

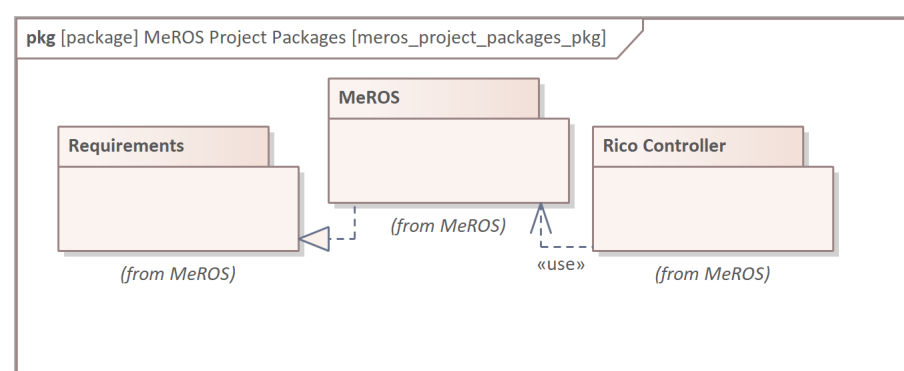
MeROS: SysML-based Metamodel for ROS-based Systems

Facilitation of Robot Operating System based projects development with Systems Engineering

