## MATH 33A Midterm 1

## **CHARLES ZHANG**

**TOTAL POINTS** 

## 46 / 50

**QUESTION 1** 

## Problem 1 10 pts

#### 1.1 2 / 2

- + 0 pts incorrect/missing
- √ + 2 pts correct answer
- + 1 pts Characterisation in terms of being represented by a matrix

#### 1.2 2/2

- + 0 pts incorrect/missing
- √ + 1 pts preservation of addition of vectors
- √ + 1 pts preservation of scalar multiplication
- + 1 pts Using characterization of being represented by a matrix
- + 1 pts Stating that the matrix characterisation is an equivalent definition

#### 1.3 3/3

## √ + 3 pts Correct

+ 0 pts Missing/incorrect

#### 1.4 2/2

#### √ + 2 pts Correct

+ 0 pts incorrect: rank is 2

#### 1.5 1/1

## √ + 1 pts Correct

+ 0 pts Incorrect

#### **QUESTION 2**

10 pts

#### 2.1 6 / 6

## √ - 0 pts Correct

- 3 pts T and S fail to commute

- + 1 pts but gives definition of commuting [only given if 2 is given] [mutually exclusive with 5]
  - 3 pts S and U do commute
- + 1 pts but gives definition of not commuting [only given if 4 is given] [mutually exclusive with 3]
  - 6 pts No credit
  - 2 pts S has changed

#### 2.2 2/2

√ + 1 pts A correct (45 degree counterclockwise rotation + scaling by 1/sqrt(2)) - [note: it's OK to get the scaling factor incorrect, as long as some nontrivial scaling is done. Must mention or draw scaling].

 $\sqrt{+1}$  pts B correct (reflection through x-axis / the line y = 0)

+ 0 pts All incorrect / blank

#### 2.3 2/2

## √ + 2 pts Correct (up to possibly switching the two vectors)

- + 1 pts Drew BA instead of AB [note that AB means B first, then A]
  - + 1 pts Computed the matrix AB correctly
  - + 0 pts Incorrect/blank

### **QUESTION 3**

10 pts

## 3.1 4 / 4

#### √ - 0 pts Correct

- 1 pts Point 1: Put into RREF with minor arithmetic error
- 2 pts Point 1: Unable to put into RREF (Substantial error)
- 3 pts Point 1: Unable to use Gauss-Jordan

elimination

 - 1 pts Point 2: Incorrectly reading off solutions from RREF

## 3.2 3/3

- √ 0 pts Correct
  - 1 pts Incorrect Answer
  - 2 pts Incorrect Justification

#### 3.3 3/3

- √ 0 pts Correct
- **1 pts** Incorrectly stated that no solutions was possible.
- 1 pts Incorrectly stated that one solution was possible.
  - 2 pts Did not justify Answer
  - 3 pts Incorrect

#### **QUESTION 4**

10 pts

#### 4.1 1/2

- + 2 pts Correct
- √ + 1 pts Partial credit: The student states a theorem
  about invertible matrices but not the actual
  definition, e.g. that an invertible matrix row reduces
  to the identity. The student also could have
  attempted to give the actual definition but made
  some sort of small error.
  - + 0 pts Incorrect

## 4.2 0/2

+ 2 pts Correct: student gives either a non-invertible transformation T from R2 to R2 or a 2x2 non-invertible matrix

## √ + 0 pts Incorrect

This is not a transformation from R2 to R2.

#### 4.3 3/4

- + 4 pts Completely correct
- √ + 1 pts Full Credit Criterion 1: Student states that A
  is invertible

 $\checkmark$  + 2 pts Full Credit Criterion 2: Student is able to preform row operations to reduce A down to the identity.

- + 1 pts Full Credit Criterion 3: Student gives correct form of A^(-1)
- + **0 pts** The student was unable to completely row reduce A correctly and did not determine that A was invertible.

#### 4.4 2/2

√ + 2 pts Correct: There are either infinitely many or no solutions

+ 0 pts Incorrect

#### QUESTION 5

10 pts

#### 5.1 2 / 2

- √ 0 pts Correct
  - 2 pts Incorrect

#### 5.2 2/2

- √ 0 pts Correct
  - 2 pts Incorrect

#### 5.3 2/2

- √ + 2 pts Correct
  - + 0 pts Incorrect

#### 5.4 2/2

- √ + 2 pts Correct
  - + 0 pts Incorrect

## 5.5 2/2

- √ + 2 pts Correct (False)
  - + 0 pts Incorrect (True)
  - + 0 pts Blank/no answer

# Midterm 1 (Math 33A, Fall 2019)

Your Name: Charles Zhang
UCLA id: 305-413-659
Date: 10/21/19

The rules: You can answer using a pencil or ink pen. You are allowed to use only this paper, pencil or pen, and the scratch paper provided. You should not hand the scratch paper in. No calculators. No books, no notebooks, no notes, no mobile phones, no web access. You must write your name and UCLA id. You have exactly 50 minutes.

