# Statistics for ArrowElectronics/Robotics\_AMR

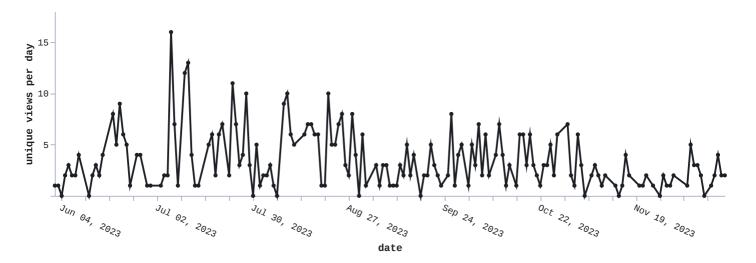
Generated for ArrowElectronics/Robotics\_AMR with jgehrcke/github-repo-stats at 2023-12-17 23:16 UTC.

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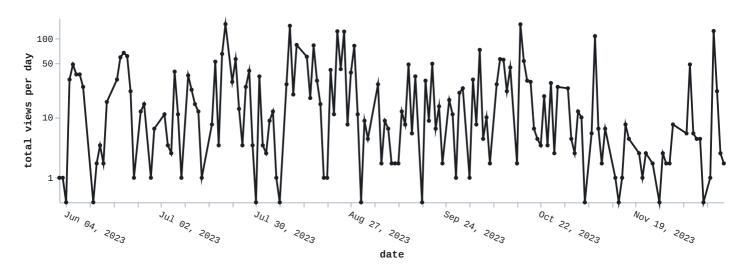
### **Views**

#### **Unique visitors**



Cumulative: 562

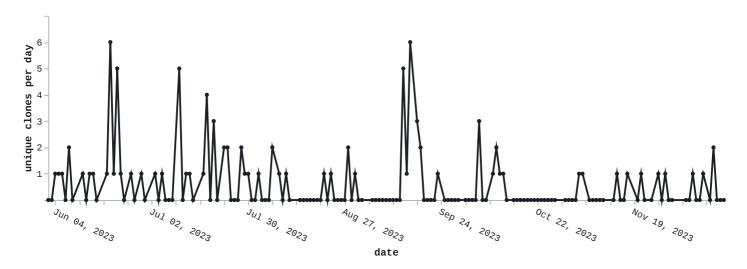
#### **Total views**



Cumulative: 3610

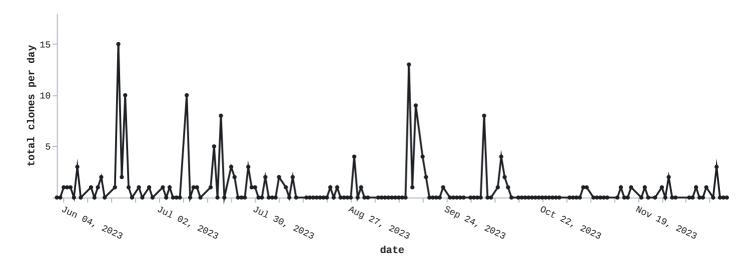
## **Clones**

### **Unique cloners**



Cumulative: 96

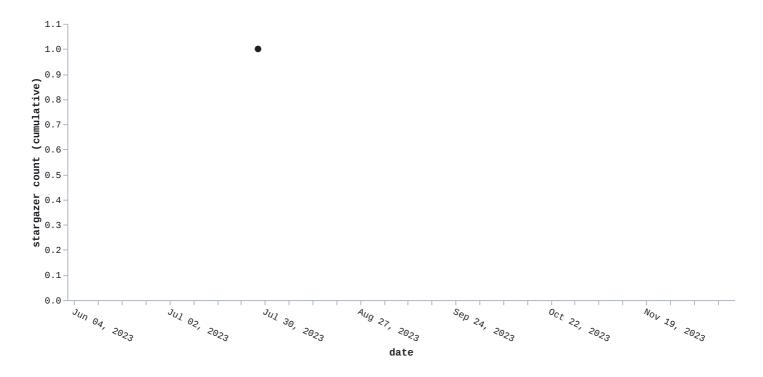
#### **Total clones**



Cumulative: 152

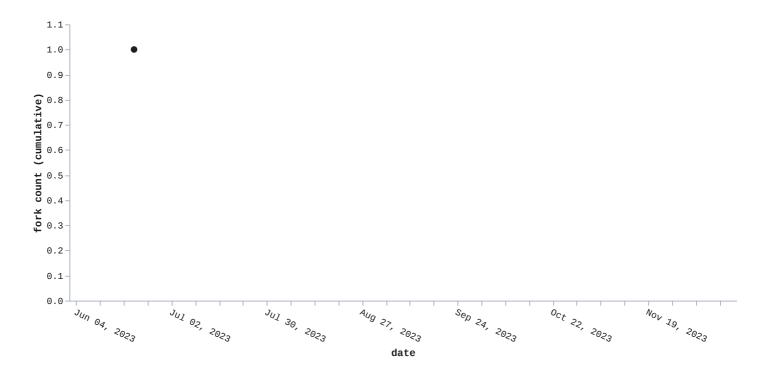
## **Stargazers**

Each data point corresponds to at least one stargazer event. The time resolution is one day.