version 1.1.1

Tomasz Winiarski et al.

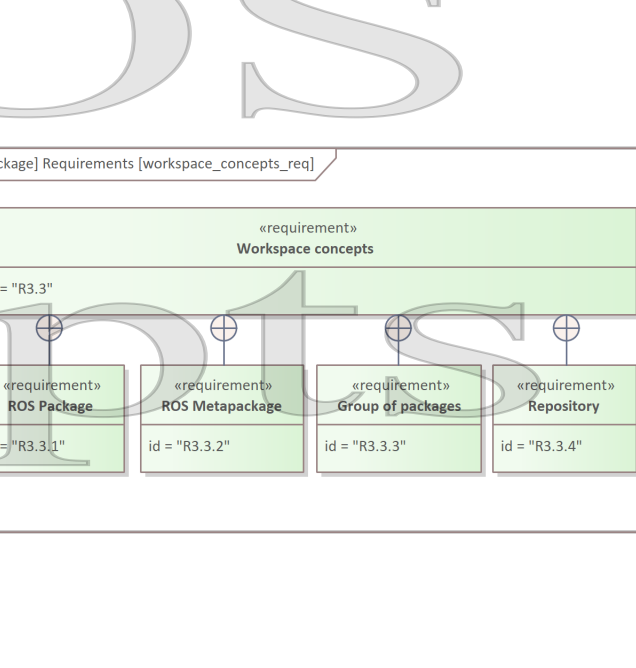
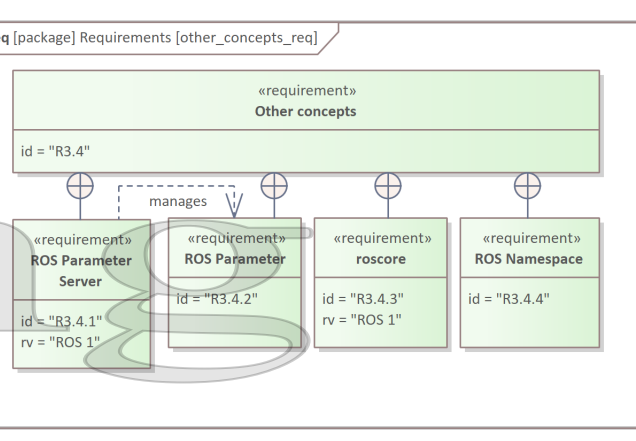
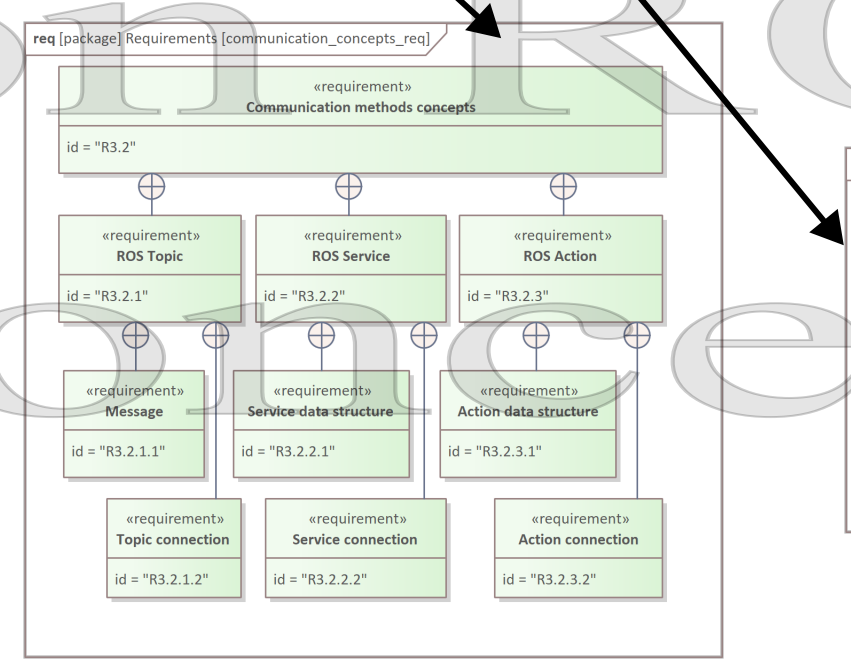
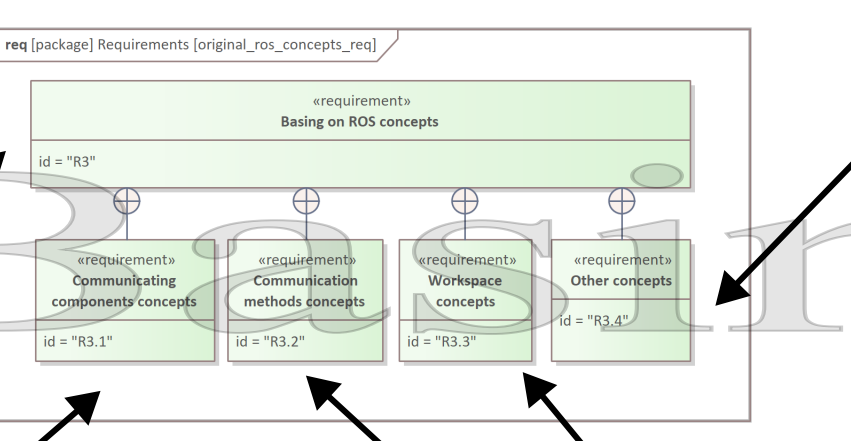
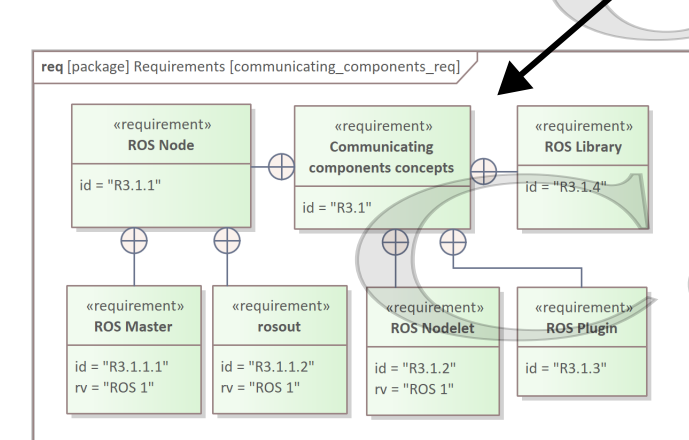
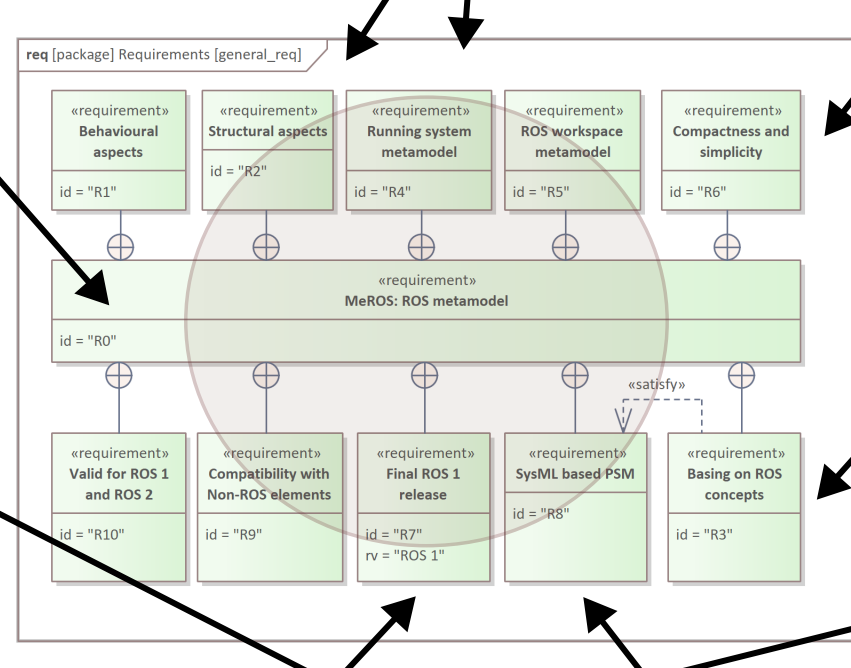
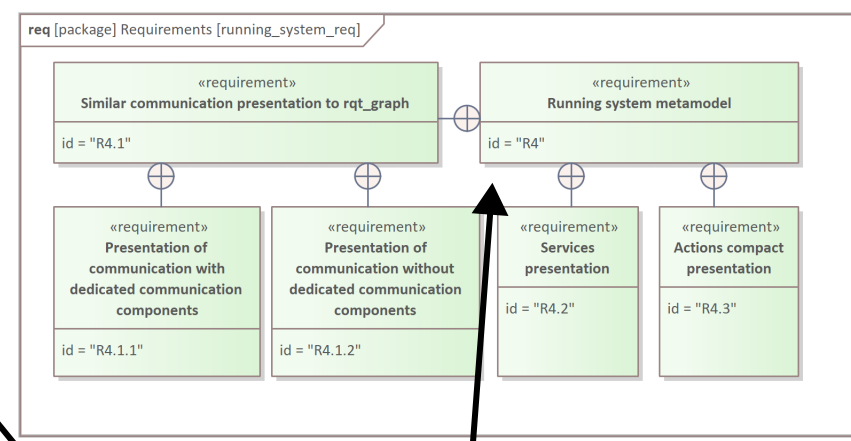
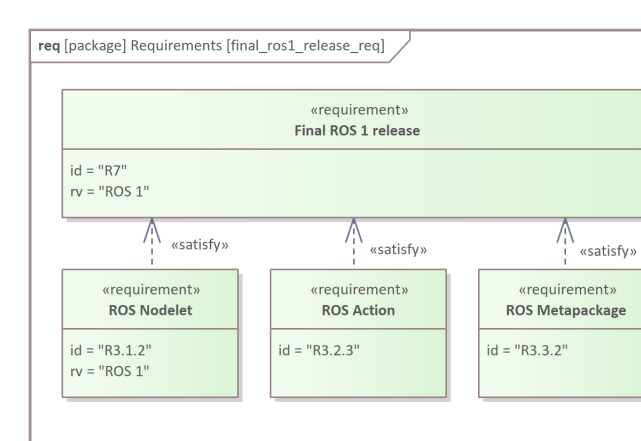
<https://github.com/twiniars/MeROS>
Warsaw University of Technology, Poland



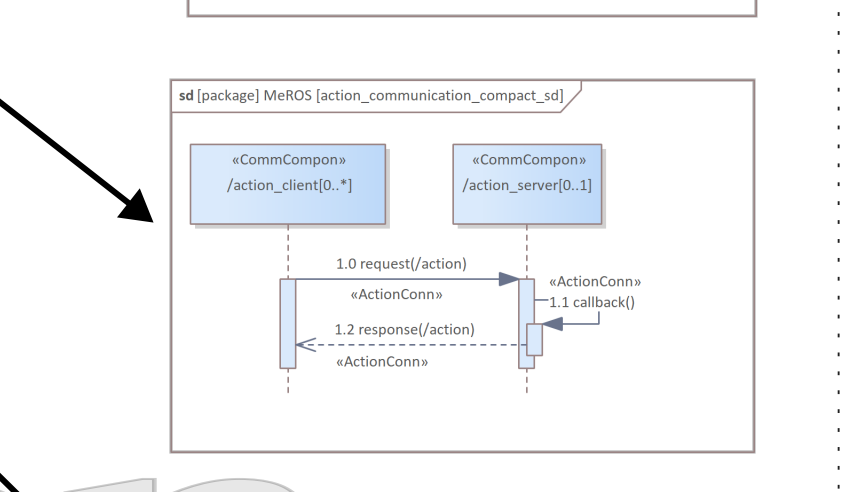
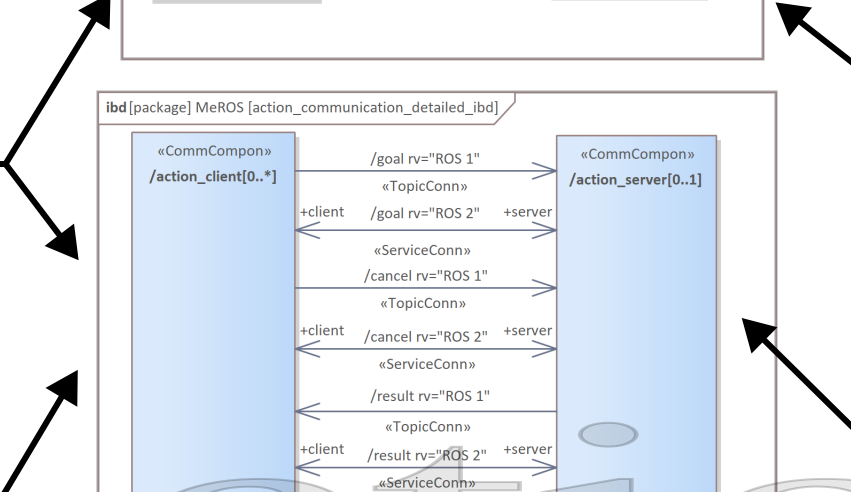
