



Finding Time Period-Based Most Frequent Path in Big Trajectory Data¹

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Summary

Finding
TPMFP in
BTD

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Overview

Key
Properties

1 Overview

2 Key Properties



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- The main task: find *the most frequent*(MFP) during user-specified time periods in large-scale historical trajectory data.
- They refer to this query as *time period-based MFP*(TPMFP).
- Specifically, given a time period T , a source v_s and a destination v_d , TPMFP searches the MFP from v_s to v_d during T .



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- None of the previous work can well reflect people's common sense notion which can be described by the following key properties:
 - *suffix-optimal*
 - *length-insensitive*
 - *bottleneck-free*
- The first task is to give a TPMFP definition that satisfies the above three properties.
- The next task is to find TPMFP over huge amount of trajectory data efficiently.(over 11,000,000 trajectories.)



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PROPERTY (SUFFIX-OPTIMAL)

Let P^ denote the $v_s - v_d$ MFP. For any vertex $u \in P^*$, the sub-path (suffix) of P^* from u to v_d should be the $u-v_d$ MFP.*

PROPERTY (LENGTH-INSENSITIVE)

The length of any path should not be a deciding factor of whether it is the $v_s - v_d$ MPF.

PROPERTY (BOTTLENECK-FREE)

The MPF P^ should not contain infrequent edges (i.e., bottlenecks).*