CS340 Cheat Sheet Tristan Rice 2016-12-12

Assignment 1

Decision Trees:

- Classify by walking tree
- Greedy recursive splitting
- Information gain as score, entropy
- O(mnd log n),

Decision Stump Rule Search:

- Ignore rules outside feature ranges.
- Sort examples O(n log n)
- O(n) score updates
- Total cost: O(nd log n), data size: O(nd)

Learning Theory:

- THE TEST DATA CANNOT INFLUENCE THE TRAINING PHASE IN ANY WAY.
- Fundamental Trade-Off:
- 1. How small you can make the training error.
- 2. How well training error approximates the test error.
- Simple models have good approximation of test error, but fit training data poorly.
- Cross validation, test on your training data, use each point as test once.
- No free lunch theorem: no best machine learning model for every problem

Naive Bayes:

$$p(y_i = ||span|| ||x_i||) = \frac{p(x_i | y_i = ||span||)}{p(x_i)}$$

- Compute p(y="spam"|xi) > p(y="not spam",xi)
- Need to estimate p(xi|y="spam")
- Runtime: Test: O(kd); Train: O(nkd+n)

Bayes Rule:

$$P(A|B) = \frac{P(B|A)P(A)}{P(B)}$$

Descriptive Statistics:

- Mean, Median, Quantiles (v s.t. x% < v)
- Box Plot

Assignment 2

KNN:

- Non-parametric
- Distance fn: Euclidean, L1 Dist, Jaccard similarity, Cosine, Distance after dimension reduction, Metric learning

Jaccard similarity: D(x1,x2)=(x1 x2)/(x1 U x2)

Ensemble Methods: Boosting, Averaging

Random Forests:

- Train number of deep decision trees on bootstrapped samples from the main dataset + small random subset of features on each stump
- Very fast, good out of the box classifier
- Bayesian Model Averaging
- Train O(tmnd log n), t = #trees, m = depth, d = #features, can be sqrt(d)
- Classify one is O(tm)

Clustering: No best method, no test error

K-Means:

- k clusters, random center
- add one point and update mean based on assignment
- initialization important, need to know k
- Total cost: O(ndk), updating means O(nd)
- vector quantization: cluster colors
- K-Medians: Can also use L1-norm + median
- K-Means++, init clusters by furthest distance
- Convex clusters

Density based clustering:

- Non-convex clusters

DBSCAN:

- Radius, if at least minPoints of same type become "core"
- Merge clusters if reachable
- Can have outliers
- Sensitive to boundaries
- need lots of points in high dimensions
- finding cluster is expensive
- O(n^2d)

Lp-norms: L1, L2, L-inf

$$\left\|\mathbf{x}
ight\|_p := igg(\sum_{i=1}^n \left|x_i
ight|^pigg)^{1/p}.$$

Elbow method: choose k in which the sharpest elbow (biggest change in slope) for minimum error vs k.

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Assignment 3

Linear regression (adding bias, change of basis, RBFs, regularization, cost of training/testing, effect of basis parameters).

formalifiers).
$$f(w) = \sum_{i=1}^n (wx_i - y_i)^2$$
 - Minimize least squares
$$w = \frac{\sum_{i=1}^n y_i x_i}{\sum_{i=1}^n x_i^2}$$
 - Solution

- Bias variable, add row with 1s
- Change of basis, linear least squares
- each row: $[1 \times x^2 ... \times p]$; $[1 \times \sin(6x)]$
- Radial basis functions: non-parametric

- Can combine both

Assignment 4:

Convex and MLE/MAP estimation (showing functions are convex, connection between probabilities and losses/regularizers)

- likelihood function: p(y|X,w)
- minimize negative log-likelihood

$$f(w) = -\sum_{i=1}^{n} \log(p(y_i|x_i, w))$$

$$p(w|X,y) \propto p(y|X,w)p(w)$$

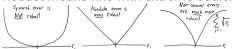
Logistic Regression:

$$p(y) = -\log(p(w|X, y)) = -\sum_{i=1}^{n} \log(p(y_i|x_i, w)) - \sum_{j=1}^{d} \log(p(w_j)) + const$$

Sigmoid: $h(z) = 1/(1 + \exp(-z))$

Robust regression (weighted least squares, smooth approximations, computing gradients).

