

Final (7pm-10pm)

Started: Mar 16 at 7pm

Quiz Instructions

Question 1

3 pts

The following LISP function is designed to output the number of atoms in a (possibly nested) list. Match the items into corresponding blanks to make the function work properly.

```
(defun F(x)
```

```
(cond
```

```
  ([1] 0) ; returns 0
```

```
  ([2] 1) ; returns 1
```

```
  (t
```

```
    (+ (F (car x)) (F [3])) ;else
```

```
  )
```

```
)
```

```
)
```

[1]

[Choose]



[2]

[Choose]



[3]

[Choose]



Question 2**1 pts**

As shown in the picture, a driver in Manhattan can only drive along two directions, either drive along a street or along an avenue. Suppose you are at (x_1, y_1) , and you want to go to (x_2, y_2) , please formulate this as a search problem.



Suppose each state in this problem is a crossroad (U-turn allowed), what is the branching factor of this search problem?

- ☐ 1
- ☐ 2
- ☐ 3
- ☐ 4

Question 3**1 pts**

As shown in the previous question, the blue line is an example of the heuristic of L_2 distance.

Is this an admissible heuristic?

☐ Yes☐ No**Question 4****1 pts**

As shown in the previous question, the red line is an example of the heuristic of L₁ distance.

Is this an consistent heuristic?

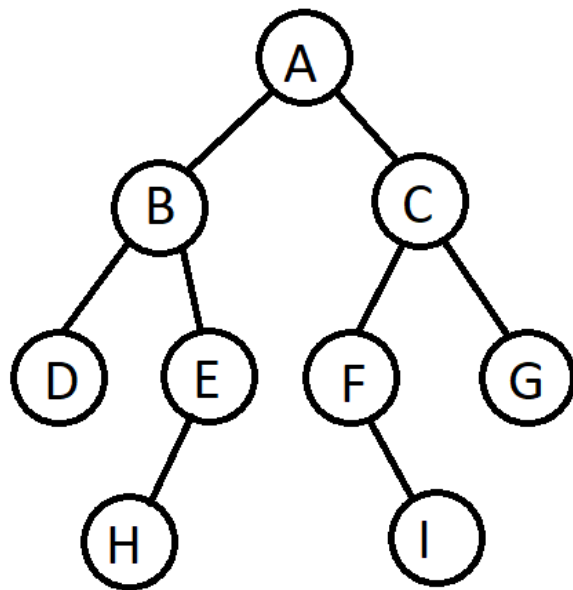
☐ Yes☐ No**Question 5****1 pts**

Any consistent heuristic is also admissible.

☐ True☐ False**Question 6****9 pts**

You are given a search tree with one node **A** labeled as a start state and another node **F** labeled as a goal state. Number the nodes in the tree according to the order in which they will be expanded (not the order in which they are generated). The goal test is applied when the node is expanded. When the order of expansion is arbitrary, assume that nodes are expanded from left to right.

Breadth First Search



A

[Choose]



B

[Choose]



C

[Choose]



D

[Choose]



E

[Choose]



F

[Choose]



G

[Choose]



H

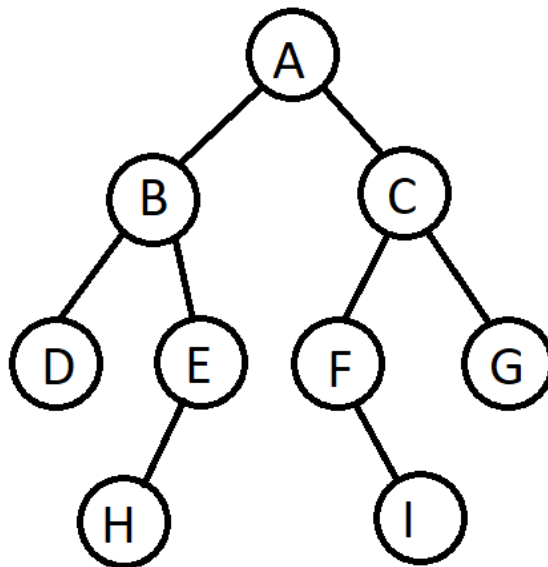


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**Question 7****12 pts**

You are given a search tree with one node **A** labeled as a start state and another node **F** labeled as a goal state. Write the order of node expansion (not the order in which they are generated). The goal test is applied when the node is expanded. When the order of expansion is arbitrary, assume that nodes are expanded from left to right.

