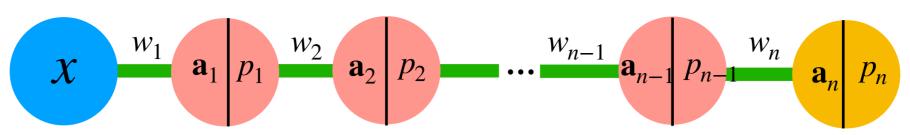
딥러닝 올인원

기울기 사라짐



연쇄 법칙과 활성화 함수

$$p_1 = a_1(w_1x)$$
 $p_2 = a_2(w_2p_1)$ $p_{n-1} = a_{n-1}(w_{n-1}p_{n-2})$ $p_n = a_n(w_np_{n-1})$



$$\frac{\partial p_n}{\partial w_1} = \frac{\partial p_n}{\partial p_{n-1}} \frac{\partial p_{n-1}}{\partial w_1} = \frac{\partial p_n}{\partial p_{n-1}} \frac{\partial p_{n-1}}{\partial p_{n-2}} \frac{\partial p_{n-2}}{\partial p_{n-3}} \cdots \frac{\partial p_2}{\partial p_1} \frac{\partial p_1}{\partial w_1}$$

$$\frac{\partial p_1}{\partial w_1} = \frac{\partial a_1}{\partial w_1} x \qquad \frac{\partial p_n}{\partial p_{n-1}} = \frac{\partial a_n}{\partial p_{n-1}} w_n$$



연쇄 법칙과 활성화 함수

$$\frac{\partial p_1}{\partial w_1} = \frac{\partial a_1}{\partial w_1} x, \frac{\partial p_n}{\partial p_{n-1}} = \frac{\partial a_n}{\partial p_{n-1}} w_n$$

$$p_n = a_n (w_n p_{n-1})$$

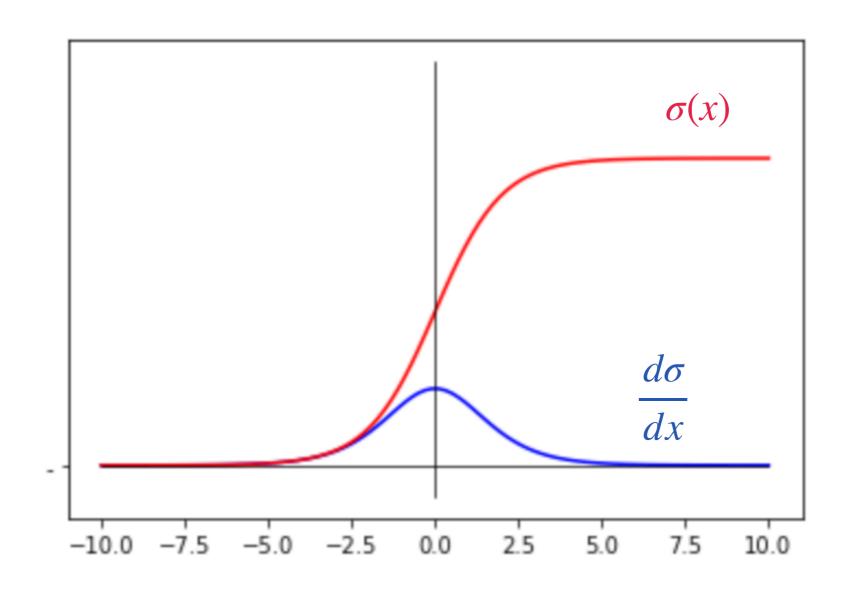
$$\frac{\partial p_n}{\partial w_1} = \frac{\partial p_n}{\partial p_{n-1}} \frac{\partial p_{n-1}}{\partial w_1} = \frac{\partial p_n}{\partial p_{n-1}} \frac{\partial p_{n-1}}{\partial p_{n-2}} \frac{\partial p_{n-2}}{\partial p_{n-3}} \cdots \frac{\partial p_2}{\partial p_1} \frac{\partial p_1}{\partial w_1}$$

$$= \frac{\partial a_n}{\partial p_{n-1}} w_n \frac{\partial a_{n-1}}{\partial p_{n-2}} w_{n-1} \frac{\partial a_{n-2}}{\partial p_{n-3}} w_{n-2} \cdots \frac{\partial a_2}{\partial p_1} w_2 \frac{\partial a_1}{\partial w_1} x$$

$$= \frac{\partial a_n}{\partial p_{n-1}} \frac{\partial a_{n-1}}{\partial p_{n-2}} \frac{\partial a_{n-2}}{\partial p_{n-2}} \cdots \frac{\partial a_2}{\partial p_1} \frac{\partial a_1}{\partial w_1} w_n w_{n-1} w_{n-2} \cdots w_2 x$$



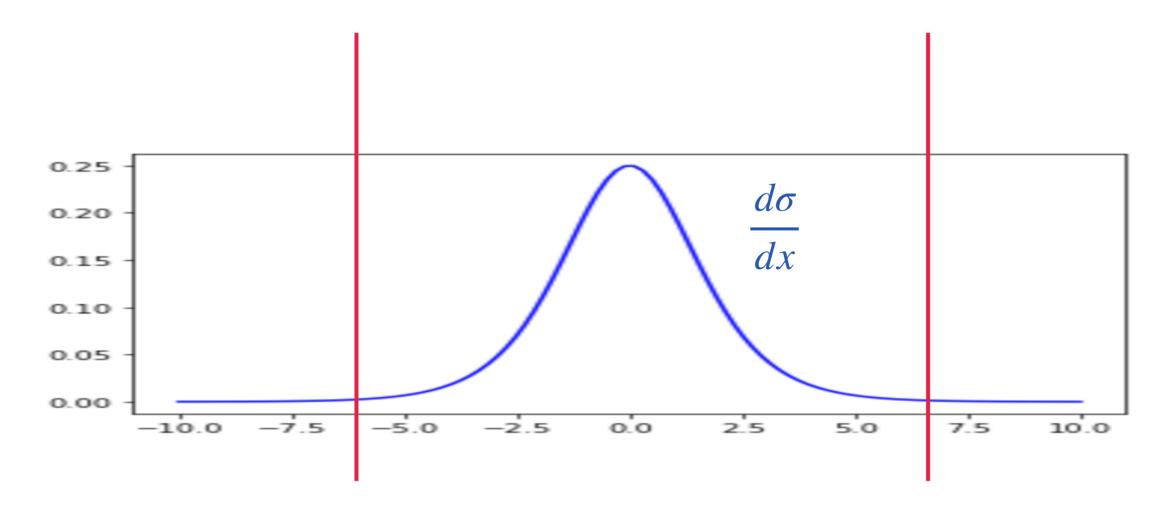
연쇄 법칙과 Sigmoid





연쇄 법칙과 Sigmoid

$$\frac{\partial p_n}{\partial w_1} = \frac{\partial a_n}{\partial p_{n-1}} \frac{\partial a_{n-1}}{\partial p_{n-2}} \frac{\partial a_{n-2}}{\partial p_{n-3}} \cdots \frac{\partial a_2}{\partial p_1} \frac{\partial a_1}{\partial w_1} w_n w_{n-1} w_{n-2} \cdots w_2 x$$





연쇄 법칙과 Sigmoid

$$\frac{\partial p_n}{\partial w_1} \to 0$$

$$w_1 \leftarrow w_1 - \alpha \frac{\partial p_n}{\partial w_1}$$

• 가중치 업데이트가 되지 않는다.



연쇄 법칙과 ReLU

