

Tutorial Book



M.Sc Higher Mathematics I

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This TutorialBook is a
complement to it's corresponding Lecture.
When in doubt regarding theory, please consult the LectureBook.

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1

First Order ODEs

Q1

An Initial Value Problem

Solve the initial value problem:

$$y' = \frac{dy}{dx} = 3y, \quad y(0) = 5.7$$

A1

The general solution is:

$$y(x) = ce^{3x}$$

From the solution and the initial condition:

$$y(0) = ce^0 = c = 5.7$$

Hence the initial value problem has the solution:

$$y(x) = 5.7e^{3x}$$

This is a particular solution which can be checked by entering it back into the main equation. Visually the solution is plotted as follows ■

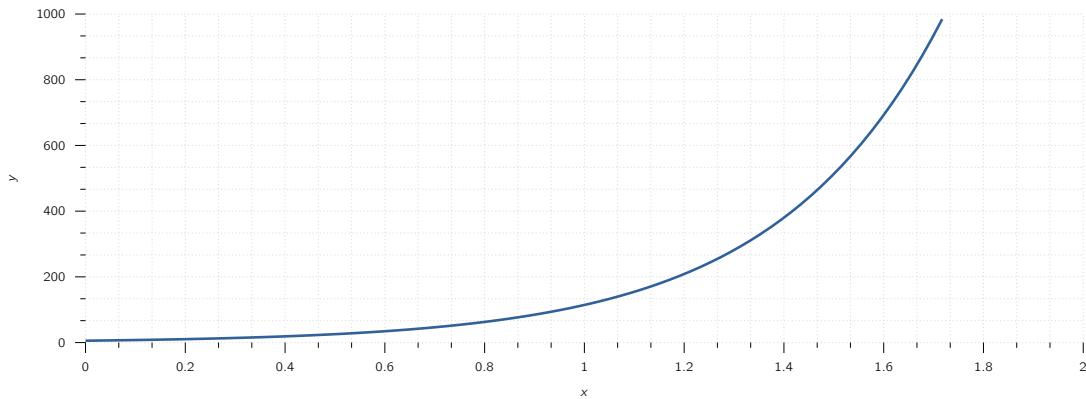


Figure 1.1: A Solution to the initial value problem.

Q2

Radioactive Decay

Given 0,5 g of a radioactive substance, find the amount present at any later time. The decay of Radium is measured to be $k = 1,4 \times 10^{-11} \text{ s}^{-1}$.



A2

We know $y(t)$ is the substance amount still present at t . Using the law of decay, the time rate of change $y'(t) = dy/dt$ is proportional to $y(t)$. This gives:

$$\frac{dy}{dt} = -ky \quad (1.1)$$

where the constant k is **positive**, and due of the minus, we get *decay*. We know k which the question has given as $k = 1,4 \times 10^{-11} \text{ s}^{-1}$. Now the given initial amount is 0,5 g, and we can call the corresponding instant $t = 0$. We have the **initial condition** $y(0) = 0.5$, which is the instant the process begins. Therefore, the mathematical model of the physical process is the initial value problem.

$$\frac{dy}{dt} = -ky, \quad y(0) = 0.5$$

We conclude the Ordinary Differential Equation (ODE) is an exponential decay and has the general solution:

$$y(0) = ce^{-kt}.$$

We now determine c by using the initial condition which gives $y(0) = c = 0.5$. Therefore:

$$y(t) = 0.5e^{-kt} \blacksquare$$

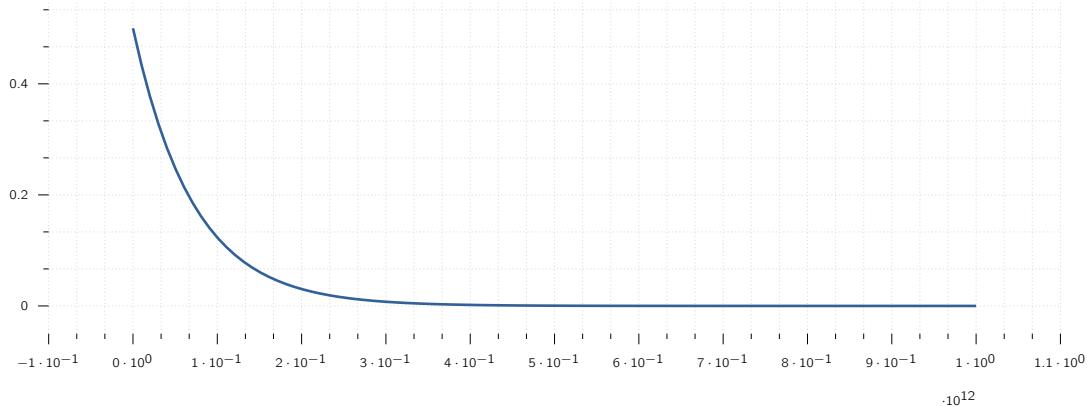


Figure 1.2: A Solution to the radioactive decay.

Q3

Separable ODE

Solve the following ODE:

$$y' = 1 + y^2$$

**A3**

The given ODE is separable because it can be written:

$$\frac{dy}{1+y^2} = dx \quad \text{By integration},$$

$$\arctan y = x + c \quad \text{or} \quad y = \tan(x + c)$$

Note It is important to introduce the constant c when the integration is performed.

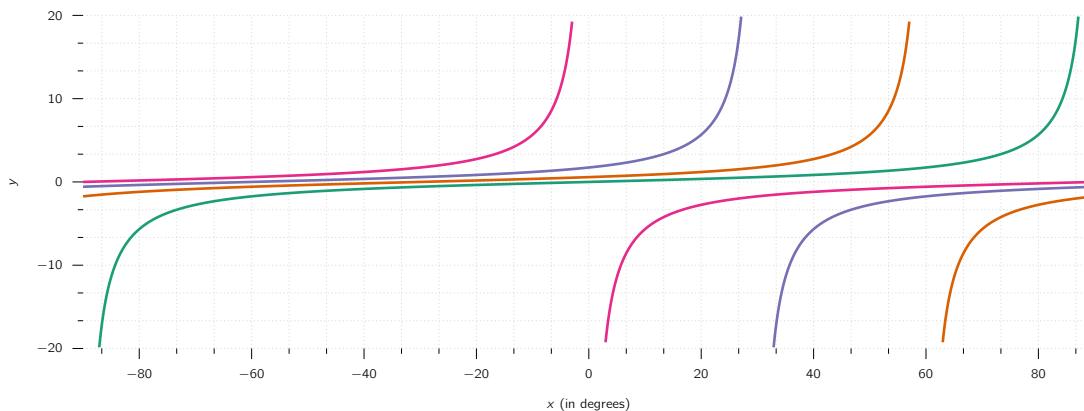


Figure 1.3: A Solution to the Separable ODE.

If we wrote $\arctan y = x$, then $y = \tan x$, and then introduced c , we would have obtained $y = \tan x + c$, which is **NOT** a solution, when $c \neq 0$ ■

Q4

A Bell Shaped Curve

Solve the following ODE:

$$y' = -2xy, \quad y(0) = 1.8$$

A4

By separation and integration,

$$\frac{dy}{y} = -2x \, dx, \quad \ln y = -x^2 + c, \quad y = ce^{-x^2}.$$

This is the general solution. From it and the initial condition, $y(0) = ce^0 = c = 1.8$. Therefore the Initial Value Problem (IVP) has the solution:

$$y = 1.8e^{-x^2}$$

This is a particular solution, representing a bell-shaped curve ■



Figure 1.4: A Solution to the Separable ODE.

Q5**Radiocarbon Dating**

In September 1991 the famous Iceman (Ötzi), a mummy from the Stone Age found in the ice of the Öetztal Alps in Southern Tirol near the Austrian-Italian border, caused a scientific sensation.

When did Ötzi approximately live if the ratio of carbon-14 to carbon-12 in the mummy is 52.5% of that of a living organism?

NOTE The half-life of carbon is 5175 years.

A5

Radioactive decay is governed by the ODE $y' = ky$ as we have discussed previously. By separation and integration

$$\frac{dy}{y} = k dt, \ln|y| = kt + c, y = y_0 e^{kt}, y_0 = e^0.$$

Next we use the half-life $H = 5715$ to determine k . When $t = H$, half of the original substance is still present. Thus,

$$y_0 e^{kH} = 0.5 y_0, \quad e^{kH} = 0.5,$$

$$k = \frac{\ln 0.5}{H} = \frac{0.693}{5715} = -0.0001213.$$

we then use the ratio 52.5% to determine the time:

$$e^{kt} = e^{-0.0001213t} = 0.525,$$

$$t = \frac{\ln 0.525}{-0.0001213} = 5312 \blacksquare$$

**Q6****Reduction to Separable Form**

Solve the following ODE:

$$2xy' = y^2 - x^2.$$

A6

To get the usual explicit form, we start by dividing the given equation by $2xy$ which gives,

$$y' = \frac{y^2 - x^2}{2xy} = \frac{y}{2x} - \frac{x}{2y}.$$

Now substitute y and y' and then we simplify by subtracting u on both sides,

$$u'x + u = \frac{u}{2} - \frac{1}{2u}, \quad u'x = -\frac{u}{2} - \frac{1}{2u} = \frac{-u^2 - 1}{2u}.$$

We see in the last equation that we can now separate the variables,

$$\frac{2u du}{1+u^2} = -\frac{dx}{x} \quad \text{and by integration} \quad \ln(1+u^2) = -\ln|x| + c^* = \ln\left|\frac{1}{x}\right| + c^*.$$

We now take exponents on both sides to get $1+u^2 = c$

$$x^2 + y^2 = cx \quad \text{therefore we can get} \quad \left(x - \frac{c}{2}\right)^2 + y^2 = \frac{c^2}{4}.$$

This general solution represents a family of circles passing through the origin with centres on the x -axis, which can be seen below ■

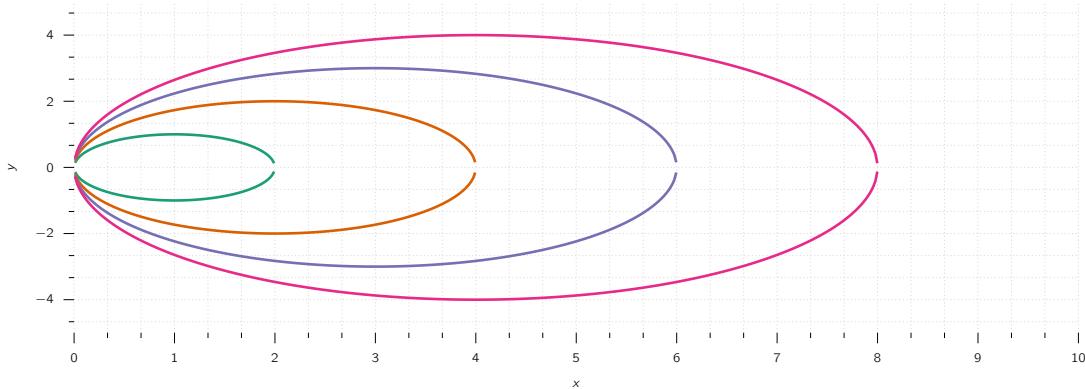


Figure 1.5: A Solution to the Separable ODE.

Q7**Exact ODE - An Initial Value Problem**

Solve the initial value problem:

$$(\cos y \sinh x + 1) dx - \sin y \cosh x dy = 0, \\ \text{with } y(1) = 2.$$

**A7**

Let's begin by verifying the given equation is **exact**:

$$\begin{aligned} M(x, y) &= (\cos y \sinh x + 1), \\ N(x, y) &= -\sin y \cosh x. \end{aligned}$$

We now apply our criteria:

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x} = -\sin y \sinh x$$

This shows the given ODE is **exact**. We find u . For a change, let us use Eq. (??):

$$u = - \int \sin y \cosh x dy + I(x) = \cos y \cosh x + I(x).$$

From this:

$$\frac{\partial u}{\partial x} = \cos y \sinh x + \frac{dI}{dx} = u = \cos y \sinh x + 1$$

Therefore $dI/dx = 1$ and by integration,

$$I(x) = x + c^*.$$

This gives the general solution

$$u(x, y) = \cos y \cosh x + x = c.$$

From the initial condition:

$$\cos 2 \cosh 1 + 1 = 0.358 = c$$

Therefore the answer is:

$$\cos y \cosh x + x = 0.358 \quad \blacksquare$$

A8**An Exact ODE**

Solve the following ODE:

$$\cos(x+y) dx + (3y^2 + 2y + \cos(x+y)) dy = 0.$$

A8

The solution is as follows:

Test for exactness First check if our equation is **exact**, try to convert the equation of the form Eq. (??):

$$\begin{aligned} M &= \cos(x+y), \\ N &= 3y^2 + 2y + \cos(x+y). \end{aligned}$$

Therefore:

$$\frac{\partial M}{\partial y} = -\sin(x+y),$$



$$\frac{\partial N}{\partial x} = -\sin(x+y).$$

This proves our equation to be exact.

Implicit General Solution From Eq. (??), we obtain by integration:

$$\begin{aligned} u &= \int M dx + k(y) \\ &= \int \cos(x+y) dx + k(y) \\ &= \sin(x+y) + k(y) \end{aligned} \tag{1.2}$$

To find $k(y)$, we differentiate this formula with respect to y and use formula Eq. (??), obtaining:

$$\frac{\partial u}{\partial y} = \cos(x+y) + \frac{dk}{dy} = N = 3y^2 + 2y + \cos(x+y)$$

Therefore $\frac{dk}{dy} = 3y^2 + 2y$. By integration, $k = y^3 + y^2 + c^*$. Inserting this result into Eq. (1.2) and observing Eq. (??), we obtain:

$$u(x,y) = \sin(x+y) + y^3 + y^2 = c \blacksquare$$

Q9**The Breakdown of Exactness**

Check the exactness of the following ODE:

$$-y dx + x dy = 0$$

A9

The above equation is **NOT** exact as $M = -y$ and $N = x$, so that:

$$\frac{\partial M}{\partial y} = -1 \quad \frac{\partial N}{\partial x} = 1$$

Let us show that in such a case the present method does **NOT** work.

$$\begin{aligned} u &= \int M dx + k(y) = -xy + k(y), \\ \frac{\partial u}{\partial y} &= -x + \frac{\partial k}{\partial y}. \end{aligned}$$

Now, $\partial u / \partial y$ should equal $N = x$, as required for this equation to be exact. However, this is impossible because $k(y)$ can depend only on y \blacksquare

Q10**A Non Homogeneous Ordinary Differential Equation**

Solve the initial value problem of the following equation:

$$y' + y \tan x = \sin 2x, \quad y(0) = 1.$$

**A10**

Here we define the parameters as:

$$p = \tan x, \quad r = \sin 2x = 2 \sin x \cos x,$$

and

$$h = \int p \, dx = \int \tan x \, dx = \ln|\sec x|.$$

From this we see that in Eq. (??),

$$\begin{aligned} e^h &= \sec x, & e^{-h} &= \cos x, \\ e^h r &= (\sec x) (2 \sin x \cos x) = 2 \sin x, \end{aligned}$$

and the general solution of our equation is:

$$\begin{aligned} y(x) &= \cos x \left(2 \int \sin x \, dx + c \right), \\ &= c \cos x - 2 \cos^2 x. \end{aligned}$$

From this and the initial condition

$$1 = c \cdot 1 - 2 \cdot 1^2, \quad \text{therefore} \quad c = 3,$$

and the solution of our initial value problem is:

$$y = 3 \cos x - 2 \cos^2 x$$

Here $3 \cos x$ is the response to the initial data, and $-2 \cos^2 x$ is the response to the input $\sin 2x$ ■

2

Second Order ODEs

Q11

A Superposition of Solutions

Verify the function $y = \cos x$ and $y = \sin x$ are solutions of the homogeneous linear ODE:

$$y'' + y = 0, \quad \text{for all } x.$$

A11

By differentiation and substitution, we obtain,

$$(\cos x)'' = -\cos x,$$

Therefore:

$$y'' + y = (\cos x)'' + \cos x = -\cos x + \cos x = 0$$

Similarly:

$$(\sin x)'' = -\sin x,$$

and we would arrive in a similar result.

$$y'' + y = (\sin x)'' + \sin x = -\sin x + \sin x = 0$$

To further elaborate on the result, multiply $\cos x$ by 4.7, and $\sin x$ by -2, and take the sum of the results, claiming that it is a solution. Indeed, differentiation and substitution gives:

$$\begin{aligned} & (4.7 \cos x - 2 \sin x)'' + (4.7 \cos x - 2 \sin x) \\ &= -4.7 \cos x + 2 \sin x + 4.7 \cos x - 2 \sin x = 0 \quad \blacksquare \end{aligned}$$

Q12

Example of a Non-Homogeneous Linear ODE

Verify the functions $y = 1 + \cos x$ and $y = 1 + \sin x$ are solutions to the following non-homogeneous linear ODE.

$$y'' + y = 1$$

**A12**

Testing out the first function

$$(1 + \cos x)'' = -\sin x$$

Plugging this to the main equation gives:

$$y'' + y = 1$$

$$-\sin x + 1 + \cos x \neq 1 \quad \blacksquare$$

The first equation is **NOT** the solution to the ODE. Trying the second one:

$$(1 + \sin x)'' = -\cos x$$

$$y'' + y = 1$$

$$-\cos x + 1 + \sin x \neq 1 \quad \blacksquare$$

The second function is also **NOT** a solution.

Q13

An Initial Value Problem

Solve the initial value problem:

$$y'' + y = 0, \quad y(0) = 3.0, \quad y'(0) = -0.5.$$

A13

General Solution From the previous examples, we know the function $\cos x$ and $\sin x$ are solutions to the ODE, and therefore we can write:

$$y = c_1 \cos x + c_2 \sin x$$

This will turn out to be a general solution as defined below.

Particular Solution

We need the derivative $y' = -c_1 \sin x + c_2 \cos x$. From this and the initial values we obtain, as $\cos 0 = 1$ and $\sin 0 = 0$,

$$y(0) = c_1 = 3 \quad \text{and} \quad y'(0) = c_2 = -0.5$$

This gives as the solution of our initial value problem the particular solution

$$y = 3.0 \cos x - 0.5 \sin x \quad \blacksquare$$

Q14

Reduction of Order

Find a basis of solutions of the ODE

$$(x^2 - x) y'' - xy' + y = 0.$$

**A14**

Inspection shows $y_1 = x$ is a solution as $y'_1 = 1$ and $y''_1 = 0$, so that the first term vanishes identically and the second and third terms cancel. The idea of the method is to substitute

$$\begin{aligned}y &= uy_1 = ux, & y' &= u'x + u, \\&& y'' &= u''x + 2u'\end{aligned}$$

into the ODE. This gives:

$$(x^2 - x)(u''x + 2u') - x(u'x + u) + ux = 0$$

ux and $-xu$ cancel and we are left with the following ODE, which we divide by x , order, and simplify,

$$\begin{aligned}(x^2 - x)(u''x + 2u') - x^2u' &= 0, \\(x^2 - x)u'' + (x - 2)u' &= 0.\end{aligned}$$

This ODE is of first order in $v = u'$, namely,

$$(x^2 - x)w' + (x - 2)w = 0.$$

Separation of variables and integration gives

$$\begin{aligned}\frac{dv}{v} &= -\frac{x-2}{x^2-x}dx = \left(\frac{1}{x-1} - \frac{2}{x}\right)dx, \\ \ln|v| &= \ln|x-1| - 2\ln|x| = \ln\frac{|x-1|}{x^2}.\end{aligned}$$

We don't need constant of integration as we want to obtain a particular solution; similarly in the next integration. Taking exponents and integrating again, we obtain n

$$\begin{aligned}v &= \frac{x-1}{x^2} = \frac{1}{x} - \frac{1}{x^2}, & u &= \int v dx = \ln|x| + \frac{1}{x}, \\&\text{hence } y_2 = ux = x \ln|x| + 1\end{aligned}$$

Since $y_1 = x$ and $y_2 = x \ln|x| + 1$ are linearly independent (their quotient is not constant), we have obtained as basic of solutions, valid for all positive x ■

Q15

A General Solution in the Case of Different Real Roots

Solve the following ODE:

$$x^2y'' + 1.5xy' - 0.5y = 0$$

A15

This equation can be classified as **Euler-Cauchy equation** and it has an auxiliary equation $m^2 + 0.5m - 0.5 = 0$. Based on this equation, the roots are 0.5 and -1 . Hence a basis of solutions for all positive x is $y_1 = x^{0.5}$ and $y_2 = 1/x$ and gives the general solution.

$$y = c_1\sqrt{x} + \frac{c_2}{x} \quad (x > 0) \quad ■$$

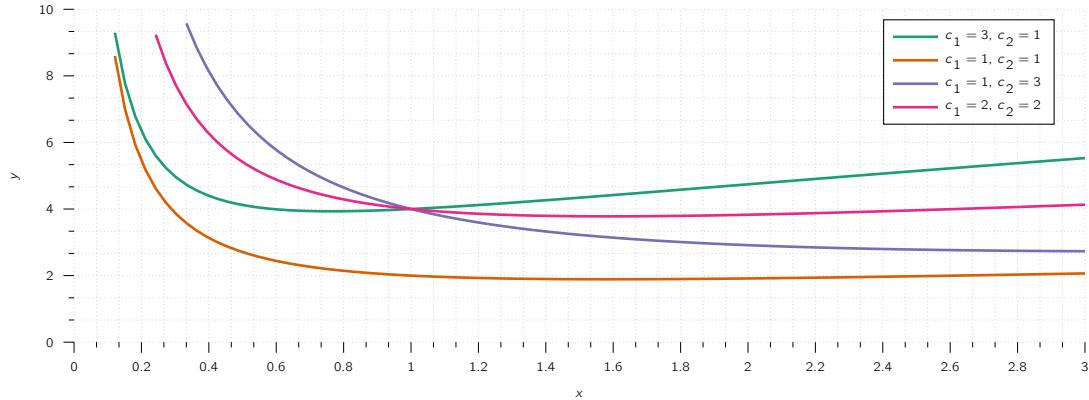


Figure 2.1: Solution to A General Solution in the Case of Different Real Roots with different constants.

Q16**A General Solution in the Case of a Double Root**

Solve the following ODE:

$$x^2y'' - 5xy' + 9y = 0$$

A16

Based on its format it can be classified as an **Euler-Cauchy** equation with an auxiliary equation $m^2 - 6m + 9 = 0$. It has the double root $m = 3$, so that a general solution for all positive x is:

$$y = (c_1 + c_2 \ln x) x^2. \blacksquare$$

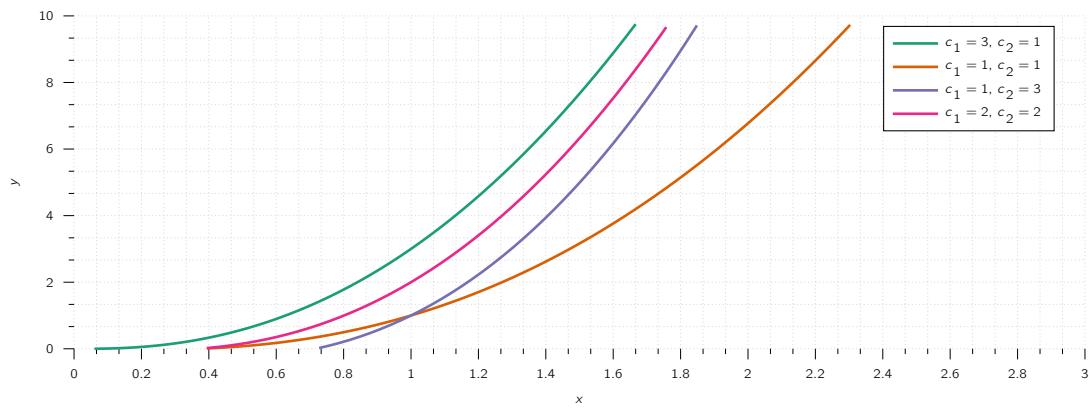


Figure 2.2: Solution to A General Solution in the Case of a Double Root with different constants.

