#### CLUSTERING

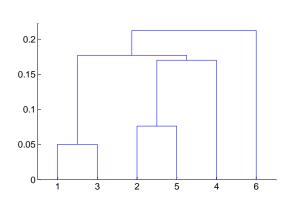
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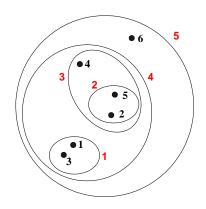
## Hierarchical Clustering

- Two main types:
  - Agglomerative
    - Start with the points as individual clusters
    - Merge clusters until only one is left
  - Divisive
    - Start with all the points as one cluster
    - Split clusters until only singleton clusters remain
  - Agglomerative is more popular
- Traditional hierarchical algorithms use a similarity or distance matrix.
  - Merge or split one cluster at a time

### Hierarchical Clustering

- Produces a set of nested clusters organized as a hierarchical tree.
- Can be visualized as a dendrogram
  - Tree like diagram
  - Records the sequences of merges or splits





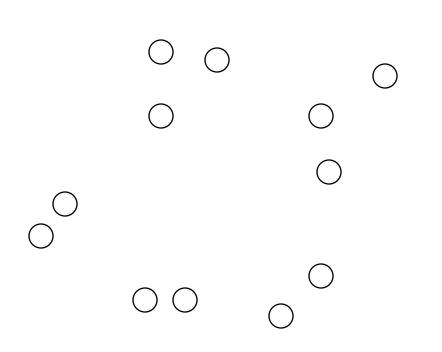
Can 'cut' the dendrogram to get a partitional clustering

## Basic Agglomerative Clustering Algorithm

- Algorithm is straightforward
  - Compute the proximity matrix, if necessary
  - Let each data point be a cluster
  - Repeat
    - Merge the two closest clusters
    - Update the proximity matrix
  - Until only a single cluster remains
- Key operation is the computation of the proximity of two clusters.
- Different approaches to defining the distance between clusters distinguishes the different algorithms.

#### Agglomerative Hierarchical Clustering:

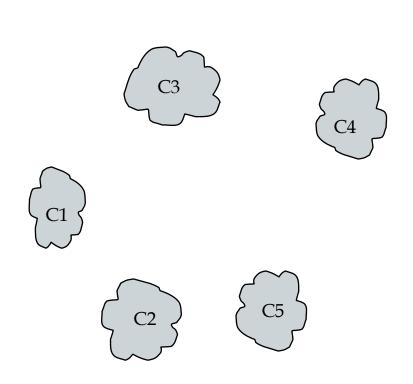
 For agglomerative hierarchical clustering we start with clusters of individual points and a proximity matrix.



	p1	p2	р3	p4	p5	<u> </u>
p1						
<u>p2</u>						
<u>p2</u> <u>p3</u>						
<u>p4</u>						
<u>p4</u> <u>p5</u>						

#### Agglomerative Hierarchical Clustering: Intermediate Situation

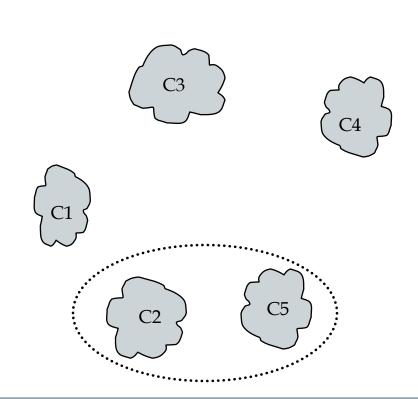
After some merging steps, we have some clusters.

