# Stochastic Uncoupled Dynamics and Nash Equilibrium

Daniel Balle

ETH Zürich

May 2017



#### Introduction

Models & Concepts

Pure Equilibria

Mixed Equilibria

Behavior Probabilities

Memory



#### Introduction

### Definition (Uncoupledness)

A dynamic process in a game is called **uncoupled** if the strategy of each player does not depend on the utility/payoff function of other players.



#### Introduction

#### Definition (Uncoupledness)

A dynamic process in a game is called **uncoupled** if the strategy of each player does not depend on the utility/payoff function of other players.

#### Hart and Mas-Colell '03

There are no deterministic uncoupled stationary dynamics that guarantee almost sure convergence to pure Nash equilibria in all games where such equilibria exist.



#### Introduction

What if players could remember previous plays? What if they had memories?



Introduction

Models & Concepts

Pure Equilibria

Mixed Equilibria

Behavior Probabilities

Memory



# Static Setup

you already know this

# Definition (Static game)

- $N \geq 2$  players denoted by  $i \in \{1, 2, ..., N\}$
- ▶ A finite set of actions  $A^i$  for each player i
- ▶ The set of action combinations  $A := A^1 \times A^2 \times ... \times A^N$
- ▶ A payoff (or utility) function  $u^i:A \to \mathbb{R}$  for each player i

We then identify a game by its payoff functions  $U := (u^1, ..., u^N)$ .



# Static Setup

you already know this

# Definition (randomized or mixed actions)

Player i assigns a probability  $x^i(a)$  to each action  $a \in A^i$ .

- ▶ The set of all mixed actions for player i is  $\Delta(A^i)$
- ▶ We denote by  $\Delta := \Delta(A^1) \times ... \times \Delta(A^N)$  the set of randomized action combinations or N-tuples.
- lacktriangle The payoff function is multi-linearly extended to  $u^i:\Delta o\mathbb{R}$



# Nash Equilibria

should also look familiar

# Definition (best replying)

We say that the randomized actions  $x^i \in \Delta(A^i)$  is an  $\epsilon$ -best reply to  $x^{-i} := (x^1,...,x^{i-1},x^{i+1},...,x^N)$  if for all  $y^i \in \Delta(A^i)$ :

$$u^{i}(x) \ge u^{i}(y^{i}, x^{-i}) - \epsilon$$



# Nash Equilibria

should also look familiar

# Definition (best replying)

We say that the randomized actions  $x^i \in \Delta(A^i)$  is an  $\epsilon$ -best reply to  $x^{-i} := (x^1,...,x^{i-1},x^{i+1},...,x^N)$  if for all  $y^i \in \Delta(A^i)$ :

$$u^{i}(x) \ge u^{i}(y^{i}, x^{-i}) - \epsilon$$

# Definition (Nash $\epsilon$ -equilibrium)

A Nash  $\epsilon$ -equilibrium is a randomized action combination  $\underline{x}=(\underline{x}^1,...,\underline{x}^N)\in \Delta$  such that each  $\underline{x}^i$  is an  $\epsilon$ -best reply to  $\underline{x}^{-i}$ .



# Dynamic Setup

# Definition (History of Play)

For repeated play of U at discrete time periods  $t=1,2,\dots$ 

- $a^i(t) \in A^i$  the action of player i at time t
- ▶  $a(t) = (a^1(t), ..., a^N(t)) \in A$  the action combination at t
- $(a(1),...,a(t-1)) \in H$  the history of play

# Dynamic Setup

#### Definition (History of Play)

For repeated play of U at discrete time periods  $t=1,2,\dots$ 

- $lackbox{a}^i(t) \in A^i$  the action of player i at time t
- ▶  $a(t) = (a^1(t), ..., a^N(t)) \in A$  the action combination at t
- $(a(1),...,a(t-1)) \in H$  the history of play

# Definition (Strategies)

- $f^i: H \to \Delta(A^i)$  the **stationary** strategy of player i
- $f(U) = (f^1(u^1),...,f^N(u^n))$  the **uncoupled** strategy mapping for U



# Recall Influence from the past

#### Definition

A strategy has R-recall if only the last R action combinations matter, i.e.  $f^i$  is of the form  $f^i(a(t-R),...,a(t-1))$  for all t>R.



