The Julia Language

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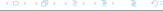
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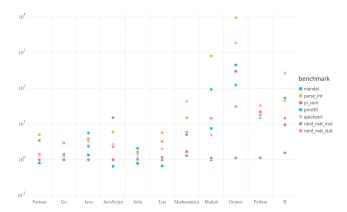
Why I use Julia

- Fast
- Plays nice with shell, C/++ and Python
- Vectors or loops
- Read/Evaluate/Print/Loop (REPL)
- Growing ecosystem





Speed



julialang.org



Calling C

```
• ccall((symbol, library) or function_pointer, ReturnType, (ArgumentType1, ...), ArgumentValue1, ...)
```

- cfunction(function::Function, ReturnType::Type, (ArgumentTypes...))
- https://github.com/timholy/Cpp.jl
- https://github.com/Keno/Cxx.jl





Calling C





Cpp.jl

```
int timestwo(int x) {
   return 2*x;
}

double timestwo(double x) {
   return 2*x;
}

julia> x = 3.5
julia> x2 = @cpp ccall((:timestwo, libdemo), Float64, (Float64,), x)
julia> y2 = @cpp ccall((:timestwo, libdemo), Int, (Int,), y)
```











Calling Julia in C

```
int main(int argc, char *argv[])
{
    /* required: setup the Julia context */
    jl_init(NULL);

    /* run Julia commands */
    jl_eval_string("print(sqrt(2.0))");

    /* strongly recommended: notify Julia that the program is about to terminate. this allows Julia time to cleanup pending write requests and run all finalizers
    */
    jl_atexit_hook(0);
    return 0;
```





Calling Python

```
Opyimport numpy.polynomial as P
Opydef type Doubler <: P.Polynomial
    _{\text{init}}(\text{self, x=10}) = (\text{self[:x] = x})
    my_method(self, arg1::Number) = arg1 + 20
    x2.get(self) = self[:x] * 2
    x2.set!(self, new val) = (self[:x] = new val / 2)
end
Doubler()[:x2]
import numpy.polynomial
class Doubler(numpy.polynomial.Polynomial):
    def __init__(self, x=10):
        self.x = x
    def my_method(self, arg1): return arg1 + 20
    @property
    def x2(self): return self.x * 2
    0x2 setter
    def x2(self. new val):
        self.x = new_val / 2
Doubler().x2
```

https://github.com/JuliaPy/PyCall.jl



Vectors and loops

```
function vectorized()
    a = [1.0, 1.0]
    b = [2.0, 2.0]
    x = [NaN. NaN]
    for i in 1:1000000
        x = a + b
    end
    return
end
function devectorized()
    a = [1.0, 1.0]
    b = [2.0, 2.0]
    x = [NaN, NaN]
    for i in 1:1000000
        for index in 1:2
            x[index] = a[index] + b[index]
        end
    end
    return
end
```





Vectors and loops

| Approach | Language | Average Time |
|--------------|----------|--------------|
| Vectorized | R | 0.49 |
| Devectorized | R | 4.72 |
| Vectorized | Julia | 0.24 |
| Devectorized | Iulia | 0.0035 |



Vectors and loops

```
julia> X .= f.(2 .* X.^2 .+ 6 .* X.^3 .- sqrt.(X))
julia> for i in eachindex(X)
    x = X[i]
   X[i] = f(2x^2 + 6x^3 - sqrt(x))
end
julia> [1 2 3] .+ [10,20,30]
3×3 Array{Int64,2}:
11 12 13
21 22 23
31 32 33
julia> s = ["The QUICK Brown", "fox jumped", "over the LAZY dog."];
julia> s .= replace.(lowercase.(s), r"\s+", "-")
3-element Array(String, 1):
 "the-quick-brown"
 "fox-jumped"
 "over-the-lazy-dog."
```



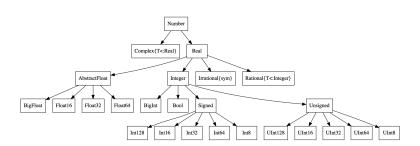


A brief Julia tutorial

- A small taste of Julia's cool features
- Personal introduction to Julia assuming background in programming
- Many other resources online
- http://docs.julialang.org/
- https://learnxinyminutes.com/docs/julia/
- https://github.com/chrisvoncsefalvay/learn-julia-the-hard-way
- https://juliabyexample.helpmanual.io/



Types



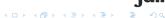




Modules

```
module MyModule
using Lib
using BigLib: thing1, thing2
import Base.show
importall OtherLib
export MyType, foo
type MyType
end
bar(x) = 2x
foo(a::MyType) = bar(a.x) + 1
show(io::IO, a::MyType) = print(io, "MyType $(a.x)")
end
```





Modules

```
module Normal
include("mycode.j1")
end

module Testing
include("safe_operators.j1")
include("mycode.j1")
end
```





Testing





The real world

```
using DifferentialEquations

srand(100)

prob = prob_sde_additive
sol =solve(prob,dt=1/2^(3))

@test typeof(sol.alg) == SRIW1

sol =solve(prob,dt=1/2^(3),alg_hints=[:additive])

@test typeof(sol.alg) == SRA1
```

https://github.com/JuliaDiffEq/DifferentialEquations.jl



The Julia Ecosystem

- Packages and people
- http://juliacon.org/ in Berkeley in 2017
- https://discourse.julialang.org/
- https://juliaobserver.com/
- https://www.reddit.com/r/Julia/
- Repository gitters
- #julia on Freenode