Q17**Electric Potential Field Between Two Concentric Spheres**

Find the electrostatic potential $v = v(r)$ between two concentric spheres of radii $r_1 = 5$ cm and $r_2 = 10$ cm kept at potentials $v_1 = 110$ V and $v_2 = 0$, respectively.

$v = v(r)$ is a solution of the *Euler-Cauchy* equation $rv'' + 2v' = 0$.

**A17**

The auxiliary equation is:

$$m^2 + m = 0$$

It has the roots 0 and -1. This gives the general solution of:

$$v(r) = c_1 + c_2/r$$

From the **boundary conditions** (i.e., the potentials on the spheres), we obtain:

$$v(5) = c_1 + \frac{c_2}{5} = 110. \quad v(10) = c_1 + \frac{c_2}{10} = 0.$$

By subtraction, $c_2/10 = 110$, $c_2 = 1100$. From the second equation, $c_1 = -c_2/10 = -110$ which gives the final equation:

$$v(r) = -110 + 1100/r \quad \blacksquare$$

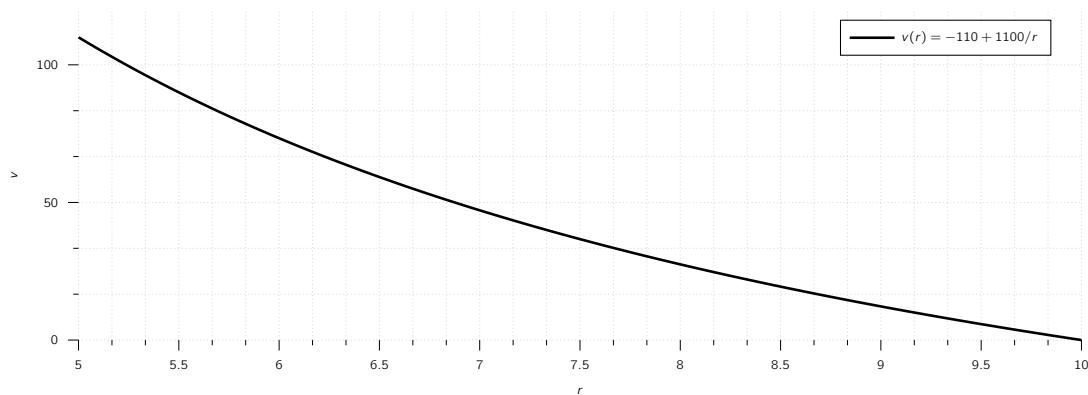


Figure 2.3: Solution to the Electric Potential Field Between Two Concentric Spheres.

Q18

Three Cases of Damped Motion

How does the motion in *Harmonic Oscillation of an Undamped Mass-Spring System* change if we change the damping constant c from one to another of the following three values, with $y(0) = 0.16$ and $y'(0) = 0$ as before?

- $c = 100 \text{ kg} \cdot \text{s}^{-1}$
- $c = 60 \text{ kg} \cdot \text{s}^{-1}$
- $c = 10 \text{ kg} \cdot \text{s}^{-1}$



A18

It is interesting to see how the behavior of the system changes due to the effect of the damping, which takes energy from the system, so that the oscillations decrease in amplitude (Case III) or even disappear (Cases II and I).

Case I With $m = 10$ and $k = 90$, as in *Harmonic Oscillation of an Undamped Mass-Spring System*, the model is the initial value problem:

$$10y'' + 100y' + 90y = 0, \quad y(0) = 0.16 \text{ m}, \quad y'(0) = 0.$$

The characteristic equation is $10\lambda^2 + 100\lambda + 90 = 0$. It has the roots $\lambda_1 = -9$ and $\lambda_2 = -1$. This gives the general solution:

$$y = c_1 e^{-9t} + c_2 e^{-t} \quad \text{We also need } y' = -9c_1 e^{-9t} - c_2 e^{-t}.$$

The initial conditions give $c_1 + c_2 = 0.16$ and $-9c_1 - c_2 = 0$. The solution is $c_1 = -0.02$, $c_2 = 0.18$. Hence in the overdamped case the solution is:

$$y = -0.02e^{-9t} + 0.18e^{-t} \blacksquare$$

It approaches 0 as $t \rightarrow 0$. The approach is rapid; after a few seconds the solution is practically 0, that is, the iron ball is at rest.

Case II The model is as before, with $c = 60$ instead of 100. The characteristic equation now has the form:

$$10\lambda^2 + 60\lambda + 90 = 10(\lambda + 3)^2 = 0$$

It has the double root $\lambda_1 = \lambda_2 = -3$. Hence the corresponding general solution is:

$$y = (c_1 + c_2 t) e^{-3t}, \quad \text{we also need } y' = (c_2 - 3c_1 - 3c_2 t) e^{-3t}$$

The initial conditions give $y(0) = c_1 = 0.16$, $y'(0) = c_2 - 3c_1 = 0$, $c_2 = 0.48$. Hence in the critical case the solution is:

$$y = (0.16 + 0.48t) e^{-3t} \blacksquare$$

It is always positive and decreases to 0 in a **monotone** fashion.

Case III The model is now:

$$10y'' + 10y' + 90y = 0.$$

As $c = 10$ is smaller critical c , we will see oscillations. The characteristic equation is:

$$10\lambda^2 + 10\lambda + 90 = 10 \left[\left(\lambda + \frac{1}{2} \right)^2 + 9 - \frac{1}{4} \right] = 0$$

This equation has complex roots:

$$\lambda = -0.5 \pm \sqrt{0.5^2 - 9} = -0.5 \pm 2.96j$$



This gives the general solution:

$$y = e^{-0.5t} (A \cos 2.96t + B \sin 2.96t)$$

Therefore $y(0) = A = 0.16$. We also need the derivative

$$y' = e^{-0.5t} (-0.5A \cos 2.96t - 0.5B \sin 2.96t - 2.96A \sin 2.96t + 2.96B \cos 2.96t)$$

Hence $y'(0) = -0.5A + 2.96B = 0$, $B = 0.5A/2.96 = 0.027$. This gives the solution:

$$y = e^{-0.5t} (0.16 \cos 2.96t + 0.027 \sin 2.96t) = 0.162e^{-0.5t} \cos(2.96t - 0.17) \blacksquare$$

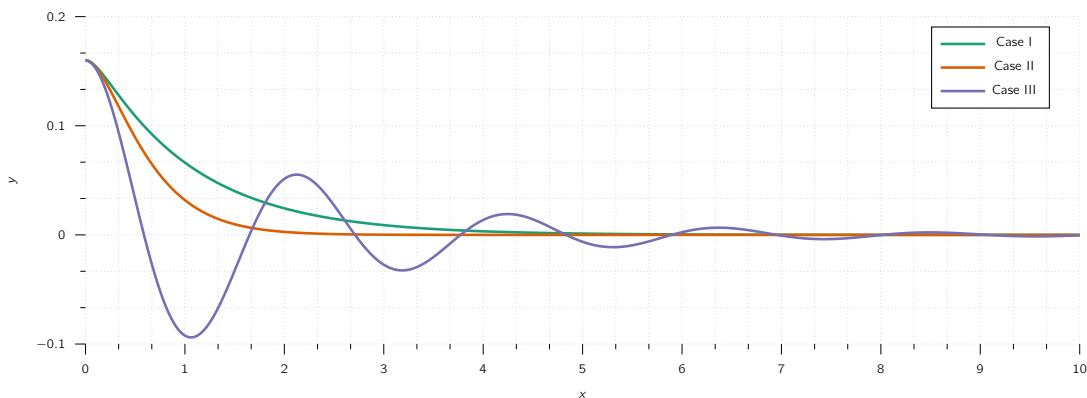


Figure 2.4: Three cases of damped motion.

Q19

Application of the Basic Rule A

Solve the initial value problem

$$y'' + y = 0.001x^2, \quad y(0) = 0, \quad y'(0) = 1.5.$$

A19

General Solution of the Homogeneous ODE The ODE $y'' + y = 0$ has the general solution

$$y_h = A \cos x + B \sin x.$$

Solution of the non-Homogeneous ODE First we try $y_p = Kx^2$ and also $y_p'' = 2K$. By

substitution:

$$2K + Kx^2 = 0.001x^2$$

For this to hold for all x , the coefficient of each power of x (x^2 and x^0) must be the same on both sides. Therefore:

$$K = 0.001, \quad \text{and} \quad 2K = 0, \quad \text{a contradiction.}$$

Looking at the table suggests the choice:

$$y_p = K_2x^2 + K_1x + K_0,$$



$$y_p'' + y_p = 2K_2 + K_2x^2 + K_1x + K_0 = 0.001x^2.$$

Equating the coefficients of x^2 , x , x^0 on both sides, we have:

$$K_2 = 0.001, \quad K_1 = 0, \quad 2K_2 + K_0 = 0$$

Therefore:

$$K_0 = -2K_2 = -0.002$$

This gives $y_p = 0.001x^2 - 0.002$, and

$$y = y_h + y_p = A \cos x + B \sin x + 0.001x^2 - 0.002.$$

Solution of the initial value problem.

Setting $x = 0$ and using the first initial condition gives $y(0) = A - 0.002 = 0$, therefore $A = 0.002$. By differentiation and from the second initial condition,

$$\begin{aligned} y' &= y'_h + y'_p = -A \sin x + B \cos x + 0.002x \\ \text{and } y'(0) &= B = 1.5. \end{aligned}$$

This gives the answer in the along with the Figure below.

$$y = 0.002 \cos x + 1.5 \sin x + 0.001x^2 - 0.002 \blacksquare$$

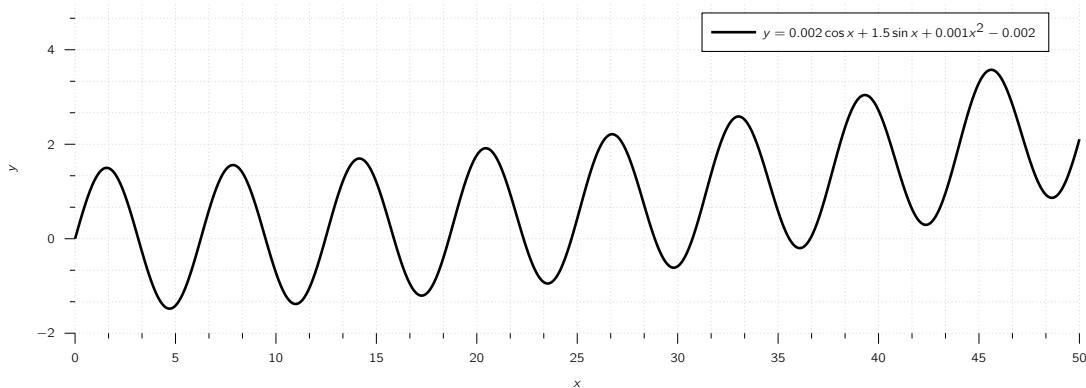


Figure 2.5: Solution to Application of the basic rule A.

Q20

Application of the Basic Rule B

Solve the initial value problem

$$\begin{aligned} y'' + 3y' + 2.25y &= -10e^{-1.5x}, \\ y(0) &= 1, \quad y'(0) = 0. \end{aligned}$$



A20

General solution of the homogeneous ODE The characteristic equation of the homogeneous ODE is

$$\lambda^2 + 3\lambda + 2.25 = (\lambda + 1.5)^2 = 0$$

Therefore the homogeneous ODE has the general solution:

$$y_h = (c_1 + c_2x)e^{-1.5x}$$

Solution y_p of the non-homogeneous ODE The function $e^{-1.5x}$ on the Right Hand Side (RHS) would normally require the choice $Ce^{-1.5x}$. However, we see from y_h that this function is a solution of the homogeneous ODE, which corresponds to a double root of the characteristic equation. Which means, according to the Modification Rule we have to multiply our choice function by x^2 . That is, we choose:

$$\begin{aligned} y_p &= Cx^2e^{-1.5x}, \quad \text{then} \\ y'_p &= C(2x - 1.5x^2)e^{-1.5x}, \\ y''_p &= C(2 - 3x - 3x + 2.25x^2)e^{-1.5x} \end{aligned}$$

We substitute these expressions into the given ODE and omit the factor $e^{-1.5x}$. This yields

$$C(2 - 6x + 2.25x^2) + 3C(2x - 1.5x^2) + 2.25Cx^2 = -10$$

Comparing the coefficients of x^2, x, x^0 gives $0 = 0, 0 = 0, 2C = -10$, hence $C = -5$. This gives the solution $y_p = -5x^5e^{-1.5x}$. Hence the given ODE has the general solution:

$$y = y_h + y_p = (c_1 + c_2x)e^{-1.5x} - 5x^2e^{-1.5x}$$

Step 3. Solution of the initial value problem Setting $x = 0$ in y and using the first initial condition, we obtain $y(0) = c_1 = 1$. Differentiation of y gives:

$$\begin{aligned} y' &= (c_2 - 1.5c_1 - 1.5c_2x)e^{-1.2x} \\ &\quad - 10xe^{-1.2x} + 7.5x^2e^{-1.2x} \end{aligned}$$

From this and the second initial condition we have $y'(0) = c_2 - 1.5c_1 = 0$. Hence $c_2 = 1.5c_1 = 1.5$ and gives the answer

$$\begin{aligned} y &= (1 + 1.5x)e^{-1.5x} - 5x^2e^{-1.5x} = \\ &\quad (1 + 1.5x - 5x^2)e^{-1.5x} \blacksquare \end{aligned}$$

The curve begins with a horizontal tangent, crosses the x -axis at $x = 0.6217$ (where $1 + 1.5x - 5x^2 = 0$) and approaches the axis from below as x increases.

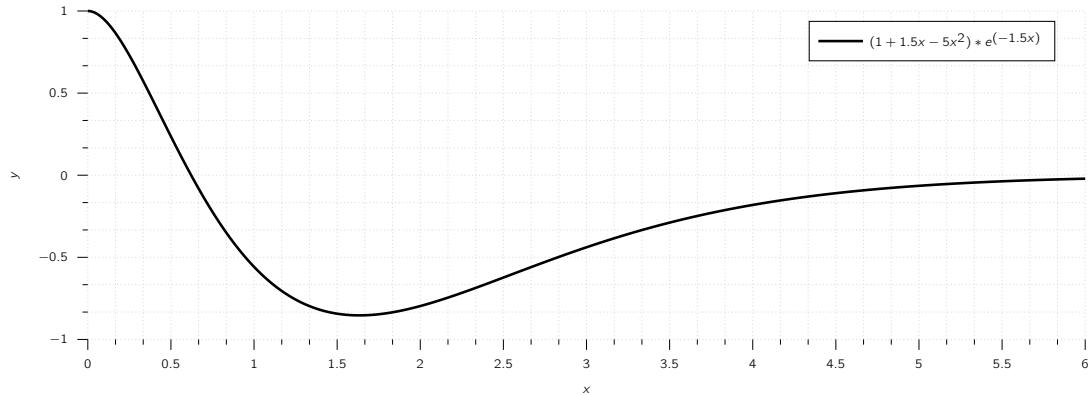


Figure 2.6: Solution to Application of the basic rule B.

Q21**Application of the Basic Rule C**

Solve the initial value problem

$$\begin{aligned}y'' + 2y' + 0.75y &= 2\cos x - 0.25\sin x + 0.09x, \\y(0) &= 2.78, \quad y'(0) = -0.43.\end{aligned}$$

A21

The General Solution The characteristic equation of the homogeneous ODE is:

$$\lambda^2 + 2\lambda + 0.75 = (\lambda + \frac{1}{2})(\lambda + \frac{3}{2}) = 0$$

which gives the solution:

$$y_h = c_1 e^{-x/2} + c_2 e^{-3x/2}.$$

The Particular Solution We write:

$$y_p = y_{p1} + y_{p2}$$

and following the table,

$$y_{p1} = K \cos x + M \sin x \quad \text{and} \quad y_{p2} = K_1 x + K_0$$

Differentiating gives:

$$\begin{aligned}y_{p1}' &= -K \sin x + M \cos x, \\y_{p1}'' &= -K \cos x - M \sin x, \\y_{p2}' &= 1, \\y_{p2}'' &= 0.\end{aligned}$$

Substitution of y_{p1} into the ODE gives, by comparing the cosine and sine terms:

$$-K + 2M + 0.75K = 2, \quad -M - 2K + 0.75M = -0.25$$



Therefore $K = 0$ and $M = 1$. Substituting y_{p2} into the ODE in (7) and comparing the x and x^0 terms gives:

$$0.75K_1 = 0.09, \quad 2K_1 + 0.75K_0 = 0,$$

therefore

$$K_1 = 0.12, \quad K_0 = -0.32.$$

Hence a general solution of the ODE is

$$y = c_1 e^{-x/2} + c_2 e^{-3x/2} + \sin x + 0.12x - 0.32 \quad \blacksquare$$

Solution of the initial value problem From y , y' and the initial conditions we obtain:

$$y(0) = c_1 + c_2 - 0.32 = 2.78,$$

$$y'(0) = -\frac{1}{2}c_1 - \frac{3}{2}c_2 + 1 + 0.12 = -0.4.$$

Hence $c_1 = 3.1$, $c_2 = 0$. This gives the solution of the IVP:

$$y = 3.1e^{-x/2} + \sin x + 0.12x - 0.32. \quad \blacksquare$$

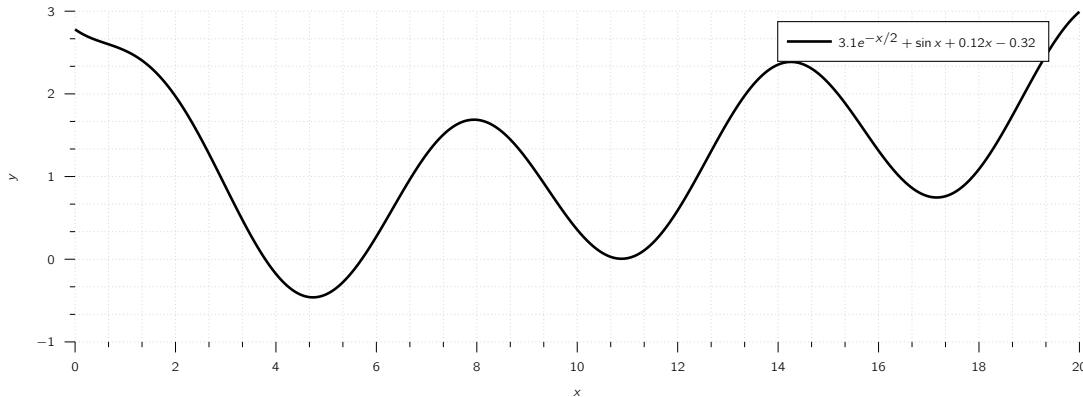


Figure 2.7: Solution to Application of the basic rule C.

Q22

Studying a RLC Circuit

Find the current $I(t)$ in an RLC-circuit with $R = 11 \Omega$, $L = 0.9 \text{ H}$, $C = 0.01 \text{ F}$, which is connected to a source of $V(t) = 110 \sin(120\pi t)$.

Note Assume that current and capacitor charge are 0 when $t = 0$.



A22

The General solution Substituting R , L , C and the derivative $V(t)$, we obtain:

$$LI'' + RI' + \frac{1}{C}I = E'(t) = E_0\omega \cos \omega t.$$

$$0.1I'' + 11I' + 100I = 110 \cdot 377 \cos 377t.$$

Therefore the homogeneous ODE is:

$$0.1I'' + 11I' + 100I = 0$$

Its **characteristic equation** is:

$$0.1\lambda^2 + 11\lambda + 100 = 0.$$

The roots are $\lambda_1 = -10$ and $\lambda_2 = -100$. The corresponding general solution of the homogeneous ODE is:

$$I_h(t) = c_1 e^{-10t} + c_2 e^{-100t}.$$

The Particular solution We calculate the reactance $S = 37.7 - 0.3 = 37.4$ and the steady-state current:

$$I_p(t) = a \cos 377t + b \sin 377t$$

with coefficients obtained from:

$$a = \frac{-110 \cdot 37.4}{11^2 + 37.4^2} = -2.71, \quad b = \frac{110 \cdot 11}{11^2 + 37.4^2} = 0.796.$$

Therefore in our present case, a general solution of the nonhomogeneous ODE is:

$$I(t) = c_1 e^{-10t} + c_2 e^{-100t} - 2.71 \cos 377t + 0.796 \sin 377t$$

Particular solution satisfying the initial conditions How to use $Q(0) = 0$? We finally determine c_1 and c_2 from the initial conditions $I(0) = 0$ and $Q(0) = 0$. From the first condition and the general solution we have:

$$I(0) = c_1 + c_2 - 2.71 = 0 \quad \text{hence} \quad c_2 = 2.71 - c_1$$

We turn to $Q(0) = 0$. The integral in (1r) equals $\int I dt$ $Q(t)$; see near the beginning of this section. Hence for $t = 0$, Eq. (1r) becomes

$$L'(0) + R \cdot 0 = 0 \quad \text{so that} \quad I'(0) = 0$$

Differentiating (6) and setting $t = 0$, we thus obtain

$$I'(0) = -10c_1 - 100c_2 + 0 + 0.796 \cdot 377 = 0 \quad \text{hence} \quad -10c_1 = 100(2.71 - c_1) - 300.1.$$

The solution of this and (7) is $c_1 = 0.323$, $c_2 = 3.033$. Hence the answer is

$$I(t) = -0.323e^{-10t} + 3.033e^{-100t} - 2.71 \cos 377t + 0.796 \sin 377t \blacksquare$$



Figure below shows $I(t)$ as well as $I_p(t)$, which practically coincide, except for a very short time near $t = 0$ because the exponential terms go to zero very rapidly.

Thus after a very short time the current will practically execute harmonic oscillations of the input frequency.

Its maximum amplitude and phase lag can be seen from (5), which here takes the form

$$I_p(t) = 2.824 \sin(377t - 1.29) \quad \blacksquare$$

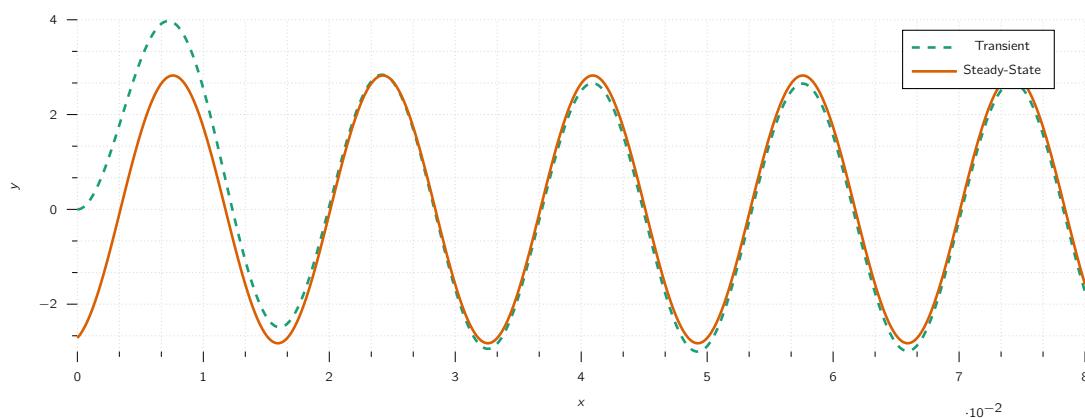


Figure 2.8: A comparison of the actual solution and the steady-state values.

