Robo Madden '22

Mindy Le, Harlee Petretta, Dusty Waters, Calvin Wetzel EF 230 Spring 2022



EF230 Project: Robo Madden '22

Calvin Wetzel, Harlee Petretta, Mindy Le, Dusty Waters

Functions:

- 1. EF230_Robo_Football
 - 1. Robo_Madden
 - 1. Inputs
 - 1. None
 - 2. Outputs
 - 1. Turn Angles
 - 2. Distance
 - 3. Vector Matrix
 - 4. Sound
 - 2. Robo_Route
 - 1. Inputs
 - 1. Turn Angles
 - 2. Distance
 - 3. Vector Matrix
 - 4. Sound
 - 2. Outputs

MATLAB Analysis MATLAB Visualization

- 1. Commands to RVR
- 2. Sound through Computer Speakers

Externals:

Robot Data

Author: mwa0000023758055

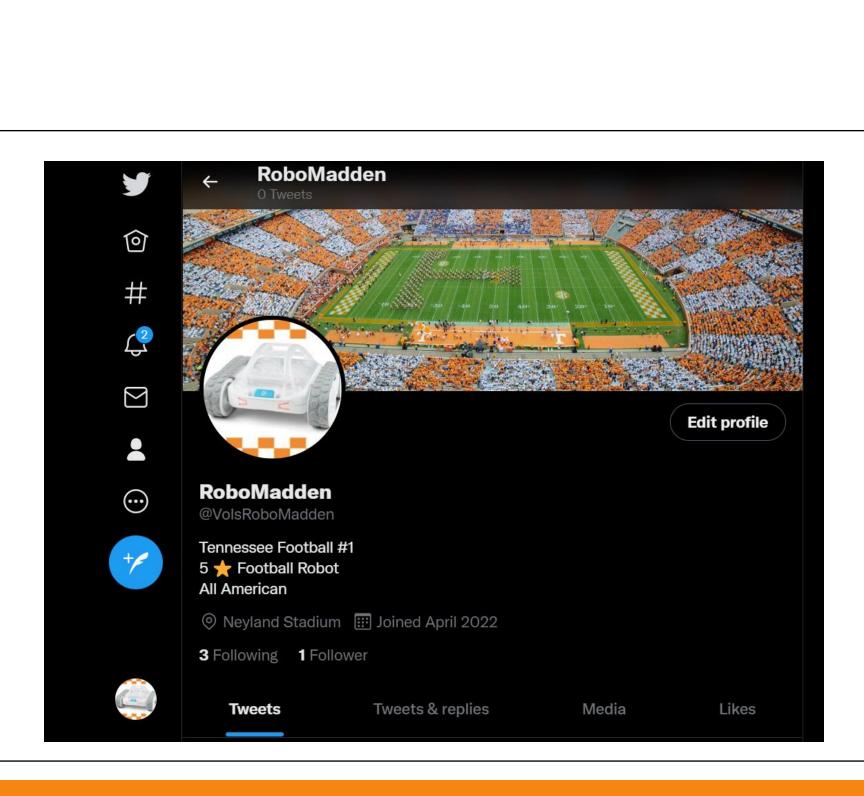
Channel Stats

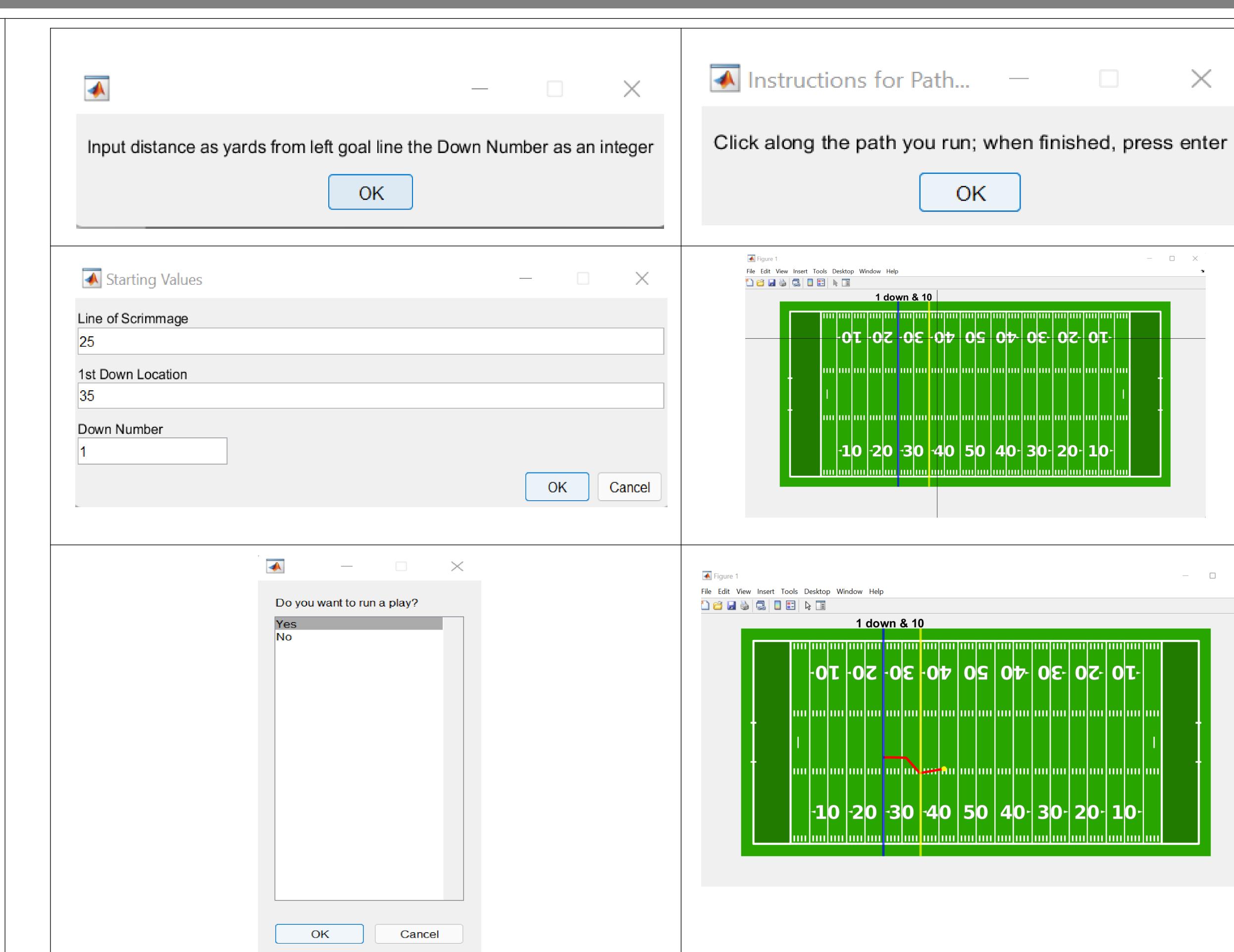
Last entry: about an hour ago

- 1. ThingSpeak: Forecast, Location, ThingTweet, Down & Distance
- 2. Twitter Page