Package management

- Stats

```
julia> Pkg.status()
No packages installed.
julia> Pkg.add("Distributions")
INFO: Cloning cache of Distributions from git://qithub.com/JuliaStats/Distributions.jl.qit
INFO: Cloning cache of NumericExtensions from git://qithub.com/lindahua/NumericExtensions.jl.qit
INFO: Cloning cache of Stats from git://github.com/JuliaStats/Stats.jl.git
INFO: Installing Distributions v0.2.7
INFO: Installing NumericExtensions v0.2.17
INFO: Installing Stats v0.2.6
INFO: REQUIRE updated.
julia> Pkg.status()
Required packages:
 - Distributions
                                 0.2.7
Additional packages:
 - NumericExtensions
                                 0.2.17
```

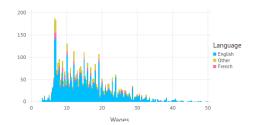
0.2.6





Gadfly

```
using Gadfly
using RDatasets
plot(dataset("car", "SLID"), x="Wages", color="Language", Geom.histogram)
```

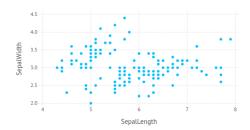






Gadfly

```
using Gadfly
using RDatasets
iris = dataset("datasets", "iris")
p = plot(iris, x=:SepalLength, y=:SepalWidth, Geom.point);
img = SVG("iris_plot.svg", 6inch, 4inch)
draw(img, p)
```

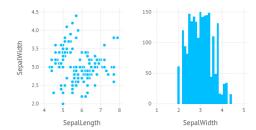






Gadfly

```
fig1a = plot(iris, x="SepalLength", y="SepalWidth", Geom.point)
fig1b = plot(iris, x="SepalWidth", Geom.bar)
fig1 = hstack(fig1a, fig1b)
```







Gadfly

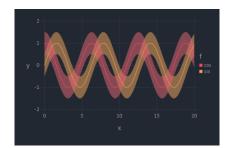
```
using DataFrames
```

```
xs = 0:0.1:20

df_cos = DataFrame(x=xs,y=cos(xs),ymin=cos(xs) .- 0.5,ymax=cos(xs) .+ 0.5,f="cos")

df_sin = DataFrame(x=xs,y=sin(xs),ymin=sin(xs) .- 0.5,ymax=sin(xs) .+ 0.5,f="sin")

df = vcat(df_cos, df_sin)
p = plot(df, x=:x, y=:y, ymin=:ymin, ymax=:ymax, color=:f, Geom.line, Geom.ribbon)
```







Mocha

```
using Mocha
      = HDF5DataLaver(name="train-data", source="train-data-list.txt", batch size=64)
      = ConvolutionLayer(name="conv1",n_filter=20,kernel=(5,5),bottoms=[:data],tops=[:conv])
      = PoolingLayer(name="pool1", kernel=(2,2), stride=(2,2), bottoms=[:conv], tops=[:pool])
conv2 = ConvolutionLayer(name="conv2",n_filter=50,kernel=(5,5),bottoms=[:pool],tops=[:conv2])
pool2 = PoolingLayer(name="pool2",kernel=(2,2),stride=(2,2),bottoms=[:conv2],tops=[:pool2])
      = InnerProductLayer(name="ip1",output_dim=500,neuron=Neurons.ReLU(),bottoms=[:pool2],
                          tops=[:ip1])
      = InnerProductLayer(name="ip2",output dim=10.bottoms=[:ip1].tops=[:ip2])
fc2
      = SoftmaxLossLayer(name="loss",bottoms=[:ip2,:label])
backend = DefaultBackend()
init(backend)
common layers = [conv. pool, conv2, pool2, fc1, fc2]
net = Net("MNIST-train", backend, [data, common lavers..., loss])
exp dir = "snapshots"
solver method = SGD()
params = make_solver_parameters(solver_method, max_iter=10000, regu_coef=0.0005,
    mom_policy=MomPolicy.Fixed(0.9),
    lr_policy=LRPolicy.Inv(0.01, 0.0001, 0.75),
    load_from=exp_dir)
solver = Solver(solver_method, params)
```





Mocha

```
setup_coffee_lounge(solver, save_into="$exp_dir/statistics.jld", every_n_iter=1000)
# report training progress every 100 iterations
add_coffee_break(solver, TrainingSummary(), every_n_iter=100)
# save snapshots every 5000 iterations
add_coffee_break(solver, Snapshot(exp_dir), every_n_iter=5000)
# show performance on test data every 1000 iterations
data_test = HDFSDataLayer(name="test-data",source="test-data-list.txt",batch_size=100)
accuracy = AccuracyLayer(name="test-accuracy",bottoms=[:ip2, :label])
test_net = Net("MNIST-test", backend, [data_test, common_layers..., accuracy])
add_coffee_break(solver, ValidationPerformance(test_net), every_n_iter=1000)
solve(solver, net)
destroy(test_net)
destroy(test_net)
shutdown(backend)
```





Where to go from here

- Read the official Julia manual
- Accept the speedbumps
- Join the community
- Questions?
- https://github.com/d9w/julia-present