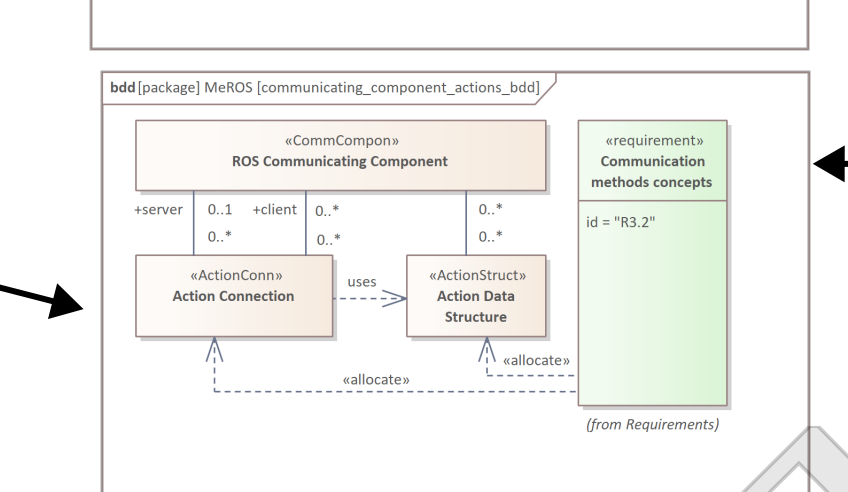
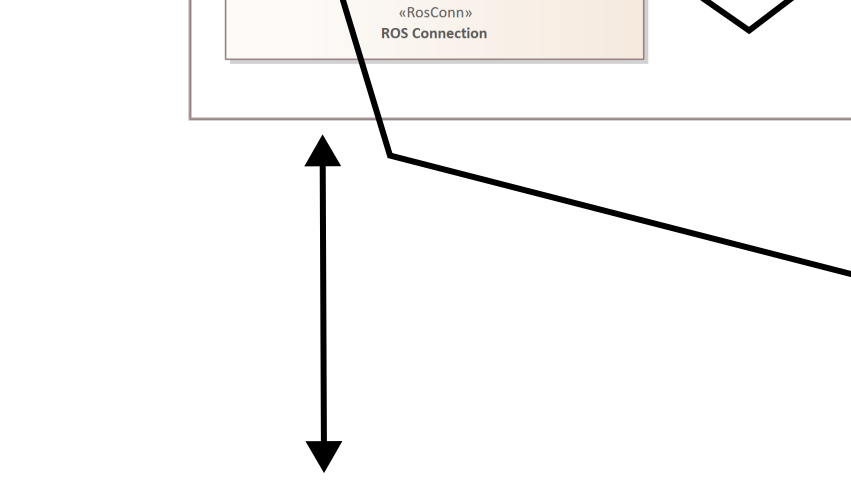
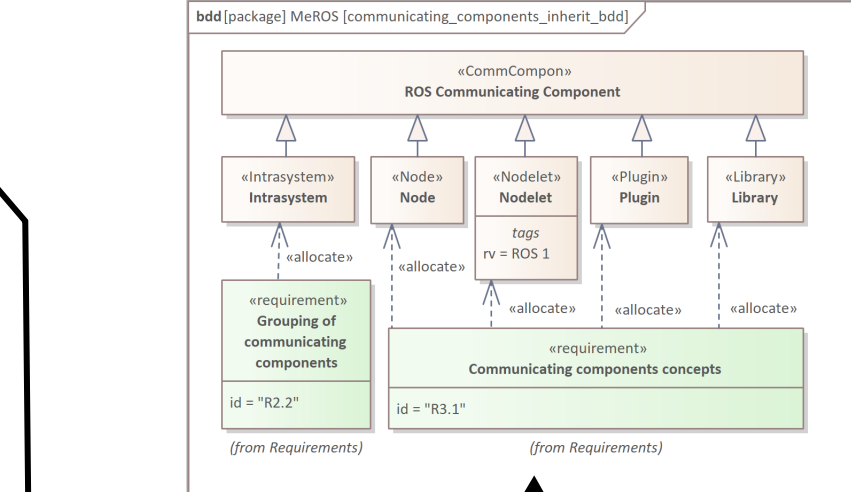
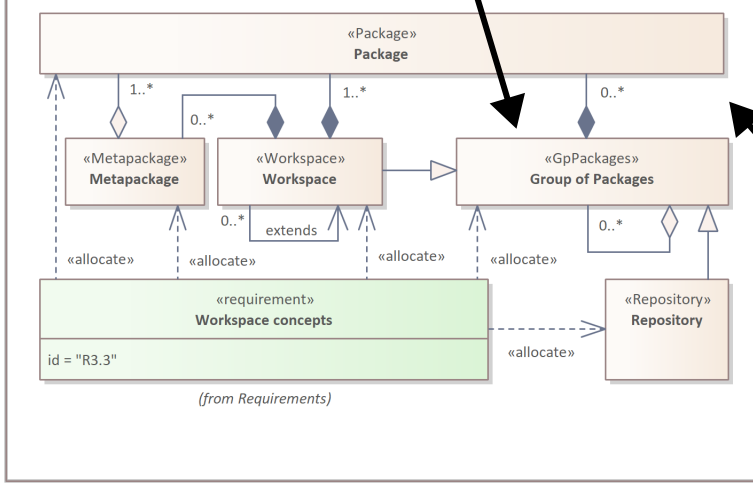
