

# Lab 4: Implementation of Dynamic Programming using C++

## Objective:

To implement and analyze two classic greedy algorithms, 0/1 Knapsack Algorithm and Single Source Shortest Path Problem. These algorithm are chosen to demonstrate the efficiency and practical applications of dynamic programming approach for solving problems.

## Theory:

Dynamic Programming (DP) is an algorithmic technique that solves complex problems by breaking them down into simpler subproblems. Its particularly useful for optimization problems.

1. 0/1 Knapsack Problem: The 0/1 Knapsack Problem is a classic optimization problem where we need to select items to maximize value while staying within a weight limit. Unlike the Fractional Knapsack Problem, items cannot be divided, they are either excluded or included.

### Algorithm :

Input : array of items with value and weight

Output: Maximum value

- a.  $N :=$  Length of items
  - b. Create a 2d array  $dp[n+1][max\_weight+1]$  initialized with all 0.
  - c. For  $i$  from 1 to  $n$ 
    - i. For  $w$  from 0 to  $max\_weight$ 
      1. If  $items[i-1].weight \leq w$  then
      2.  $dp[i][w] := \max(dp[i-1][w], dp[i-1][w-items[i-1].weight] + items[i-1].value)$
      3. Else
      4.  $dp[i][w] := dp[i-1][w]$
  - d. return  $dp[n][W]$
2. Single Source Shortest path Problem: This problem involves finding the shortest path from a source node to every other node in a weighted graph, where the weight can also be negative. It detects negative cycles and stops the algorithm.

### Algorithm :

Input : number of edges (E), number of vertices (V), set of edges where edge has source, destination and weight.

Output: vertices and minimum distance to each vertex

- a. Initialize  $\text{dist}[V]$  with  $\text{dist}[\text{src}] = 0$  and rest Infinity
- b. For  $l$  in 0 to  $v-1$ 
  - i. For  $j$  in 0 to  $E$ 
    - 1.  $u = \text{edges}[j].\text{src}$
    - 2.  $v = \text{edges}[j].\text{dest}$
    - 3.  $\text{weight} = g.\text{edges}[j].\text{weight};$
    - 4. if  $\text{dist}[u] \neq \text{Infinity}$  and  $\text{dist}[u] + \text{weight} < \text{dist}[v]$
    - 5.  $\text{dist}[v] = \text{dist}[u] + \text{weight}$
- b. For  $i$  in 0 to  $e$ 
  - i.  $u = \text{edges}[i].\text{src}$
  - ii.  $v = \text{edges}[i].\text{dest}$
  - iii.  $\text{weight} = \text{edges}[i].\text{weight}$
  - iv. if  $\text{desit}[u] \neq \text{Infinity}$  and  $\text{dist}[u] + \text{weight} < \text{dist}[v]$
  - v. print "Negative weight cycle"
  - vi. exit
- c. for  $i$  in 0 to  $v$ 
  - i. print "vertex"  $i$  "distance = "  $\text{dist}[i]$
- d. exit

## Observation

### 1. 0/1 Knapsack Problem:

```
#include <iostream>
#include "gettime.h"
#include <vector>
#include <algorithm>
using namespace std;

int knapsack(int max_w, int values[], int weights[], int n)
{
    vector<vector<int>> matrix(n + 1, vector<int>(max_w + 1, 0));
    for (int i = 1; i <= n; i++)
    {
        for (int w = 0; w <= max_w; w++)
        {
            int current_value = values[i - 1];
            int current_weight = weights[i - 1];
            if (current_weight <= w)
            {
                matrix[i][w] = max(current_value + matrix[i - 1][w -
current_weight], matrix[i - 1][w]);
            }
            else
            {
                matrix[i][w] = matrix[i - 1][w];
            }
        }
    }
    return matrix[n][max_w];
}

int main()
{
    vector<int> sizes;
    int start_size = 1000;
    int increment = 500;
    sizes.push_back(start_size);
    for (size_t i = 0; i < 4; i++)
    {
        sizes.push_back(sizes.back() + increment);
    }
    srand(time(0));
    for (int i = 0; i < sizes.size(); i++)
    {