1 down & 10

EF230 Project Data





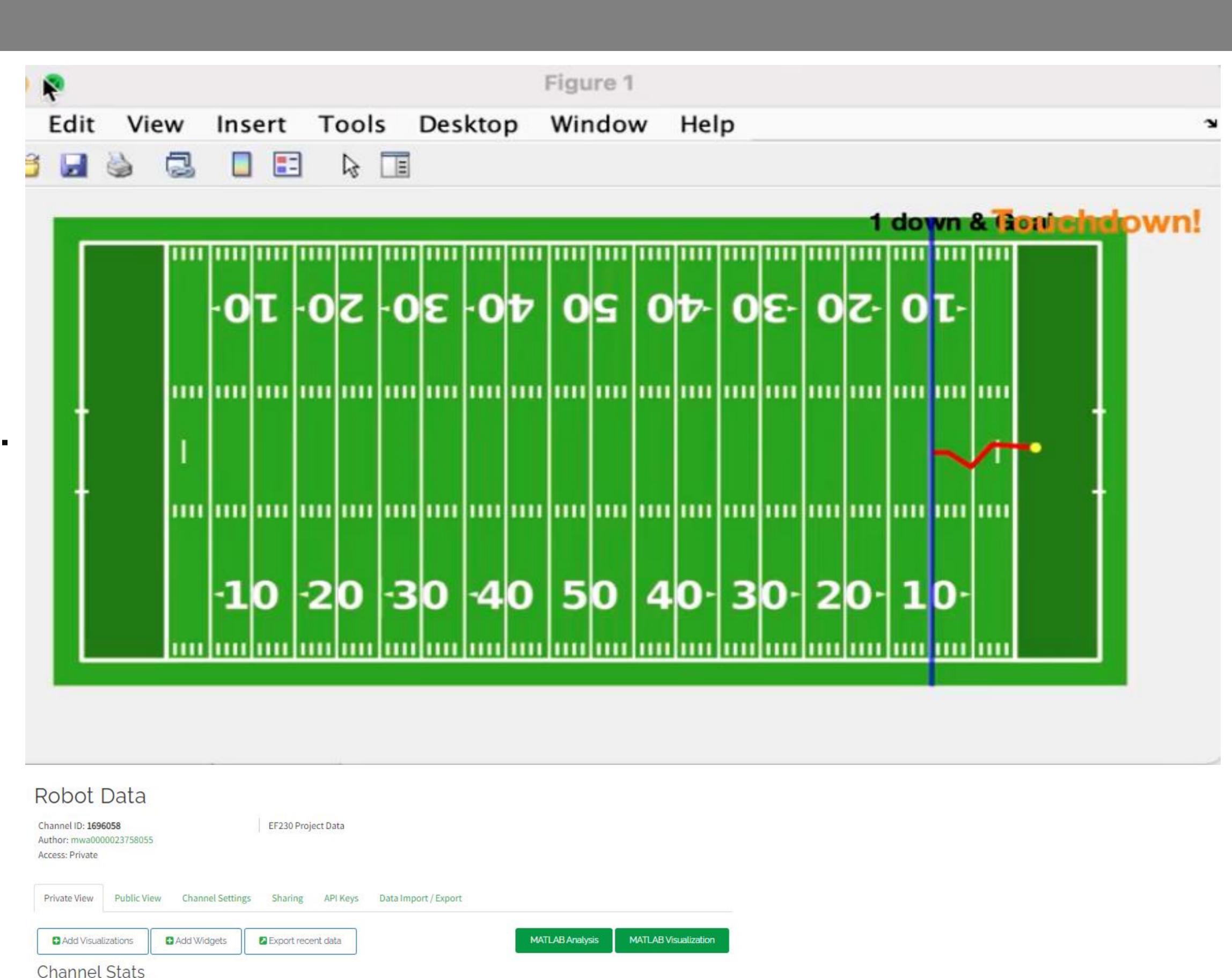
Future Improvements:

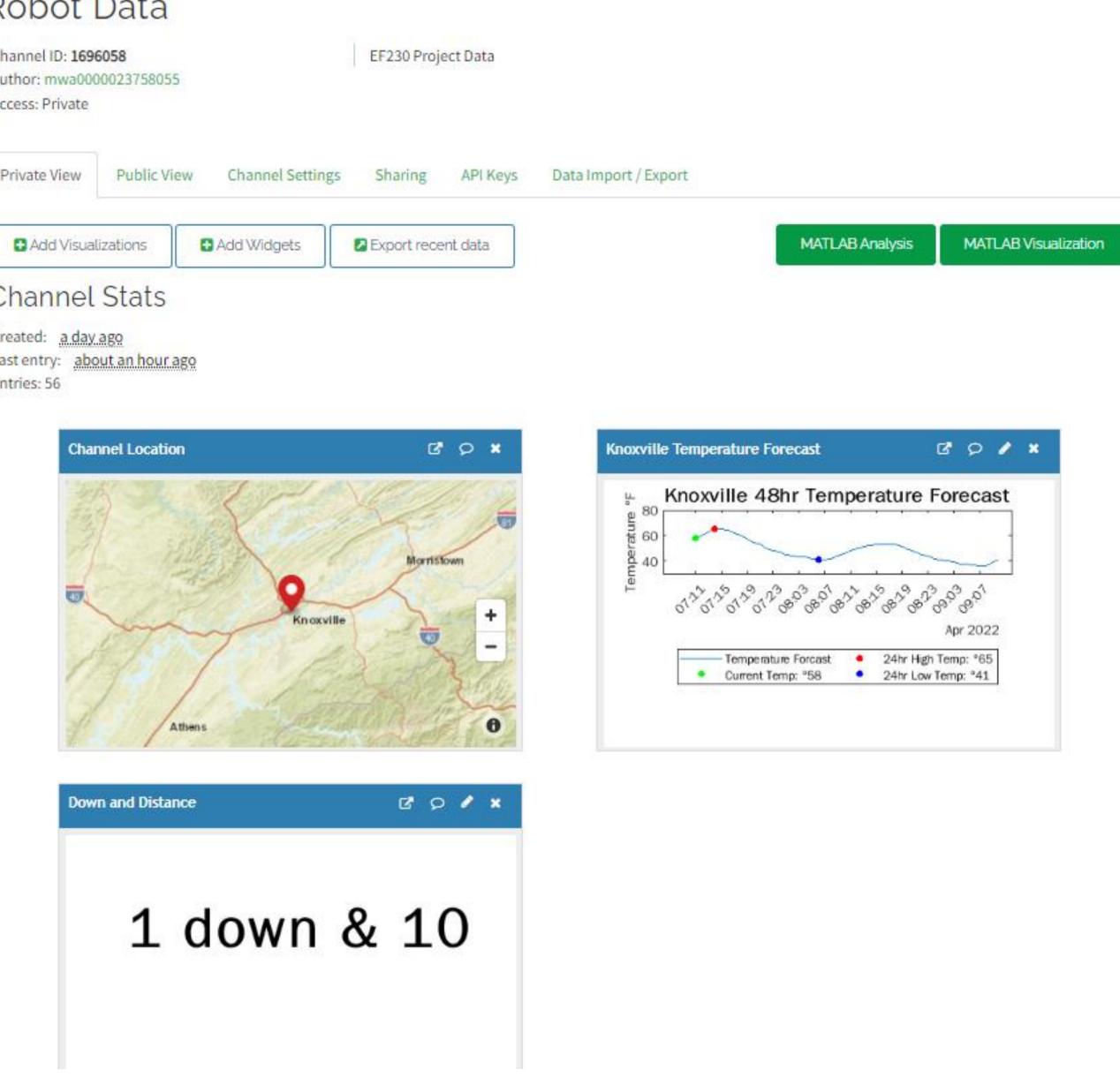
- 1) Faster Robot/MVP Robots
- 2) Robot returns to starting position/runs play indefinitely
- 3) Boosted Wi-Fi range; use a Neyland
- 4) Multiple robots/play reenactment/film study



