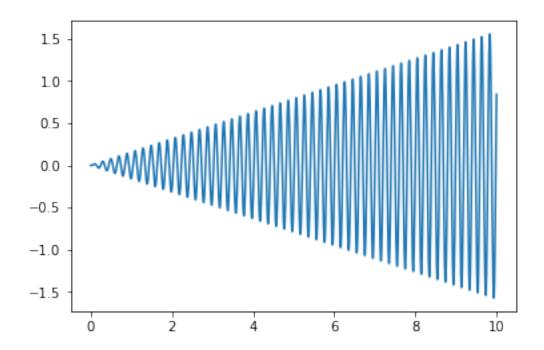
## ODE

## March 11, 2019

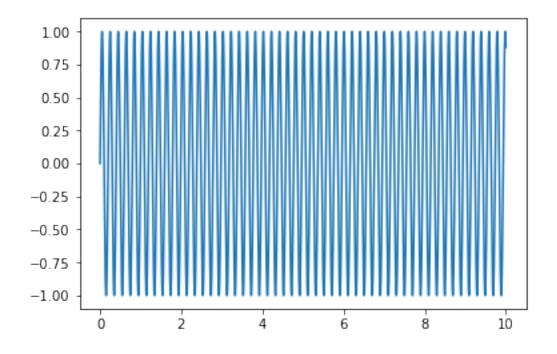
```
In [1]: from scipy.integrate import solve_ivp
        from scipy.interpolate import interp1d
        import numpy as np
In [2]: def mass_spring_forced(f, m, k):
            def mass_spring(t, y):
                dyOdt = y[1]
                dy1dt = (f(t) - k * y[0]) / m
                return [dy0dt, dy1dt]
            return mass_spring
        def random_force(t, Fs):
            n = int((t[1] - t[0]) * Fs) + 1
            return interp1d(np.linspace(t[0], t[1], n), np.random.rand(n))
        def step_function(gain, raise_time=0):
            def step(x):
                return gain * np.sign(x - raise_time)
            return step
        def sine_wave(freq, t, Fs):
            n = int((t[1] - t[0]) * Fs) + 1
            t_eval = np.linspace(t[0], t[1], n)
            return interp1d(t_eval, np.sin(t_eval * freq))
In [8]: Fs = 1000
        t = [0, 10]
        t_{eval} = np.linspace(t[0], t[1], int((t[1] - t[0]) * Fs) + 1)
        f = sine_wave(31.622, t, Fs)
        #f = random\_force(t, Fs)
        #f = step_function(10)
        m = 0.1
        k = 100
In [9]: sol = solve_ivp(mass_spring_forced(f, m, k), t, [0, 0], t_eval=t_eval)
In [10]: import matplotlib.pyplot as plt
In [11]: plt.plot(sol.t, sol.y[0])
```

Out[11]: [<matplotlib.lines.Line2D at 0x7fafb44922b0>]



In [12]: plt.plot(sol.t, f(sol.t))

Out[12]: [<matplotlib.lines.Line2D at 0x7fafb4467828>]



In [ ]: