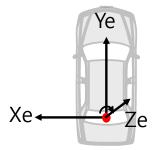
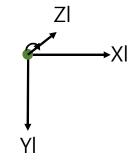


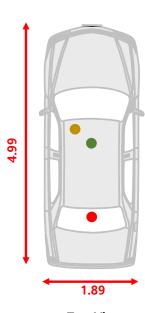
<Left Camera Coordinate System>



<Egocentric Coordinate System>



<Lidar Coordinate System>



<Top View>