Q23

Harmonic Oscillation of an Undamped Mass-Spring System

If a mass-spring system with an iron ball of weight $W = 98$ N can be regarded as undamped, and the spring is such that the ball stretches it 1.09 m, how many cycles per minute will the system execute?

What will its motion be if we pull the ball down from rest by 16 cm and let it start with zero initial velocity?

A23

Hooke's law:

$$F_1 = -ky \quad (2.1)$$

with W as the force and 1.09 meter as the stretch gives $W = 1.09k$. Therefore

$$k = \frac{W}{1.09} = \frac{98}{1.09} = 90$$

whereas the mass (m) is:

$$m = \frac{W}{g} = \frac{98}{9.8} = 10 \text{ kg}$$

This gives the frequency:

$$f = \frac{\omega_0}{2\pi} = \frac{\sqrt{k/m}}{2\pi} = \frac{3}{2\pi} = 0.48 \text{ Hz}$$

From Eq. (2.1) and the initial conditions, $y(0) = A = 0.16$ m and $y'(0) = \omega_0 B = 0$.



Hence the motion is

$$y(t) = 0.16 \cos 3t \text{ m} \quad \blacksquare$$

Q24**IVP: Case of Real Double Roots**

Solve the initial value problem:

$$y'' + y' + 0.25y = 0, \quad y(0) = 3, \quad y'(0) = -3.5.$$

A24

The characteristic equation is:

$$\lambda^2 + \lambda + 0.25 = (\lambda + 0.5)^2 = 0,$$

It has the double root $\lambda = -0.5$. This gives the general solution:

$$y = (c_1 + c_2x) e^{-0.5x}$$

We need its derivative:

$$y' = c_2 e^{-0.5x} - 0.5(c_1 + c_2x) e^{-0.5x}$$

From this and the initial conditions we obtain:

$$y(0) = c_1 = 3.0,$$

$$y'(0) = c_2 - 0.5c_1 = 3.5,$$

$$c_2 = -2$$

The particular solution of the initial value problem is:

$$y = (3 - 2x) e^{-0.5x}$$

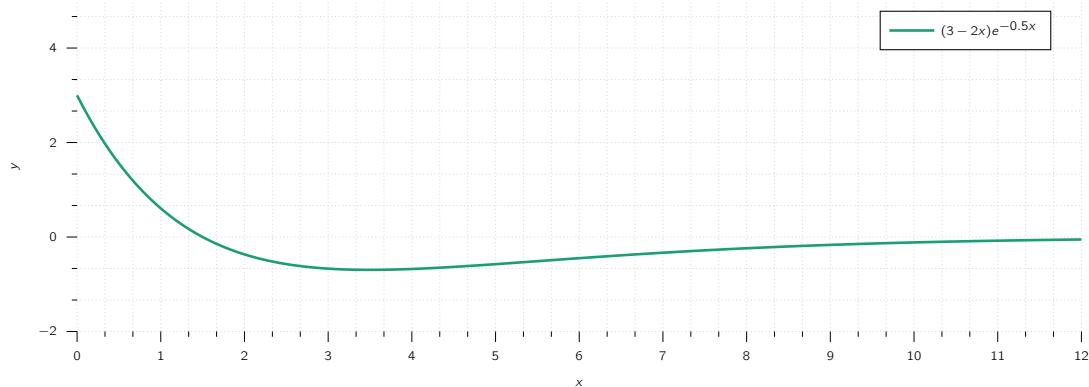


Figure 2.9: Solution to case of double roots.

Q25**IVP: Case of Complex Roots**

Solve the initial value problem:

$$y'' + 0.4y' + 9.04y = 0, \quad y(0) = 0, \quad y'(0) = 3.$$

**A25**

General Solution The characteristic equation is:

$$\lambda^2 + 0.4\lambda + 9.04 = 0$$

It has the roots of $-0.2 \pm 3j$. Hence $\omega = 3$ and the general solution is:

$$y = e^{-0.2x}(A \cos 3x + B \sin 3x).$$

Particular Solution The first initial condition gives $y(0) = A = 0$. The remaining expression is $y = Be^{-0.2x}$. We need the derivative (chain rule!)

$$y' = B(-0.2e^{-0.2x} \sin 3x + 3e^{-0.2x} \cos 3x)$$

From this and the second initial condition we obtain $y'(0) = 3B = 3$, therefore:

$$y = e^{-0.2x} \sin 3x.$$

The Figure shows y and $-e^{-0.2x}$ and $e^{-0.2x}$ (dashed), between which y oscillates. Such "damped vibrations" have important mechanical and electrical applications.

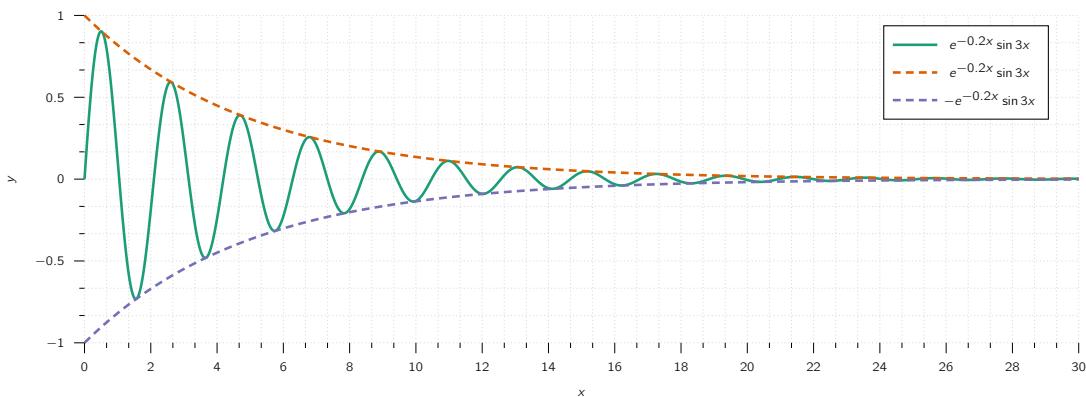


Figure 2.10: Solution to case of complex roots.

Q26

IVP: Case of Distinct Real Roots

Solve the initial value problem:

$$y'' + y' - 2y = 0, \quad y(0) = 4, \quad y'(0) = -5.$$



A26

General Solution The characteristic equation is:

$$\lambda^2 + \lambda - 2 = 0.$$

Its roots are:

$$\begin{aligned}\lambda_1 &= \frac{1}{2}(-1 + \sqrt{9}) = 1, \\ \text{and} \quad \lambda_2 &= \frac{1}{2}(-1 - \sqrt{9}) = -2.\end{aligned}$$

so that we obtain the general solution

$$y = c_1 e^x + c_2 e^{-2x}.$$

Particular Solution As we obtained the general solution with the initial conditions:

$$y(0) = c_1 + c_2 = 4, \quad y'(0) = c_1 - 2c_2 = -5.$$

Hence $c_1 = 3$ and $c_2 = 1$. This gives the answer:

$$y = e^x + 3e^{-2x} \blacksquare$$

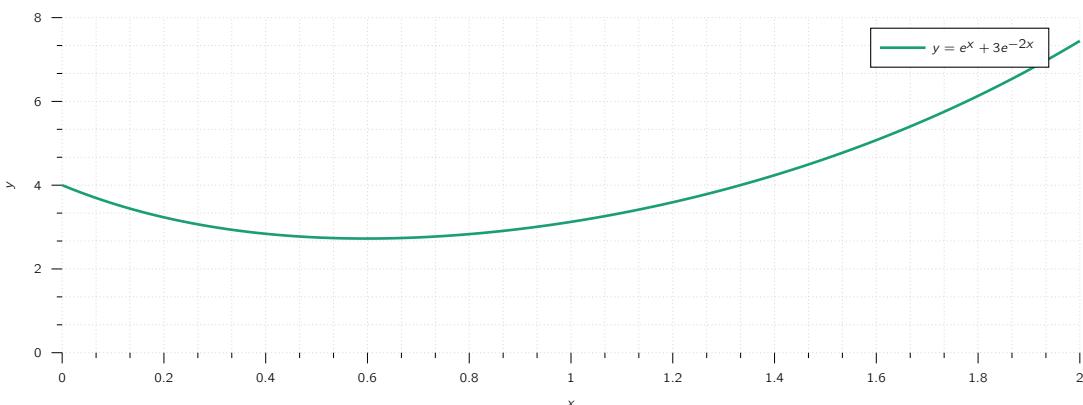


Figure 2.11: Solution to Case of distinct real roots.

3

Higher Order ODEs

Q27

Linear Dependence

Show that the functions $y_1 = x^2, y_2 = 5x, y_3 = 2x$ are linearly dependent on any interval.

A27

By inspection it can be seen that $y_2 = 0y_1 + 2.5y_3$. This relation of solutions proves linear dependence on any interval ■

Q28

A General Solution

Solve the fourth-order ODE

$$y^{iv} - 5y'' + 4y = 0 \quad \text{where} \quad y^{iv} = \frac{d^4y}{dx^4}$$

A28

Similar to Chapter ?? we substitute $y = e^{4x}$. Omitting the common factor e^{4x} , we obtain the characteristic equation:

$$\lambda^4 - 5\lambda^2 + 4 = 0$$

This is a quadratic equation in $\mu = \lambda^2$, namely,

$$\mu^2 - 5\mu + 4 = (\mu - 1)(\mu - 4) = 0$$

The roots are $\mu = 1$ and 4 . Hence $\lambda = -2, -1, 1, 2$. This gives four solutions. A general solution on any interval is

$$y = c_1 e^{-2\mu} + c_2 e^{-\nu} + c_3 e^\nu + c_4 e^{2\mu}$$

provided those four solutions are linearly independent ■

Q29

Initial Value Problem for a Third-Order Euler-Cauchy Equation

Solve the following initial value problem on any open interval I on the positive x -axis containing $x = 1$.

$$x^3 y''' - 3x^2 y'' + 6xy' - 6y = 0, \quad y(1) = 2, \quad y'(1) = 1, \quad y''(1) = -4.$$

**A29**

General Solution As in Chapter ??, try $y = x^m$. By differentiation and substitution,

$$m(m-1)(m-2)x^m - 3m(m-1)x^m + 6mx^m - 6x^m = 0.$$

Dropping x^m and ordering gives $m^3 - 6m^2 + 11m - 6 = 0$. If we can guess the root $m = 1$. We can divide by $m - 1$ and find the other roots 2 and 3, thus obtaining the solutions x, x^2, x^3 , which are linearly independent on I .

In general one shall need a numerical method, such as Newton's to find the roots of the equation.

Hence a general solution is

$$y = c_1x + c_2x^2 + c_3x^3$$

valid on any interval I , even when it includes $x = 0$ where the coefficients of the ODE divided by x^3 (to have the standard form) we not continuous.

Particular Solution The derivatives are $y' = c_1 + 2c_2x + 3c_3x^2$ and $y'' = 2c_2 + 6c_3x$. From this, and y and the initial conditions, we get by setting $x = 1$

$$\begin{array}{lll} \text{(a)} & y(1) = c_1 + & c_2 + c_3 = \\ \text{(b)} & y'(1) = c_1 + 2c_2 + & 3c_3 = 1 \\ \text{(c)} & y''(1) = 2c_2 + & 6c_3 = -4. \end{array}$$

This is solved by Cramer's rule, or by elimination, which is simple, which gives the answer:

$$y = 2x + x^2 - x^3 \blacksquare$$

Q30

Distinct Real Roots

Solve the following ODE:

$$y''' - 2y'' - y' + 2y = 0$$

A30

The characteristic equation is:

$$\lambda^3 - 2\lambda^2 - \lambda + 2 = 0$$

It has the roots:

$$\lambda_1 = -1, \quad \lambda_2 = 1, \quad \lambda_3 = 2.$$

If you find one of them by inspection, you can obtain the other two roots by solving a quadratic equation.

The corresponding general solution Eq. (??) is:

$$y = c_1e^{-x} + c_2e^x + c_3e^{2x} \blacksquare$$

**Q31****Real Double and Triple Roots**

Solve the following ODE:

$$y^v - 3y^{iv} + 3y^{iv} - y'' = 0$$

A31

The characteristic equation is:

$$\lambda^5 - 3\lambda^4 + 3\lambda^3 - \lambda^2 = 0$$

and has the roots $\lambda_1 = \lambda_2 = 0$, and $\lambda_3 = \lambda_4 = \lambda_5 = 1$, and the answer is

$$y = c_1 + c_2x + (c_3 + c_4x + c_5x^2) e^x \blacksquare$$

Q32**Simple Complex Roots**

Solve the initial value problem:

$$\begin{aligned} y''' - y'' + 100y' - 100y &= 0, \\ y(0) = 4, \quad y'(0) = 11, \quad y''(0) = -299. \end{aligned}$$

A32

The characteristic equation is:

$$\lambda^3 - \lambda^2 + 100\lambda - 100 = 0$$

It has the root 1, as can perhaps be seen by inspection. Then division by $\lambda - 1$ shows that the other roots are $\pm 10j$. Therefore, a general solution and its derivatives obtained by differentiation are:

$$\begin{aligned} y &= c_1 e^x + A \cos 10x + B \sin 10x, \\ y' &= c_1 e^x - 10A \sin 10x + 10B \cos 10x, \\ y'' &= c_1 e^x - 100A \cos 10x - 100B \sin 10x. \end{aligned}$$

From this and the initial conditions we obtain, by setting $x = 0$,

- (a) $c_1 + A = 4$,
- (b) $c_1 + 108 = 11$,
- (c) $c_1 - 1004 = -299$.

We solve this system for the unknowns A , B , and c_1 . Equation (a) minus Equation (c) gives $101A = 303$, therefore $A = 3$. Then $c_1 = 1$ from (a) and $B = 1$ from (b). The solution is:

$$y = e^x + 3 \cos 10x + \sin 10x \blacksquare$$

This gives the solution curve, which oscillates about e^x .

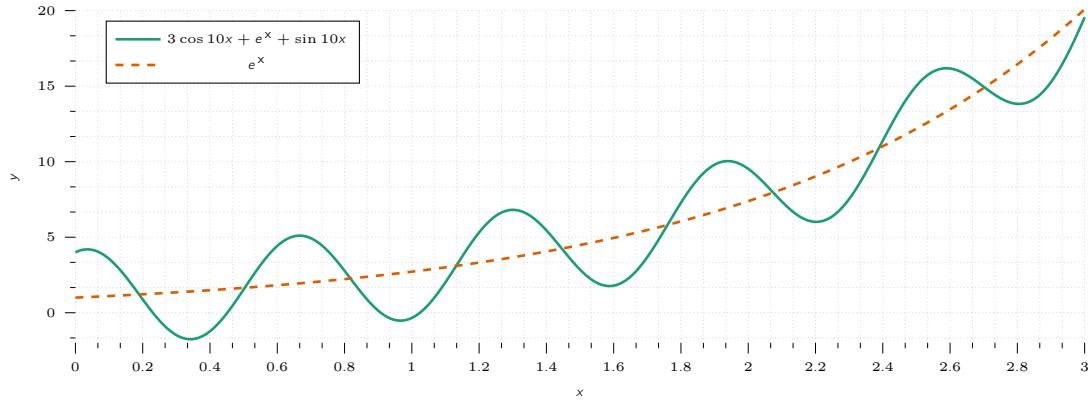


Figure 3.1: Solution to the question Simple Complex Roots

Q33**IVP: Modification Rule**

Solve the initial value problem:

$$y''' + 3y'' + 3y' + y = 30e^{-x}, \quad y(0) = 3, \quad y'(0) = -3, \quad y''(0) = -47$$

A33

Step 1 The characteristic equation is:

$$\lambda^2 + 3\lambda^2 + 3\lambda + 1 = (\lambda + 1)^3 = 0$$

It has the triple root $\lambda = -1$. Hence a general solution of the homogeneous ODE is:

$$y_h = c_1 e^{-x} + c_2 x e^{-x} + c_3 x^2 e^{-x} = (c_1 + c_2 x + c_3 x^2) e^{-x}$$

Step 2 If we try $y_p = Ce^{-x}$, we get $-C + 3C - 3C + C = 30$, which has **NO** solution. Try Cxe^{-x} and Cx^2e^{-x} . The Modification Rule calls for

$$y_p = Cx^3 e^{-x}$$

Then

$$\begin{aligned} y_p' &= C(3x^2 - x^3) e^{-x}, \\ y_p'' &= C(6x - 6x^2 + x^3) e^{-x}, \\ y_p''' &= C(6 - 18x + 9x^2 - x^3) e^{-x}. \end{aligned}$$

Substitution of these expressions into (6) and omission of the common factor e^{-x} gives

$$C(6 - 18x + 9x^2 - x^3) + 3C(6x - 6x^2 + x^3) + 3C(3x^2 - x^3) + Cx^3 = 30.$$

The linear, quadratic, and cubic terms drop out, and $6C = 30$. Hence $C = 5$, giving $y_p = 5x^3 e^{-x}$.

Step 3 We now write down $y = y_h + y_p$, the general solution of the given ODE. From it we find c_1 by the first initial condition. We insert the value, differentiate, and determine c_2 from the second



initial condition, insert the value, and finally determine c_3 from $y'(0)$ and the third initial condition:

$$\begin{aligned}y &= y_h + y_p = (c_1 + c_2 + c_3x^2)e^{-x} + 5x^3e^{-x}, \quad y(0) = c_1 = 3 \\y' &= [-3 + c_2 + (-c_2 + 2c_3)x + (15 - c_3)x^2 - 5x^3]e^{-x}, \quad y'(0) = -3 + c_2 = -3, \quad c_2 = 0 \\y'' &= [3 + 2c_3 + (30 - 4c_3)x + (-30 + c_3)x^2 + 5x^3]e^{-x}, \quad y''(0) = 3 + 2c_3 = -47, \quad c_3 = -25.\end{aligned}$$

Hence the answer to our problem is:

$$y = (3 - 25x^2)e^{-x} + 5x^3e^{-x} \blacksquare$$

The curve of y begins at $(0, 3)$ with a negative slope, as expected from the initial values, and approaches zero as $x \rightarrow \infty$.

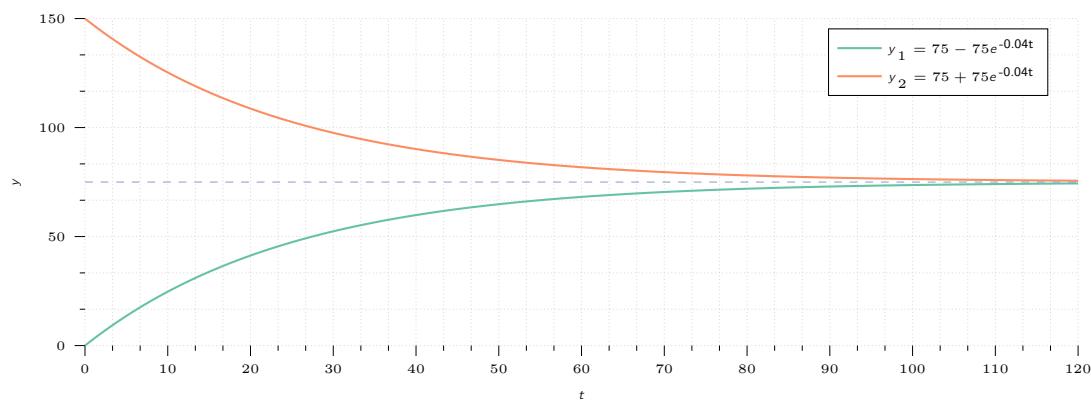
4

System of ODEs

Q34

Mixing Problem Involving Two Tanks

A34



Q35

An Electrical Network

Find the currents $I_1(t)$ and $I_2(t)$ in the network.

NOTE Assume all currents and charges zero at $t = 0$, the instant when the switch is **closed**.

A35

The solution is as follows:

Setting up the mathematical model The model of this network is obtained from Kirchhoff's Voltage Law.

Information: Kirchhoff's Voltage Law

The sum of the voltage differences around any closed loop in a circuit must be zero. A loop in a circuit is any path which ends at the same point at which it starts.

Let $I_1(t)$ and $I_2(t)$ be the currents in the left (L) and right (R) loops, respectively.



In (L), the voltage drops are:

$$\begin{aligned} L_1 I'_1 &= (1) I'_1 V && \text{Over Inductor} \\ R_1 (I_1 - I_2) &= 4 (I_1 - I_2) \text{ volt} && \text{Over Resistor} \end{aligned}$$

The difference is caused by I_1 and I_2 flowing through the resistor in **opposite** directions.

By Kirchhoff's Voltage Law the sum of these drops equals the voltage of the battery:

$$I'_1 + 4 (I_1 - I_2) = 12$$

Cleaning the aforementioned equation creates our first ODE:

$$I'_1 = -4I_1 + 4I_2 + 12. \quad (4.1)$$

In (R), the voltage drops are:

$$\begin{aligned} R_2 I_2 &= 6I_2 V && \text{Over Resistor} \\ R_1 (I_2 - I_1) &= 4 (I_2 - I_1) V && \text{Over Resistor} \\ (1/C) \int I_2 dt &= 4 \int I_2 dt V && \text{Over Capacitor} \end{aligned}$$

As there is no voltages sources in the (R) loop, the voltage sum **MUST** be zero.

$$6I_2 + 4 (I_2 - I_1) + 4 \int I_2 dt = 0 \quad \text{or} \quad 10I_2 - 4I_1 + 4 \int I_2 dt = 0.$$

Division by 10 and differentiation gives $I'_2 - 0.4I_1[t] + 0.4I_2 = 0$.

