

# MSIA HW #8

1a)  $JK \rightarrow Q(t+1) = Q(t)(K'(t) + Q'(t)J(t))$

$y_1(t+1) = (y_1(y_0'y_1'x_1')) + y_1'(y_0 + x_0')$

$y_1(t+1) = y_1(y_0 + y_1 + x_1') + y_1'(y_0 + x_0') \rightarrow y_1 + y_0 + x_0'$

$T \rightarrow Q(t+1) = Q(t) \oplus T(t)$

$y_0(t+1) = y_0 \oplus (x_1'y_0' + y_1'x_0)$

$A \oplus B = AB' + A'B$

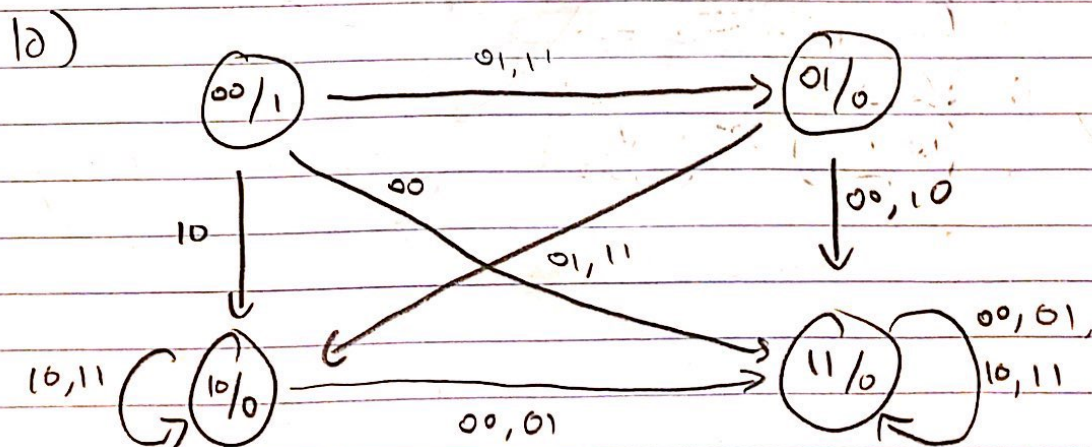
$y_0(t+1) = y_0(x_1'y_0' + y_1'x_0)' + y_0'(x_1'y_0' + y_1'x_0)$

$z = y_1'y_0'$

1b)

| PS<br>$y_1(t) y_0(t)$ | Input $x_1(t) x_0(t)$ |    |    |    | Output<br>$z$ |
|-----------------------|-----------------------|----|----|----|---------------|
|                       | 00                    | 01 | 10 | 11 |               |
| 00                    | 11                    | 01 | 10 | 01 | 1             |
| 01                    | 11                    | 10 | 11 | 10 | 0             |
| 10                    | 11                    | 11 | 10 | 10 | 0             |
| 11                    | 11                    | 11 | 11 | 11 | 0             |
| $y_1(t+1)y_0(t+1)$    |                       |    |    |    |               |
| NS                    |                       |    |    |    |               |

1c) Moore

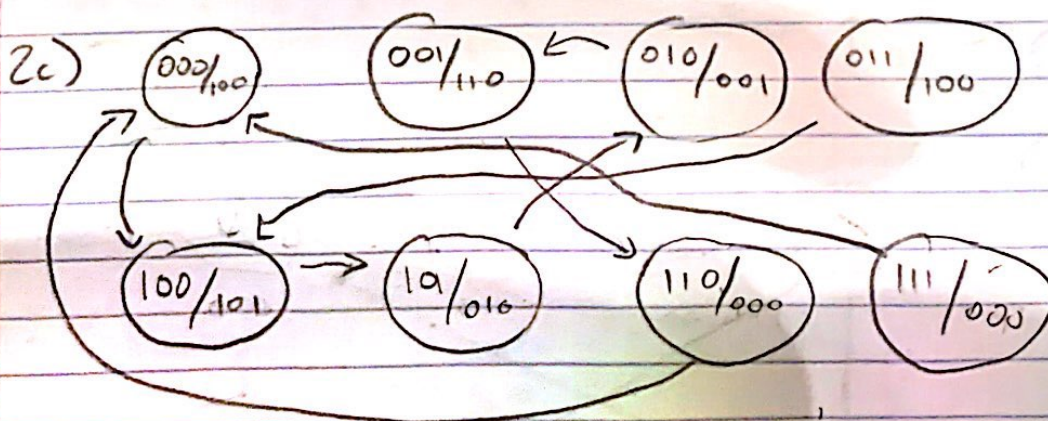




2a)  $TZ = (Q_0 + (Q_2 \oplus Q_1))'$   
 $TZ = Q_0 + (Q_2 Q_1' + Q_2' Q_1)$   
 $TZ = Q_0 + (Q_2 Q_1')' (Q_2' Q_1)'$   
 $TZ = Q_0 + (Q_2' + Q_1) (Q_2 + Q_1')$   
 $TZ = Q_0 + (Q_1 Q_2) + (Q_1' Q_2')$   
 $TI = Q_1 + Q_0$   
 $TO = Q_1 + (Q_2 \oplus Q_1)$   
 $TO = Q_1 + (Q_2 Q_1' + Q_2' Q_1)$