```

```

        int size = sizes[i];
        int *values = new int[size];
        int *weights = new int[size];
        for (int i = 0; i < size; i++)
        {
            values[i] = rand() % 1000;
            weights[i] = rand() % 1000;
        }
        int max_w = 100;
        long long time = getTime([&]()
                                { knapsack(max_w, values, weights, size); });
        cout << "Size: " << size << " Time: " << time << endl;
    }
    return 0;
}

```

Output:

```

Size: 1000 Time: 35054700
Size: 1500 Time: 138440900
Size: 2000 Time: 254552900
Size: 2500 Time: 340822000
Size: 3000 Time: 397872500

```

2. Single source shortest problem:

```

#include <iostream>
#include <vector>
#include <algorithm>
#include "gettime.h"
using namespace std;

class Edge
{
public:
    int src, dest, weight;
    Edge()
    {
    }
    Edge(int src, int dest, int weight)
    {
        this->src = src;
        this->dest = dest;
    }
}

```

```

        this->weight = weight;
    }
};

class Graph
{
public:
    int V, E;
    Edge *edges;
    Graph(int V, int E)
    {
        this->V = V;
        this->E = E;
        this->edges = new Edge[E];
    }
};

void bellman_ford(Graph g, int src)
{
    int v = g.V;
    int e = g.E;
    int *dist = new int[v];
    for (int i = 0; i < v; i++)
    {
        dist[i] = INT_MAX;
    }
    dist[src] = 0;
    for (int i = 0; i < v - 1; i++)
    {
        for (int j = 0; j < e; j++)
        {
            int u = g.edges[j].src;
            int v = g.edges[j].dest;
            int weight = g.edges[j].weight;
            if (dist[u] != INT_MAX && dist[u] + weight < dist[v])
            {
                dist[v] = dist[u] + weight;
            }
        }
    }
    for (int i = 0; i < e; i++)
    {
        int u = g.edges[i].src;
        int v = g.edges[i].dest;
        int weight = g.edges[i].weight;

```

```

        if (dist[u] != INT_MAX && dist[u] + weight < dist[v])
        {
            cout << "Negative weight cycle " << endl;
            return;
        }
    }

    for (int i = 0; i < v; i++)
    {
        cout << i << "\t\t " << dist[i] << endl;
    }
}

```

```

int main()
{
    int V = 5;
    int E = 8;
    Graph graph(V, E);

    graph.edges[0].src = 0;
    graph.edges[0].dest = 1;
    graph.edges[0].weight = -1;

    graph.edges[1].src = 0;
    graph.edges[1].dest = 2;
    graph.edges[1].weight = 4;

    graph.edges[2].src = 1;
    graph.edges[2].dest = 2;
    graph.edges[2].weight = 3;

    graph.edges[3].src = 1;
    graph.edges[3].dest = 3;
    graph.edges[3].weight = 2;

    graph.edges[4].src = 1;
    graph.edges[4].dest = 4;
    graph.edges[4].weight = 2;

    graph.edges[5].src = 3;
    graph.edges[5].dest = 2;
    graph.edges[5].weight = 5;

    graph.edges[6].src = 3;
    graph.edges[6].dest = 1;
}

```

```

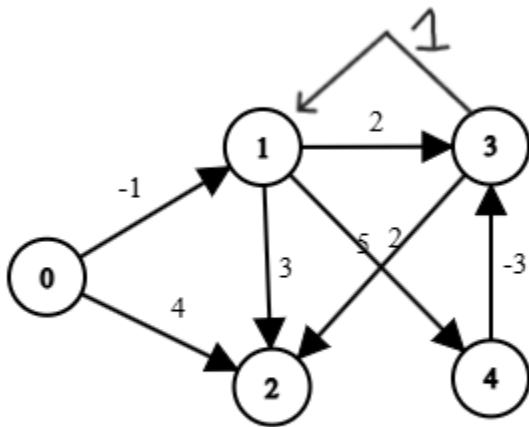
graph.edges[6].weight = 1;

graph.edges[7].src = 4;
graph.edges[7].dest = 3;
graph.edges[7].weight = -3;

long long time = getTime([&]()
                        { bellman_ford(graph, 0); });
cout << "time = " << time << " ns";
}

```

Input:



Output:

```

0      0
1      -1
2      2
3      -2
4      1
time = 3988800 ns

```

## Conclusion

We solved fractional knapsack problem and single source shortest algorithm by applying dynamic programming in C++.