To simplify the solution process, we first get rid of $0.4I'_1$, which by Eq. (4.1) equals $0.4(-4I_1 + 4I_2 + 12)$. Substitution into the present ODE gives

$$I'_2 = 0.4I_1[t] - 0.4I_2 = 0.4(-4I_1 + 4I_2 + 12) - 0.4I_2$$

and by simplification

$$I'_2 = -1.6I_1 + 1.2I_2 + 4.8. \quad (4.2)$$

In matrix form, Eq. (4.1) and Eq. (4.2) are (we write \mathbf{J} since \mathbf{I} is the unit matrix)

$$\mathbf{J}' = \mathbf{A}\mathbf{J} + \mathbf{g}, \quad \text{where} \quad \mathbf{J} = \begin{bmatrix} I_1 \\ I_2 \end{bmatrix}, \quad \mathbf{A} = \begin{bmatrix} -4.0 & 4.0 \\ -1.6 & 1.2 \end{bmatrix}, \quad \mathbf{g} = \begin{bmatrix} 12.0 \\ 4.8 \end{bmatrix}. \quad (4.3)$$

General Solution

As we have a vector \mathbf{g} , this is a **non-homogeneous** system, and we try to proceed as for a single ODE, solving first the homogeneous system $\mathbf{J}' = \mathbf{A}\mathbf{J}$ (thus $\mathbf{J}' - \mathbf{A}\mathbf{J} = 0$) by substituting $\mathbf{J} = \mathbf{x}e^{\lambda t}$. This gives

$$\mathbf{J}' = \lambda \mathbf{x} e^{\lambda t} = \mathbf{A} \mathbf{x} e^{\lambda t} \quad \text{hence} \quad \mathbf{A} \mathbf{x} = \lambda \mathbf{x}$$



Hence, to obtain a non-trivial solution, we again need the eigenvalues and eigenvectors. For the present matrix \mathbf{A} they are:

$$\lambda_1 = -2, \quad \mathbf{x}^{(1)} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}; \quad \lambda_2 = -0.8, \quad \mathbf{x}^{(2)} = \begin{bmatrix} 1 \\ 0.8 \end{bmatrix}$$

Hence a *general solution* of the homogeneous system is:

$$\mathbf{J}_h = c_1 \mathbf{x}^{(1)} e^{-2t} + c_2 \mathbf{x}^{(2)} e^{-0.8t}.$$

For a particular solution of the nonhomogeneous system Eq. (4.3), since \mathbf{g} is constant, we try a constant column vector $\mathbf{J}_p = \mathbf{a}$ with components a_1, a_2 . Then $\mathbf{J}'_p = 0$, and substitution into Eq. (4.3) gives $\mathbf{A}\mathbf{a} + \mathbf{g} = 0$, in components,

$$-4.0a_1 + 4.0a_2 + 12.0 = 0$$

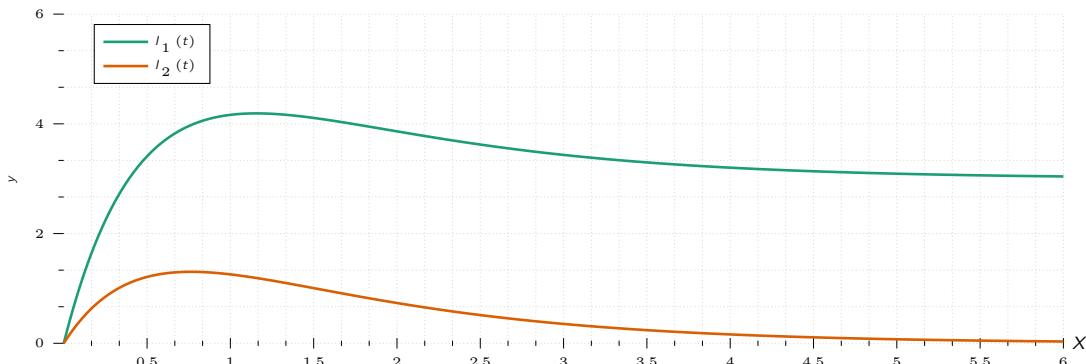
$$-1.6a_1 + 1.2a_2 + 4.8 = 0.$$

The solution is $a_1 = 3, a_2 = 0$; thus $\mathbf{a} = \begin{bmatrix} 3 \\ 0 \end{bmatrix}$. Hence

$$\mathbf{J} = \mathbf{J}_h + \mathbf{J}_p = c_1 \mathbf{x}^{(1)} e^{-2t} +$$

This is a parametric representation with time as the parameter t . It is often important to know in which sense such a curve is traced. This can be indicated by an arrow in the sense of increasing t . The I_1, I_2 -plane is called the **phase plane** of our system Eq. (4.3), and the curve in ?? is called a trajectory.

In following chapters we will see that such *phase plane representations* are far more important than graphs because they will give a much better qualitative overall impression of the general behavior of whole families of solutions, not merely of one solution as in the present case. ■



Q36

Mass on a String

To gain confidence in the conversion method, let us apply it to an old problem of ours:

modelling the free motions of a mass on a spring with value given as $m = 1$, $c = 2$, and $k = 0.75$.

$$my'' + cy' + ky = 0 \quad \text{or}$$

$$y'' = -\left(\frac{c}{m}\right)y' - \left(\frac{k}{m}\right)y.$$

**A36**

For this ODE given in the question can be written in the form of Eq. (??), making the system shown Eq. (??) as **linear** and **homogeneous**, applying to our system in question.

$$\begin{aligned}y'_1 &= y_2 \\y'_2 &= -\frac{k}{m}y_1 - \frac{c}{m}y_2.\end{aligned}$$

Setting $\mathbf{y} = \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$, we get in matrix form:

$$\mathbf{y}' = \mathbf{A}\mathbf{y} = \begin{bmatrix} 0 & 1 \\ -\frac{k}{m} & -\frac{c}{m} \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}.$$

The characteristic equation is:

$$\det(\mathbf{A} - \lambda \mathbf{I}) = \begin{vmatrix} -\lambda & 1 \\ -\frac{k}{m} & -\frac{c}{m} - \lambda \end{vmatrix} = \lambda^2 + \frac{c}{m}\lambda + \frac{k}{m} = 0$$

Entering the values of $m = 1$, $c = 2$, and $k = 0.75$, produces:

$$\lambda^2 + 2\lambda + 0.75 = (\lambda + 0.5)(\lambda + 1.5) = 0$$

This gives the eigenvalues:

$$\lambda_1 = -0.5 \quad \text{and} \quad \lambda_2 = -1.5$$

Eigenvectors follow from the first equation in $\mathbf{A} - \lambda \mathbf{I} = 0$, which is $-\lambda x_1 + x_2 = 0$. $\lambda_1 = 0.5$ produces $0.5x_1 + x_2 = 0$, which have solutions $x_1 = 2$, $x_2 = -1$. $\lambda_2 = -1.5$ produces $1.5x_1 + x_2 = 0$, which have solutions $x_1 = 1$, $x_2 = -1.5$. These eigenvectors $1.5x_1 + x_2 = 0$, say, $x_1 = 1$, $x_2 = -1.5$. These eigenvectors

$$\mathbf{x}^{(1)} = \begin{bmatrix} 2 \\ -1 \end{bmatrix}, \quad \mathbf{x}^{(2)} = \begin{bmatrix} 1 \\ -1.5 \end{bmatrix}$$

Which gives:

$$\mathbf{y} = c_1 \begin{bmatrix} 2 \\ -1 \end{bmatrix} e^{-0.5t} + c_2 \begin{bmatrix} 1 \\ -1.5 \end{bmatrix} e^{-1.5t}.$$

This vector solution has the first component

$$y = y_1 = 2c_1 e^{-0.5t} + c_2 e^{-1.5t}$$

which is the expected solution. The second component is its derivative:

$$y_2 = y'_1 = y' = -c_1 e^{-0.5t} - 1.5c_2 e^{-1.5t} \blacksquare$$

Q37**Type I: Improper Node**

Find solutions of the following system:

$$\mathbf{y}' = \mathbf{A}\mathbf{y} = \begin{bmatrix} -3 & 1 \\ 1 & -3 \end{bmatrix} \mathbf{y}, \quad \text{therefore} \quad \begin{aligned}y'_1 &= -3y_1 + y_2, \\y'_2 &= y_1 - 3y_2.\end{aligned}$$

**A37**

To see what is going on, let us find the solutions of the system. It is always a good idea to start with known solutions. Substituting $\mathbf{y} = xe^{\lambda t}$ and $\mathbf{y}' = \lambda xe^{\lambda t}$ and dropping the exponential function, as they exist both on the Left Hand Side (LHS) and RHS we can eliminate them, we get $\mathbf{A}\mathbf{x} = \lambda\mathbf{x}$. The characteristic equation is:

$$\det(\mathbf{A} - \lambda\mathbf{I}) = \begin{bmatrix} -3 - \lambda & 1 \\ 1 & -3 - \lambda \end{bmatrix} = \lambda^2 + 6\lambda + 8 = 0$$

This gives the eigenvalues $\lambda_1 = -2$ and $\lambda_2 = -4$. Eigenvectors are then obtained from:

$$(-3 - \lambda)x_1 + x_2 = 0.$$

For $\lambda_1 = -2$ this is $-x_1 + x_2 = 0$. Hence we can take $\mathbf{x}^{(1)} = [1 \quad 1]^T$. For $\lambda_2 = -4$ this becomes $x_1 + x_2 = 0$, and an eigenvector is $\mathbf{x}^{(2)} = [1 \quad -1]^T$.

This gives the general solution:

$$\mathbf{y} = \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = c_1 \mathbf{y}^{(1)} + c_2 \mathbf{y}^{(2)} = c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{-2t} + c_2 \begin{bmatrix} 1 \\ -1 \end{bmatrix} e^{-4t} \blacksquare$$

Q38**Type II: Proper Node**

A **proper node** is a critical point P_0 at which every trajectory has a definite limiting direction and for any given direction \mathbf{d} at P_0 there is a trajectory having \mathbf{d} as its limiting direction. Let's study the following system:

$$\mathbf{y}' = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \mathbf{y}, \quad \text{Therefore} \quad y'_1 = y_1 \quad \text{and} \quad y'_2 = y_2$$

A38

The equation has a proper node at the origin with the matrix being the **identity matrix**. Its characteristic equation $(1 - \lambda)^2 = 0$ has the root $\lambda = 1$.

Note: Any $\mathbf{x} \neq 0$ is an eigenvector.

and we can take $[1 \quad 0]^T$ and $[0 \quad 1]^T$.

Hence, a general solution is:

$$\mathbf{y} = c_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} e^t + c_2 \begin{bmatrix} 0 \\ 1 \end{bmatrix} e^t \quad \text{or} \quad y_1 = c_1 e^t, \quad y_2 = c_2 e^t. \quad \text{or} \quad c_1 y_2 = c_2 y_1 \blacksquare$$



Q39

Type III: Saddle Point

A **saddle point** is a critical point P_0 at which there are two (2) incoming trajectories, two outgoing trajectories, and all the other trajectories in a neighborhood of P_0 bypass P_0 . Let's study the following system:

$$\mathbf{y}' = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \mathbf{y}, \quad \text{Therefore} \quad \begin{aligned} y'_1 &= y_1 \\ y'_2 &= -y_2 \end{aligned}$$

A39

The equation has a saddle point at the **origin** and its characteristic equation

$$(1 - \lambda)(-1 - \lambda) = 0.$$

has the roots $\lambda_1 = 1$ and $\lambda_2 = -1$. For $\lambda = 1$ in eigenvector $[1 \ 0]^T$ is obtained from the second row of $(\mathbf{A} - \lambda \mathbf{I})\mathbf{x} = \mathbf{0}$, that is, $0x_1 + (-1 - 1)x_2 = 0$.

For $\lambda_2 = -1$, the first row gives $[0 \ 1]^T$. Hence a general solution is:

$$\mathbf{y} = c_1 \begin{bmatrix} 1 \\ 0 \end{bmatrix} e^t + c_2 \begin{bmatrix} 0 \\ 1 \end{bmatrix} e^{-t} \quad \text{or} \quad \begin{aligned} y_1 &= c_1 e^t \\ y_2 &= c_2 e^{-t} \end{aligned} \quad \text{or} \quad y_1 y_2 = \text{const.}$$

This is a family of **hyperbolas** ■.

Q40

Type IV: Centre Node

A **centre** is a critical point that is enclosed by infinitely many closed trajectories. Let's study the following system:

$$\mathbf{y}' = \begin{bmatrix} 0 & 1 \\ -4 & 0 \end{bmatrix} \mathbf{y}, \quad \text{Therefore} \quad \begin{aligned} y'_1 &= y_2 \\ y'_2 &= -4y_1 \end{aligned} \quad (4.5)$$

A40

The equation has a center at the origin.

The characteristic equation $\lambda^2 + 4 = 0$ gives the eigenvalues $2\mathbf{j}$ and $-2\mathbf{j}$. For $2\mathbf{j}$, an eigenvector follows from the first equation $-2\mathbf{j}x_1 + x_2 = 0$ of $(\mathbf{A} - \lambda \mathbf{I})\mathbf{x} = \mathbf{0}$, which can be, $[1 \ 2\mathbf{j}]^T$.

For $\lambda = -2\mathbf{j}$ that equation is $-(-2\mathbf{j})x_1 + x_2 = 0$ and gives, say, $[1 \ -2\mathbf{j}]^T$. Hence a complex general solution is:

$$\mathbf{y} = c_1 \begin{bmatrix} 1 \\ 2\mathbf{j} \end{bmatrix} e^{2\mathbf{j}t} + c_2 \begin{bmatrix} 1 \\ -2\mathbf{j} \end{bmatrix} e^{-2\mathbf{j}t}, \quad \text{therefore} \quad \begin{aligned} y_1 &= c_1 e^{2\mathbf{j}t} + c_2 e^{-2\mathbf{j}t}, \\ y_2 &= 2\mathbf{j} c_1 e^{2\mathbf{j}t} - 2\mathbf{j} c_2 e^{-2\mathbf{j}t}. \end{aligned} \quad (4.6)$$

A real solution is obtained from Eq. (4.6) by the Euler formula or from Eq. (4.5).

Namely, we can create a relation of $-4y_1 y_2^2$.

$$-4y_1 y'_1 = y_2 y'_2 \quad \text{By Integration} \quad 2y_1^2 + \frac{1}{2}y_2^2 = \text{const.}$$

This is a family of ellipses enclosing the center at the origin. ■



Q41

Type V: Spiral Node

A **spiral point** is a critical point P_0 about which the trajectories spiral, approaching P_0 as $t \rightarrow \infty$.

or tracing these spirals in the opposite sense, away from P_0 .

The system:

$$\mathbf{y}' = \begin{bmatrix} -1 & 1 \\ -1 & -1 \end{bmatrix} \mathbf{y}, \quad \begin{aligned} y'_1 &= -y_1 + y_2 \\ y'_2 &= -y_1 - y_2 \end{aligned} \quad (4.7)$$

A41

has a spiral point at the origin.

The characteristic equation is $\lambda^2 + 2\lambda + 2 = 0$ which gives the eigenvalues $-1 + j$ and $-1 - j$. Corresponding eigenvectors are obtained from $(-1 - \lambda)x_1 + x_2 = 0$. For $\lambda = -1 + j$ this becomes $-jx_1 + x_2 = 0$ and we can take $[1 \ j]^T$ as an eigenvector. Similarly, an eigenvector corresponding to $-1 - j$ is $[1 \ -j]^T$.

This gives the **complex** general solution:

$$\mathbf{y} = c_1 \begin{bmatrix} 1 \\ j \end{bmatrix} e^{(-1+j)t} + c_2 \begin{bmatrix} 1 \\ -j \end{bmatrix} e^{(-1-j)t}$$

The next step would be the transformation of this complex solution to a real general solution by the Euler formula. We multiply the first equation in Eq. (4.7) by y_1 , the second by y_2 and add, obtaining:

$$y_1 y'_1 + y_2 y'_2 = - (y_1^2 + y_2^2).$$

We now introduce polar coordinates r, t , where $r^2 = y_1^2 + y_2^2$. Differentiating this with respect to t gives:

$$2rr' = 2y_1 y'_1 + 2y_2 y'_2$$

Hence the previous equation can be written

$$rr' = -r^2, \quad \text{Thus,} \quad r' = -r, \quad dr/r = -dt, \quad \ln|r| = -t + c^*, \quad r = ce^{-t}.$$

For each real c this is a spiral.

Q42

Linearisation of a Free Undamped Pendulum

A pendulum consists of a body of mass m (the bob) and a rod of length L . Determine the locations and type of the critical points.

Warning Assume that the mass of the rod and an reference are negligible.



A42

Let us begin tackling the problem:

Setting Up the Mathematical Model Let θ denote the *angular displacement*, measured counterclockwise from the equilibrium position. The weight of the bob is mg , where g is the acceleration of gravity.

This causes a restoring force $mg \sin \theta$ tangent to the curve of motion (circular arc) of the bob. By Newton's 2nd law, at each instant this force is balanced by the force of acceleration $mL\theta''$, where $L\theta''$ is the **acceleration**.

Therefore, the resultant of these two forces is zero, and we obtain as the mathematical model:

$$mL\theta'' + mg \sin \theta = 0.$$

Dividing this by mL , we have:

$$\theta'' + k \sin \theta = 0 \quad \text{with} \quad \left(k = \frac{g}{L} \right). \quad (4.8)$$

When θ is very small, we can approximate $\sin \theta$ rather accurately by θ and obtain as an approximate solution $A \cos \sqrt{k}t + B \sin \sqrt{k}t$, but the *exact* solution for any θ is not an **elementary function**.

Critical Points and Linearisation To obtain a system of ODEs, we set $\theta = y_1$, $\theta' = y_2$. Then from Eq. (4.8) we obtain a nonlinear system Eq. (??) of the form:

$$\begin{aligned} y'_1 &= f_1(y_1, y_2) = y_2, \\ y'_2 &= f_2(y_2, y_1) = -k \sin y_1. \end{aligned}$$

The right sides are both zero when $y_2 = 0$ and $\sin y_1 = 0$. This gives **infinitely** many critical points $(n\pi, 0)$, where $n = 0, \pm 1, \pm 2, \dots$.

We consider $(0, 0)$. Since the Maclaurin series is

$$\sin y_1 = y_1 - \frac{1}{6}y_1^3 + \dots \approx y_1,$$

the linearized system at $(0, 0)$ is:

$$\mathbf{y}' = \mathbf{A}\mathbf{y} = \begin{bmatrix} 0 & 1 \\ -k & 0 \end{bmatrix} \mathbf{y} \quad \text{Therefore} \quad \begin{aligned} y'_1 &= y_2 \\ y'_2 &= -ky_1. \end{aligned}$$

To apply our criteria in Sec. 4.4 we calculate:

$$\begin{aligned} p &= a_{11} + a_{22} = 0, \\ q &= \det(\mathbf{A}) = k = g/L \quad (> 0), \end{aligned}$$



$$\Delta = p^2 - 4q = -4k.$$

From this and Table 4.1(c) in Sec. 4.4 we conclude that $(0, 0)$ is a **centre**, which is **always stable**. Since $\sin \theta = \sin y_1$ is periodic with period of 2π . **Warning** This means the critical points $(n\pi, 0)$,

$n = \pm 2, \pm 4, \dots$, are all centres. We now consider the critical point $(\pi, 0)$, setting:

$$\begin{aligned} y_1 &= \theta - \pi \\ y_2 &= (\theta - \pi)' \end{aligned}$$

Then in Eq. (4.8), we can apply the MacLaurin series:

$$\sin \theta = \sin(y_1 + \pi) = -\sin y_1 = -y_1 + \frac{1}{2}y_1^2 - + \dots = -y_1$$

and the linearised system at $(\pi, 0)$ is now

$$\mathbf{y}' = \mathbf{A}\mathbf{y} = \begin{bmatrix} 0 & 1 \\ k & 0 \end{bmatrix} \mathbf{y} \quad \text{Thus} \quad \begin{aligned} y'_1 &= y_2, \\ y'_2 &= ky_1. \end{aligned}$$

We see that:

$$\begin{aligned} p &= 0, \\ q &= -k \quad (< 0), \\ \Delta &= -4q = 4k. \end{aligned}$$

Hence, by Table 4.1(b), this gives a saddle point, which is always unstable.

Because of periodicity, the critical points $(n\pi, 0)$, $n = \pm 1, \pm 3, \dots$, are all **saddle points**.

Q43

Linearisation of a Damped Pendulum

To gain further experience in investigating critical points, as another practically important, let us see how the previous example changes when we add a damping term $c\theta'$, (damping proportional to the angular velocity) to equation Eq. (4.8), so that it becomes:

$$\theta'' + c\theta' + k \sin \theta = 0$$

where $k > 0$ and $c \geq 0$ (which includes our previous case of no damping, $c = 0$).

A43

First we start by setting $\theta = y_1$, $\theta' = y_2$ as before, we obtain the nonlinear system (use $\theta'' = y_2'$),

$$\begin{aligned} y'_1 &= y_2 \\ y'_2 &= -k \sin y_1 - cy_2. \end{aligned}$$



We see the critical points have the same locations as the example before, namely, $(0, 0)$, $(\pm\pi, 0)$, $(\pm 2\pi, 0)$, ... To analyse this system, we start with analysing $(0, 0)$. Linearising $\sin y_1 \approx y_1$ as in the previous example, we get the linearised system at $(0, 0)$.

$$\mathbf{y}' = \mathbf{A}\mathbf{y} = \begin{bmatrix} 0 & 1 \\ -k & -c \end{bmatrix} \mathbf{y} \quad \text{therefore} \quad \begin{aligned} y'_1 &= y_2 \\ y'_2 &= ky_1 - cy_2 \end{aligned}$$

This is identical with the system in previous example, except for the **positive** factor m (and except for the physical meaning of y_1). Hence for $c = 0$ (no damping) we have a centre, for small damping we have a spiral point, and so on.

We now consider the critical point $(\pi, 0)$. We set $\theta - \pi = y_1$, $(\theta - \pi)' = y_2$ and linearise

$$\sin \theta = \sin(y_1 + \pi) = -\sin y_1 \approx -y_1.$$

This gives the new linearized system at $(\pi, 0)$:

$$\mathbf{y}' = \mathbf{A}\mathbf{y} = \begin{bmatrix} 0 & 1 \\ k & -c \end{bmatrix} \mathbf{y}, \quad \text{therefore} \quad \begin{aligned} y'_1 &= y_2 \\ y'_2 &= ky_1 - cy_2. \end{aligned}$$

For our criteria, we calculate:

$$\begin{aligned} p &= a_{11} + a_{22} = -c \\ q &= \det \mathbf{A} = -k \\ \Delta &= p^2 - 4q = c^2 + 4k \end{aligned}$$

This gives the following results for the critical point $(\pi, 0)$.

No Damping $c > 0, p = 0, q < 0, \Delta > 0$, a saddle point, Sec. Fig. 3b.

Damping $c > 0, p < 0, q < 0, \Delta > 0$, a saddle point, Sec. Fig. 94.