Iterative Deepening Search: For example, we first limit the search depth to 1, which means the 1st node expanded is A; then we limit the search depth to 2, again the first node expanded is A, which means the 2nd node in the sequence is also A. You are required to filling the rest of the expansion sequence.



1st

[Choose]

▼

2nd

[Choose]

▼

3rd

[Choose]

▼

4th

[Choose]

▼

5th

[Choose]

▼

6th

[Choose]

▼

7th

[Choose]

▼

8th

[Choose]

▼

9th

[Choose]

▼

10th

[Choose]

▼

11th

[Choose]

▼

12th

[Choose]

▼

Question 8

1 pts

Uniform-cost search with a cost function $g(n) = \text{depth}(n)$ is equivalent to breadth first search. Assume the goal test of both algorithms is performed at node expansion.

- ☐ True
- ☐ False

Question 9**1 pts**

If the branching factor is finite and step costs are all identical, breadth first search is an optimal but incomplete search strategy.

- ☐ True
- ☐ False

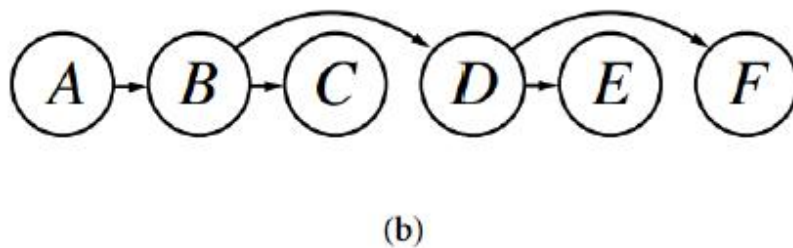
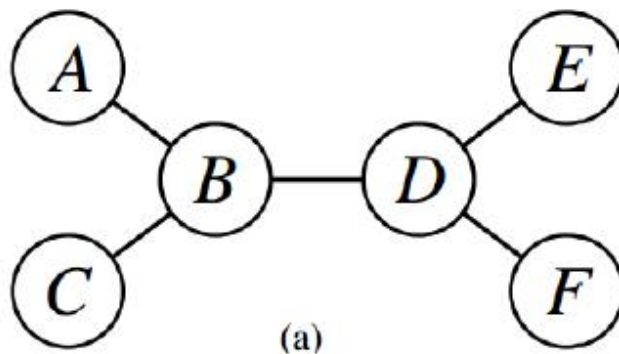
Question 10**1 pts**

One of the main advantages of hill climbing search is its small space requirements.

- ☐ True
- ☐ False

Question 11**1 pts**

Consider the tree-structured constraint satisfaction problem. We have already obtained a topological sorting of the tree, shown in picture (b).



In what order should we perform value elimination (maintain arc consistency) between each node and its parent?

- ☐ From F to A
- ☐ From A to F

Question 12

1 pts

Same as the previous question, after maintaining arc consistency, in what order should we perform value assignment?

- ☐ From A to F
- ☐ From F to A

Question 13

1 pts

Suppose we have n nodes in a tree-structured CSP graph, and the domain of each node is at most of size d . What is the time complexity of solving such a CSP problem?

Choose the most precise one.

☐ $O(nd^2)$

☐ $O(nd)$

☐ $O(d^n)$

☐ $O(n^d)$

Question 14

1 pts

The minimax procedure is guaranteed to compute an optimal move if the other player also plays optimally.

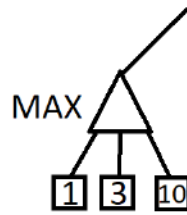
☐ True

☐ False

Question 15

1 pts

Suppose the EXPECT-MINIMAX algorithm encounters such a node shown in the picture. This node has 3 possible child nodes, each has its utility values 1,3,10 respectively. The MAX player has three actions to choose from, each will lead to a distribution over possible successors. According to the EXPECT-MINIMAX algorithm, which action will be chosen?