Project Description

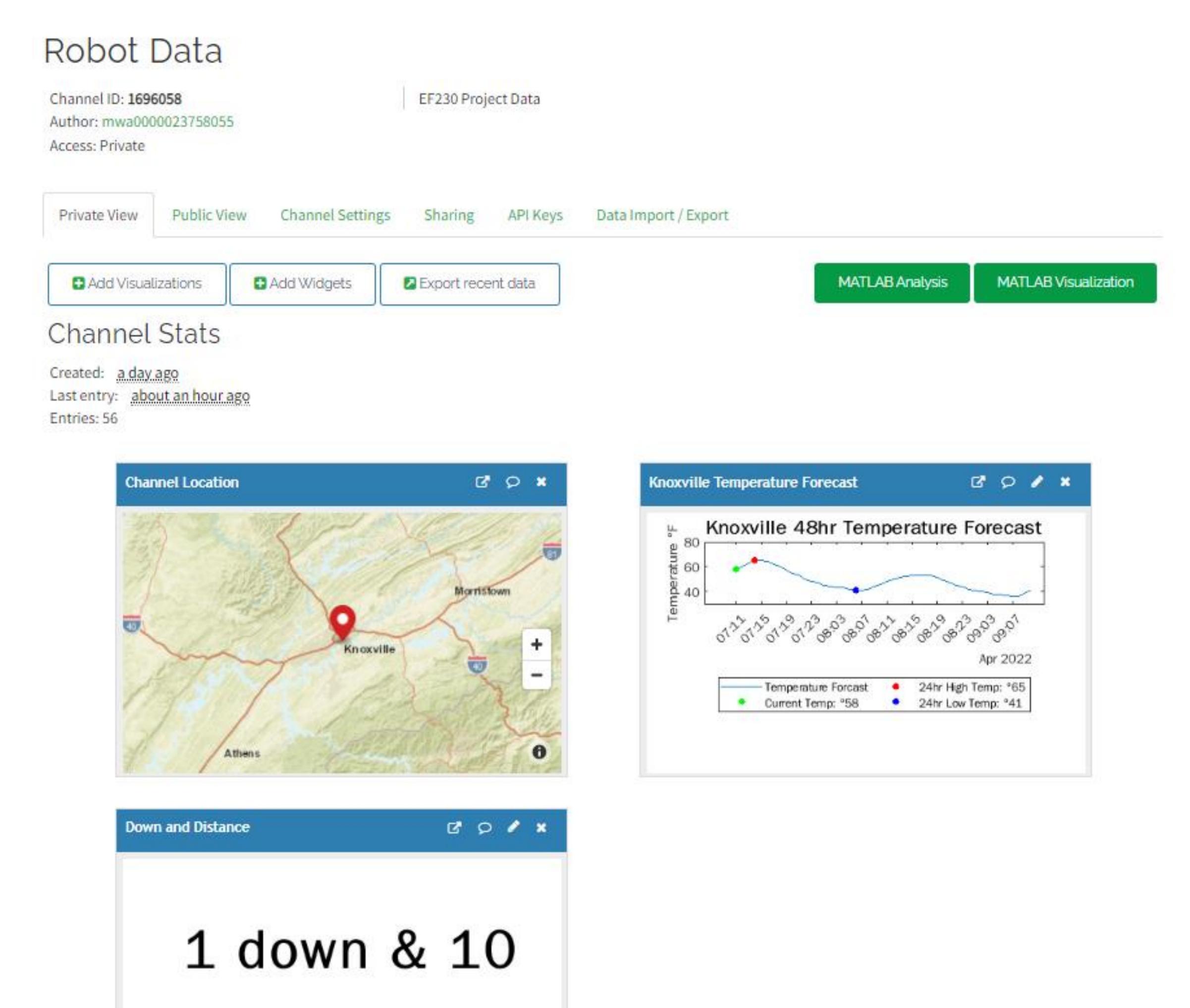
- Objective:
- -RVR completes path draw by user
- Description:
- Down, Distance, and field position selected
- Robo_Madden records path draw by user
- Path's points converted into distance vectors
- Robo_Route converts distance vectors to time values.
 Uses turn angles and time of travel values to direct
 RVR
- Technical expertise skills: Live updates on the current weather, channel location, and tweets will be sent out.
- Areas of Expertise:
- Live mapping of location (Neyland Stadium)
- Live weather forecast (48hr Knoxville)
- Tweeting game updates (Down and distance, touchdowns, 3rd downs)
- Best/Unique Features:
 - When the robot scores a touchdown, "Rocky Top" is played.
 - When robot runs into own endzone, safety is displayed
 - Tweets for Down and Distance, 3rd down, Touchdowns
 - Live updates of Down and Distance