As $\sin y_1$ is periodic with period of 2π , the critical points $(\pm 2\pi, 0)$, $(\pm 4\pi, 0)$, ... are of the same type as $(0, 0)$, and the critical points $(-\pi, 0), (\pm 3\pi, 0), \dots$ are of the same type as $(\pi, 0)$, so that our task is finished. ■

5

Special Functions for ODEs

Q44

Power Series Solution

Solve the following ODE:

$$y' - y = 0$$

A44

First insert:

$$y = a_0 + a_1x + a_2x^2 + a_3x^3 + \dots = \sum_{m=0}^{\infty} a_m x^m$$

and the series obtained by term-wise differentiation:

$$y' = a_1 + 2a_2x + 3a_3x^2 + 4a_4x^3 + \dots = \sum_{m=0}^{\infty} m a_m x^{m-1} \quad (5.1)$$

We put these values into the ODE:

$$(a_1 + 2a_2x + 3a_3x^2 + 4a_4x^3 + \dots) - (a_0 + a_1x + a_2x^2 + a_3x^3 + \dots) = 0$$

Then we collect like powers of x , finding:

$$(a_1 - a_0) + (2a_2 - a_1)x + (3a_3 - a_2)x^2 + \dots = 0$$

Equating the coefficient of each power of x to zero, we have

$$a_1 - a_0 = 0, \quad 2a_2 - a_1 = 0, \quad 3a_3 - a_2 = 0 \dots$$

Solving these equations, express a_1, a_2, \dots in terms of a_0 , which remains arbitrary:

$$a_1 = a_0, \quad a_2 = \frac{a_1}{2} = \frac{a_0}{2!}, \quad a_3 = \frac{a_2}{3} = \frac{a_0}{3!}, \quad \dots \quad a_n = \frac{a_{n-1}}{n} = \frac{a_0}{n!}.$$

With these values of the coefficients, the series solution becomes the familiar general solution

$$y = a_0 + a_0x + \frac{a_0}{2!}x^2 + \frac{a_0}{3!}x^3 + \dots = a_0 \left(1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots \right) = \sum_{m=0}^{\infty} \frac{x^m}{m!} = ae^x. \quad \blacksquare$$

Q45

A Special Legendre Function

Solve the following ODE:

$$(1 - x^2)y'' - 2xy' + 2y = 0$$



A45

Substitute Eq. (??), Eq. (5.1), and Eq. (??) into the ODE, $(1 - x^2)y''$ gives two (2) series: for y'' , and for $-x^2y''$. For the term $-2xy'$ use Eq. (5.1) and in $2y$ use Eq. (??). Write like powers of x vertically aligned for easy viewing. This gives:

$$\begin{aligned} y'' &= 2a_2 + 6a_3x + 12a_4x^2 + 20a_5x^3 + 30a_6x^4 + \dots \\ -xy'' &= \quad \quad \quad -2a_2x^2 - 6a_3x^3 - 12a_4x^4 - \dots \\ -2xy' &= \quad \quad \quad -2a_1x - 4a_5x^2 - 6a_9x^3 - 8a_4x^4 - \dots \\ 2y &= 2a_0 + 2a_1x - 2a_2x^2 + 2a_3x^3 + 2a_4x^4 + \dots \end{aligned}$$

Add terms of like powers of x . For each power x^0 , x , x^2 equate the sum obtained to zero. Denote these sums by 0 (constant terms), 1 (first power of x), and so on and write it down to the following table:

Sum	Power	Equation
0	x^0	$a_2 = -a_0$
1	x	$a_3 = 0$
2	x^2	$14a_4 = 4a_2, \quad a_4 = \frac{4}{12}a_2 = -\frac{1}{3}a_0$
3	x^3	$a_5 = 0 \quad \text{since} \quad a_3 = 0$
4	x^4	$30a_6 = 18a_4, \quad a_6 = \frac{18}{30}a_4 = \frac{18}{30}\left(-\frac{1}{3}\right)a_0 = -\frac{1}{5}a_0$

This gives the solution

$$y = a_1x + a_0 \left(1 - x^2 - \frac{1}{3}x^4 - \frac{1}{5}x^6 - \dots \right) \blacksquare$$

Note: a_0, a_1 remain arbitrary.

Therefore, this is a **general solution** consisting of two (2) solutions: x and

$$1 - x^2 - \frac{1}{3}x^4 - \frac{1}{5}x^6 - \dots$$

These two (2) solutions are members of families of functions called *Legendre polynomials* $P_n(x)$ and *Legendre functions* $Q_1(x)$. Here we have

$$x = P_1(x)$$

and

$$1 - x^2 - \frac{1}{3}x^4 - \frac{1}{5}x^6 - \dots = -Q_1(x)$$

Note: The minus is by convention. The index 1 is called the *order* of these functions and here the order is 1. ■

**Q46****Frobenius Method of Euler-Cauchy**

Solve the following ODE:

$$x^2 y'' + b_0 x y' + c_0 y = 0 \quad \text{where } b_0, c_0 \text{ are constant.}$$

As can be seen this equation obeys the form of Euler-Cauchy. Here we will solve the problem using the Frobenius method.

A46

Substitution of $y = x^r$ gives the auxiliary equation:

$$r(r-1) + b_0 r + c_0 = 0,$$

which is the **indicial equation**. For different roots r_1, r_2 we get a basis

$$y_1 = x^{r_1}, y_2 = x^{r_2},$$

and for a double root r we get a basis $x^r, x^r \ln x$. Accordingly, for this simple ODE, Case 3 plays no extra role.

Q47**Frobenius Method - Double Root**

Solve the ODE

$$x(x-1)y'' + (3x-1)y'' + y = 0 \quad (5.2)$$

A47

Writing Eq. (5.2) in the standard form Eq. (??):

$$\begin{aligned} y'' + \frac{b(x)}{x} y' + \frac{c(x)}{x^2} y &= 0 \\ b(x) = \frac{3x-1}{x-1} &\quad c(x) = \frac{x}{x-1} \end{aligned}$$

we see it satisfies the assumptions in **Theorem 1** (i.e., analytic as $x = 0$). By inserting Eq. (??) and its derivatives Eq. (??) into Eq. (5.2) we obtain:

$$\begin{aligned} \sum_{m=0}^{\infty} (m+r)(m+r-1)a_m x^{m+r} - \sum_{m=0}^{\infty} (m+r)(m+r-1)a_m x^{m+r-1} \\ + 3 \sum_{m=0}^{\infty} (m+r)a_m x^{m+r} - \sum_{m=0}^{\infty} (m+r)a_m x^{m+r-1} + \sum_{m=0}^{\infty} a_m x^{m+r} = 0 \end{aligned} \quad (5.3)$$

The smallest power is x^{r-1} , occurring in the 2nd and the fourth series; by equating the sum of its coefficients to zero we have

$$[-r(r-1) - r] a_0 = 0, \quad \text{therefore} \quad r^2 = 0.$$

Hence this indicial equation has the double root $r = 0$.

First Solution



Insert this value $r = 0$ into Eq. (5.3) and equate the sum of the coefficients of the power x^s to zero, obtaining:

$$s(s-1)a_s - (s+1)a_{s+1} + 3a_s - (s+1)a_{s+1} + a_s = 0$$

thus $a_{s+1} = a_s$. Hence $a_0 = a_1 = a_2 = \dots$, and by choosing $a_0 = 1$ we obtain the solution

$$y_1(x) = \sum_{m=0}^{\infty} x^m = \frac{1}{1-x} \quad (|x| < 1).$$

Second Solution

We get a 2nd independent solution y_2 by the method of reduction of order, substituting $y_2 = uy_1$ and its derivatives into the equation. This leads to (9). Sec. 2.1, which we shall use in this example, instead of stating reduction of order from scratch (as we shall do in the next example). In (9) of Sec. 2.1 we have $p = (3x-1)/(x^2-x)$, the coefficient of y' in (11) in standard form. By partial fractions,

$$-\left[p \, dx \right] = -\left[\frac{3x-1}{3(x-1)} \, dx \right] = -\left[\left(\frac{2}{x-1} + \frac{1}{x} \right) \, dx \right] = -2 \ln(x-1) - \ln x.$$

Hence becomes

$$u' = U = y_1^{-2} e^{-\int p \, dx} = \frac{(x-1)^2}{(x-1)^2 x} = \frac{1}{x}, \quad u = \ln x, \quad y_2 = w_1 = \frac{\ln x}{1-x}.$$

y_1 and y_2 are shown in Fig. 109. These functions are linearly independent and thus form a basis on the interval $0 < x < 1$ (as well as on $1 < x < \infty$).

Q48

Working with Bessel Functions

Please calculate the bessel functions of $J_0(x)$ and $J_1(x)$.

A48

For $n = 0$ we obtain from Eq. (??) the *Bessel function* of order 0:

$$J_0(x) = \sum_{m=0}^{\infty} \frac{(-1)^m x^{2m}}{2^{2m} (m!)^2} = 1 - \frac{x^2}{2^2 (1!)^2} + \frac{x^4}{2^4 (2!)^2} - \frac{x^6}{2^6 (3!)^2} + \dots \quad (5.4)$$

which looks similar to a cosine. For $n = 1$ we obtain in the *Bessel function* of order 1:

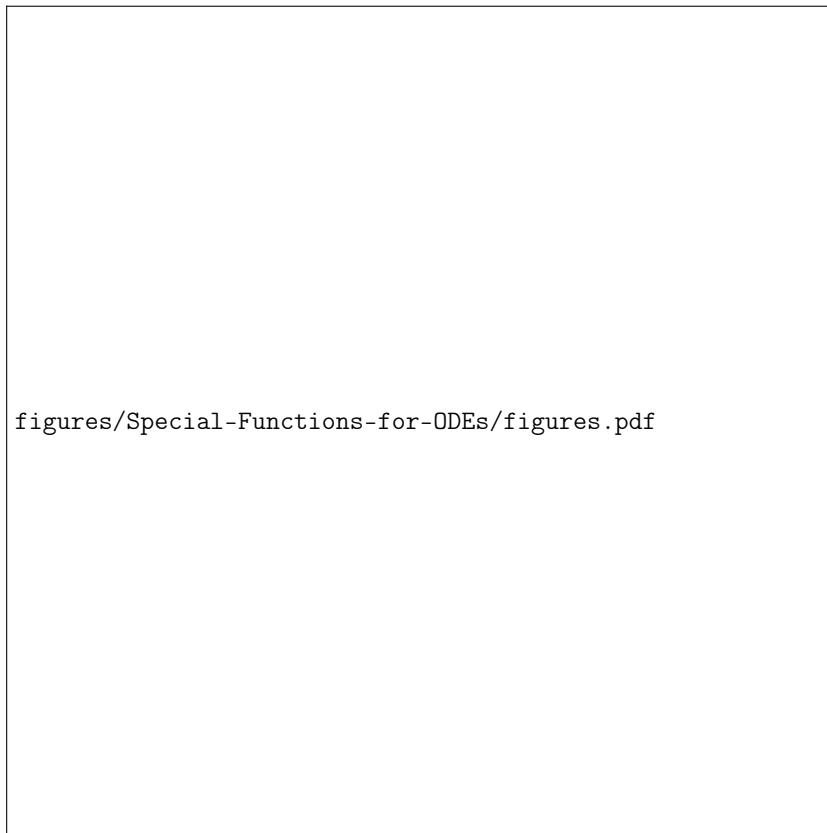
$$J_1(x) = \sum_{m=0}^{\infty} \frac{(-1)^m x^{2m+1}}{2^{2m+1} m! (m+1)!} = \frac{x}{2} - \frac{x^3}{2^3 1! 2} + \frac{x^5}{2^5 2! 3} - \frac{x^7}{2^7 3! 4} + \dots \quad (5.5)$$

which looks similar to a sine. But the zeros of these functions are not completely regularly spaced and the height of the "waves" decreases with increasing x . Heuristically, n^2/x^2 in Eq. (??) in standard form (i.e., Eq. (??) divided by x^2) is zero (if $n = 0$) or small in absolute value for large x , and so is y'/x , so that then Bessel's equation comes close to $y' + y = 0$, the equation of $\cos x$ and $\sin x$; also y'/x acts as a "damping term," in part responsible for the decrease in height. One can show that for large x ,



$$J_n(x) \sim \sqrt{\frac{2}{\pi x}} \cos\left(x - \frac{n\pi}{2} - \frac{\pi}{4}\right) \quad (5.6)$$

where \sim is read "asymptotically equal" and means that for fixed n the quotient of the two sides approaches 1 as $x \rightarrow \infty$ $\frac{x^2}{2^2(1!)^2}$.



figures/Special-Functions-for-ODEs/figures.pdf

Figure 5.1

Formula Eq. (5.6) is surprisingly accurate even for smaller $x (>0)$. For instance, it will give you good starting values in a computer program for the basic task of computing zeros. For example, for the first three zeros of f_0 , you obtain the values 2.356 (2.405 exact to 3 decimals, error 0.049), 5.498 (5.520, error 0.022), 8.639 (8.654, error 0.015), etc.

6

Laplace Transform

Q49

Introduction to Laplace Transform

Let $f(t) = 1$ when $t \geq 0$ using this information, please find $F(s)$.

A49

From Eq. (??) we obtain by integration:

$$\mathcal{L}(f) = \mathcal{L}(1) = \int_0^\infty e^{-st} dt = -\frac{1}{s}e^{-st} \Big|_0^\infty = \frac{1}{s} \quad (s > 0)$$

Such an integral is called an **improper integral** and, is evaluated according to the rule:

$$\int_0^\infty e^{-st} f(t) dt = \lim_{T \rightarrow \infty} \int_0^T e^{-st} f(t) dt.$$

Therefore our convention notation means:

$$\int_0^\infty e^{-st} dt = \lim_{T \rightarrow \infty} \left[-\frac{1}{s}e^{-st} \right]_0^T = \lim_{T \rightarrow \infty} \left[-\frac{1}{s}e^{-sT} + \frac{1}{s}e^0 \right] = \frac{1}{s}$$

where $(s > 0)$ ■

Q50

Laplace Transform of an Exponential Function

Let $f(t) = e^{at}$ when $t \geq 0$, where a is given as a constant. Using this information, please find $\mathcal{L}(f)$.

A50

From Eq. (??) we obtain by integration:

$$\mathcal{L}(e^{at}) = \int_0^\infty e^{-st} e^{at} dt = \frac{1}{a-s} e^{-(s-a)t} \Big|_0^\infty$$

Therefore, when $s - a > 0$,

$$\mathcal{L}(e^{at}) = \frac{1}{s-a} \quad ■.$$

Q51

Hyperbolic Functions

Find the transforms of the following hyperbolic functions:

$$\cosh at \quad \text{and} \quad \sinh at$$

**A51**

We know the following relations exist for the hyperbolic functions:

$$\cosh at = \frac{1}{2}(e^{at} + e^{-at}) \quad \text{and} \quad \sinh at = \frac{1}{2}(e^{at} - e^{-at})$$

Using this, we can obtain the definitions of them using the exponential function definition from an earlier example.

$$\begin{aligned}\mathcal{L}(\cosh at) &= \frac{1}{2}(\mathcal{L}(e^{at}) + \mathcal{L}(e^{-at})) = \frac{1}{2}\left(\frac{1}{s-a} + \frac{1}{s+a}\right) = \frac{s}{s^2-a^2} \\ \mathcal{L}(\sinh at) &= \frac{1}{2}(\mathcal{L}(e^{at}) - \mathcal{L}(e^{-at})) = \frac{1}{2}\left(\frac{1}{s-a} - \frac{1}{s+a}\right) = \frac{a}{s^2-a^2} \blacksquare\end{aligned}$$

Q52**Cosine and Sine**

Derive the following formulas:

$$\mathcal{L}(\cos \omega t) = \frac{s}{s^2 + \omega^2} \quad \text{and} \quad \mathcal{L}(\sin \omega t) = \frac{\omega}{s^2 + \omega^2}.$$

A52

We start by write $L_e = \mathcal{L}(\cos \omega t)$ and $L_s = \mathcal{L}(\sin \omega t)$. Integrating by parts and noting that the integral-free parts give no contribution from the upper limit ∞ , we obtain:

$$\begin{aligned}L_e &= \int_0^\infty e^{-st} \cos \omega t \, dt = \frac{e^{-st}}{-s} \cos \omega t \Big|_0^\infty - \frac{\omega}{s} \int_0^\infty e^{-st} \sin \omega t \, dt = \frac{1}{s} - \frac{\omega}{s} L_s, \\ L_s &= \int_0^\infty e^{-st} \sin \omega t \, dt = \frac{e^{-st}}{-s} \sin \omega t \Big|_0^\infty + \frac{\omega}{s} \int_0^\infty e^{-st} \cos \omega t \, dt = \frac{\omega}{s} L_c.\end{aligned}$$

By substituting L_s into the formula for L_c on the right and then by substituting L_c into the formula for L_s on the right, we obtainOf course, this is not the only method as one can just use one of the operations **twice** over the get the same result:

$$\begin{aligned}L_c &= \frac{1}{s} - \frac{\omega}{s} \left(\frac{\omega}{s} L_c \right), & L_c \left(1 + \frac{\omega^2}{s^2} \right) &= \frac{1}{s}, & L_c &= \frac{s}{s^2 + \omega^2} \blacksquare \\ L_s &= \frac{\omega}{s} \left(\frac{1}{s} - \frac{\omega}{s} L_s \right), & L_s \left(1 + \frac{\omega^2}{s^2} \right) &= \frac{\omega}{s^2}, & L_s &= \frac{\omega}{s^2 + \omega^2} \blacksquare\end{aligned}$$

Q53**Damped Vibrations**

Using the below definitions:

$$\mathcal{L}\{e^{at} \cos \omega t\} = \frac{s-a}{(s-a)^2 + \omega^2} \quad \text{and} \quad \mathcal{L}\{e^{at} \sin \omega t\} = \frac{\omega}{(s-a)^2 + \omega^2}.$$

Find the inverse of the transform:

$$\mathcal{L}(f) = \frac{3s - 137}{s^2 + 2s + 401}.$$

**A53**

Applying the inverse transform, and using its linearity, we obtain

$$f = \mathcal{L}^{-1}\left\{\frac{3(s+1) - 140}{(s+1)^2 + 400}\right\} = 3\mathcal{L}^{-1}\left\{\frac{s+1}{(s+1)^2 + 20^2}\right\} - 7\mathcal{L}^{-1}\left\{\frac{20}{(s+1)^2 + 20^2}\right\}.$$

We now see that the inverse of the right side is the damped vibration.

$$f(t) = e^{-t}(3 \cos 20t - 7 \sin 20t) \quad \blacksquare$$

Q54**Inverse Using Integrations**

Find the inverse of the following functions

$$\frac{1}{s(s^2 + \omega^2)} \quad \text{and} \quad \frac{1}{s^2(s^2 + \omega^2)}$$

A54

Using a standard Laplace Transform table we obtain the following:

$$\mathcal{L}^{-1}\left\{\frac{1}{s^2 + \omega^2}\right\} = \frac{\sin \omega t}{\omega}, \quad \mathcal{L}^{-1}\left\{\frac{1}{s(s^2 + \omega^2)}\right\} = \int_0^1 \frac{\sin \omega t}{\omega} d\tau = \frac{1}{\omega^2}(1 - \cos \omega t).$$

The second one we obtain as the following:

$$\mathcal{L}^{-1}\left\{\frac{1}{s^2(s^2 + \omega^2)}\right\} = \frac{1}{\omega^2} \int_0^t (1 - \cos \omega \tau) d\tau = \left[\frac{\tau}{\omega^2} - \frac{\sin \omega \tau}{\omega^2} \right]_0^t = \frac{t}{\omega^2} - \frac{\sin \omega t}{\omega^3}.$$

Q55**Inversion of Y**

Solve

$$y'' - y = t, \quad y(0) = 1, \quad y'(0) = 1.$$

A55

Step 1: Using a Standard Laplace Transform we get the subsidiary equation [with $Y = \mathcal{L}(y)$]

$$s^2Y - sy(0) - y'(0) - Y = 1/s^2,$$

therefore:

$$(s^2 - 1)Y = s + 1 + 1/s^2.$$

Step 2: The transfer function is $Q = 1/(s^2 - 1)$, and becomes

$$Y = (s+1)Q + \frac{1}{s^2}Q = \frac{s+1}{s^2-1} + \frac{1}{s^2(s^2-1)}.$$

Simplification of the first fraction and an expansion of the last fraction gives

$$Y = \frac{1}{s-1} + \left(\frac{1}{s^2-1} - \frac{1}{s^2} \right).$$



Step 3. From this expression for Y and Table 6.1 we obtain the solution

$$y(t) = \mathcal{L}^{-1}(Y) = \mathcal{L}^{-1}\left\{\frac{1}{s-1}\right\} + \mathcal{L}^{-1}\left\{\frac{1}{s^2-1}\right\} - \mathcal{L}^{-1}\left\{\frac{1}{s^2}\right\} = e^t + \sinh t - t \blacksquare$$

Q56**Comparison with Previous Methods**

Solve the IVP:

$$y'' + y' + 9y = 0, \quad y(0) = 0.16, \quad y'(0) = 0$$

A56

We see that the subsidiary equation is:

$$s^2Y - 0.16s + sY - 0.16 + 9Y = 0,$$

Therefore

$$(s^2 + s + 9)Y = 0.16(s + 1)$$

The solution to the algebraic equation is:

$$Y = \frac{0.16(s+1)}{s^2+s+9} = \frac{0.16(s+\frac{1}{2})+0.08}{(s+\frac{1}{2})^2+\frac{35}{4}}.$$

Therefore by the first shifting theorem and the formulas for cos and sin in from this Laplace Transform table we obtain:

$$\begin{aligned} y(t) &= \mathcal{L}^{-1}(Y) \\ &= e^{-t/2} \left(0.16 \cos \sqrt{\frac{35}{4}}t + \frac{0.08}{\frac{1}{2}\sqrt{35}} \sin \sqrt{\frac{35}{4}}t \right) \\ &= e^{-0.5t} (0.16 \cos 2.96t + 0.027 \sin 2.96t) \blacksquare \end{aligned}$$

Q57**Shifted Data**

As a note for this question, shifted data means initial value problems with initial conditions given at some $t = t_0 > 0$ instead of $t = 0$.

For such a problem, set $t = \tilde{t} + t_0$, so that $t = t_0$ gives $\tilde{t} = 0$ and the Laplace transform can be applied.

For instance, solve:

$$y'' + y = 2t, \quad y(\frac{1}{4}\pi) = \frac{1}{2}\pi, \quad y'(\frac{1}{4}\pi) = 2 - \sqrt{2}.$$

**A57**

We have $t_0 = \frac{1}{4}\pi$ and we set $t = \tilde{t} + \frac{1}{4}\pi$. Then the problem becomes:

$$\begin{aligned}\tilde{y}'' + \tilde{y} &= 2\left(\tilde{t} + \frac{1}{4}\pi\right) \\ \tilde{y}(0) &= \frac{1}{2}\pi, \quad \tilde{y}'(0) = 2 - \sqrt{2}.\end{aligned}$$

where $\tilde{y}(\tilde{t}) = y(t)$. Using a standard Laplace Transform table and denoting the transform of \tilde{y} by \tilde{Y} , we see that the subsidiary equation of the **shifted** initial value problem is:

$$s^2\tilde{Y} - s\left(\frac{1}{2}\pi\right) - (2 - \sqrt{2}) + \tilde{Y} = \frac{2}{s^2} + \frac{\left(\frac{1}{2}\pi\right)}{s}$$

Therefore:

$$(s^2 + 1)\tilde{Y} = \frac{2}{s^2} + \frac{\left(\frac{1}{2}\pi\right)}{s} + \frac{1}{2}\pi s + 2 - \sqrt{2}.$$

Solving this *algebraically* for \tilde{Y} , we obtain

$$\tilde{Y} = \frac{2}{(s^2 + 1)s^2} + \frac{\frac{1}{2}\pi}{(s^2 + 1)s} + \frac{\frac{1}{2}\pi s}{s^2 + 1} + \frac{2 - \sqrt{2}}{s^2 + 1}$$

The inverse of the first two terms can be seen from a previous example (with $\omega = 1$), and the last two terms give \cos and \sin ,

$$\begin{aligned}\tilde{y} &= \mathcal{L}^{-1}(\tilde{Y}) \\ &= 2\left(\tilde{t} - \sin \tilde{t}\right) + \frac{1}{2}\pi\left(1 - \cos \tilde{t}\right) \\ &\quad + \frac{1}{2}\pi \cos \tilde{t} + (2 - \sqrt{2}) \sin \tilde{t} \\ &= 2\tilde{t} + \frac{1}{2}\pi - \sqrt{2} \sin \tilde{t}.\end{aligned}$$

Now $\tilde{t} = t - 1/4\pi$, $\sin \tilde{t} = \frac{1}{\sqrt{2}}(\sin t - \cos t)$, so that the answer (the solution) is:

$$y = 2t - \sin t + \cos t \blacksquare$$

Q58

Use of Unit Step Function

Write the following function using unit step functions and find its transform.

$$f(t) = \begin{cases} 2 & \text{if } 0 < t < 1 \\ \frac{1}{2}t^2 & \text{if } 1 < t < \frac{1}{2}\pi \\ \cos t & \text{if } t > \frac{1}{2}\pi. \end{cases}$$

(Fig. 122)

**A58**

Step 1 In terms of unit step functions,

$$f(t) = 2(1 - u(t - 1)) + \frac{1}{2}t^2(u(t - 1) - u(t - \frac{1}{2}\pi)) + (\cos \theta u(t - \frac{1}{2}\pi)).$$

Indeed, $2(1 - u(t - 1))$ gives $f(t)$ for $0 < t < 1$, and so on.

