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close all;clear;;image1 = imread('gauss.jpg');;image2 = imread('dyoung.jpg');;;N = length(imagel);;;%% Create 5-point finite difference Laplacian on a square;A = dels q(numgrid('S',N+2));;;%% Increment the diagonal by diagonalIncremement;;diagonalIncr emement = 0.5; ¿A=A+diagonalIncremement\*speye(length(A)); ¿¿% Create b such that image 2 is answer to Ax = b¿b = A\*cast(reshape(image2, N^2, 1), 'double'); ¿¿% Make image1 o ur initial guess to Ax = b¿x0 = cast(reshape(image1, N^2, 1), 'double'); ¿% Visualize initial guess; ¿image (reshape (x0, N, N)); colormap (gray (256)); axis equal off tight; draw now;;;%% Set up matrix splitting of A;D = diag(diag(A));;L = -1\*tril(A,-1);;U = -1\*tril(A,-1); riu(A,1);¿¿% The iteration matrix for Gauss-Seidel uses the lower triangular matrix of A; % instead of the diagonal.; M = inv(D-L);;; % Prepare diagonal splitting version of Jacobi method;; %% Perform Jacobi iteration; x = x0; % initial guess; e0 = no  $rm(x - cast(reshape(image2, N^2, 1), 'double'));$  % initial error; numIterations = 50 % number of iterations;for iter = 2:numIterations;; xold = x; % u pdate previous solution; x = M \* (b + U \* x); %M \* (b + DSU\*x); % compute current solution; % print out current error; eiter = norm(x - cast(reshape(image2, N + DSU\*x)); % compute current error; eiter = norm(x - cast(reshape(image2, N + DSU\*x)); % compute current error; eiter = norm(x - cast(reshape(image2, N + DSU\*x)); % compute current error; eiter = norm(x - cast(reshape(image2, N + DSU\*x)); % compute current error; eiter = norm(x - cast(reshape(image2, N + DSU\*x)); % compute current error; eiter = norm(x - cast(reshape(image2, N + DSU\*x)); % compute current error; eiter = norm(x - cast(reshape(image2, N + DSU\*x)); % compute current error; eiter = norm(x - cast(reshape(image2, N + DSU\*x)); % compute current error; eiter = norm(x - cast(reshape(image2, N + DSU\*x)); % compute current error; eiter = norm(x - cast(reshape(image2, N + DSU\*x)); % compute current error; eiter = norm(x - cast(reshape(image2, N + DSU\*x)); % compute current error; eiter = norm(x - cast(reshape(image2, N + DSU\*x)); % compute current error; eiter = norm(x - cast(reshape(image2, N + DSU\*x)); % compute current error; eiter = norm(x - cast(reshape(image2, N + DSU\*x)); % compute current error; eiter = norm(x - cast(reshape(image2, N + DSU\*x)); % compute current error; eiter = norm(x - cast(reshape(image2, N + DSU\*x)); % compute current error; eiter = norm(x - cast(reshape(image2, N + DSU\*x)); % compute current error; eiter = norm(x - cast(reshape(image2, N + DSU\*x)); % compute current error; eiter = norm(x - cast(reshape(image2, N + DSU\*x)); % compute current error; eiter = norm(x - cast(reshape(image2, N + DSU\*x)); % compute current error; eiter = norm(x - cast(reshape(image2, N + DSU\*x)); % compute current error; eiter = norm(x - cast(reshape(image2, N + DSU\*x)); % compute current error; eiter = norm(x - cast(reshape(image2, N + DSU\*x)); % compute current error; eiter = norm(x - cast(reshape(image2, N + DSU\*x)); % compute current error; eiter = norm(x - cast(reshape(image2, N + DSU\*x)); % compute current error; eiter = norm(x - cast(res^2,1),'double'))/e0;; % visualize current solution; cla; image(reshape(x,N, colormap(gray(256)); pause(.25); end; axis equal off tight;