## **Forks**

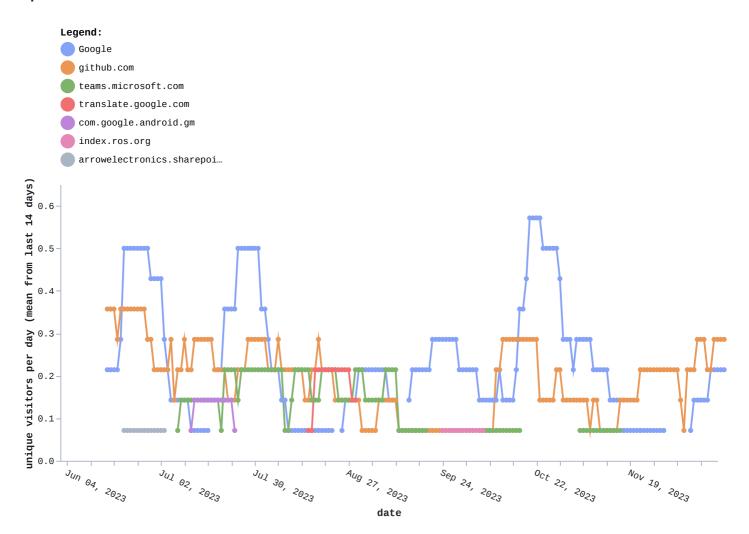
Each data point corresponds to at least one fork event. The time resolution is one day.



### Top referrers and paths

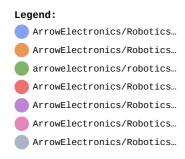
Note: Each data point in the plots shown below is influenced by the 14 days leading up to it. Each data point is the arithmetic mean of the "unique visitors per day" metric, built from a time window of 14 days width, and plotted at the right edge of that very time window. That is, these plots respond slowly to change (narrow peaks are smoothed out).

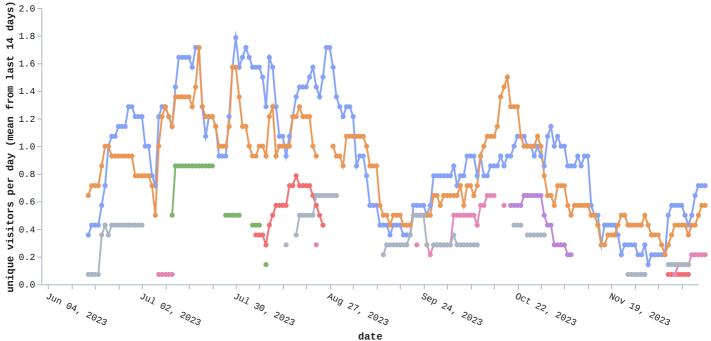
#### Top referrers



Top 15 referrers: 01: Google, 02: github.com, 03: teams.microsoft.com, 04: translate.google.com, 05: com.google.android.gm, 06: index.ros.org, 07: arrowelectronics.sharepoint.com, 08: arrow.com, 09: statics.teams.cdn.office.net, 10: com.linkedin.android, 11: Bing, 12: redhat.my.salesforce.com, 13: github-com.translate.goog

#### Top paths





Top 15 paths: 01: ArrowElectronics/Robotics\_AMR/wiki, 02: ArrowElectronics/Robotics\_AMR, 03: arrowelectronics/robotics\_AMR/wiki, 04: ArrowElectronics/Robotics\_AMR/wiki/Setup-of-System-Components, 05: ArrowElectronics/Robotics\_AMR/wiki/ToF%E2%80%90using%E2%80%90ROS\_Bindings, 06: ArrowElectronics/Robotics\_AMR/wiki/Interfacing-TOF-With-RTABMAP, 07: ArrowElectronics/Robotics\_AMR/wiki/Interfacing-TOF-With-AGX-ORIN, 08: ArrowElectronics/Robotics\_AMR/tree/devel/docker, 09:

 $\label{locker} Arrow Electronics/Robotics\_AMR/blob/devel/docker/humble/Dockerfile.ros2-humble-jammy, \ensuremath{\mathbf{10}}\xspace: Arrow Electronics/Robotics\_AMR/wiki/Ros2-Galactic-Docker-Setup, \ensuremath{\mathbf{11}}\xspace: Arrow Electronics/Robotics\_AMR/wiki/Ros2-Galactic-Docker-Setup, \ensuremath{\mathbf{11}}\xspace: Arrow Electronics/Robotics\_AMR/wiki/Ros2-Galactic-Docker-Setup, \ensuremath{\mathbf{11}}\xspace: Arrow Electronics/Robotics\_AMR/wiki/Ros2-Galactic-Docker-Setup, \ensuremath{\mathbf{10}}\xspace: Arrow Electronics/Robotics/Robotic-Docker-Setup, \ensuremath{\mathbf{10}}\xspace: Arrow Electronics/Robotic-Docker-Setup, \ensuremath{\mathbf{10}}\xspace: Arrow Elect$ 

 $\label{lem:arrowelectronics/Robotics_AMR/blob/devel/docker/galactic/Dockerfile.ros2-galactic-focal, 12: $$ArrowElectronics/Robotics_AMR/wiki/Flash-AGX-Orin-through-flash-script-or-for-Emulation-of-Orin-into-Nano-or-NX, 13: $$ArrowElectronics/Robotics_AMR/tree/devel/docker/galactic, 14: $$ArrowElectronics/Robotics_AMR/wiki/Sensor-Fusion-and-Navigation-With-TOF-Tutorial-On-AMR, 15: $$ArrowElectronics/Robotics_AMR/wiki/ToF%E2%80%90using%E2%80%90SDK$$