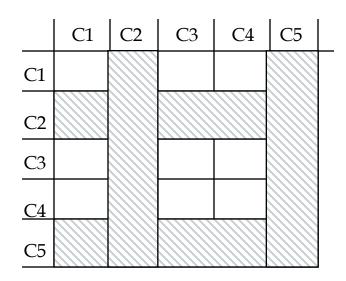


	C1	C2	C3	C4	C5
C1					
C2					
C3					
<u>C4</u>					
C5					

# Agglomerative Hierarchical Clustering: Intermediate Situation

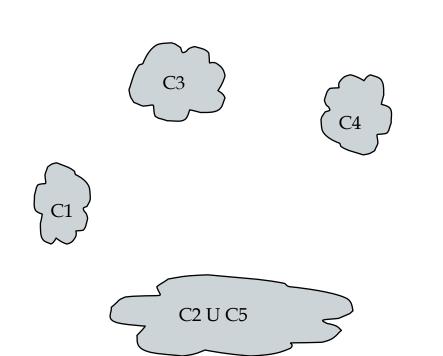
 We want to merge the two closest clusters (C2 and C5) and update the proximity matrix.

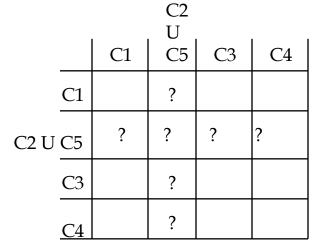


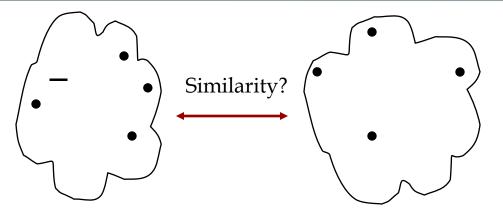


## Agglomerative Hierarchical Clustering: After Merging

The question is "How do we update the proximity matrix?"







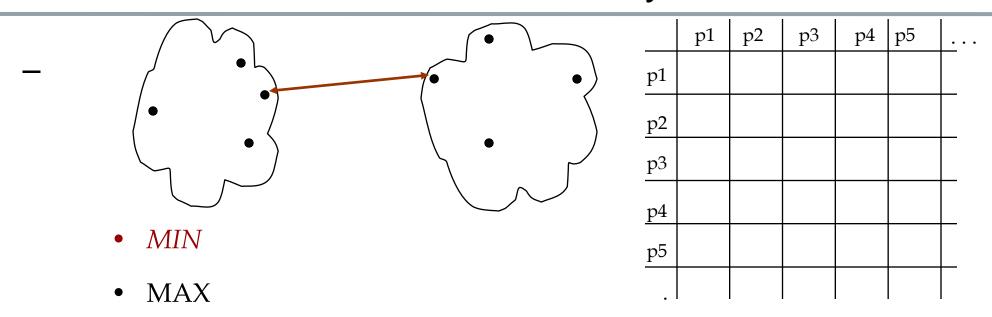
 p1
 p2
 p3
 p4
 p5
 . .

 p1
 p2
 p3
 p4
 p5
 . .

 p3
 p4
 p5
 . .
 p5
 . .

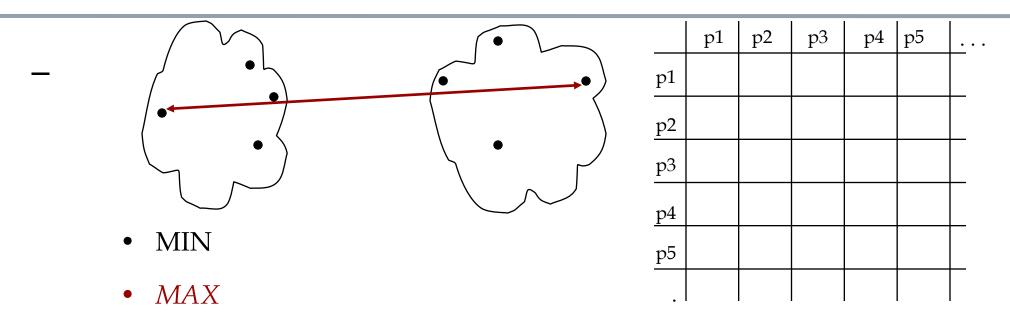
- MIN
- MAX
- Group Average
- Distance Between Centroids