## Points:

Problem 1: \_\_\_\_/10
Problem 2: \_\_\_\_/10
Problem 3: \_\_\_\_/10
Problem 4: \_\_\_\_/10
Problem 5: \_\_\_\_/10
Total: \_\_\_\_\_ (out of 50)

## Problem 1 (10 points in total)

Consider the map  $T \colon \mathbb{R}^3 \to \mathbb{R}^2$  defined by

$$T\left(\begin{bmatrix} v_1\\v_2\\v_3\end{bmatrix}\right) = \begin{bmatrix} v_1\\v_2\end{bmatrix}$$

for any vector  $\begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix}$  in  $\mathbb{R}^3$ .

1. (2 points) Write down the definition of linear transformation.

Solution: A transformation  $T: \mathbb{R}^n \to \mathbb{R}^n$  such that  $T(\vec{v} + \vec{\omega}) = T(\vec{v}) + T(\vec{\omega})$  and  $T(k\vec{v}) = kT(\vec{v})$ .

2. (2 points) Show that the map T is a linear transformation.

Solution:  $\vec{U} = \begin{bmatrix} \vec{V}_1 \\ \vec{V}_2 \end{bmatrix} \qquad \vec{U} = \begin{bmatrix} \vec{U}_1 \\ \vec{V}_2 \end{bmatrix} \qquad = \begin{bmatrix} \vec{V}_1 + \vec{U}_1 \\ \vec{V}_2 + \vec{U}_2 \end{bmatrix} = \begin{bmatrix} \vec{V}_1 + \vec{U}_1 \\ \vec{V}_2 \end{bmatrix} = \begin{bmatrix} \vec{V}_1 \\$ 

3. (3 points) Write down the matrix A such that T(v) = Av for all vectors v in  $\mathbb{R}^3$ .

4. (2 points) Compute the rank of A.

Solution: 
$$A = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} = rref(A)$$

$$2 | ending | | | | | | |$$

$$rank(k) = 2$$

5. (1 point) Let B be any matrix of the same size as A. Can B have rank larger than A?

Solution:	rank en	*	

## Problem 2 (10 points in total)

1. (6 points) Give an example of three linear transformations  $T: \mathbb{R}^2 \to \mathbb{R}^2$  and  $S: \mathbb{R}^2 \to \mathbb{R}^2$  and  $U: \mathbb{R}^2 \to \mathbb{R}^2$  such that the matrices that represent T and S commute, while the matrices that represent S and U do not commute. (Recall: we say that an  $n \times m$  matrix A represents a linear transformation  $T: \mathbb{R}^m \to \mathbb{R}^n$  if T(v) = Av for all  $v \in \mathbb{R}^m$ .)

## Solution:

T: R2 -> 1R2 With matrix [ 0 -1], representing a counterclockwise 90° rotation

S: R2->1R2 with matrix [9 0], representing a clockwise 90° rotation.

O: 12->182 with motifix [ o -1], representing a reflection over the x-axis.

2. (4 points in total) Let 
$$A = \begin{bmatrix} 0.5 & -0.5 \\ 0.5 & 0.5 \end{bmatrix}$$
 and  $B = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$ .

• (2 points) Give a geometric interpretation of the transformations represented by

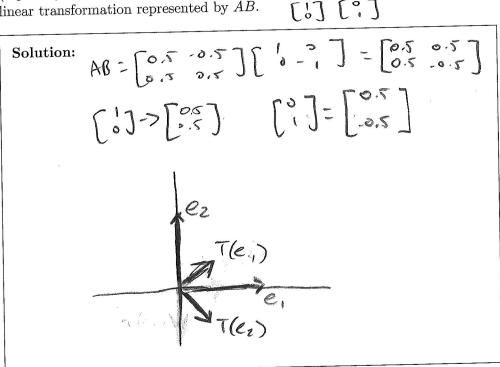
• (2 points) Give a geometric interpretation of the transformations represented by A and B. (In words, or using a drawing.)

Solution:

The transfirmation represented by A is a scaling down by JZ and a 45° counterclockwise rotation.

The transformation represented by B is a reflection over the x-axli.

(2 points) Draw the images of the standard basis unit vectors of  $\mathbb{R}^2$  under the [:] [:] linear transformation represented by AB.