2b)

| PS            | NS/output                    | Trips    |
|---------------|------------------------------|----------|
| $Q_2 Q_1 Q_0$ | $Q_2(t+1) Q_1(t+1) Q_0(t+1)$ | TZ TI TO |
| 000           | 100                          | 1 0 0    |
| 001           | 110                          | 1 1 1    |
| 010           | 001                          | 0 1 1    |
| 011           | 100                          | 1 1 1    |
| 100           | 101                          | 0 0 1    |
| 101           | 010                          | 1 1 1    |
| 110           | 000                          | 1 1 0    |
| 111           | 000                          | 1 1 1    |

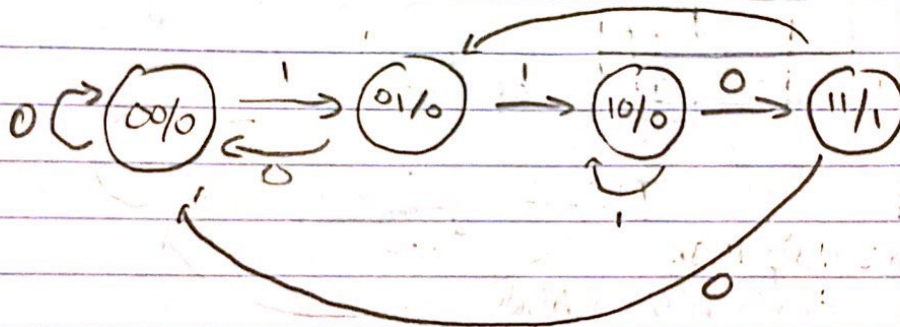


3) 001

4a) Input:  $x(t) \in \{0,1\}$

Output:  $z(t) \in \{0,1\}$

Function:  $z(t) = \begin{cases} 1 & \text{if } x(t-3,t) = 110 \\ 0 & \text{otherwise} \end{cases}$



4b)

| PS | Input    |          | z |
|----|----------|----------|---|
|    | $x(t)=0$ | $x(t)=1$ |   |
| 00 | 00       | 01       | 0 |
| 01 | 00       | 10       | 0 |
| 10 | 11       | 10       | 0 |
| 11 | 00       | 01       | 1 |
| NS |          |          |   |

4c)  $D_A \rightarrow \text{left}, D_B \rightarrow \text{right}$

| PS |   | Input | NS |   | $D_A$ | $D_B$ | z |
|----|---|-------|----|---|-------|-------|---|
| A  | B | x     | A  | B |       |       |   |
| 0  | 0 | 0     | 0  | 0 | 0     | 0     | 0 |
| 0  | 0 | 1     | 0  | 1 | 0     | 1     | 0 |
| 0  | 1 | 0     | 0  | 0 | 0     | 0     | 0 |
| 0  | 1 | 1     | 1  | 0 | 1     | 0     | 0 |
| 1  | 0 | 0     | 1  | 1 | 1     | 1     | 0 |
| 1  | 0 | 1     | 1  | 0 | 1     | 0     | 0 |
| 1  | 1 | 0     | 0  | 0 | 0     | 0     | 1 |
| 1  | 1 | 1     | 0  | 1 | 0     | 1     | 1 |



4c)  $D_A:$

|   |   |   |     |   |
|---|---|---|-----|---|
|   |   |   | $x$ |   |
|   | 0 | 0 | 1   | 0 |
| A | 1 | 1 | 0   | 0 |
|   |   |   | $B$ |   |

$D_B:$

|   |   |   |     |   |
|---|---|---|-----|---|
|   |   |   | $x$ |   |
|   | 0 | 1 | 0   | 0 |
| A | 1 | 0 | 1   | 0 |
|   |   |   | $B$ |   |