Step 2 To apply Theorem 1, we must write each term in $f(t)$ in the form $f(t - a)u(t - a)$. Thus, $2(1 - u(t - 1))$ remains as it is and gives the transform $2(1 - e^{-s})/s$. Then

$$\begin{aligned} \mathcal{R}\left\{\frac{1}{2}t^2u(t - 1)\right\} &= \mathcal{R}\left(\frac{1}{2}(t - 1)^2 + (t - 1) + \frac{1}{2}\right)u(t - 1) \\ &= \left(\frac{1}{s^2} + \frac{1}{s^2} + \frac{1}{2s}\right)e^{-s} \\ \mathcal{L}\left\{\frac{1}{2}t^2u\left(t - \frac{1}{2}\pi\right)\right\} &= \mathcal{L}\left\{\frac{1}{2}\left(t - \frac{1}{2}\pi\right)^2 + \frac{\pi}{2}\left(t - \frac{1}{2}\pi\right) + \frac{\pi^2}{8}\right\}u\left(t - \frac{1}{2}\pi\right) \\ &= \left(\frac{1}{s^2} + \frac{\pi}{2s^2} + \frac{\pi^2}{8s}\right)e^{-\pi s/2} \\ \mathcal{L}\left\{\cos \theta u\left(t - \frac{1}{2}\pi\right)\right\} &= \mathcal{L}\left\{-\left(\sin\left(t - \frac{1}{2}\pi\right)\right)u\left(t - \frac{1}{2}\pi\right)\right\} \end{aligned}$$

Together,

$$\mathcal{L}(f) = \frac{2}{s} - \frac{2}{s}e^{-s} + \left(\frac{1}{s^2} + \frac{1}{s^2} + \frac{1}{2s}\right)e^{-s} - \left(\frac{1}{s^3} + \frac{\pi}{2s^2} + \frac{\pi^2}{8s}\right)e^{-\pi s/2} - \frac{1}{s^2 + 1}e^{-\pi s/2}.$$

If the conversion of $f(t)$ to $f(t - a)$ is inconvenient, replace it by

$$\mathcal{L}\{f(t)u(t - a)\} = e^{-at}\mathcal{L}\{f(t + a)\}.$$

Q59

Application of Both Shifting Theorems

Find the inverse transform $f(t)$ of

$$F(s) = \frac{e^{-s}}{s^2 + \pi^2} + \frac{e^{-2s}}{s^2 + \pi^2} + \frac{e^{-2s}}{(s + 2)^2}.$$

**A59**

Without the exponential functions in the numerator the three terms of $F(s)$ would have the inverses $(\sin \pi t)/\pi$, $(\sin \pi t)/\pi$, and te^{-2t} as $1/s^2$ has the inverse t , so that $1/(s+2)^2$ has the inverse te^{-2t} by the *first shifting theorem*. Therefore by the *second shifting theorem* (t -shifting),

$$\begin{aligned} f(t) &= \frac{1}{\pi} \sin(\pi(t-1)) u(t-1) \\ &\quad + \frac{1}{\pi} \sin(\pi(t-2)) u(t-2) \\ &\quad + (t-3) e^{-2(t-3)} u(t-3) \end{aligned}$$

Now $\sin(\pi t - \pi) = -\sin \pi t$ and $\sin(\pi t - 2\pi) = \sin \pi t$, so the first and second terms cancel each other when $t > 2$. Therefore we obtain:

$$\begin{aligned} f(t) &= 0 && \text{if } 0 < t < 1, \\ &= -(\sin \pi t)/\pi && \text{if } 1 < t < 2, \\ &= 0 && \text{if } 2 < t < 3, \\ &= (t-3) e^{-2(t-3)} && \text{if } t > 3 \quad \blacksquare \end{aligned}$$

Q60

Response of a RC-Circuit to a Singular Rectangular Wave

Find the current $i(t)$ in the RC -circuit if a single rectangular wave with voltage V_0 is applied. The circuit is assumed to be quiescentIn this state, it means it is in a state or period of inactivity or dormancy. before the wave is applied.

A60

The input is $V_0(u(t-a) - u(t-b))$. Therefore the circuit is modeled by the integro-differential equation

$$RI(t) + \frac{q(t)}{C} = RI(t) + \frac{1}{C} \int_0^t i(\tau) d\tau = v(t) = V_0(u(t-a) - u(t-b))$$

Using Theorem 3 in Sec. 6.2 and formula (1) in this section, we obtain the subsidiary equation

$$RI(s) + \frac{I(s)}{sC} = \frac{V_0}{s} (e^{-as} - e^{-bs})$$

Solving this equation algebraically for $I(s)$, we get:

$$I(s) = F(s) (e^{-as} - e^{-bs}) \quad \text{where} \quad F(s) = \frac{V_0/R}{s + 1/(RC)} \quad \text{and} \quad \mathcal{L}^{-1}(F) = \frac{V_0}{R} e^{-t(1/RC)}$$

Q61

Mass-Spring System Under a Square Wave

Determine the response of the damped mass-spring system under a square wave.

$$\begin{aligned} y'' + 3y' + 2y &= u(t-1) - u(t-2), \\ y(0) &= 0, \quad y'(0) = 0. \end{aligned}$$

**A61**

From (1) and (2) in Sec. 6.2 and (2) and (4) in this section we obtain the subsidiary equation

$$s^2Y + 3sY + 2Y = \frac{1}{s}(e^{-s} - e^{-2s}). \quad \text{Solution} \quad Y(s) = \frac{1}{s(s^2 + 3s + 2)}(e^{-s} - e^{-2s}).$$

We have seen that $Y(s)$ is bounded from s -direction.

Using the notation $F(s)$ and partial fractions, we obtain

$$F(s) = \frac{1}{s(s^2 + 3s + 2)} = \frac{1}{s(s+1)(s+2)} = \frac{\frac{1}{2}}{s} - \frac{1}{s+1} + \frac{\frac{1}{2}}{s+2}.$$

From Table 6.1 in Sec. 6.1, we see that the inverse is

$$f(t) = \mathcal{L}^{-1}(F) = \frac{1}{2} - e^{-t} + \frac{1}{2}e^{-2t}.$$

Q62**Convolution - I**

Let $H(s) = 1/[(s-a)s]$. Find $h(t)$.

A62

$1/(s-a)$ has the inverse $f(t) = e^{at}$, and $1/s$ has the inverse $g(t) = 1$. With $f(\tau) = e^{at}$ and $g(t-\tau) = 1$ we thus obtain from Eq. (??) the answer:

$$\begin{aligned} h(t) &= e^{at} * 1 = \int_0^t e^{a\tau} \cdot 1 d\tau \\ &= \frac{1}{a} (e^{at} - 1) \end{aligned}$$

To check the above result we can calculate:

$$\begin{aligned} H(s) &= \mathcal{L}(h)(s) = \frac{1}{a} \left(\frac{1}{s-a} - \frac{1}{s} \right) \\ &= \frac{1}{s} \cdot \frac{a}{s^2 - as} \\ &\quad \frac{1}{s-a} \cdot \frac{1}{s} \\ &= \mathcal{L}(e^{at}) \mathcal{L}(1) \quad \blacksquare \end{aligned}$$

7

Vector Calculus

Q63

Simple Vectors

Find the components of the vector \mathbf{v} with given initial point P and terminal point Q . Find $|\mathbf{v}|$ and unit vector $\hat{\mathbf{v}}$.

$$\begin{array}{lll} P(3, 2, 0), & Q(5, -2, 2), & P(1, 1, 1), \quad Q(-4, -4, -4) \\ P\{ \cdot \} 1, 0, 1.2, & Q\{ \cdot \} 0, 0, 6.2, & P(2, -2, 0), \quad Q(0, 4, 6) \\ P(4, 3, 2), & Q(-4, -3, 2), & P(0, 0, 0), \quad Q\{ \cdot \} 6, 8, 10 \end{array}$$

A63

The solution is as follows:

$$\begin{aligned} \mathbf{v} &= (5-3)\hat{x} + (-2-2)\hat{y} + (2-0)\hat{z} = (2)\hat{x} + (-4)\hat{y} + (2)\hat{z}, \\ |\mathbf{v}| &= \sqrt{(2)^2 + (-4)^2 + (2)^2} = 2\sqrt{6}. \\ \hat{\mathbf{v}} &= \frac{\mathbf{v}}{|\mathbf{v}|} = \frac{(2)\hat{x} + (-4)\hat{y} + (2)\hat{z}}{2\sqrt{6}} = \left(\frac{1}{\sqrt{6}}\right)\hat{x} + \left(-\frac{2}{\sqrt{6}}\right)\hat{y} + \left(\frac{1}{\sqrt{6}}\right)\hat{z} \quad \blacksquare \end{aligned}$$

$$\begin{aligned} \mathbf{v} &= (-4-1)\hat{x} + (-4-1)\hat{y} + (-4-1)\hat{z} = (-5)\hat{x} + (-5)\hat{y} + (-5)\hat{z}, \\ |\mathbf{v}| &= \sqrt{(-5)^2 + (-5)^2 + (-5)^2} = 5\sqrt{3}. \\ \hat{\mathbf{v}} &= \frac{\mathbf{v}}{|\mathbf{v}|} = \frac{(-5)\hat{x} + (-5)\hat{y} + (-5)\hat{z}}{5\sqrt{3}} = \left(-\frac{1}{\sqrt{3}}\right)\hat{x} + \left(-\frac{1}{\sqrt{3}}\right)\hat{y} + \left(-\frac{1}{\sqrt{3}}\right)\hat{z} \quad \blacksquare \\ \mathbf{v} &= (0-1)\hat{x} + (0-0)\hat{y} + (6.2-1.2)\hat{z} = (-1)\hat{x} + (0)\hat{y} + (5)\hat{z}, \\ |\mathbf{v}| &= \sqrt{(-1)^2 + (0)^2 + (5)^2} = \sqrt{26}. \\ \hat{\mathbf{v}} &= \frac{\mathbf{v}}{|\mathbf{v}|} = \frac{(-1)\hat{x} + (0)\hat{y} + (5)\hat{z}}{\sqrt{26}} = \left(-\frac{1}{\sqrt{26}}\right)\hat{x} + (0)\hat{y} + \left(-\frac{5}{\sqrt{26}}\right)\hat{z} \quad \blacksquare \end{aligned}$$

$$\begin{aligned} \mathbf{v} &= (0-2)\hat{x} + (4-(-2))\hat{y} + (6-0)\hat{z} = (-2)\hat{x} + (6)\hat{y} + (6)\hat{z}, \\ |\mathbf{v}| &= \sqrt{(-2)^2 + (6)^2 + (6)^2} = 2\sqrt{19}. \\ \hat{\mathbf{v}} &= \frac{\mathbf{v}}{|\mathbf{v}|} = \frac{(-2)\hat{x} + (6)\hat{y} + (6)\hat{z}}{2\sqrt{19}} = \left(-\frac{1}{\sqrt{19}}\right)\hat{x} + \left(\frac{3}{\sqrt{19}}\right)\hat{y} + \left(\frac{3}{\sqrt{19}}\right)\hat{z} \quad \blacksquare \\ \mathbf{v} &= (-4-4)\hat{x} + (-3-3)\hat{y} + (2-2)\hat{z} = (-8)\hat{x} + (-6)\hat{y} + (0)\hat{z}, \\ |\mathbf{v}| &= \sqrt{(-8)^2 + (-6)^2 + (0)^2} = 10. \\ \hat{\mathbf{v}} &= \frac{\mathbf{v}}{|\mathbf{v}|} = \frac{(-6)\hat{x} + (-8)\hat{y} + (0)\hat{z}}{10} = \left(-\frac{3}{5}\right)\hat{x} + \left(-\frac{4}{5}\right)\hat{y} + (0)\hat{z} \quad \blacksquare \end{aligned}$$



$$\mathbf{v} = (6 - 0) \hat{\mathbf{x}} + (8 - 0) \hat{\mathbf{y}} + (10 - 0) \hat{\mathbf{z}} = (6) \hat{\mathbf{x}} + (8) \hat{\mathbf{y}} + (10) \hat{\mathbf{z}},$$

$$|\mathbf{v}| = \sqrt{(6)^2 + (8)^2 + (10)^2} = 10\sqrt{2}.$$

$$\hat{\mathbf{v}} = \frac{\mathbf{v}}{|\mathbf{v}|} = \frac{(6) \hat{\mathbf{x}} + (8) \hat{\mathbf{y}} + (0) \hat{\mathbf{z}}}{10\sqrt{2}} = \left(\frac{3}{5\sqrt{2}} \right) \hat{\mathbf{x}} + \left(\frac{4}{5\sqrt{2}} \right) \hat{\mathbf{y}} + \left(\frac{1}{\sqrt{2}} \right) \hat{\mathbf{z}} \blacksquare$$

Q64**Finding the Points**

Given the components of a vector $\mathbf{v} = [v_x, v_y, v_z]$ and a particular initial point P , find the corresponding terminal point Q and the length of \mathbf{v} (i.e., $|\mathbf{v}|$).

$$\mathbf{v} = [3, -1, 0]; \quad P(4, 6, 0), \quad \mathbf{v} = [8, 4, 2]; \quad P(-8, -4, -2),$$

$$\mathbf{v} = [0.25, 2, 0.75]; \quad P(0, -0.5, 0), \quad \mathbf{v} = [3, 2, 6]; \quad P(4, 6, 0),$$

$$\mathbf{v} = [4, 2, -2]; \quad P(4, 6, 0), \quad \mathbf{v} = [3, -3, 3]; \quad P(4, 6, 0),$$

A64

Previously we have defined $\mathbf{v} = Q - P$. Here we have \mathbf{v} and P . To calculate Q we only need to add individual components of the vector with the initial point P .

$$Q = \mathbf{v} + P = (3 + 4) \hat{\mathbf{x}} + (-1 + 6) \hat{\mathbf{y}} + (0 + 0) \hat{\mathbf{z}} = (7) \hat{\mathbf{x}} + (5) \hat{\mathbf{y}} + (0) \hat{\mathbf{z}},$$

$$|\mathbf{v}| = \sqrt{(3)^2 + (-1)^2 + (0)^2} = \sqrt{10} \blacksquare$$

$$Q = \mathbf{v} + P = (8 + (-8)) \hat{\mathbf{x}} + (4 + (-4)) \hat{\mathbf{y}} + (-2 + 2) \hat{\mathbf{z}} = (0) \hat{\mathbf{x}} + (0) \hat{\mathbf{y}} + (0) \hat{\mathbf{z}},$$

$$|\mathbf{v}| = \sqrt{(8)^2 + (4)^2 + (2)^2} = 2\sqrt{21} \blacksquare$$

$$Q = \mathbf{v} + P = (0.25 + 0) \hat{\mathbf{x}} + (2 + (-0.5)) \hat{\mathbf{y}} + (0.75 + 0) \hat{\mathbf{z}} = (0.25) \hat{\mathbf{x}} + (1.5) \hat{\mathbf{y}} + (0.75) \hat{\mathbf{z}},$$

$$|\mathbf{v}| = \sqrt{(0.25)^2 + (1.5)^2 + (0.75)^2} = \sqrt{74}/4 \blacksquare$$

$$Q = \mathbf{v} + P = (3 + 4) \hat{\mathbf{x}} + (2 + 6) \hat{\mathbf{y}} + (6 + 0) \hat{\mathbf{z}} = (7) \hat{\mathbf{x}} + (8) \hat{\mathbf{y}} + (6) \hat{\mathbf{z}},$$

$$|\mathbf{v}| = \sqrt{(7)^2 + (8)^2 + (6)^2} = \sqrt{149} \blacksquare$$

$$Q = \mathbf{v} + P = (4 + 4) \hat{\mathbf{x}} + (2 + 6) \hat{\mathbf{y}} + (-2 + 0) \hat{\mathbf{z}} = (8) \hat{\mathbf{x}} + (8) \hat{\mathbf{y}} + (-2) \hat{\mathbf{z}},$$

$$|\mathbf{v}| = \sqrt{(8)^2 + (8)^2 + (-2)^2} = 2\sqrt{33} \blacksquare$$

$$Q = \mathbf{v} + P = (3 + 4) \hat{\mathbf{x}} + (-3 + 6) \hat{\mathbf{y}} + (3 + 0) \hat{\mathbf{z}} = (7) \hat{\mathbf{x}} + (3) \hat{\mathbf{y}} + (3) \hat{\mathbf{z}},$$

$$|\mathbf{v}| = \sqrt{(7)^2 + (3)^2 + (3)^2} = 2\sqrt{67} \blacksquare$$

Q65**Vector Addition**

Let $\mathbf{a} = [2, 1, 0]$, $\mathbf{b} = [-4, 2, 5]$ and $\mathbf{c} = [0, 0, 3]$. Calculate the following vector operations:

$$2\mathbf{a}, \quad -\mathbf{a}, \quad -1/2\mathbf{a},$$

$$5(\mathbf{a} - \mathbf{c}), \quad 5\mathbf{a} - 5\mathbf{c}, \quad (3\mathbf{a} - 5\mathbf{b}) + 2\mathbf{c},$$

$$3\mathbf{a} + (-5\mathbf{b} + 2\mathbf{c}), \quad \mathbf{a} + 2\mathbf{b}, \quad 2\mathbf{b} + \mathbf{a}.$$



A65

The answers are the following:

$$\begin{aligned}
 2\mathbf{a} &= (4) \hat{\mathbf{x}} + (2) \hat{\mathbf{y}} + (0) \hat{\mathbf{z}}, \\
 -\mathbf{a} &= (-2) \hat{\mathbf{x}} + (-1) \hat{\mathbf{y}} + (0) \hat{\mathbf{z}}, \\
 -1/2\mathbf{a} &= (-1) \hat{\mathbf{x}} + (-0.5) \hat{\mathbf{y}} + (0) \hat{\mathbf{z}}, \\
 5(\mathbf{a} - \mathbf{c}) &= (10) \hat{\mathbf{x}} + (5) \hat{\mathbf{y}} + (-15) \hat{\mathbf{z}}, \\
 5\mathbf{a} - 5\mathbf{c} &= (10) \hat{\mathbf{x}} + (5) \hat{\mathbf{y}} + (-15) \hat{\mathbf{z}}, \\
 (3\mathbf{a} - 5\mathbf{b}) + 2\mathbf{c} &= (26) \hat{\mathbf{x}} + (-7) \hat{\mathbf{y}} + (-19) \hat{\mathbf{z}}, \\
 3\mathbf{a} + (-5\mathbf{b} + 2\mathbf{c}) &= (26) \hat{\mathbf{x}} + (-7) \hat{\mathbf{y}} + (-19) \hat{\mathbf{z}}, \\
 \mathbf{a} + 2\mathbf{b} &= (-6) \hat{\mathbf{x}} + (5) \hat{\mathbf{y}} + (10) \hat{\mathbf{z}}, \\
 2\mathbf{a} + \mathbf{b} &= (-6) \hat{\mathbf{x}} + (5) \hat{\mathbf{y}} + (10) \hat{\mathbf{z}}.
 \end{aligned}$$

Q66

Finding the Dot Product

Find the dot product (i.e., $\mathbf{a} \cdot \mathbf{b}$) on the lengths of $\mathbf{a} = [1, 2, 0]$ and $\mathbf{b} = [3, -2, 1]$ as well as the angle (θ) between vectors.

A66

To find the angle between two vector we exploit the following identity:

$$\begin{aligned}
 \mathbf{a} \cdot \mathbf{b} &= |\mathbf{a}| |\mathbf{b}| \cos \theta, \\
 \theta &= \cos^{-1} \left(\frac{\mathbf{a} \cdot \mathbf{b}}{|\mathbf{a}| |\mathbf{b}|} \right) = \cos^{-1} \left(\frac{3 + (-4) + 0}{\sqrt{(1)^2 + (2)^2 + (0)^2} \sqrt{(3)^2 + (-2)^2 + (1)^2}} \right), \\
 &= \cos^{-1} \left(-\frac{1}{\sqrt{70}} \right) = 96.86 \text{ deg} \quad \blacksquare
 \end{aligned}$$

Q67

Finding the Vector Properties

Let $\mathbf{a} = [2, 1, 4]$, $\mathbf{b} = [-4, 0, 3]$ and $\mathbf{c} = [3, -2, 1]$. Find the following descriptions.

$$\begin{array}{ll}
 |\mathbf{a}|, |\mathbf{b}|, |\mathbf{c}|, & \mathbf{a} \cdot (\mathbf{b} + \mathbf{c}), \mathbf{a} \cdot \mathbf{b} + \mathbf{a} \cdot \mathbf{c}, \\
 \mathbf{a} \cdot \mathbf{b} + \mathbf{b} \cdot \mathbf{c} + \mathbf{c} \cdot \mathbf{a}, & 4\mathbf{a} \cdot 3\mathbf{c}, 12\mathbf{a} \cdot \mathbf{c}, \\
 |\mathbf{b} + \mathbf{c}|, |\mathbf{b}| + |\mathbf{c}|, & \mathbf{a} \cdot \mathbf{c}, |\mathbf{a}| |\mathbf{c}|.
 \end{array}$$

A67

The answers are the following:

$$\begin{aligned}
 |\mathbf{a}| &= \sqrt{21}, & |\mathbf{b}| &= 5, & |\mathbf{c}| &= \sqrt{14}. \\
 \mathbf{a} \cdot (\mathbf{b} + \mathbf{c}) &= \mathbf{a} \cdot \mathbf{b} + \mathbf{a} \cdot \mathbf{c} = 12, \\
 \mathbf{a} \cdot \mathbf{b} + \mathbf{b} \cdot \mathbf{c} + \mathbf{c} \cdot \mathbf{a} &= 3, \\
 4\mathbf{a} \cdot 3\mathbf{c} &= 12\mathbf{a} \cdot \mathbf{c} = 96,
 \end{aligned}$$



$$|\mathbf{b} + \mathbf{c}| = \sqrt{21}, \quad |\mathbf{b}| + |\mathbf{c}| = 5 + \sqrt{14}, \\ \mathbf{a} \cdot \mathbf{c} = 8, \quad |\mathbf{a}||\mathbf{c}| = 7\sqrt{6},$$

Q68 Find the Angle Between

Let $\mathbf{a} = [1, 1, 1]$, $\mathbf{b} = [2, 3, 1]$ and $\mathbf{c} = [-1, 1, 0]$. Find the angle between the following:

$$(\mathbf{a} - \mathbf{c}) \text{ and } (\mathbf{b} - \mathbf{c}), \quad (\mathbf{a}) \text{ and } (\mathbf{b} - \mathbf{c}).$$

A68

The answers are as follows:

$$33.21 \text{ deg}, \quad 22.20 \text{ deg} \quad \blacksquare$$

Q69 Calculate the Vector Product

Find the vector product $\mathbf{a} \times \mathbf{b}$ of $\mathbf{a} = [1, 1, 0]$ and $\mathbf{b} = [3, 0, 0]$.

A69

Q70 Find the Cross Product

Let $\mathbf{a} = [1, 2, 0]$, $\mathbf{b} = [3, -4, 0]$, $\mathbf{c} = [3, 5, 2]$, $\mathbf{d} = [6, 2, 0]$. Calculate the cross product of:

$$\begin{array}{ll} \mathbf{a} \times \mathbf{b}, & \mathbf{b} \times \mathbf{a}, \\ (\mathbf{c} + \mathbf{d}) \times \mathbf{d}, & \mathbf{c} \times \mathbf{d}, \\ (\mathbf{a} + \mathbf{b}) \times (\mathbf{b} + \mathbf{a}), & (\mathbf{a} \times \mathbf{b}) \times \mathbf{c}, \end{array} \quad \begin{array}{ll} \mathbf{a} \times \mathbf{c}, & |\mathbf{a} \times \mathbf{c}|, \\ \mathbf{b} \times \mathbf{c} + \mathbf{c} \times \mathbf{b}, & \mathbf{a} \cdot \mathbf{c}, \\ (\mathbf{a} \times \mathbf{b}) \times (\mathbf{b} \times \mathbf{c}), & \mathbf{a} \times (\mathbf{b} \times \mathbf{c}). \end{array}$$

A70

Q71 What is the Gradient

Find the gradient of $r = \sqrt{x^2 + y^2 + z^2}$.

A71

Q72 More of the Gradient

Find the gradient (∇f) of the following functions:

$$\begin{array}{ll} f(x, y) = x^2 + \frac{1}{9}y^2, & f(x, y) = x^4 + y^4, \\ f(x, y) = \ln(x^2 + y^2), & f(\cdot) x, y, z = x^2 + 4y^2 + 9z^2, \\ f(x, y) = \frac{y}{x^2 + y^2}, & f(x, y) = x^2y - \frac{1}{3}y^3. \end{array}$$

A72



Q73

Find the Divergence

Find the divergence ($\nabla \cdot$) to the following vector functions:

$$\begin{aligned} \mathbf{v} &= (x^3 + y^3) \hat{\mathbf{x}} + (3xy^2) \hat{\mathbf{y}} + (3zy^2) \hat{\mathbf{z}}, & \mathbf{v} &= (e^x) \hat{\mathbf{x}} + (\ln xy) \hat{\mathbf{y}} + (e^{xyz}) \hat{\mathbf{z}}, \\ \mathbf{v} &= (x^2 + y^2) \hat{\mathbf{x}} + (2xyz) \hat{\mathbf{y}} + (z^2 + x^2) \hat{\mathbf{z}}, & \mathbf{v} &= (x) \hat{\mathbf{x}} + (y) \hat{\mathbf{y}} + (z) \hat{\mathbf{z}}. \end{aligned}$$

A73

Q74

Cylindrical Divergence

Find the divergence of the function:

$$\mathbf{v} = \left(s \left(2 + \sin^2 \phi \right) \right) \hat{\mathbf{s}} + (s \sin \phi \cos \phi) \hat{\mathbf{\phi}} + (3z) \hat{\mathbf{z}}.$$

A74

Q75

Curls of Functions

Find the curl ($\nabla \times$) of the following functions.

$$\begin{aligned} \mathbf{v} &= (y) \hat{\mathbf{x}} + (2x^2) \hat{\mathbf{y}} + (0) \hat{\mathbf{z}}, & \mathbf{v} &= (y^n) \hat{\mathbf{x}} + (z^n) \hat{\mathbf{y}} + (x^n) \hat{\mathbf{z}}, \\ \mathbf{v} &= (\sin y) \hat{\mathbf{x}} + (\cos z) \hat{\mathbf{y}} + (-\tan x) \hat{\mathbf{z}}, & \mathbf{v} &= (x^2 - z) \hat{\mathbf{x}} + (xe^z) \hat{\mathbf{y}} + (xy) \hat{\mathbf{z}}. \end{aligned}$$

A75

Q76

Checking the Product Rule

Check the product rule $\nabla \cdot (\mathbf{A} \times \mathbf{B}) = \mathbf{B} \cdot (\nabla \times \mathbf{A}) - \mathbf{A} \cdot (\nabla \times \mathbf{B})$ by calculating each term separately for the functions:

$$\mathbf{A} = (x) \hat{\mathbf{x}} + (2y) \hat{\mathbf{y}} + (3z) \hat{\mathbf{z}}, \quad \mathbf{B} = (3y) \hat{\mathbf{x}} + (-2x) \hat{\mathbf{y}} + (0) \hat{\mathbf{z}}.$$

A76

Q77

Find the Laplacian

Calculate the Laplacian of the following functions:

$$\begin{aligned} T_a &= x^2 + 3xy + 3z + 4, & T_b &= \sin x \sin y \sin z, \\ T_c &= e^{-5x} \sin 4y \cos 3z, & \mathbf{v} &= (x^2) \hat{\mathbf{x}} + (3xz^2) \hat{\mathbf{y}} + (-2xz) \hat{\mathbf{z}}. \end{aligned}$$

A77



Q78

Dirac Delta Function Integrals

Evaluate the following integrals with Dirac delta functions:

$$\int_2^6 (3x^2 - 2x - 1) \delta(x - 3) dx, \quad \int_0^5 \cos x \delta(x - \pi) dx,$$

$$\int_0^3 x^3 \delta(x + 1) dx, \quad \int_{-\infty}^{+\infty} \ln(x + 3) \delta(x + 2) dx.$$

A78

Q79

Double Integrals

Find the following double integrals:

$$\int_0^1 \int_x^{2x} (x + y)^2 dy dx, \quad \int_0^1 \int_y^{\sqrt{y}} (1 - 2xy) dx dy,$$

$$\int_0^3 \int_x^3 \cosh(x + y) dy dx, \quad \int_0^1 \int_0^{y^3} \exp y^4 dx dy.$$

A79

The solution to integrations are as follows:

$$\begin{aligned} \int_0^1 \int_x^{2x} (x + y)^2 dy dx &= \int_0^1 \int_x^{2x} x^2 + 2xy + y^2 dy dx, = \int_0^1 \left[yx^2 + xy^2 + \frac{y^3}{3} \right]_x^{2x} dx, \\ &= \int_0^1 \left(4x^3 + \frac{7x^3}{3} \right) dx, = \left[4x^3 + \frac{7x^4}{12} \right]_0^1 = \frac{19}{12} \blacksquare \\ \int_0^1 \int_y^{\sqrt{y}} (1 - 2xy) dx dy &= \int_0^1 \left[x - x^2 y \right]_y^{\sqrt{y}} dy, \\ &= \int_0^1 \left[(\sqrt{y} - y^2) - (y - y^3) \right] dy = \int_0^1 [y^3 + \sqrt{y} - y^2 - y] dy, \\ &= \left[\frac{y^4}{4} + \frac{2}{3}y^{3/2} - \frac{y^3}{3} - \frac{y^2}{2} \right]_0^1, = \left(\frac{1}{4} + \frac{2}{3} - \frac{1}{3} - \frac{1}{2} \right) - (0) = \frac{1}{12} \blacksquare \\ \int_0^3 \int_x^3 \cosh(x + y) dy dx &= \int_0^1 [\sinh(x + y)]_x^3 dx = \int_0^1 [\sinh(3 + x) - \sinh(2x)] dx \end{aligned}$$

Q80

Work in a Force Field

Find the work done by the force field $\mathbf{F} = (y - x^2) \hat{x} + (z - y^2) \hat{y} + (x - z^2) \hat{z}$ along the curve $\mathbf{r}(t) = (t) \hat{x} + (t^2) \hat{y} + (t^3) \hat{z}$, $0 \leq t \leq 1$ from 0 to 1.

A80



Q81

Fluid Flow

A fluid's velocity field is $\mathbf{F} = (x) \hat{\mathbf{x}} + (z) \hat{\mathbf{y}} + (y) \hat{\mathbf{z}}$. Find the flow along the helix $\mathbf{r}(t) = (\cos t) \hat{\mathbf{x}} + (\sin t) \hat{\mathbf{y}} + (t) \hat{\mathbf{z}}$ with a range of $0 \leq t \leq \pi/2$.

A81

We first evaluate \mathbf{F} on the curve:

$$\mathbf{F} = (x) \hat{\mathbf{x}} + (z) \hat{\mathbf{y}} + (y) \hat{\mathbf{z}} = (\cos t) \hat{\mathbf{x}} + (t) \hat{\mathbf{y}} + (\sin t) \hat{\mathbf{z}} \quad \text{Substitute } x = \cos t, z = t, y = \sin t.$$

and then find $d\mathbf{r}/dt$:

$$\frac{d\mathbf{r}}{dt} = (-\sin t) \hat{\mathbf{x}} + (\cos t) \hat{\mathbf{y}} + (0) \hat{\mathbf{z}}.$$

Then we integrate $\mathbf{F} \cdot (d\mathbf{r}/dt)$ from $t = 0$ to $t = \pi/2$:

$$\begin{aligned} \mathbf{F} \cdot \frac{d\mathbf{r}}{dt} &= (\cos t)(-\sin t) + (t)(\cos t) + (\sin t)(1), \\ &= -\sin t \cos t + t \cos t + \sin t. \end{aligned}$$

Which makes,

$$\begin{aligned} \text{Flow} &= \int_{t=a}^{t=b} \mathbf{F} \cdot \frac{d\mathbf{r}}{dt} dt = \int_0^{\pi/2} (-\sin t \cos t + t \cos t + \sin t) dt, \\ &= \left[\frac{\cos^2 t}{2} + t \sin t \right]_0^{\pi/2} = \left(0 + \frac{\pi}{2} \right) - \left(\frac{1}{2} + 0 \right) = \frac{\pi}{2} - \frac{1}{2} \quad \blacksquare \end{aligned}$$

Q82

Field Circulation

Find the circulation of the field $\mathbf{F} = (x - y) \hat{\mathbf{x}} + x \hat{\mathbf{y}}$ around the circle $\mathbf{r}(t) = (\cos t) \hat{\mathbf{x}} + (\sin t) \hat{\mathbf{y}} + (0) \hat{\mathbf{z}}$ with a range of $0 \leq t \leq 2\pi$.

A82

On the circle, $\mathbf{F} = (x - y) \hat{\mathbf{x}} + (x) \hat{\mathbf{y}} + (0) \hat{\mathbf{z}} = (\cos t - \sin t) \hat{\mathbf{x}} + (\cos t) \hat{\mathbf{y}} + (0) \hat{\mathbf{z}}$ and

$$\frac{d\mathbf{r}}{dt} = (-\sin t) \hat{\mathbf{x}} + (\cos t) \hat{\mathbf{y}} + (0) \hat{\mathbf{z}}.$$

Then

$$\mathbf{F} \cdot \frac{d\mathbf{r}}{dt} = -\sin t \cos t + \underbrace{\sin^2 t + \cos^2 t}_1,$$

Gives.

$$\begin{aligned} \text{Circulation} &= \int_0^{2\pi} \mathbf{F} \cdot \frac{d\mathbf{r}}{dt} dt = \int_0^{2\pi} (1 - \sin t \cos t) dt \\ &= \left[t - \frac{\sin^2 t}{2} \right]_0^{2\pi} = 2\pi \quad \blacksquare \end{aligned}$$



Q83

Work Done by a Field

Suppose the force field $\mathbf{F} = \nabla f$ is the gradient of the function:

$$f(\cdot) x, y, z = -\frac{1}{x^2 + y^2 + z^2}.$$

Find the work done by \mathbf{F} in the moving an object along a smooth curve C joining $(1,0,0)$ to $(0,0,2)$ that does not pass through the origin.

A83

Q84

Testing Stokes's Theorem

Evaluate Stokes's theorem for the hemisphere $S : x^2 + y^2 + z^2 = 9, z \geq 0$, its bounding circle $C : x^2 + y^2 = 9, z = 0$ and the field $\mathbf{F} = (y) \hat{\mathbf{x}} + (-x) \hat{\mathbf{y}} + (0) \hat{\mathbf{z}}$. (**Tip:** Parametrisation of a circle is: $x = r \cos \theta, y = r \sin \theta$ and $da = \frac{3}{z} dA$)

A84

Q85

Evaluating Divergence Theorem

Evaluate both sides of the Divergence theorem for the expanding vector field $\mathbf{F} = (x) \hat{\mathbf{x}} + (y) \hat{\mathbf{y}} + (z) \hat{\mathbf{z}}$ over the sphere $x^2 + y^2 + z^2 = a^2$

A85

Q86

Measuring the Field Flux

Find the flux of $\mathbf{F} = (xy) \hat{\mathbf{x}} + (yz) \hat{\mathbf{y}} + (xz) \hat{\mathbf{z}}$ outward through the surface of the cube cut from the first octant by the planes $x = 1, y = 1$, and $z = 1$.

A86

Q87

A Divergence or Not

Check the divergence theorem for the function:

$$\mathbf{v} = (r^2 \cos \theta) \hat{\mathbf{r}} + (r^2 \cos \phi) \hat{\theta} + (-r^2 \cos \theta \sin \phi) \hat{\phi}.$$

using as your volume one octant of the sphere of radius R .

A87

Q88

Calculating the Integral along a Path

Compute the line integral of:

$$\mathbf{v} = (6) \hat{\mathbf{x}} + (yz^2) \hat{\mathbf{y}} + (3y + z) \hat{\mathbf{z}},$$

along the triangular path shown below. Afterwards check your answer using Stokes' theorem.



A88

Q89

An Example of Divergence Theorem

Evaluate both sides of the Divergence theorem for the expanding vector field $\mathbf{F} = (x) \hat{\mathbf{x}} + (y) \hat{\mathbf{y}} + (z) \hat{\mathbf{z}}$ over the sphere $x^2 + y^2 + z^2 = a^2$

A89

The outer unit normal to S , calculated from the gradient of $f \{ \cdot \}$ $x, y, z = x^2 + y^2 + z^2 - a^2$, is:

$$\hat{\mathbf{n}} = \frac{\nabla S}{|\nabla S|} = \frac{(2x) \hat{\mathbf{x}} + (2y) \hat{\mathbf{y}} + (2z) \hat{\mathbf{z}}}{\sqrt{4x^2 + 4y^2 + 4z^2}} = \frac{(x) \hat{\mathbf{x}} + (y) \hat{\mathbf{y}} + (z) \hat{\mathbf{z}}}{a}. \quad x^2 + y^2 + z^2 = a^2 \text{ on } S$$

Therefore:

$$(\mathbf{F} \cdot \hat{\mathbf{n}}) da = \frac{x^2 + y^2 + z^2}{a} da = \frac{a^2}{a} da = a da.$$

This in turn gives us:

$$\iint_S (\mathbf{F} \cdot \hat{\mathbf{n}}) da = \iint_S a da = a \iint_S da = a (4\pi a^2) = 4\pi a^3. \quad \text{Area of } S \text{ is } 4\pi a^2$$

The divergence of \mathbf{F} is:

$$\nabla \cdot \mathbf{F} = \frac{\partial}{\partial x} (x) + \frac{\partial}{\partial y} (y) + \frac{\partial}{\partial z} (z) = 3,$$

So,

$$\iiint_V (\nabla \cdot \mathbf{v}) d\tau = \iiint_V 3 d\tau = 3 \left(\frac{4}{3} \pi a^3 \right) = 4\pi a^3 \quad \blacksquare$$

Q90

Divergence Theorem of an Octant of a Sphere

Check the divergence theorem for the function:

$$\mathbf{v} = (r^2 \cos \theta) \hat{\mathbf{r}} + (r^2 \cos \phi) \hat{\mathbf{\theta}} + (-r^2 \cos \theta \sin \phi) \hat{\mathbf{\phi}}.$$

using as your volume one octant of the sphere of radius R .

A90

It is always useful to write the theorem we are going to work on:

$$\iiint_V (\nabla \cdot \mathbf{v}) dV = \iint_S \mathbf{v} \cdot \mathbf{n} da. \quad \begin{matrix} \text{Divergence integral} \\ \text{Outward flux} \end{matrix}$$

First solve the left hand side of the equation:

$$\begin{aligned} \nabla \cdot \mathbf{v} &= \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 r^2 \cos \theta) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta r^2 \cos \phi) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} (-r^2 \cos \theta \sin \phi), \\ &= \frac{1}{r^2} 4r^3 \cos \theta + \frac{1}{r \sin \theta} \cos \theta r^2 \cos \phi + \frac{1}{r \sin \theta} (-r^2 \cos \theta \cos \phi), \\ &= \frac{r \cos \theta}{\sin \theta} [4 \sin \theta + \cos \phi - \cos \phi] = 4r \cos \theta. \end{aligned}$$

$$\int (\nabla \cdot \mathbf{v}) d\tau = \int (4r \cos \theta) r^2 \sin \theta dr d\theta d\phi = 4 \int_0^R r^3 dr \int_0^{\pi/2} \cos \theta \sin \theta d\theta \int_0^{\pi/2} d\phi,$$



$$= \left(R^4 \right) \left(\frac{1}{2} \right) \left(\frac{\pi}{2} \right) = \frac{\pi R^4}{4} \quad \blacksquare$$

Now it is time to solve the right hand side of the question. As we are aware from the shape, an octant of the sphere has 4 sides to it: the curved surface $xyz \rightarrow \mathbf{a}_1$, and $xz \rightarrow \mathbf{a}_2$, $yz \rightarrow \mathbf{a}_3$ and $xy \rightarrow \mathbf{a}_4$. These are

$$\begin{aligned} d\mathbf{a}_1 &= \hat{\mathbf{r}} dl_\theta dl_\phi = \hat{\mathbf{r}} R^2 \sin \theta d\phi d\theta, & d\mathbf{a}_2 &= dl_r dl_\theta = -\hat{\phi} r dr d\theta, \\ d\mathbf{a}_3 &= \hat{\phi} dl_r dl_\theta = \hat{\phi} r dr d\theta, & d\mathbf{a}_4 &= dl_r dl_\phi = \hat{\theta} r dr d\theta. \quad (\theta = \pi/2) \end{aligned}$$

$$\begin{aligned} \iint_S \mathbf{v} \cdot d\mathbf{a} &= \iint_{S_1} \mathbf{v} \cdot d\mathbf{a} + \iint_{S_2} \mathbf{v} \cdot d\mathbf{a} + \iint_{S_3} \mathbf{v} \cdot d\mathbf{a} + \iint_{S_4} \mathbf{v} \cdot d\mathbf{a}, \\ &= \int_0^{\pi/2} \int_0^{\pi/2} \left[r^2 \cos \theta \hat{\mathbf{r}} + r^2 \cos \phi \hat{\theta} - r^2 \cos \theta \sin \phi \hat{\phi} \right] \Big|_{r=R} \cdot \left(\hat{\mathbf{r}} R^2 \sin \theta d\phi d\theta \right) \\ &\quad + \int_0^{\pi/2} \int_0^R \left[r^2 \cos \theta \hat{\mathbf{r}} + r^2 \cos \phi \hat{\theta} - r^2 \cos \theta \sin \phi \hat{\phi} \right] \Big|_{\phi=0} \cdot \left(-\hat{\phi} r dr d\theta \right) \\ &\quad + \int_0^{\pi/2} \int_0^R \left[r^2 \cos \theta \hat{\mathbf{r}} + r^2 \cos \phi \hat{\theta} - r^2 \cos \theta \sin \phi \hat{\phi} \right] \Big|_{\phi=\pi/2} \cdot \left(\hat{\phi} r dr d\theta \right) \\ &\quad + \int_0^{\pi/2} \int_0^R \left[r^2 \cos \theta \hat{\mathbf{r}} + r^2 \cos \phi \hat{\theta} - r^2 \cos \theta \sin \phi \hat{\phi} \right] \Big|_{\theta=\pi/2} \cdot \left(\hat{\theta} r dr d\theta \right), \end{aligned}$$

Time to do some integration.

$$\begin{aligned} \iint_S \mathbf{v} \cdot d\mathbf{a} &= \int_0^{\pi/2} \int_0^{\pi/2} \left[R^2 \cos \theta \hat{\mathbf{r}} + R^2 \cos \phi \hat{\theta} - R^2 \cos \theta \sin \phi \hat{\phi} \right] \cdot \left(\hat{\mathbf{r}} R^2 \sin \theta d\phi d\theta \right) \\ &\quad + \int_0^{\pi/2} \int_0^R \left[r^2 \cos \theta \hat{\mathbf{r}} + r^2(1) \hat{\theta} - (0) \sin \phi \hat{\phi} \right] \cdot \left(-\hat{\phi} r dr d\theta \right) \\ &\quad + \int_0^{\pi/2} \int_0^R \left[r^2 \cos \theta \hat{\mathbf{r}} + (0)\phi \hat{\theta} - r^2 \cos \theta (1) \hat{\phi} \right] \cdot \left(\hat{\phi} r dr d\theta \right) \\ &\quad + \int_0^{\pi/2} \int_0^R \left[(0) \hat{\mathbf{r}} + r^2 \cos \phi \hat{\theta} - (0) \hat{\phi} \right] \cdot \left(\hat{\theta} r dr d\theta \right). \end{aligned}$$

Final touches and cleaning up,

$$\begin{aligned} \iint_S \mathbf{v} \cdot d\mathbf{a} &= \int_0^{\pi/2} \int_0^{\pi/2} R^4 \sin \theta \cos \theta d\phi d\theta + 0 - \overbrace{\int_0^{\pi/2} \int_0^R r^3 \cos \theta dr d\theta + \int_0^{\pi/2} \int_0^R r^3 \cos \theta dr d\phi}^{=0}, \\ &= R^4 \left(\int_0^{\pi/2} d\phi \right) \left(\int_0^{\pi/2} \sin \theta \cos \theta d\theta \right), \\ &= R^4 \left(\frac{\pi}{2} \right) \left(\frac{\pi}{2} \right), \\ &= \frac{\pi R^4}{4} \quad \blacksquare \end{aligned}$$



Q91

Surface Area of an Implicit Surface

Find the area of the surface cut from the bottom of the paraboloid $x^2 + y^2 - z = 0$ by the plane $z = 4$.

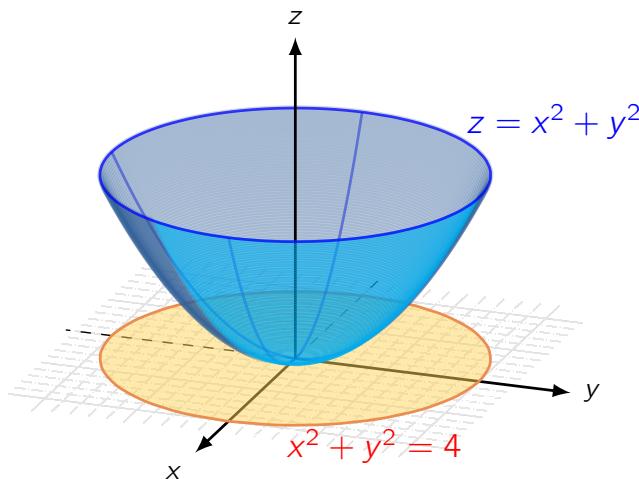


Figure 7.1: The paraboloid of "Surface Area of an Implicit Surface".