## Problem 3 (10 points in total)

Consider the following system of three linear equations in the variables  $x_1, x_2, x_3, x_4$ :

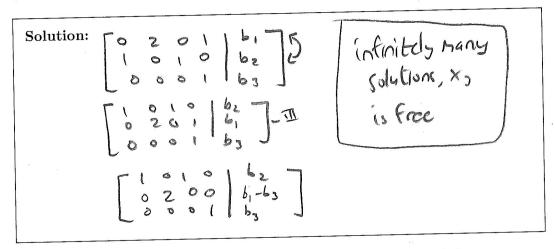
$$2x_2 + x_4 = 1$$
$$x_1 + x_3 = 1$$
$$x_4 = 1$$

1. (4 points) Solve the system using the Gauss-Jordan elimination algorithm.

2. (3 points) Let  $b_1, b_2, b_3$  be arbitrary real numbers. How many solutions does the system

$$2x_2 + x_4 = b_1$$
$$x_1 + x_3 = b_2$$
$$x_4 = b_3$$

have?



3. (3 points) Let A be any  $n \times n$  matrix. Is there always a sequence of elementary row operations that transforms the identity matrix  $I_n$  into A? You should motivate your answer.

Solution: No, A could have a row of zeroes, which would be impossible to transform into, as multiplying a row by zero is not an elementary row operation.

## **Problem 4** (10 points in total)

1. (2 points) Write down the definition of invertible matrix.

is equal to n.

2. (2 points) Give an example of a linear transformation  $T: \mathbb{R}^2 \to \mathbb{R}^2$  such that the matrix that represents T is not invertible.

Solution:  $T([\sqrt{2}]) = [\sqrt{2}]$  is not

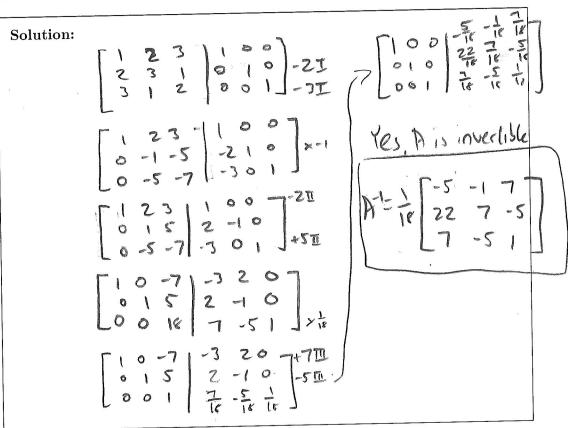
invertible, as the matrix A isn't

Square.

3. (4 points) Consider the following matrix

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \\ 3 & 1 & 2 \end{bmatrix}$$

Is A invertible? If yes, compute its inverse.



4. (2 points) Let A be an  $n \times n$  matrix. Assume that A is not invertible. How many solutions does the system Ax = b have?

solution: A has either no solution or infinitely many solutions since rank (A) \$ 1.

Problem 5 (10 points total; 2 points each)

Answer the following questions with true or false.

 $\sqrt{.}$  Any  $4 \times 3$  matrix with rank equal to 3 is invertible.

False

2. Let  $\theta$  and  $\eta$  be any two angles with  $\theta \neq \eta$ . Let  $T_{\theta} \colon \mathbb{R}^2 \to \mathbb{R}^2$  be the counterclockwise rotation in  $\mathbb{R}^2$  through  $\theta$ , and  $T_{\eta} \colon \mathbb{R}^2 \to \mathbb{R}^2$  the counterclockwise rotation in  $\mathbb{R}^2$  through  $\eta$ . Then  $T_{\eta} \circ T_{\theta} = T_{\theta} \circ T_{\eta}$ .

True

 $3\sqrt{1}$  There exists a real number a for which the following matrix is in reduced row echelon form:

$$\begin{bmatrix} 1 & 0 & 0 & 4 \\ 0 & a & 1 & 1 \\ 0 & 1 & 0 & 0 \end{bmatrix}$$

False

4. The transformation  $T: \mathbb{R}^2 \to \mathbb{R}^2$  defined by  $T\left(\begin{bmatrix} v_1 \\ v_2 \end{bmatrix}\right) = \begin{bmatrix} v_1^2 + 2v_1 + 1 \\ v_1 + v_2 \end{bmatrix}$  is linear.

5. A linear transformation  $T: \mathbb{R}^n \to \mathbb{R}^n$  is invertible if and only if for every  $v \in \mathbb{R}^n$  there exists a unique  $w \in \mathbb{R}^n$  such that T(v) = w.

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