- Other methods driven by an objective function
  - Ward's Method uses squared error



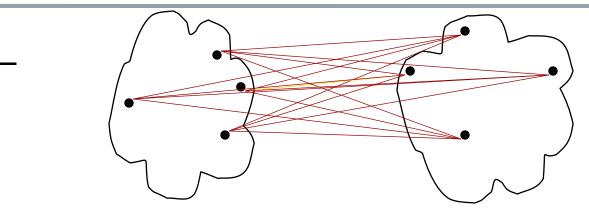
- Group Average
- Distance Between Centroids

- Proximity Matrix
- Other methods driven by an objective function
  - Ward's Method uses squared error



- Group Average
- Distance Between Centroids

- Proximity Matrix
- Other methods driven by an objective function
  - Ward's Method uses squared error



	p1	p2	р3	p4	p5	<u> </u>
p1						
<u>p2</u>						
p3						
p4						_
<u>p4</u> <u>p5</u>						

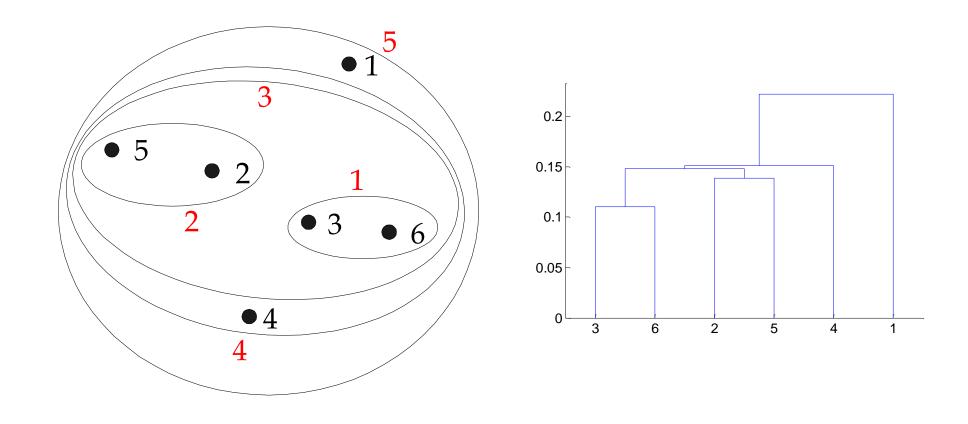
- MIN
- MAX
- Group Average
- Distance Between Centroids

- **Proximity Matrix**
- Other methods driven by an objective function
  - Ward's Method uses squared error

## Cluster Similarity: MIN or Single Link

- Similarity of two clusters is based on the two closest points in the different clusters.
  - Determined by one pair of points, i.e., by one link in the proximity graph.
- Can handle non-elliptical shapes.
- Sensitive to noise and outliers.