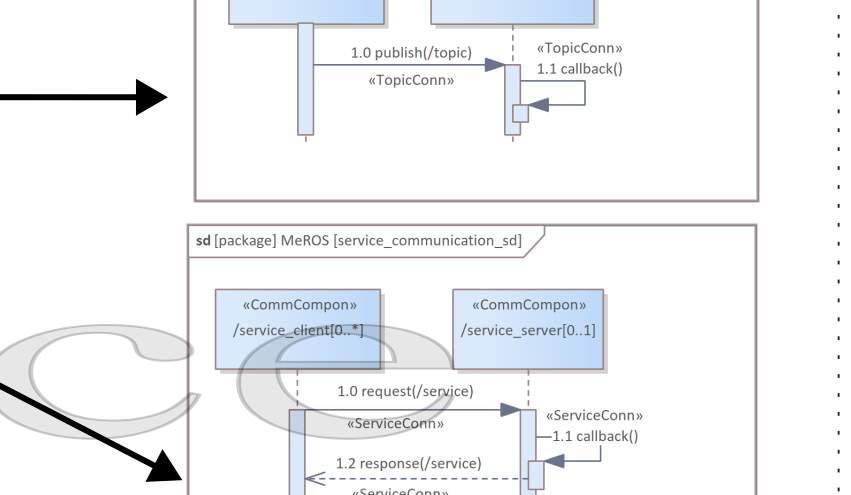
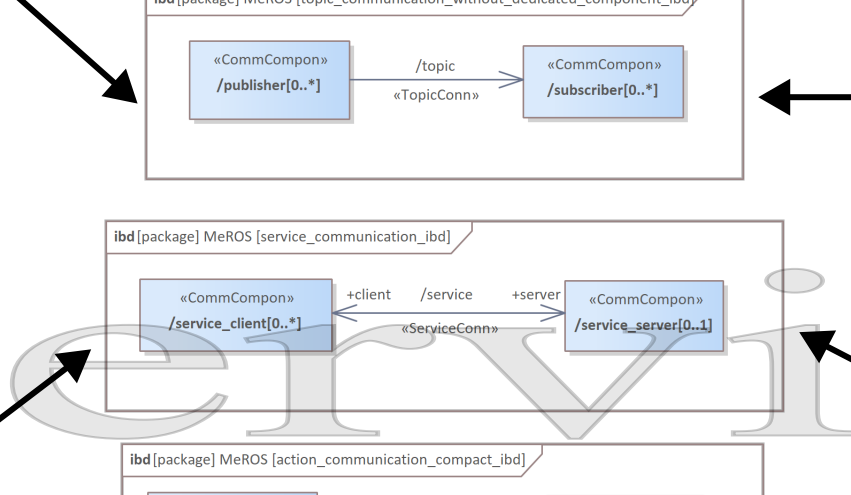
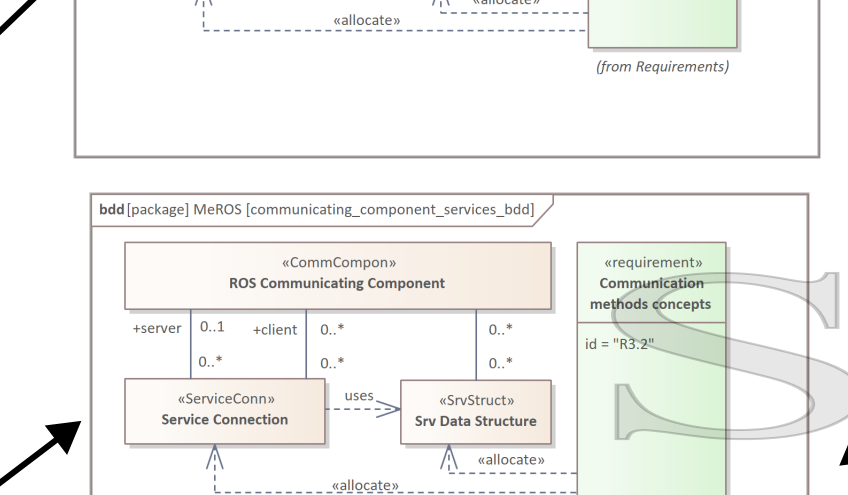
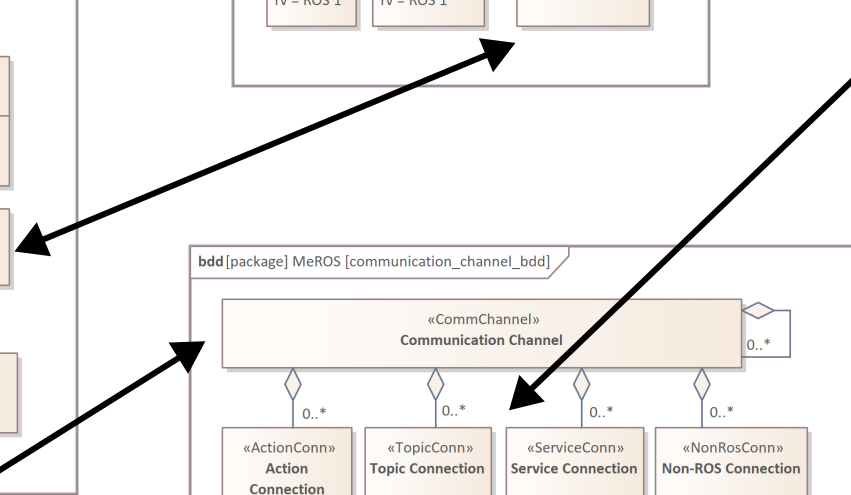
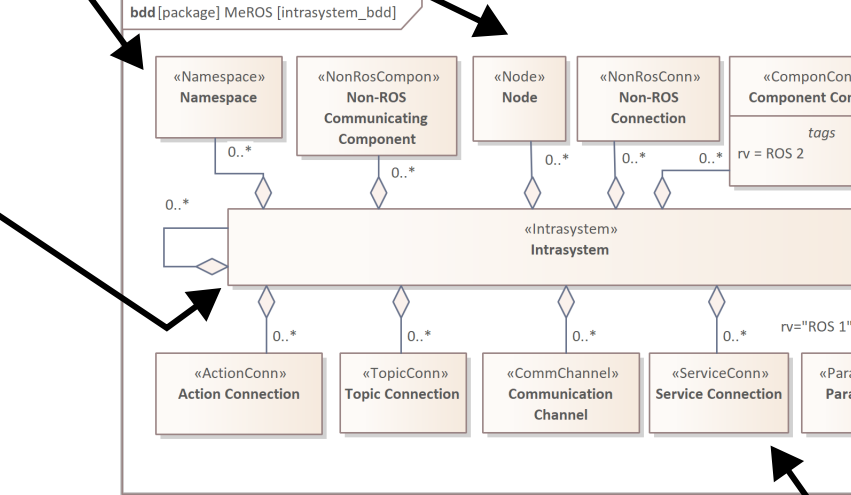