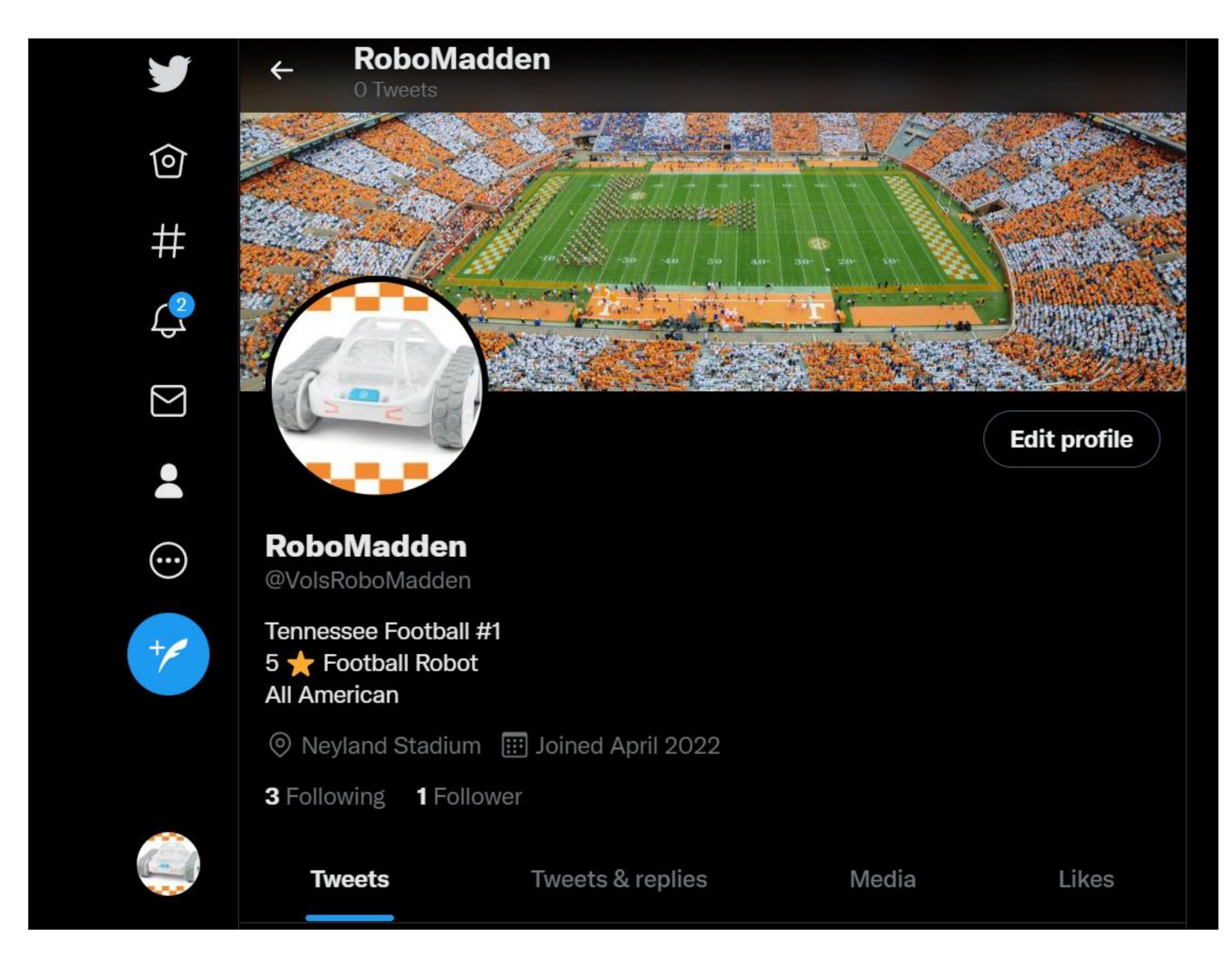




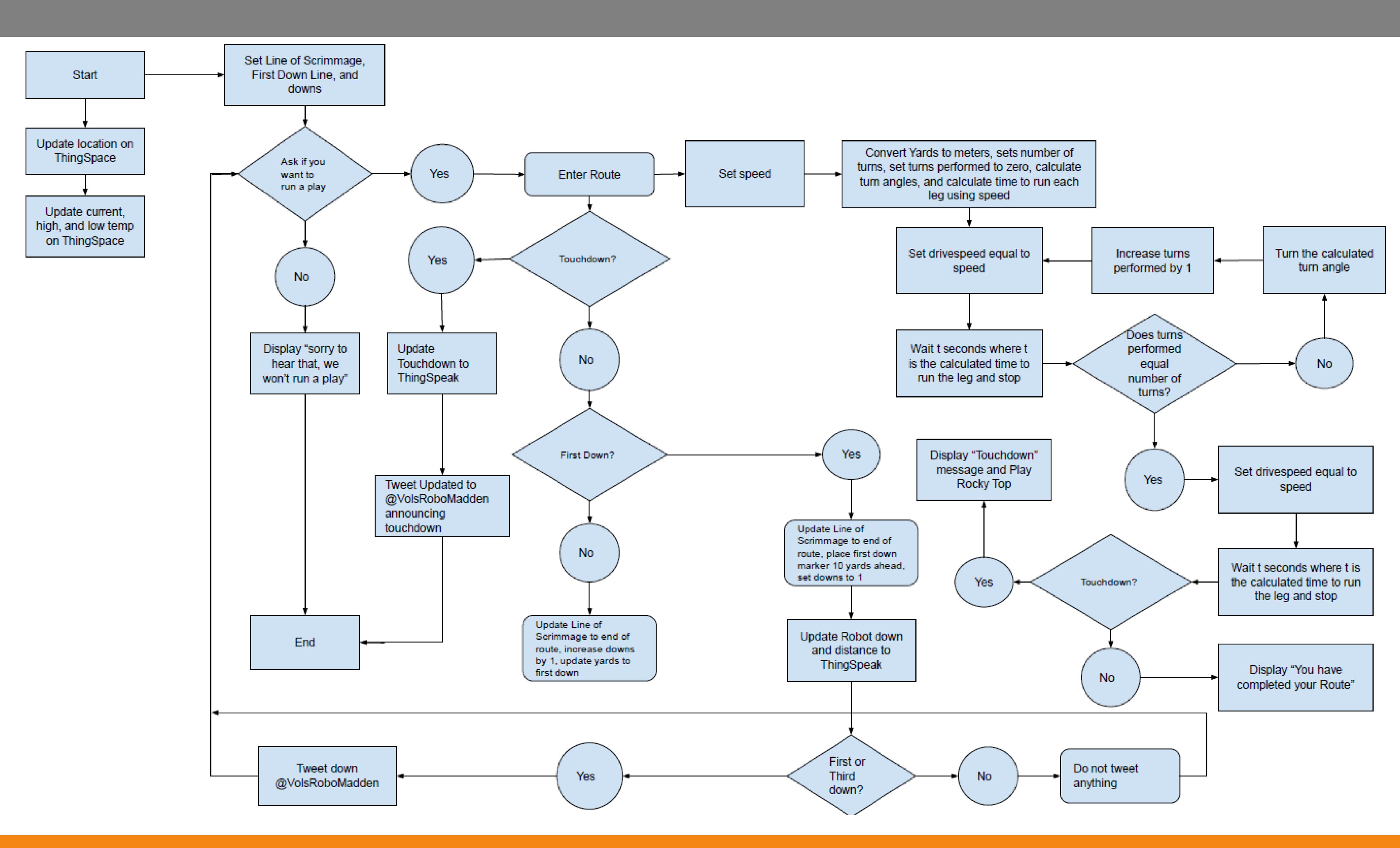


Technical Expertise Photos





Final Logic Flow Chart



Next Step/Future Work/Improvements

If we had more time, we would implement more advanced Areas of Technical Expertise. Such as: ...

- If we had more resources (boosted Wi-Fi), we would test the robot on a large scale, possibly in Neyland Stadium.
- Develop program using MVP robots (NFL's padded robots)
- Market to football team: play development, route practice, film study, & play rehearsal
- Use program on multiple robots: run plays as team of robots, run plays indefinitely (return to starting position), etc.