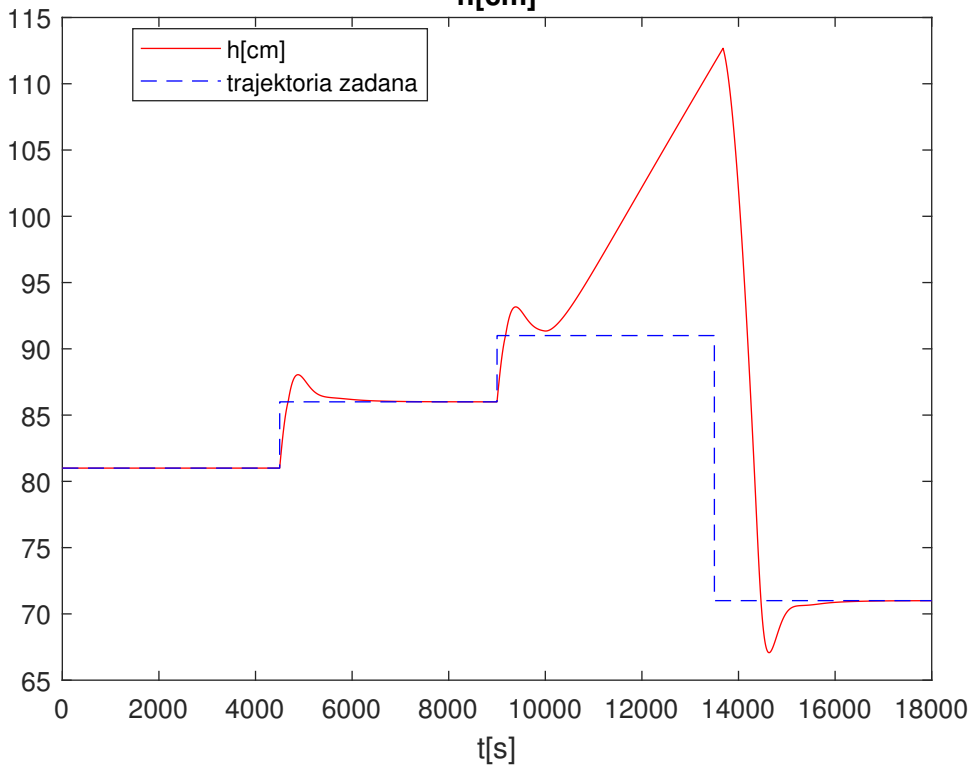


Regulator PI bez odsprężania

$h[\text{cm}]$

$h[\text{cm}]$



$t[\text{s}]$