Dhruv Sharma

82 Rochefort Street, Kitchener ON \cdot d
32sharm@gmail.com \cdot 226-606-0988 \cdot https://ca.linkedin.com/in/dhruvsharmauw https://github.com/d32sharm

SKILLS

C, C++, MATLAB, Python, TensorFlow, PyTorch, CUDA, ROS, Gazebo, Unreal Engine Software: Hardware: NVIDIA Tegra - Jetson TX1, Drive PX, Data Acquisition Systems, Raspberry PI, Arduino

Interests

Intelligent Robotics, Artificial Intelligence, Autonomous Mobile Robots, Computer Vision

Research Publication

Sharma, D., Kuwajerwala, A., Shkurti, F. (2022). Augmenting Imitation Experience via Equivariant Representations. IEEE International Conference on Robotics and Automation (ICRA 2022). (Text) Sharma, D., Zafar, S., Tizhoosh, H., Babaie, M. (2018). Facial Recognition with Encoded Local Projections. IEEE-Symposium Series on Computational Intelligence 2018. (Text)

Work Experience

Huawei Canada, Noah's Ark Lab

Computer Vision Researcher

Toronto, ON June 2022 | Present

- Research in camera/lidar based perception for autonomous driving.
- Explored and implemented Neural Radiance (NeRF) and related research for AV simulation.
- Trained neural rendering models for static and dynamic scenes with a focus on 3d geometry.

Convolve AI Inc. Toronto, ON April 2022 | Present

AI Consultant

- Built software tools for businesses and helped integrate AI and automation in workflows.
- Integrated openAI GPT based Large Language Models in lead gen tools.
- Leverated chatgpt and other openAI tools to improve productivity and customer interactions.

Prof Florian Shkurti, University of Toronto

Toronto, ON

Graduate Student Researcher

Sept 2019 | March 2021

- Research at the intersection of robotics, artificial intelligence, and computer vision.
- Developed novel techniques to enhance the state of the art in robotics, and empowering robots to perform with minimal supervision and training.
- Worked on improving robot navigation using imitation learning combined with enhanced visual scene understanding.
- Acted as a teaching assistant for CSC321 Neural Networks and Machine Learning (Winter 2021). Delivered tutorials to 4th year CS students and graded papers.

NVIDIA Holmdel, NJ Oct 2018 | Oct 2019

Software Engineer - Autonomous Driving

- Worked on End to End learning for self-driving cars. Developed infrastructure for training and validation and trained and tested several models.
- Contributed to the development of the self driving simulator. Created and deployed new features for model testing and evaluation.

Prof Krzysztof Czarnecki, University of Waterloo

Research Engineer - Waterloo Self-Driving Car Project

Wateroo, ON July 2018 | Sept 2018

- Simulation based research in autonomous driving using Coppelia Robotics V-rep simulator and Unreal Engine based simulator.
- Significantly contributed in integrating the dynamic vehicle model for the car developed using MapleSim into the simulation pipeline.

Prof Hamid Tizhoosh, University of Waterloo

Waterloo, ON

Research Project Student

Jan 2018 | June 2018

- Conducted research in facial recognition under the supervision of Prof Hamid Tizhoosh. Developed a projection based algorithm (Encoded Local Projections) to face recognition.
- Successfully obtained desired results and published the work in the IEEE-Symposium Series on Computational Intelligence 2018.

NVIDIA Holmdel, NJ

Deep Learning Intern - Autonomous Driving

May 2017 | Sep 2017

- Worked on developing autonomous driving technology on NVIDIA Drive PX 2. Gained experience in perception applied to autonomous driving.
- Integrated navigation using maps and GPS into the autonomous driving pipeline.
- Implemented in C++, fusion of GPS and IMU using EKF to derive better orientation estimates.

NVIDIA Holmdel, NJ

Deep Learning Intern - Autonomous Driving

Aug 2016 | Dec 2016

- Trained and tested on road, several end to end deep neural networks that were demonstrated at various international trade shows and conferences. Ran experiments to improve the network performance.
- Wrote CUDA kernels to improve the performance of the in house augmented driving simulator.
- Created a speed control application for the car to cruise at speeds below 20 mph the range where inbuilt ACC of the car does not work.

NVIDIA Santa Clara, CA Infrastructure Software Engineer Jan 2016 | Apr 2016

mijastracture Sojiware Engineer

- Participated in creation and approval process of schematic symbols (Cadence Allegro Designer).
- Created test setup to characterize sense resistors. Analyzed parts from different vendors based on performance, cost, and lead time.
- Created interactive dashboards to improve the state of engineering processes across the company (Tableau Desktop).

Capital One

Kitchener, ON

Data Scientist

May 2015 | Aug 2015

• Natural Language Processing using Sklearn to analyze customer text feedback.

• Built text classification pipeline (feature extraction, feature selection, classification - Linear Support Vector Classifier). Performed sentiment analysis on comments.

EDUCATION

University of Toronto

Toronto, ON

Master of Science: Computer Science

2019 - 2021

Research at the intersection of Autonomous Robotics and Artificial Intelligence

CGPA: 4.0 Projects

• Augmenting Imitation Experience via Equivariant Representations

- Cartpole Control using Deep Q-Learning
- Monocular visual odometry on KITTI dataset

University of Waterloo

Waterloo, ON 2013 - 2018

Bachelor of Applied Science: Honours Mechatronics Engineering

Average: 89.78% (Dean's Honours List)

Capstone Design Project

- Autonomous wall painting robot mapping, localization, planning, controls. (trymist.com)
- Awarded for best technical content (\$1000). Robot featured in TechCrunch (Link)

Relevant Courses

Perception for Robotics, State Estimation for Robotics, Control for Robotics, Machine Intelligence, Autonomous vehicles, Multisensor Data Fusion, Autonomous Mobile Robots, Image Processing, Digital Control Systems

Honors and Awards

Ontario Graduate Scholarship Granted the Ontario Graduate research Scholarship (\$15000)	UToronto 2019 - 2020
Best Technical Content, Mechatronics Design Symposium Team awarded for capstone project MIST robot (\$1000).	UWaterloo 2018
President's International Experience Award Awarded for excelling at international internships (\$1500).	UWaterloo 2018
President's Research Award Awarded for excelling at research internship (\$1500).	UWaterloo 2015
3rd Place, Waterloo Engineering Senior Design Competition Team awarded 3rd place in senior design competition.	WEC 2014
First in Class Engineering Scholarship Rank 1 in class of 150 students in summer 2014 term (\$500).	UWaterloo 2014
$3 \times Deans Honours List$ Recognized on the deans honor list due to academic excellence.	UWaterloo 2014 - 2018
University of Waterloo President's Scholarship of Distinction Entrance award for high admission average (\$2000).	UWaterloo 2013