Introduction

Models & Concepts

Pure Equilibria

Mixed Equilibria

Behavior Probabilities

Memory



#### Theorem

There are no uncoupled, 1-recall, stationary strategy mappings that guarantee almost sure convergence to pure Nash equilibria in all games where such equilibria exist.

Proof

	$\alpha$	$\beta$	$\gamma$
$\alpha$	1,0	0,1	1,0
β	0, 1	1,0	1,0
$\gamma$	0, 1	0,1	1,1
	•		

Figure: A simple two-player game U

#### Observation

In each action combination  $\boldsymbol{a}(t)$  at least one of the two players is best-replying.



Proof

$\alpha$	$\beta$	$\gamma$
1,0	0, 1	1,0
0, 1	1,0	1,0
0, 1	0, 1	1,1
		$ \begin{array}{c cccc} 1, 0 & 0, 1 \\ 0, 1 & 1, 0 \end{array} $

Figure: A simple two-player game U

#### Observation

In each action combination  $\boldsymbol{a}(t)$  at least one of the two players is best-replying.

#### Lemma

If player i is best-replying in state a(t) he will play the same move at t+1



Proof

	$\alpha$	β	$\gamma$
$\alpha$	1, <b>2</b>	0, 1	1,0
$\beta$	0, 1	1,0	1,0
$\gamma$	0, 1	0, 1	1, 0

Figure: Another two-player game  $U^\prime$ 

#### Proof 1/2.

- ▶ Pick a(t) where player 1 is best-replying
- $\blacktriangleright$  Create a new game  $U'=(u^1,\bar{u}^2)$  such that a(t) becomes the unique Nash equilibria



Proof

	$\alpha$	β	$\gamma$
$\alpha$	1, <b>2</b>	0, 1	1,0
$\beta$	0, 1	1,0	1,0
$\gamma$	0, 1	0, 1	1, <b>0</b>
$\gamma$	0,1	0, 1	1, 0

Figure: Another two-player game  $U^\prime$ 

### Proof 2/2.

- ▶ The strategy mapping f converges and is 1-recall and thus neither player will move from a(t) at t+1
- $\blacktriangleright \ \ {\rm Yet \ by \ uncoupledness} \ f^1(U) = f^1(U')$



Proof

	$\alpha$	$\beta$	$\gamma$
$\alpha$	1,0	0, 1	1,0
$\beta$	0, 1	1,0	1,0
$\gamma$	0, 1	0,1	1,1

Figure: The initial two-player game  ${\it U}$ 

#### Observation 2

In any action combination a(t) in which only player i plays  $\gamma$ , player i is not best-replying and thus player j is.



Proof

	$\alpha$	β	$\gamma$
$\alpha$	1,0	0, 1	1,0
$\beta$	0, 1	1,0	1,0
$\gamma$	0, 1	0,1	1,1

Figure: The initial two-player game U

#### Observation 2

In any action combination a(t) in which only player i plays  $\gamma$ , player i is not best-replying and thus player j is.

#### Conclusion.

It follows that the state  $(\gamma, \gamma)$  can never be reached when starting from any other state.



#### Recall to the Rescue

#### Theorem

There exist uncoupled, 2-recall, stationary strategy mappings that guarantee almost sure convergence to pure Nash equilibria in every game where such equilibria exist.

Introduction

Models & Concepts

Pure Equilibria

Mixed Equilibria

Behavior Probabilities

Memory



Introduction

Models & Concepts

Pure Equilibria

Mixed Equilibria

Behavior Probabilities

Memory



Introduction

Models & Concepts

Pure Equilibria

Mixed Equilibria

Behavior Probabilities

Memory



Introduction

Models & Concepts

Pure Equilibria

Mixed Equilibria

Behavior Probabilities

Memory