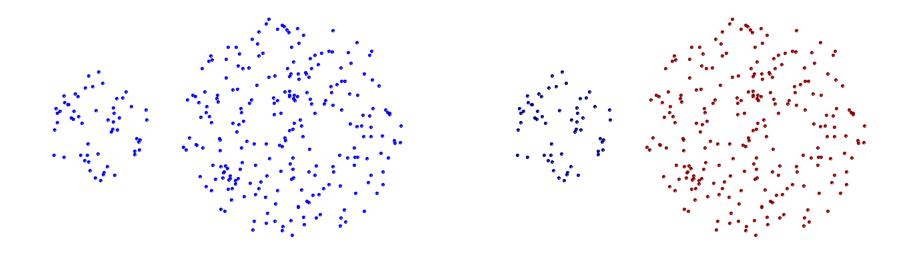
## Hierarchical Clustering: MIN



**Nested Clusters** 

Dendrogram

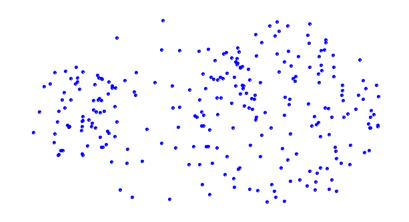
# Strength of MIN

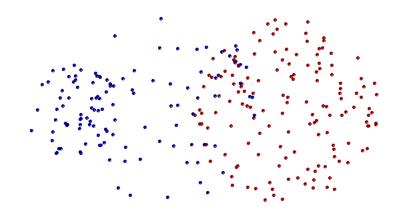


Original Points

Two Clusters

## Limitations of MIN





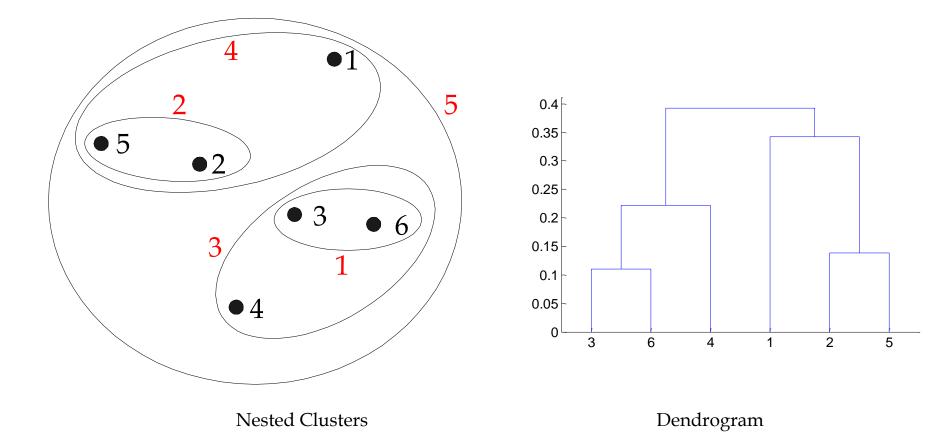
Original Points

Two Clusters

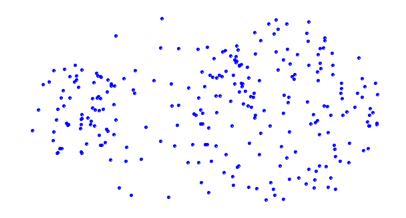
## Cluster Similarity: MAX or Complete Linkage

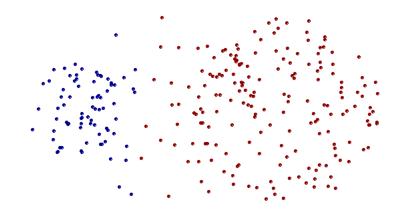
- Similarity of two clusters is based on the two most distant points in the different clusters.
  - Determined by all pairs of points in the two clusters.
- Tends to break large clusters.
- Less susceptible to noise and outliers.
- Biased towards globular clusters.

