeling of continuum case

The formal L^2 -gradient flow of the energy

- ▶ We shall prove that $\partial_t c_k = (\partial_{x_k} p)^2 - \nu |c_k|^{\gamma-2} c_k$.
- ▶ (Calculus of variations) Let $\phi = \text{diag}(\phi_1, \phi_2, \dots, \phi_n)$ be a diagonal matrix, and ε is arbitrarily small. We have the expansion

$$p[c + \varepsilon \phi] = p_0 + \varepsilon p_1 + O(\varepsilon^2)$$

The modeling of continuum case

The formal L^2 -gradient flow of the energy

- ▶ We shall prove that $\partial_t c_k = (\partial_{x_k} p)^2 - \nu |c_k|^{\gamma-2} c_k$.
- ▶ (Calculus of variations) Let $\phi = \text{diag}(\phi_1, \phi_2, \dots, \phi_n)$ be a diagonal matrix, and ε is arbitrarily small. We have the expansion

$$p[c + \varepsilon \phi] = p_0 + \varepsilon p_1 + O(\varepsilon^2)$$

- ▶ Consider the derivation at $\varepsilon = 0$, e.g. $\left. \frac{d}{d\varepsilon} \mathcal{E}[c + \varepsilon \phi] \right|_{\varepsilon=0}$

The modeling of continuum case

The formal L^2 -gradient flow of the energy

- ▶ We shall prove that $\partial_t c_k = (\partial_{x_k} p)^2 - \nu |c_k|^{\gamma-2} c_k$.
- ▶ (Calculus of variations) Let $\phi = \text{diag}(\phi_1, \phi_2, \dots, \phi_n)$ be a diagonal matrix, and ε is arbitrarily small. We have the expansion

$$p[c + \varepsilon \phi] = p_0 + \varepsilon p_1 + O(\varepsilon^2)$$

- ▶ Consider the derivation at $\varepsilon = 0$, e.g. $\left. \frac{d}{d\varepsilon} \mathcal{E}[c + \varepsilon \phi] \right|_{\varepsilon=0}$
- ▶ Estimate the L^2 -gradient flow with the identities one deduces.

The modeling of continuum case

The formal L^2 -gradient flow of the energy

- ▶ We shall prove that $\partial_t c_k = (\partial_{x_k} p)^2 - \nu |c_k|^{\gamma-2} c_k$.
- ▶ (Calculus of variations) Let $\phi = \text{diag}(\phi_1, \phi_2, \dots, \phi_n)$ be a diagonal matrix, and ε is arbitrarily small. We have the expansion

$$p[c + \varepsilon \phi] = p_0 + \varepsilon p_1 + O(\varepsilon^2)$$

- ▶ Consider the derivation at $\varepsilon = 0$, e.g. $\left. \frac{d}{d\varepsilon} \mathcal{E}[c + \varepsilon \phi] \right|_{\varepsilon=0}$
- ▶ Estimate the L^2 -gradient flow with the identities one deduces.
- ▶ (Proof to the next page)

The modeling of continuum case

Steps for the proof.

1. The expansion $p[c + \varepsilon\phi] = p_0 + \varepsilon p_1 + O(\varepsilon^2)$.

$$2. \left. \frac{d\mathcal{E}[c + \varepsilon\phi]}{dt} \right|_{\varepsilon=0} = \sum_{k=1}^d \int_{\Omega} (\partial_{x_k} p_0)^2 \phi_k + 2c_k (\partial_{x_k} p_0) (\partial_{x_k} p_1) + \nu |c_k|^{\gamma-2} c_k \phi_k dx.$$

3. Let $\mathcal{M}[c + \varepsilon\phi] = \sum_{k=1}^n \int_{\Omega} p[c + \varepsilon\phi] \cdot \partial_{x_k} (c_k \partial_{x_k} p[c + \varepsilon\phi]) dx$, we have

$$\sum_{k=1}^d \int_{\Omega} (c_k + \varepsilon\phi_k) (\partial_{x_k} p_0)^2 + \varepsilon c_k (\partial_{x_k} p_0) (\partial_{x_k} p_1) dx = \int_{\Omega} S p_0 dx + \mathcal{O}(\varepsilon^2).$$