	A1	A2	A3
1	1/3	0	1/2
3	1/3	1	0
10	1/3	0	1/2

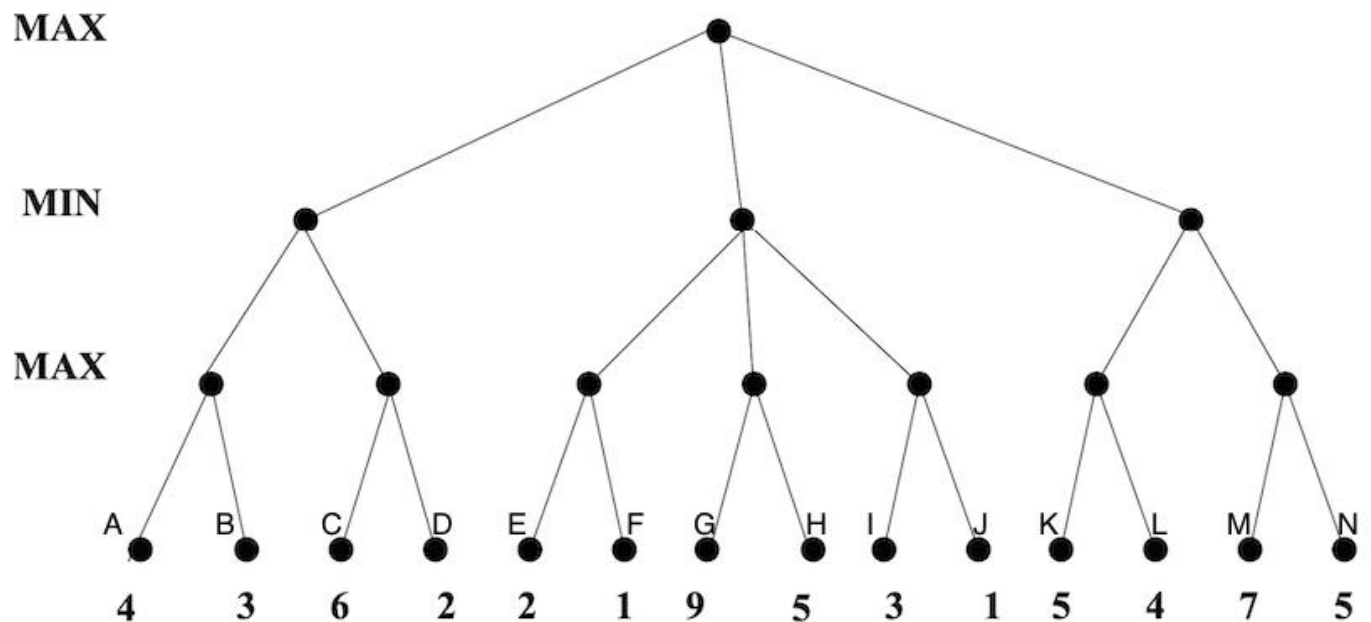
☐ A1

☐ A2

☐ A3

Question 16

14 pts



Given the above search tree, suppose we are using alpha-beta pruning to help with the search. Indicate each leaf node that will be pruned by Alpha-Beta Pruning.

A

[Choose]



B

[Choose]



C

[Choose]



D

[Choose]



E

[Choose]



F

[Choose]



G

[Choose]



H

[Choose]



I

[Choose]



J

[Choose]



K

[Choose]



L

[Choose]



M

[Choose]



N

[Choose]



Question 17**1.5 pts**

What is the initial value of alpha in alpha-beta pruning?

- ☐ Negative Infinity
- ☐ Positive Infinity
- ☐ 0
- ☐ 1

Question 18**1.5 pts**

A computer technician notes that $\frac{1}{2}$ of computers fail because of the hard drive, $\frac{1}{3}$ because of the microprocessor and $\frac{1}{6}$ fails because of both. What is the probability that the microprocessor fails given that the hard drive has failed?

- ☐ $\frac{1}{3}$
- ☐ $\frac{1}{2}$
- ☐ $\frac{1}{6}$
- ☐ Non above

Question 19**8 pts**

Match the following probability concepts with their definitions or formulae

Probability

[Choose]



Conditional independence

[Choose]



Independence

[Choose]



Product rule (chain rule)

[Choose]



Conditional probability

[Choose]



Unconditional probability

[Choose]



Bayes' rule

[Choose]



Joint probability distribution

[Choose]

**Question 20****1.5 pts**

$Pr(\alpha) = Pr(\alpha \wedge \beta) + Pr(\alpha \wedge \neg\beta)$ for any events α and β .