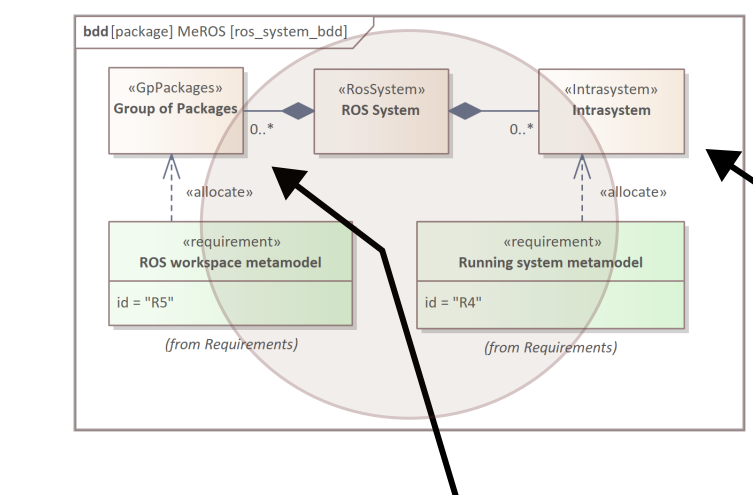
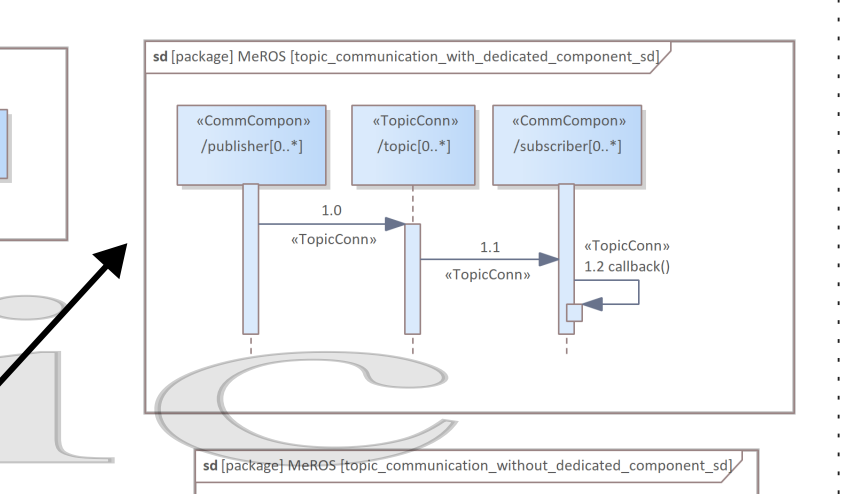
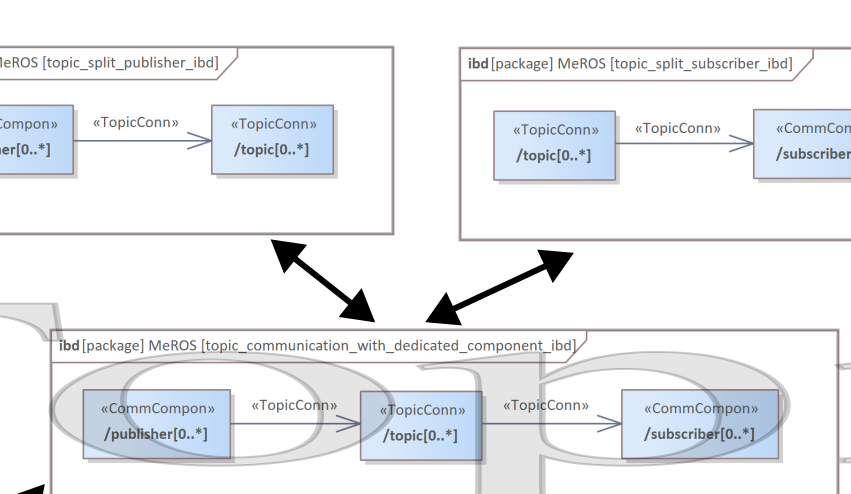
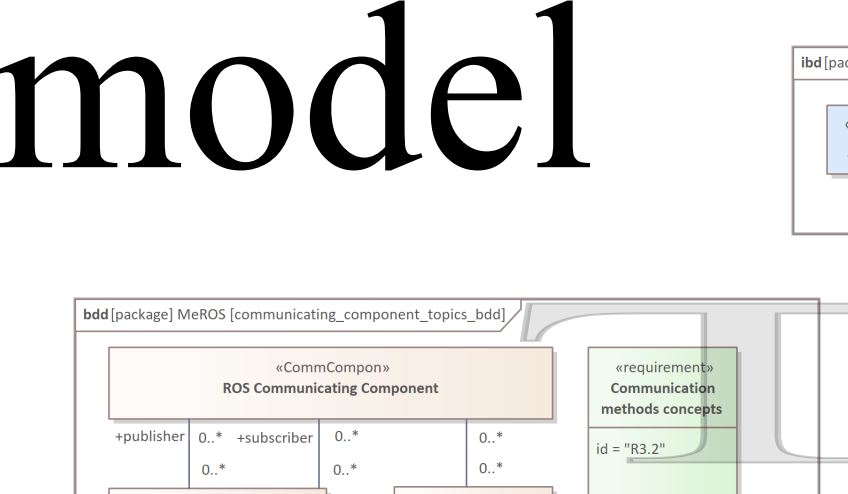