- Robust means fine with extreme outliers



- Absolute is most robust convex error function
- Weighted least squares: weight on each training example

Convexity:

- 1-variable, twice-differentiable function is convex iff $f''(w) \ge 0$ for all 'w'.
- A convex function multiplied by non-negative constant is convex.
- Norms and squared norms are convex.
- The sum of convex functions is a convex function.
- The max of convex functions is a convex function.
- Composition of a convex function and a linear function is convex.
- Not true: composition of convex and convex is convex

Regularizers:

- "robust" = less influenced by large values
- L0 sparsity, non-convex
- L1 makes things more sparse, non-convex
- Huber loss:

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$$L_\delta(a) = egin{cases} rac{1}{2}a^2 & ext{for } |a| \leq \delta, \ \delta(|a| - rac{1}{2}\delta), & ext{otherwise}. \end{cases}$$

- L Infinite = max, log-sum-exp is smooth approx

 $p(y_i|x_i, w) = \frac{1}{1 + \exp(-y_i w^T x_i)}$ $f(w) = \sum_{i=1}^n \log(1 + \exp(-y_i w^T x_i)) + \frac{\lambda}{2} ||w||^2$

- LSE(x1,...,xn) = log(exp(x1)+...+exp(xn))
- Frobenius Norm: sgrt(each element squared)

0-1 Loss: Number of classification errors

- Hinge: Convex, max{0, 1-y_iw^Tx_i}
- SVM is hinge loss + L2-regularizer
- Logistic: smooth approximation to hinge, differentiable

Regularized logistic regression (loss functions for binary classification, effect of different regularizers on overfitting and sparsity)

Vectors/matrices/norms (summation and vector/matrix/norm notation, minimizing quadratic functions as linear systems)

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Multi-class Logistic (one-vs-all, softmax loss derivatives and implementation)

- multi-class yi is row of d [+1/-1]
- multi-class classification, exactly one +1, encode as
- can take max of yi to get correct classification softmax/multinomial logistic regression $\exp(w_T^T x_i)$

$$p(y_i|x_i, w) = \frac{\exp(w_{y_i}^T x_i)}{\sum_{c=1}^k \exp(w_c^T x_i)}$$

- logistic regerssion for binary labels
- softmax for multi-class
- ordinal logistic regression, thresholds of sigmoid as params

Assignment 5:

Principle Compontent Analysis PCA (computing 1st PC, scaling issue, PCA for visualization, PCA for compression)

- $||w||_2 = 1$
- X=ZW
- $f(Z,W) = sum_{i=1}^n(w*z_i-x_i)^2$
- reduce dimensionality

$$f(W,Z) = \frac{1}{2} \sum_{i=1}^{n} \sum_{j=1}^{d} (w_j^T z_i - x_{ij})^2 = \frac{1}{2} ||ZW - X||_F^2$$

- Solve via:
- Singular value decomposition (SVD) non-iterative
- Alternate between updating W and Z
- Stochastic gradient / Gradient Descent
- X: n by d, Z: n by k, W: k x d

Beyond PCA (different loss functions, effect of regularizers)

- PCA minimized approximation error
- PCA maximizes variance

$$var(X) = \frac{1}{n} ||X||_F^2$$

- Regularizers can split into different components, sparsity
- Non-negative matrix factorization
- Regularizes, negative can't cancel out large values

Multi-dimensional scaling (basic model, ISOMAP and geodesic distance)

- Directly optimize the location of zi values
- Gradient descent
- non-convex, sensitive to initialization

$$f(Z) = \sum_{i=1}^{n} \sum_{j=i+1}^{n} d_3(d_2(z_i, z_j) - d_1(x_i, x_j))$$

ISOMAP: Geodesic distance

- Use neighbors to compute edge weights
- Use dijkstra's to find shortest path distances

t-SNE: wayyy better, but ugly hack

- focus on small distances
- allow large variance in large distances
- not always better than PCA, can "twist" the plane

Assignment 6:

PageRank (random walk model)

- Probability of landing on page as t->inf
- Add small probability of going to random webpage
- At each step follow random link on page

Stochastic gradient and neural networks

- effect of step-size: too large = can't converge, too small = can't get to the solution
- effect of standardization: helps typically
- effect of initialization: random weights work better with non-convex losses
- effect of non-linearity: makes it a universal approximator
- effect of regularization: higher training error, better estimate of test error
- Dropout: randomly set some xi, zi = 0
- Convolutional
- Vanishing gradient, ReLU (hinge loss)