☐ True☐ False**Question 21****1.5 pts**

$Pr(\alpha \vee \neg\beta) = Pr(\alpha) + Pr(\neg\beta)$ for any events α and β .

☐ True☐ False

Question 22**1.5 pts**

If $\alpha \models \beta$, then $Pr(\alpha) \leq Pr(\beta)$

- ☐ True
- ☐ False

Question 23**1.5 pts**

The sentence $\exists x Person(x) \wedge Rich(x) \wedge (\forall y (Person(y) \wedge Rich(y)) \Rightarrow x = y)$ says

- ☐ At least one person is rich
- ☐ There is exactly one person who is rich
- ☐ All the people are rich
- ☐ No person is rich
- ☐ None of the others

Question 24**1.5 pts**

$(X \vee Y) \wedge (\neg X \vee \neg Y)$ is a disjunctive normal form (X, Y are variables).

- ☐ True
- ☐ False

Question 25**1.5 pts**

$A \vee B \vee \neg C$ is a Horn clause (A , B and C are variables).

☐ True

☐ False

Question 26

1.5 pts

$\Delta \models \alpha$ if and only if $\Delta \wedge \neg \alpha$ is not valid.

☐ True

☐ False

Question 27

1.5 pts

A sentence α is valid if and only if $\neg \alpha$ is unsatisfiable.

☐ True

☐ False

Question 28

1.5 pts

Consider the knowledge base $\Delta = \{A \Rightarrow B, \neg C \Rightarrow \neg B, A \Rightarrow \neg C\}$. Which of the following sentences is entailed by Δ : (and means \wedge , or means \vee , not means \neg)

☐ A and C

☐ A or B

☐ not A

☐ not A and B

☐ None of the others

Question 29**1.5 pts**

The following two sentences:

$$\exists t \text{ time}(t) \wedge (\forall x \text{ person}(x) \implies \text{fooled}(x, t))$$

$$\forall x \text{ person}(x) \implies (\exists t \text{ time}(t) \wedge \text{fooled}(x, t))$$

are:

- ☐ Equivalent.
- ☐ The first implies the second.
- ☐ The second implies the first.
- ☐ None of the others.

Question 30**1.5 pts**

$\forall x \exists y \text{ Likes}(x, y)$ is equivalent to $\exists x \forall y \text{ Likes}(x, y)$

- ☐ True
- ☐ False

Question 31**1.5 pts**

The CNF of $\neg(\forall x \exists y (P(x) \implies Q(x, y)))$ is: (A is the Skolemization constant)

A. $P(F(A)) \vee \neg Q(F(A), y)$.

B. $P(F(A)) \wedge \neg Q(F(A), y)$.

C. $P(A) \vee \neg Q(A, y)$.

D. $P(A) \wedge \neg Q(A, y)$.

☐ A

☐ B

☐ C

☐ D

☐ None of the others

Question 32

1.5 pts

Any sentence in first-order logic can be expressed without using the universal \forall quantifier.

☐ True

☐ False

Question 33

1.5 pts

Given two propositional sentences Δ and α , if we have $\Delta \models \alpha$, then Δ must have at least a single model (satisfied by at least one world).

☐ True

☐ False

Question 34**1.5 pts**

A unifier exists for $P(F(B), F(G(w)), w)$ and $P(F(y), F(y), B)$.

- ☐ True
- ☐ False

Question 35**1.5 pts**

If α can be derived from a knowledge base Δ using some inference rules, then α can be derived from Δ' using the same inference rules, where Δ' is a larger knowledge base that includes every sentence in Δ .

- ☐ True
- ☐ False

Question 36**1.5 pts**

A sibling is another child of one's parent (not necessarily all parents). Which of the following sentences reflects this fact:

- A. $\forall x, y \text{ Sibling}(x, y) \Leftrightarrow (x \neq y \wedge \forall p \text{ Parent}(p, x) \wedge \text{Parent}(p, y))$.
- B. $\exists x, y \text{ Sibling}(x, y) \Leftrightarrow (x \neq y \wedge \exists p \text{ Parent}(p, x) \wedge \text{Parent}(p, y))$.
- C. $\forall x, y \text{ Sibling}(x, y) \Leftrightarrow (x \neq y \wedge \exists p \text{ Parent}(p, x) \wedge \text{Parent}(p, y))$.
- D. $\forall x, y \text{ Sibling}(x, y) \Leftrightarrow (\exists p \text{ Parent}(p, x) \wedge \text{Parent}(p, y))$.