$z:$

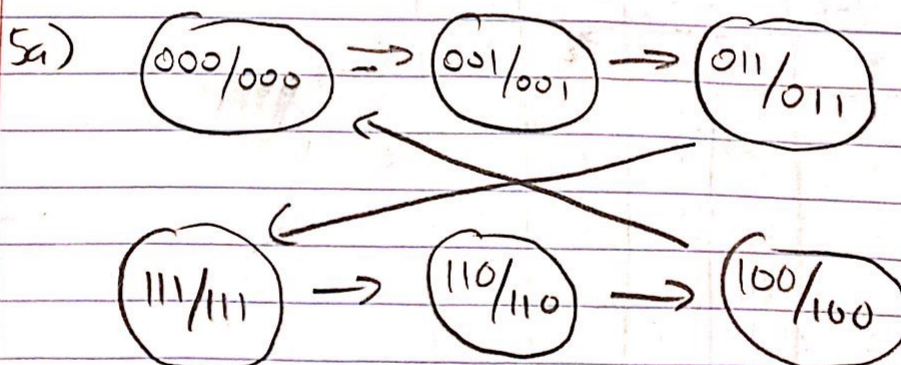
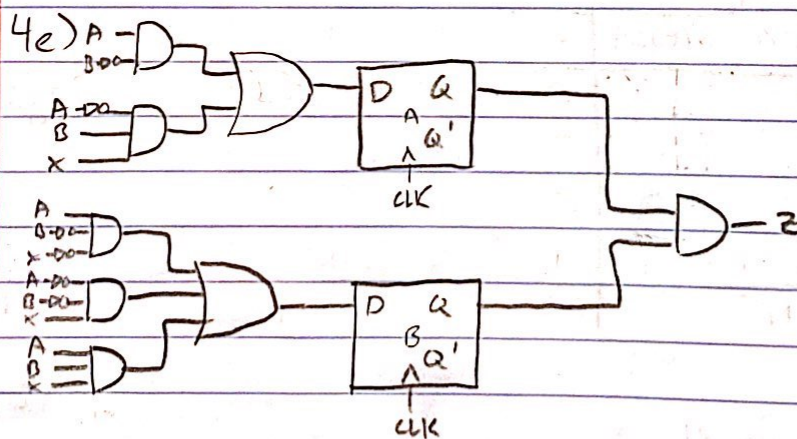
|   |   |   |     |   |
|---|---|---|-----|---|
|   |   |   | $x$ |   |
|   | 0 | 0 | 0   | 0 |
| A | 0 | 0 | 1   | 1 |
|   |   |   | $B$ |   |

4d)

$$D_A = AB' + A'Bx$$

$$D_B = AB'x' + A'B'x + ABx$$

$$z = AB$$

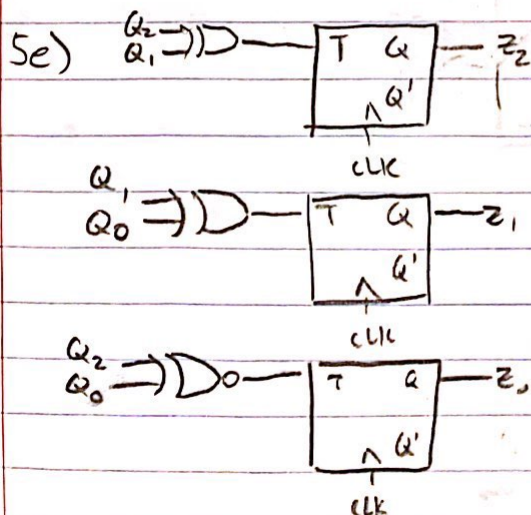


| 5b) | PS            | NS                           | T-inputs      |
|-----|---------------|------------------------------|---------------|
|     | $Q_2 Q_1 Q_0$ | $Q_2(t+1) Q_1(t+1) Q_0(t+1)$ | $T_2 T_1 T_0$ |
| 0   | 0 0 0         | 0 0 1                        | 0 0 1         |
| 1   | 0 0 1         | 0 1 1                        | 0 1 0         |
| 3   | 0 1 1         | 1 1 1                        | 1 0 0         |
| 7   | 1 1 1         | 1 1 0                        | 0 0 1         |
| 6   | 1 1 0         | 1 0 0                        | 0 1 0         |
| 4   | 1 0 0         | 0 0 0                        | 1 0 0         |

|     |        |       |        |       |
|-----|--------|-------|--------|-------|
| 5c) | $T_2:$ | $Q_0$ | $T_1:$ | $Q_0$ |
|     | $Q_2$  | $Q_1$ | $Q_2$  | $Q_1$ |
|     | 0      | 0     | 0      | 1     |
|     | 0      | 1     | 0      | 0     |
|     | 1      | 0     | 0      | 0     |
|     | 1      | 1     | 0      | 0     |

|        |       |
|--------|-------|
| $T_0:$ | $Q_0$ |
| $Q_2$  | $Q_1$ |
| 1      | 0     |
| 0      | 1     |
| 0      | 0     |
| 1      | 0     |

5d)  $T_2 = Q_2 Q_1' + Q_2' Q_1 = Q_2 \oplus Q_1$   
 $T_1 = Q_1' Q_0 + Q_1 Q_0' = Q_1 \oplus Q_0$   
 $T_0 = Q_2' Q_0' + Q_2 Q_0 = (Q_2 \oplus Q_0)'$





6)  $z_1 = xyz + xy'z' + x'y'z$   
 $z_2 = xy'z + xy'z' + x'y'z$   
 $z_1 = \sum m(3, 6, 7)$   
 $z_2 = \sum m(3, 5, 6)$