A91

We sketch the surface S and the region R below it in the xy -plane (**Fig. 7.1**). The surface S is part of the level surface $F(x, y, z) = x^2 + y^2 - z = 0$, and R is the disk $x^2 + y^2 \leq 4$ in the xy -plane. To get a unit vector normal (i.e., \hat{n}) to the plane R , we can take $\hat{n} = \hat{z}$. At any point (x, y, z) on the surface, we have:

$$\begin{aligned} F(x, y, z) &= x^2 + y^2 - z \\ \nabla F &= (2x) \hat{x} + (2y) \hat{y} + (-1) \hat{z} \\ |\nabla F| &= \sqrt{(2x)^2 + (2y)^2 + (-1)^2} \\ &= \sqrt{4x^2 + 4y^2 + 1} \\ |\nabla F \cdot \hat{n}| &= |\nabla F \cdot \hat{z}| = |-1| = 1. \end{aligned}$$

In the region R , the area is defined to be $dA = dx dy$. Therefore:

$$\begin{aligned} \text{Surface Area} &= \iint_R \frac{|\nabla F|}{|\nabla F \cdot \hat{n}|} dA \\ &= \iint_{x^2+y^2 \leq 4} \sqrt{4x^2 + 4y^2 + 1} dx dy \\ &= \int_0^{2\pi} \int_0^2 \sqrt{4r^2 + 1} r dr d\theta \\ &= \int_0^{2\pi} \frac{1}{12} (4r^2 + 1)^{3/2} \Big|_0^2 d\theta \end{aligned}$$



$$\begin{aligned}
 &= \int_0^{2\pi} \frac{1}{12} (17^{3/2} - 1) d\theta \\
 &= \frac{\pi}{6} (17\sqrt{17} - 1) \quad \blacksquare
 \end{aligned}$$

Q92

Stokes' Theorem Over a Hemisphere

Evaluate Stokes's theorem for the hemisphere $S : x^2 + y^2 + z^2 = 9, z \geq 0$, its bounding circle $C : x^2 + y^2 = 9, z = 0$ and the field $\mathbf{F} = (y) \hat{x} + (-x) \hat{y} + (0) \hat{z}$.

Tip: Parametrisation of a circle is: $x = r \cos \theta, y = r \sin \theta$ and $da = \frac{3}{2} dA$)

A92

The start by calculating the counter-clockwise circulation around C using the following parametrisation:

$$\begin{aligned}
 \mathbf{\ell}(\theta) &= (3 \cos \theta) \hat{x} + (3 \sin \theta) \hat{y} + (0) \hat{z}, \\
 \text{where } 0 &\leq \theta \leq 2\pi.
 \end{aligned}$$

Using this we can calculate the **counter-clockwise** circulation.

$$\begin{aligned}
 d\mathbf{\ell} &= (-3 \sin \theta d\theta) \hat{x} + (3 \cos \theta d\theta) \hat{y} + (0) \hat{z}, \\
 \mathbf{F} &= (y) \hat{x} + (-x) \hat{y} + (0) \hat{z} \\
 &= (3 \sin \theta) \hat{x} + (-3 \cos \theta) \hat{y} + (0) \hat{z}, \\
 \mathbf{F} \cdot d\mathbf{\ell} &= -9 \sin^2 \theta d\theta - 9 \cos^2 \theta d\theta = -9 d\theta, \\
 \oint_C \mathbf{F} \cdot d\mathbf{\ell} &= \int_0^{2\pi} -9 d\theta = -18\pi.
 \end{aligned}$$

For the curl of integral we have:

$$\begin{aligned}
 \nabla \times \mathbf{F} &= \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \partial/\partial x & \partial/\partial y & \partial/\partial z \\ F_x & F_y & F_z \end{vmatrix} \\
 &= (0 - 0) \hat{x} + (0 - 0) \hat{y} + (-1 - 1) \hat{z} = -2 \hat{z} \\
 \hat{n} &= \frac{\nabla S}{|\nabla S|} = \frac{(x) \hat{x} + (y) \hat{y} + (z) \hat{z}}{\sqrt{x^2 + y^2 + z^2}} \\
 &= \frac{(x) \hat{x} + (y) \hat{y} + (z) \hat{z}}{3} \quad \text{Unit normal}
 \end{aligned}$$

Now it is time to define the area of integration (da):

$$\begin{aligned}
 da &= \frac{|\nabla S|}{|\nabla S \cdot \hat{n}|} dA \\
 &= \frac{|(2x) \hat{x} + (2y) \hat{y} + (2z) \hat{z}|}{2z} \\
 &= \frac{2 \sqrt{x^2 + y^2 + z^2}}{2z}
 \end{aligned}$$



$$= \frac{3}{z} dA,$$

$$\nabla \times \mathbf{F} \cdot \mathbf{n} da = -\frac{2z}{3} \frac{3}{z} dA = -2 dA$$

The cardinal direction $\hat{\mathbf{z}}$ comes from being the direction **perpendicular** to the surface (S).

$$\iint_S \nabla \times \mathbf{F} \cdot \mathbf{n} da = \iint_{x^2+y^2 \leq 9} -2 dA = -18\pi$$

The circulation around the circle equals the integral of the curl over the hemisphere ■

Q93**The Volume of a Sphere**

Find the volume of a sphere of radius R .

A93

The derivation is as follows:

$$V = \int d\tau$$

$$\int_{r=0}^R \int_{\theta=0}^{\pi} \int_{\phi=0}^{2\pi} r^2 \sin \theta dr d\theta d\phi,$$

$$= \left(\int_0^R r^2 dr \right) \left(\int_0^{\pi} \sin \theta d\theta \right) \left(\int_0^{2\pi} d\phi \right)$$

$$= \left(\frac{R^3}{3} \right) (2) (2\pi) = \frac{4}{3}\pi R^3 \blacksquare$$

Q94**Finding Vector Components - I**

Find the components of the vector \mathbf{v} with given initial point P and terminal point Q . Find $|\mathbf{v}|$ and unit vector $\hat{\mathbf{v}}$.

$$\begin{array}{ll} P(3, 2, 0), & Q(5, -2, 2), \\ P(1, 0, 1.2), & Q(0, 0, 6.2), \\ P(4, 3, 2), & Q(-4, -3, 2), \end{array} \quad \begin{array}{ll} P(1, 1, 1), & Q(-4, -4, -4) \\ P(2, -2, 0), & Q(0, 4, 6) \\ P(0, 0, 0), & Q(6, 8, 10) \end{array}$$

A94

The solution is as follows:

$$\mathbf{v} = (5-3)\hat{\mathbf{x}} + (-2-2)\hat{\mathbf{y}} + (2-0)\hat{\mathbf{z}} = (2)\hat{\mathbf{x}} + (-4)\hat{\mathbf{y}} + (2)\hat{\mathbf{z}},$$

$$|\mathbf{v}| = \sqrt{(2)^2 + (-4)^2 + (2)^2} = 2\sqrt{6}.$$

$$\hat{\mathbf{v}} = \frac{\mathbf{v}}{|\mathbf{v}|} = \frac{(2)\hat{\mathbf{x}} + (-4)\hat{\mathbf{y}} + (2)\hat{\mathbf{z}}}{2\sqrt{6}} = \left(\frac{1}{\sqrt{6}}\right)\hat{\mathbf{x}} + \left(-\frac{2}{\sqrt{6}}\right)\hat{\mathbf{y}} + \left(\frac{1}{\sqrt{6}}\right)\hat{\mathbf{z}} \blacksquare$$

$$\mathbf{v} = (-4-1)\hat{\mathbf{x}} + (-4-1)\hat{\mathbf{y}} + (-4-1)\hat{\mathbf{z}} = (-5)\hat{\mathbf{x}} + (-5)\hat{\mathbf{y}} + (-5)\hat{\mathbf{z}},$$

$$|\mathbf{v}| = \sqrt{(-5)^2 + (-5)^2 + (-5)^2} = 5\sqrt{3}.$$



$$\hat{v} = \frac{\mathbf{v}}{|\mathbf{v}|} = \frac{(-5) \hat{x} + (-5) \hat{y} + (-5) \hat{z}}{5\sqrt{3}} = \left(-\frac{1}{\sqrt{3}} \right) \hat{x} + \left(-\frac{1}{\sqrt{3}} \right) \hat{y} + \left(-\frac{1}{\sqrt{3}} \right) \hat{z} \quad \blacksquare$$

$$\mathbf{v} = (0 - 1) \hat{x} + (0 - 0) \hat{y} + (6.2 - 1.2) \hat{z} = (-1) \hat{x} + (0) \hat{y} + (5) \hat{z},$$

$$|\mathbf{v}| = \sqrt{(-1)^2 + (0)^2 + (5)^2} = \sqrt{26}.$$

$$\hat{v} = \frac{\mathbf{v}}{|\mathbf{v}|} = \frac{(-1) \hat{x} + (0) \hat{y} + (5) \hat{z}}{\sqrt{26}} = \left(-\frac{1}{\sqrt{26}} \right) \hat{x} + (0) \hat{y} + \left(-\frac{5}{\sqrt{26}} \right) \hat{z} \quad \blacksquare$$

$$\mathbf{v} = (0 - 2) \hat{x} + (4 - (-2)) \hat{y} + (6 - 0) \hat{z} = (-2) \hat{x} + (6) \hat{y} + (6) \hat{z},$$

$$|\mathbf{v}| = \sqrt{(-2)^2 + (6)^2 + (6)^2} = 2\sqrt{19}.$$

$$\hat{v} = \frac{\mathbf{v}}{|\mathbf{v}|} = \frac{(-2) \hat{x} + (6) \hat{y} + (6) \hat{z}}{2\sqrt{19}} = \left(-\frac{1}{\sqrt{19}} \right) \hat{x} + \left(\frac{3}{\sqrt{19}} \right) \hat{y} + \left(\frac{3}{\sqrt{19}} \right) \hat{z} \quad \blacksquare$$

$$\mathbf{v} = (-4 - 4) \hat{x} + (-3 - 3) \hat{y} + (2 - 2) \hat{z} = (-8) \hat{x} + (-6) \hat{y} + (0) \hat{z},$$

$$|\mathbf{v}| = \sqrt{(-8)^2 + (-6)^2 + (0)^2} = 10.$$

$$\hat{v} = \frac{\mathbf{v}}{|\mathbf{v}|} = \frac{(-8) \hat{x} + (-6) \hat{y} + (0) \hat{z}}{10} = \left(-\frac{3}{5} \right) \hat{x} + \left(-\frac{4}{5} \right) \hat{y} + (0) \hat{z} \quad \blacksquare$$

$$\mathbf{v} = (6 - 0) \hat{x} + (8 - 0) \hat{y} + (10 - 0) \hat{z} = (6) \hat{x} + (8) \hat{y} + (10) \hat{z},$$

$$|\mathbf{v}| = \sqrt{(6)^2 + (8)^2 + (10)^2} = 10\sqrt{2}.$$

$$\hat{v} = \frac{\mathbf{v}}{|\mathbf{v}|} = \frac{(6) \hat{x} + (8) \hat{y} + (0) \hat{z}}{10\sqrt{2}} = \left(\frac{3}{5\sqrt{2}} \right) \hat{x} + \left(\frac{4}{5\sqrt{2}} \right) \hat{y} + \left(\frac{1}{\sqrt{2}} \right) \hat{z} \quad \blacksquare$$

Q95**Finding Vector Components - II**

Given the components of a vector $\mathbf{v} = [v_x, v_y, v_z]$ and a particular initial point P , find the corresponding terminal point Q and the length of \mathbf{v} (i.e., $|\mathbf{v}|$).

$$\begin{array}{lll} \mathbf{v} = [3, -1, 0]; & P(4, 6, 0), & \mathbf{v} = [8, 4, 2]; & P(-8, -4, -2), \\ \mathbf{v} = [0.25, 2, 0.75]; & P(\cdot, 0, -0.5, 0), & \mathbf{v} = [3, 2, 6]; & P(4, 6, 0), \\ \mathbf{v} = [4, 2, -2]; & P(4, 6, 0), & \mathbf{v} = [3, -3, 3]; & P(4, 6, 0), \end{array}$$

A95

Previously we have defined $\mathbf{v} = Q - P$. Here we have \mathbf{v} and P . To calculate Q we only need to add individual components of the vector with the initial point P .

$$\begin{aligned} Q &= \mathbf{v} + P = (3 + 4) \hat{x} + (-1 + 6) \hat{y} + (0 + 0) \hat{z} = (7) \hat{x} + (5) \hat{y} + (0) \hat{z}, \\ |\mathbf{v}| &= \sqrt{(3)^2 + (-1)^2 + (0)^2} = \sqrt{10} \quad \blacksquare \\ Q &= \mathbf{v} + P = (8 + (-8)) \hat{x} + (4 + (-4)) \hat{y} + (-2 + 2) \hat{z} = (0) \hat{x} + (0) \hat{y} + (0) \hat{z}, \\ |\mathbf{v}| &= \sqrt{(8)^2 + (4)^2 + (2)^2} = 2\sqrt{21} \quad \blacksquare \\ Q &= \mathbf{v} + P = (0.25 + 0) \hat{x} + (2 + (-0.5)) \hat{y} + (0.75 + 0) \hat{z} = (0.25) \hat{x} + (1.5) \hat{y} + (0.75) \hat{z}, \\ |\mathbf{v}| &= \sqrt{(0.25)^2 + (1.5)^2 + (0.75)^2} = \sqrt{74}/4 \quad \blacksquare \\ Q &= \mathbf{v} + P = (3 + 4) \hat{x} + (2 + 6) \hat{y} + (6 + 0) \hat{z} = (7) \hat{x} + (8) \hat{y} + (6) \hat{z}, \\ |\mathbf{v}| &= \sqrt{(7)^2 + (8)^2 + (6)^2} = \sqrt{149} \quad \blacksquare \\ Q &= \mathbf{v} + P = (4 + 4) \hat{x} + (2 + 6) \hat{y} + (-2 + 0) \hat{z} = (8) \hat{x} + (8) \hat{y} + (-2) \hat{z}, \end{aligned}$$



$$|\mathbf{v}| = \sqrt{(8)^2 + (8)^2 + (-2)^2} = 2\sqrt{33} \quad \blacksquare$$

$$\mathbf{Q} = \mathbf{v} + \mathbf{P} = (3+4) \hat{\mathbf{x}} + (-3+6) \hat{\mathbf{y}} + (3+0) \hat{\mathbf{z}} = (7) \hat{\mathbf{x}} + (3) \hat{\mathbf{y}} + (3) \hat{\mathbf{z}},$$

$$|\mathbf{v}| = \sqrt{(7)^2 + (3)^2 + (3)^2} = 2\sqrt{67} \quad \blacksquare$$

Q96**Vector Addition and Scalar Multiplication**

- Let $\mathbf{a} = [2, 1, 0]$, $\mathbf{b} = [-4, 2, 5]$ and $\mathbf{c} = [0, 0, 3]$. Calculate the following vector operations:

$2\mathbf{a}$,	$-\mathbf{a}$,	$-1/2\mathbf{a}$,
$5(\mathbf{a} - \mathbf{c})$,	$5\mathbf{a} - 5\mathbf{c}$,	$(3\mathbf{a} - 5\mathbf{b}) + 2\mathbf{c}$,
$3\mathbf{a} + (-5\mathbf{b} + 2\mathbf{c})$,	$\mathbf{a} + 2\mathbf{b}$,	$2\mathbf{b} + \mathbf{a}$.

reset

- Find the dot product (i.e., $\mathbf{a} \cdot \mathbf{b}$) on the lengths of $\mathbf{a} = [1, 2, 0]$ and $\mathbf{b} = [3, -2, 1]$ as well as the angle (θ) between vectors.

- Let $\mathbf{a} = [2, 1, 4]$, $\mathbf{b} = [-4, 0, 3]$ and $\mathbf{c} = [3, -2, 1]$. Find the following descriptions.

$ \mathbf{a} , \mathbf{b} , \mathbf{c} ,$	$\mathbf{a} \cdot (\mathbf{b} + \mathbf{c}), \mathbf{a} \cdot \mathbf{b} + \mathbf{a} \cdot \mathbf{c},$
$\mathbf{a} \cdot \mathbf{b} + \mathbf{b} \cdot \mathbf{c} + \mathbf{c} \cdot \mathbf{a},$	$4\mathbf{a} \cdot 3\mathbf{c}, 12\mathbf{a} \cdot \mathbf{c},$
$ \mathbf{b} + \mathbf{c} , \mathbf{b} + \mathbf{c} ,$	$\mathbf{a} \cdot \mathbf{c}, \mathbf{a} \mathbf{c} .$

reset

- Let $\mathbf{a} = [1, 1, 1]$, $\mathbf{b} = [2, 3, 1]$ and $\mathbf{c} = [-1, 1, 0]$. Find the angle between the following:

$$(\mathbf{a} - \mathbf{c}) \text{ and } (\mathbf{b} - \mathbf{c}), \quad (\mathbf{a}) \text{ and } (\mathbf{b} - \mathbf{c}).$$

- Find the vector product $\mathbf{a} \times \mathbf{b}$ of $\mathbf{a} = [1, 1, 0]$ and $\mathbf{b} = [3, 0, 0]$.

- Let $\mathbf{a} = [1, 2, 0]$, $\mathbf{b} = [3, -4, 0]$, $\mathbf{c} = [3, 5, 2]$, $\mathbf{d} = [6, 2, 0]$. Calculate the cross product of:

$\mathbf{a} \times \mathbf{b}, \mathbf{b} \times \mathbf{a},$	$\mathbf{a} \times \mathbf{c}, \mathbf{a} \times \mathbf{c} , \mathbf{a} \cdot \mathbf{c},$
$(\mathbf{c} + \mathbf{d}) \times \mathbf{d}, \mathbf{c} \times \mathbf{d},$	$\mathbf{b} \times \mathbf{c} + \mathbf{c} \times \mathbf{b},$
$(\mathbf{a} + \mathbf{b}) \times (\mathbf{b} + \mathbf{a}),$	$(\mathbf{a} \times \mathbf{b}) \times \mathbf{c}, \mathbf{a} \times (\mathbf{b} \times \mathbf{c}).$

A96**An Example of a Curl**

Find the curl ($\nabla \times$) of the following functions.

$$\mathbf{v} = (y) \hat{\mathbf{x}} + (2x^2) \hat{\mathbf{y}} + (0) \hat{\mathbf{z}}, \quad \mathbf{v} = (y^n) \hat{\mathbf{x}} + (z^n) \hat{\mathbf{y}} + (x^n) \hat{\mathbf{z}},$$

$$\mathbf{v} = (\sin y) \hat{\mathbf{x}} + (\cos z) \hat{\mathbf{y}} + (-\tan x) \hat{\mathbf{z}}, \quad \mathbf{v} = (x^2 - z) \hat{\mathbf{x}} + (xe^z) \hat{\mathbf{y}} + (xy) \hat{\mathbf{z}}.$$

**A97**

The curl ($\nabla \times$) of the functions are as follows:

$$\begin{aligned} f(x, y, z) &= (y) \hat{x} + (2x^2) \hat{y} + (0) \hat{z}, \\ \nabla \times f &= (0) \hat{x} + (0) \hat{y} + (-1 + 4x) \hat{z}. \\ f(x, y, z) &= (y^n) \hat{x} + (z^n) \hat{y} + (x^n) \hat{z}, \\ \nabla \times f &= (-nz^{n-1}) \hat{x} + (-nx^{n-1}) \hat{y} + (-ny^{n-1}) \hat{z}. \\ f(x, y, z) &= (\sin y) \hat{x} + (\cos z) \hat{y} + (-\tan x) \hat{z}, \\ \nabla \times f &= (\sin z) \hat{x} + (\sec^2 x) \hat{y} + (-\cos y) \hat{z}. \\ f(x, y, z) &= (x^2 - z) \hat{x} + (xe^z) \hat{y} + (xy) \hat{z}, \\ \nabla \times f &= (x - e^z x) \hat{x} + (-1 - y) \hat{y} + (e^z) \hat{z}. \end{aligned}$$

Q98

The Laplacian of a Vector

Calculate the Laplacian of the following functions:

$$\begin{aligned} (i) \quad T_a &= x_2 + 3xy + 3z + 4, & (ii) \quad T_b &= \sin x \sin y \sin z, \\ (iii) \quad T_c &= e^{-5x} \sin 4y \cos 3z, & (iv) \quad \mathbf{v} &= (x^2) \hat{x} + (3xz^2) \hat{y} + (-2xz) \hat{z}. \end{aligned}$$

A98

The solution to the Laplacian of the functions are as follows:

$$\begin{aligned} (i) \quad \frac{\partial^2 T_a}{\partial x^2} &= 2; \quad \frac{\partial^2 T_a}{\partial y^2} = 0; \quad \frac{\partial^2 T_a}{\partial z^2} = 0 \quad \rightarrow \quad \nabla^2 T_a = 2 \quad \blacksquare \\ (ii) \quad \frac{\partial^2 T_b}{\partial x^2} &= \frac{\partial^2 T_b}{\partial y^2} = \frac{\partial^2 T_b}{\partial z^2} = -3T_b \quad \rightarrow \quad \nabla^2 T_b = -3T_b = 3 \sin x \sin y \sin z \quad \blacksquare \\ (iii) \quad \frac{\partial^2 T_c}{\partial x^2} &= 25T_c; \\ \frac{\partial^2 T_c}{\partial y^2} &= -16T_c; \quad \frac{\partial^2 T_c}{\partial z^2} = -9T_c \quad \rightarrow \quad \nabla^2 T_c = 0 \quad \blacksquare \\ (iv) \quad \frac{\partial^2 v_x}{\partial x^2} &= 2; \quad \frac{\partial^2 v_x}{\partial y^2} = 0; \quad \frac{\partial^2 v_x}{\partial z^2} = 0 \quad \rightarrow \quad \nabla^2 v_x = 0, \\ \frac{\partial^2 v_y}{\partial x^2} &= 0; \quad \frac{\partial^2 v_y}{\partial y^2} = 0; \quad \frac{\partial^2 v_y}{\partial z^2} = 6 \quad \rightarrow \quad \nabla^2 v_y = 6x, \\ \frac{\partial^2 v_z}{\partial x^2} &= 0; \quad \frac{\partial^2 v_z}{\partial y^2} = 0; \quad \frac{\partial^2 v_z}{\partial z^2} = 0 \quad \rightarrow \quad \nabla^2 v_z = 0, \\ \nabla^2 \mathbf{v} &= 2 \hat{x} + 6x \hat{y} \quad \blacksquare \end{aligned}$$

Q99

A Simple Dirac Integral

Evaluate the following integral:

$$\int_0^3 x^3 \delta(x - 2) \, dx$$

A99

The delta function picks out the value of x^3 at the point $x = 2$, so the integral is $2^3 = 8$. Notice, however, that if the upper limit had been 1 (instead of 3), the answer would be 0, because the spike would then be outside the domain of integration.

Q100

1D Dirac Delta Function

Evaluate the following integrals with Dirac delta functions:

$$\int_2^6 (3x^2 - 2x - 1) \delta(x - 3) dx, \quad (\text{i})$$

$$\int_0^5 \cos x \delta(x - \pi) dx, \quad (\text{ii})$$

$$\int_0^3 x^3 \delta(x + 1) dx, \quad (\text{iii})$$

$$\int_{-\infty}^{+\infty} \ln(x + 3) \delta(x + 2) dx. \quad (\text{iv})$$

A100

The solution are as follows:

(a) $3(3^2) - 2(3) - 1 = 27 - 6 - 1 = 20 \blacksquare$

(b) $\cos \pi = -1 \blacksquare$

(c) 0 \blacksquare

(d) $\ln(-2 + 3) = \ln 1 = 0 \blacksquare$

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