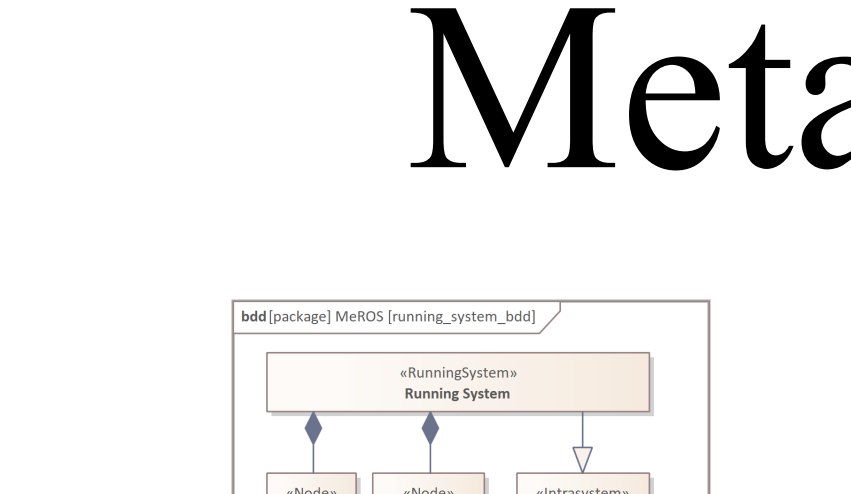
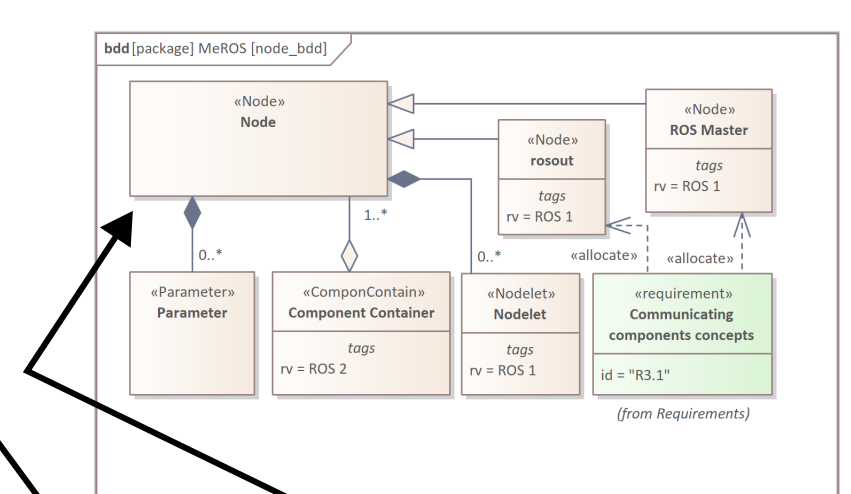
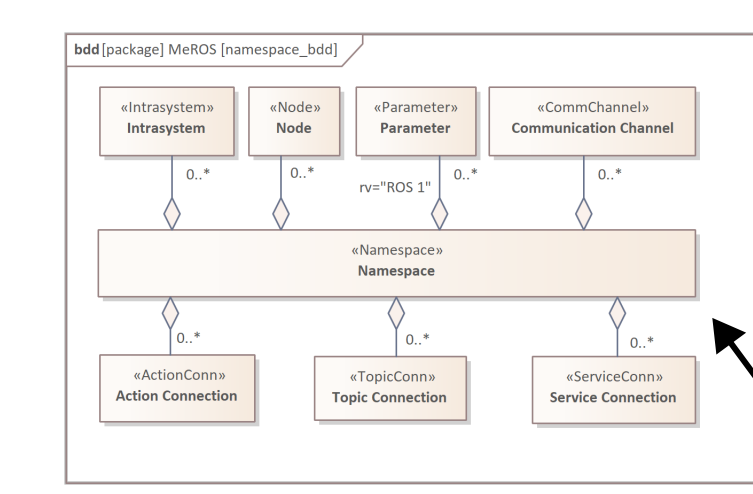
Requirements



Robot Operating System



Metamodel



Application