 $(AB)^{-1} = B^{-1}A^{-1}$

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Inner product $a^Tb = b^Ta$ $a^T(b+c) = a^Tb + a^Tc$ Orthogonal $a^Tb = 0$ Orthonormol $a^Tb = 1$ Matrix Multiplication A(BC) = (AB)CA(B+C) = AB + AC $AB \neq BC$ $(AB)^T = B^T A^T$ $(AB)^2 = ABAB$ Matrix * vector = vector $x^T A y = x^T (A y) = (A y)^T x = y^T A^T x$ Inverses $A^{-1}A = I = AA^{-1}$ $(A^{-1})^T = (A^T)^{-1}$ $(\gamma A)^{-1} = \gamma^{-1} A^{-1}$

Assignment 1:

Summary statistics (like range, median, and quantiles).

Data visualization (histogram, scatterplot, and box plot).

Decision trees (how to fit stumps using classification error, how to classify a new example, runtime in O() notation, effect of depth).

Learning theory (training vs. test error, validation sets and cross-validation, fundamental trade-off)

Naive Bayes (conditional probability, fitting the probabilities, classifying a new example, runtime).

Assignment 2:

K-nearest neighbours (how to classify a new example, runtime in O() notation, effect of k, condensed version).

Random forests (what bootstrap does, how random trees works, effect of number of trees/random-features, how to classify new example).

K-Means (effect of initialization, error functions, runtime, how to cluster new example, elbow method, k-medians, vector quantization).

Density-based clustering (effect of parameters, shape of clusters).

Assignment 3:

Vectors/matrices/norms (summation and vector/matrix/norm notation, minimizing quadratic functions as linear systems)

Linear regression (adding bias, change of basis, RBFs, regularization, cost of training/testing, effect of basis parameters).

Robust regression (weighted least squares, smooth approximations, computing gradients).

Assignment 4:

Regularized logistic regression (loss functions for binary classification, effect of different regularizers on overfitting and sparsity)

Convex and MLE/MAP estimation (showing functions are convex, connection between probabilities and losses/regularizers)

Multi-class Logistic (one-vs-all, softmax loss derivatives and implementation)

Assignment 5:

PCA (computing 1st PC, scaling issue, PCA for visualization, PCA for compression) Beyond PCA (different loss functions, effect of regularizers)

Multi-dimensional scaling (basic model, ISOMAP and geodesic distance)

Assignment 6:

PageRank (random walk model)

Stochastic gradient and neural networks (effect of step-size, effect of standardization, effect of initialization, effect of non-linearity, effect of regularization)

| Operation | Input | Output | Algorithm | Complexity |
|------------------------------|---|--|--|--------------------------------|
| Matrix multiplication | Two <i>n×n</i> matrices | One <i>n×n</i> matrix | Schoolbook matrix multiplication | O(n ³) |
| | | | Strassen algorithm | O(n ^{2.807}) |
| | | | Coppersmith–Winograd algorithm | O(n ^{2.376}) |
| | | | Optimized CW-like algorithms ^{[14][15][16]} | O(n ^{2.373}) |
| Matrix multiplication | One <i>n×m</i> matrix & one <i>m×p</i> matrix | One <i>n×p</i> matrix | Schoolbook matrix multiplication | O(nmp) |
| Matrix inversion* | One <i>n×n</i> matrix | One <i>n×n</i> matrix | Gauss-Jordan elimination | O(n ³) |
| | | | Strassen algorithm | O(n ^{2.807}) |
| | | | Coppersmith–Winograd algorithm | O(n ^{2.376}) |
| | | | Optimized CW-like algorithms | O(n ^{2.373}) |
| Singular value decomposition | One <i>m×n</i> matrix | One mxm matrix, one mxn matrix, & one nxn matrix | | O(mn ²) (m ≤ n) |
| | | One mxr matrix, one rxr matrix, & one nxr matrix | | |
| Determinant | One <i>n×n</i> matrix | One number | Laplace expansion | O(n!) |
| | | | Division-free algorithm ^[17] | O(n ⁴) |
| | | | LU decomposition | O(n ³) |
| | | | Bareiss algorithm | O(n ³) |
| | | | Fast matrix multiplication ^[18] | O(n ^{2.373}) |
| Back substitution | Triangular matrix | n solutions | Back substitution ^[19] | O(n ²) |