

Members:

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Background

- LCD display names
- Joystick control LEDs
- Morse code display with LEDs
- Date and time display
- What we Learned :
 - ✓ Interrupts trigger functions
 - ✓ default Pull-Down

Background

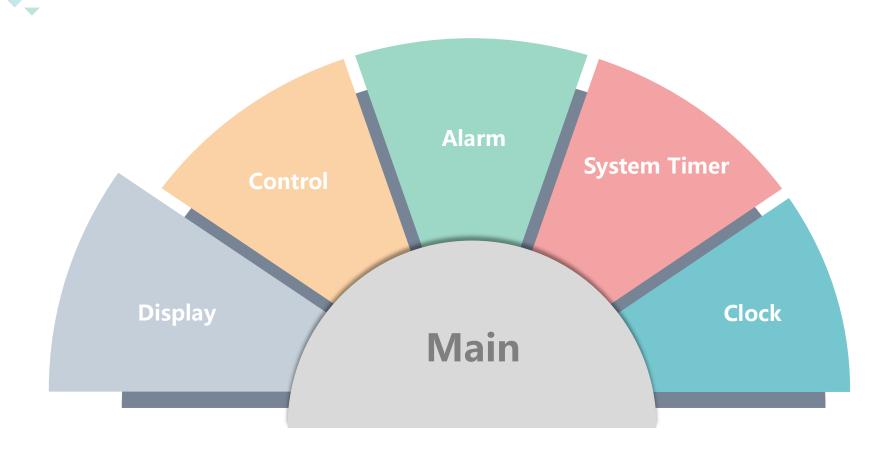
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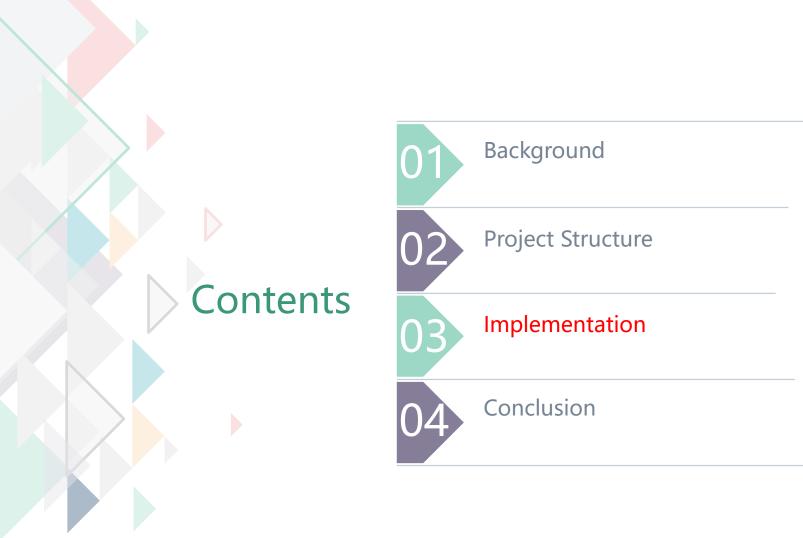
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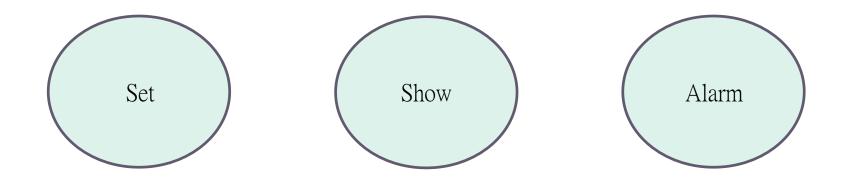


Project Structure





- Design interrupt settings for each button
- Determine current condition with "State"



```
for(i = 0; i < 4; ++i) {</pre>
   GPIOE->ODR |= 1 << LED PIN;
   delay_ms(1000);
   GPIOE->ODR &= \sim(1 << LED PIN);
   delay ms(1000);
delay ms(2000);
for(i = 0; i < 3; ++i) {
   GPIOE->ODR |= 1 << LED PIN;
   delay ms(3000);
   GPIOE->ODR &= \sim(1 << LED_PIN);
   delay ms(1000);
delay ms(2000);
```

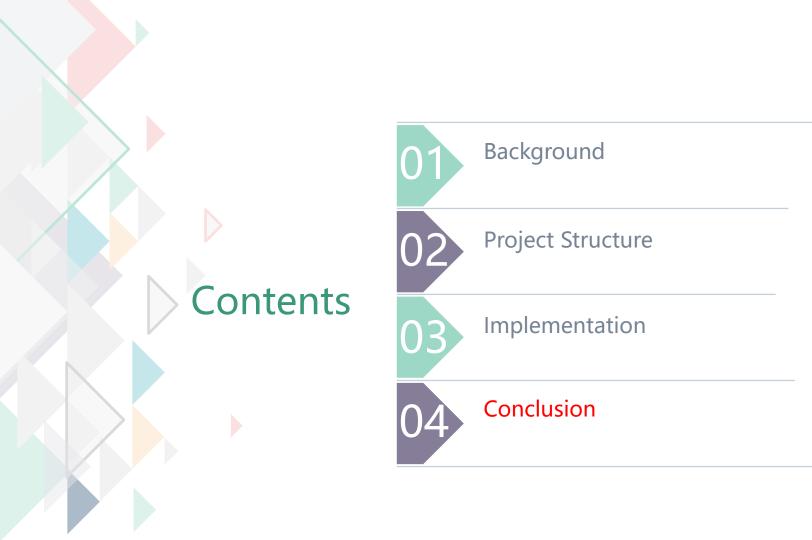
```
void delay_ms(unsigned int t) {
  unsigned int i, j;
  for (i = 0; i < t; i++) {
      for (j = 0; j < 2000; j++);
```

```
void delay s(unsigned int t) {
  uint32 t hour, minute, second;
     RTC_Read_Time(&hour, &minute, &second);
     second += t;
     if(second > 59) {
         second -= 60;
        ++minute;
      if(minute > 59) {
        minute -= 60:
        ++hour;
      if(hour > 23)
        hour -= 23;
     set alarm(hour, minute, second);
```

```
static int digit = 0;
int delay[] = {
   1, 1, 1, 1, 1, 1, 1, 3, 3, 1,
   3, 1, 3, 3, 3, 1, 1, 1, 1, 3,
   3, 1, 1, 1, 1, 3, 1, 1, 1, 3,
3;
void display Hobbit(void) {
   if(!digit)
      Red LED Toggle();
   Green LED Toggle();
   if(digit < (sizeof(delay) / sizeof(delay[0])))</pre>
      delay s(delay[digit++]);
   else {
      digit = 0:
      Red LED Toggle();
```

```
void delay_ms(unsigned int t) {
  unsigned int i, j;
  for (i = 0; i < t; i++) {
     for (j = 0; j < 2000; j++);
```

```
void delay s(unsigned int t) {
   uint32 t hour, minute, second;
      RTC_Read_Time(&hour, &minute, &second);
      second += t;
      if(second > 59) {
         second -= 60:
         ++minute;
      if(minute > 59) {
         minute -= 60;
         ++hour;
      if(hour > 23)
         hour -= 23;
      set_alarm(hour, minute, second);
```



Conclusion

- Always forgive basic knowledge
- Shift is important in CA
- Team member cooperation is essential of project completing
- Others:
 - University of PITT has exquisite buildings
 - Easy to understand what Dr. Jingtong teaches