4. Subtracting the identity

$$\sum_{k=1}^d \int_{\Omega} c_k (\partial_{x_k} p_0)^2 dx = \int_{\Omega} S p_0 dx$$

5. Plugging into 1. to obtain

$$\frac{d}{d\varepsilon} \mathcal{E}[c + \varepsilon\phi] \Big|_{\varepsilon=0} = \sum_{k=1}^d \int_{\Omega} \left[-(\partial_{x_k} p_0)^2 + \nu |c_k|^{\gamma-2} c_k \right] \phi_k dx$$

6. Hence $\partial_t c_k = (\partial_{x_k} p)^2 - \nu |c_k|^{\gamma-2} c_k$.

The establishment of full PDE system

Two drawbacks of the theoretical Poisson function

- ▶ The Poisson equation $\nabla \cdot (c \nabla p) = s$ is possibly strongly degenerate since in general the eigenvalues (i.e., diagonal elements) of the permeability tensor c may vanish.

The establishment of full PDE system

Two drawbacks of the theoretical Poisson function

- ▶ The Poisson equation $\nabla \cdot (c \nabla p) = s$ is possibly strongly degenerate since in general the eigenvalues (i.e., diagonal elements) of the permeability tensor c may vanish.
- ▶ The diffusion constant r is introduced, i.e. $c' := r\mathbb{I} + c$ with $r(x) \geq r_0 > 0$, where \mathbb{I} is the unit matrix with dimension d .

The establishment of full PDE system

Two drawbacks of the theoretical Poisson function

- ▶ The Poisson equation $\nabla \cdot (c \nabla p) = s$ is possibly strongly degenerate since in general the eigenvalues (i.e., diagonal elements) of the permeability tensor c may vanish.
- ▶ The diffusion constant r is introduced, i.e. $c' := r\mathbb{I} + c$ with $r(x) \geq r_0 > 0$, where \mathbb{I} is the unit matrix with dimension d .
- ▶ The amended Poisson equation

$$\nabla \cdot (c' \nabla p) = \nabla \cdot (c + r\mathbb{I} \nabla p) = s$$

is uniformly elliptic as long as the eigenvalues of c' are non-negative.

The establishment of full PDE system

Two drawbacks of the theoretical Poisson function

- ▶ The equation $\partial_t c_k = (\partial_{x_k} p)^2 - \nu |c_k|^{\gamma-2} c_k$ is merely a family of ODEs parametrized by the spatial variable $x \in \Omega$

The establishment of full PDE system

Two drawbacks of the theoretical Poisson function

- ▶ The equation $\partial_t c_k = (\partial_{x_k} p)^2 - \nu |c_k|^{\gamma-2} c_k$ is merely a family of ODEs parametrized by the spatial variable $x \in \Omega$
- ▶ A linear diffusive term $D^2 \nabla^2 c_k$ is introduced to model the random fluctuations in the medium.

The establishment of full PDE system

Two drawbacks of the theoretical Poisson function

- ▶ The equation $\partial_t c_k = (\partial_{x_k} p)^2 - \nu |c_k|^{\gamma-2} c_k$ is merely a family of ODEs parametrized by the spatial variable $x \in \Omega$
- ▶ A linear diffusive term $D^2 \nabla^2 c_k$ is introduced to model the random fluctuations in the medium.
- ▶ Hence we obtain

$$\partial_t c_k = D^2 \nabla^2 c_k + (\partial_{x_k} p)^2 - \nu |c_k|^{\gamma-2} c_k$$

The establishment of full PDE system

The solution

- The solution of the PDE system

$$\begin{aligned}\partial_t c_k &= D^2 \nabla^2 c_k + |\nabla p|^2 - \nu |c_k|^{\gamma-2} c_k \\ S &= -\nabla \cdot (+ r \mathbb{I} \nabla p)\end{aligned}$$

$$c(t, x) \equiv 0, \quad \partial_n p(t, x) \equiv 0, \quad \text{for all } x \in \partial\Omega \text{ and } t > 0$$

is

$$\mathcal{E}'[c(t)] = \mathcal{E}'[c_0] + \sum_{k=1}^d \int_0^t \int_{\Omega} (\partial_t c_k(s, x))^2 \, dx \, ds$$

Thanks for listening.