MBT Experiments

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This text contains a description of how to perform experiments with MBT ILP models.

1 Structure of the directory experiments/

- data/ instance files to be solved
- logs/ log files for elapsed time (timelog.txt) and objective function value (objlog.txt)
- manual/ this manual
- models/ ILP models coded in AMPL
- old/ old version of the experiment scripts (no need to bother about them)

2 Running the experiment

The main script for running the experiments is mbtrun.sh. The script is executed by typing

./mbtrun.sh [path to directory with input files] <time limit>

or

./mbtrun.sh [path to one input file] <time limit>

from the directory experiments/ (where mbtrun.sh is located). The first parameter specifying either a directory containing instance files, or a single instance file is required. If the optional parameter <time limit> in seconds is not specified, the default value (3600s) applies.

3 Input data

The input data files are not expected to follow any specific naming convention. The instances is encoded as

```
cardV cardS cardE
v1 v2
v1 v3
v2 v4
...
s1 s2 s3...
lb ub
```

where cardV is the number of nodes, cardS is the number of sources and cardE is the number of edges (potential communication links). The first line is followed by a list of edges, and the second last line consists of a list of source nodes. Finally, 1b and ub denote lower and upper bound on the optimal solution, respectively. There must not be any other characters. An example of an input file representing a path on 9 nodes with one source "0" look as follows:

```
9 8 1
0 1
1 2
2 3
3 4
4 5
5 6
6 7
7 8
0
4 12
```

4 How it works

The script iterates over all filenames in the input directory and reads the data from them. We study two models, let's call them <code>maxInformed</code> and <code>minTime</code>. Both models are written in <code>models/MBT-combined.mod</code>. It contains two objective functions, and commands <code>drop [constraint_name]</code> and <code>restore [constraint_name]</code> specify which constraints are used for which model. Once the data are loaded, the script runs LP relaxation of the model <code>maxInformed</code>, then the same model without the relaxation, and finally the model <code>minTime</code>.

When running the model *maxInformed*, the script iterates over increasing deadline. The iterative process terminates once either the objective value is cardV-cardS, or elapsed time exceeds a given time limit, or the number of iteration reaches an upper bound.

The file mbtrun.sh is very ad-hoc and contains several hard coded parameters (location of the cplex solver, log files, etc.), which should be adjusted according to the machine on which it is executed.

5 Logging

Elapsed time in seconds and objective function value of individual methods are stored in files logs/timelog.txt and logs/objlog.txt. Each line starts with a filename of the processed instance followed by the respective values in the order mentioned above.

The reported elapsed time for model *maxInformed* is a sum of elapsed times of all calls of the **solve** command during the iterative procedure.