- ☐ A
- ☐ B
- ☐ C

- ☐ D
-
- ☐ None of the others

Question 37**1.5 pts**

Which of the following is equivalent to the sentence $\forall x \exists y \neg \text{Friends}(x, y)$?

- A. $\exists x \forall y \neg \text{Friends}(x, y)$
- B. $\neg \exists x \forall y \text{Friends}(x, y)$
- C. $\neg \forall x \exists y \text{Friends}(x, y)$
- D. $\neg \exists x \neg \forall y \neg \text{Friends}(x, y)$

- ☐ A
-
- ☐ B
-
- ☐ C
-
- ☐ D

Question 38**1.5 pts**

$\alpha \models \beta$ if and only if $\neg(\alpha \implies \beta)$ is not valid.

- ☐ True
-
- ☐ False

Question 39**1.5 pts**

The result of dropping quantifiers from $\forall x \exists y \text{Friends}(x, y)$ during the process of converting to Conjunctive Normal Form (CNF), gives (A is the Skolemization constant, F

is the Skolemization function)

- ☐ Friends(x,y)
- ☐ Friends(F(x), y)
- ☐ Friends(x, F(y))
- ☐ Friends(x, A)
- ☐ None of the others

Question 40

1.5 pts

Consider a Bayesian network with structure $(X \leftarrow Z \rightarrow Y)$ (X and Y are children of Z). Then $Pr(x, y, z)$ is equal to:

- ☐ $Pr(x) Pr(y) Pr(z)$.
- ☐ $Pr(x|z) Pr(y|z) Pr(z)$.
- ☐ $Pr(x|z) Pr(y|z)$.
- ☐ $Pr(x) Pr(y) Pr(z|xy)$.
- ☐ None of the others.

Question 41

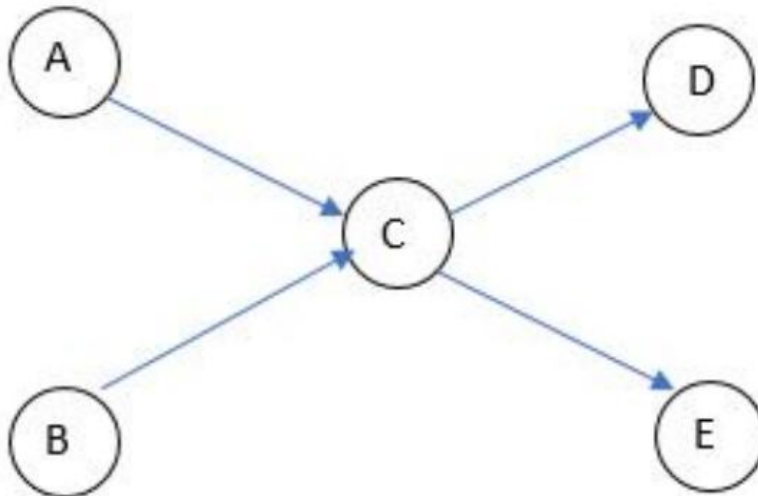
1.5 pts

If a student scores an A+ on CS111 (X), then that student must be exceptional (E) and, hence, will most probably score an A on CS161 (Y). If we want to represent this scenario using a Bayesian network, which of the following causal structures should we use? '<-' and '->' indicate arrows in Bayesian networks.

- ☐ None of the others.
- ☐ $X <- E, Y <- E$
- ☐ $X <- E, Y -> E$

☐ $X \rightarrow E, Y \leftarrow E$

☐ $X \rightarrow E, Y \rightarrow E$

Question 42**1.5 pts**

Given the above the Bayesian network, state whether the following arguments are true or false

A and B are conditionally dependent if C or D or E have been given

☐ True

☐ False

Question 43**1.5 pts**

Following the same Bayesian network, state whether the following arguments are true or false

E is conditionally independent of A, B and D if C is not given

☐ True

☐ False**Question 44****1.5 pts**

Following the same Bayesian network, state whether the following arguments are true or false

D is conditionally independent of A, B and E if C is given

☐ True☐ False**Question 45****1.5 pts**

Following the same Bayesian network, state whether the following arguments are true or false

D and E are dependent if C is not given

☐ True☐ False

Quiz saved at 7:01pm

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