# Hierarchical Clustering: MAX



# Strength of MAX

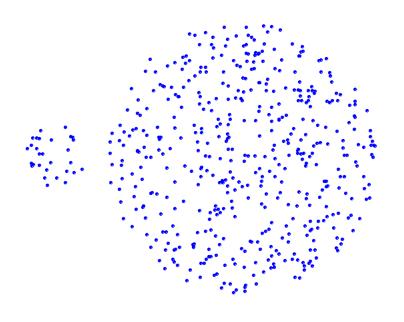




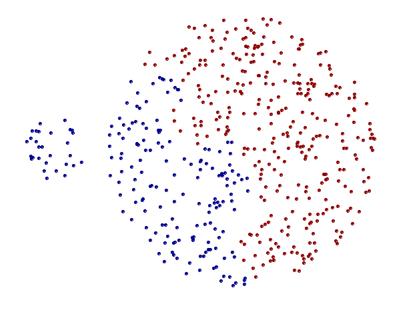
Original Points

Two Clusters

# Limitations of MAX



**Original Points** 



Two Clusters

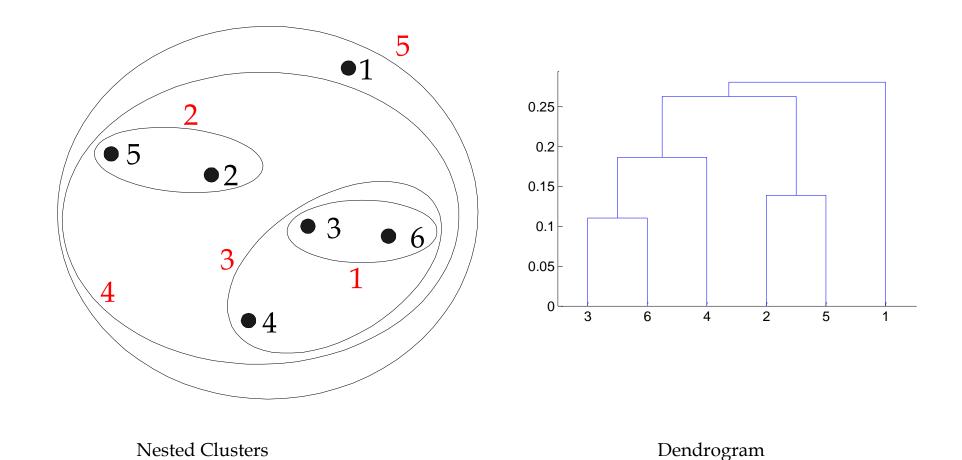
### Cluster Similarity: Group Average

 Distance of two clusters is the average of pairwise distance between points in the two clusters.

```
distance(Quster_i, Cluster_j) = \frac{\sum_{\substack{p_i \in Cluster_i\\p_j \in Cluster_j}}}{|Cluster_i| * |Cluster_i|}
```

- Compromise between Single and Complete Link.
- Need to use average connectivity for scalability since total connectivity favors large clusters.
- Less susceptible to noise and outliers.
- Biased towards globular clusters.

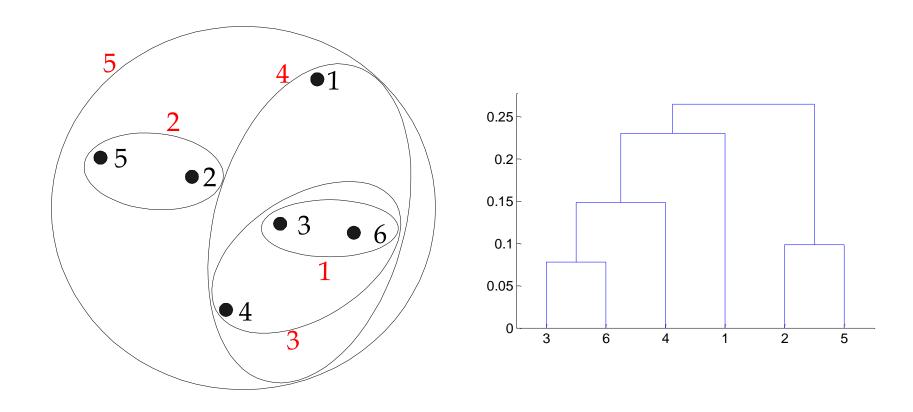
## Hierarchical Clustering: Group Average



### Cluster Similarity: Ward's Method

- Similarity of two clusters is based on the increase in squared error when two clusters are merged.
  - Similar to group average if distance between points is distance squared.
- Less susceptible to noise and outliers.
- Biased towards globular clusters.
- Hierarchical analogue of K-means
  - But Ward's method does not correspond to a local minimum
  - Can be used to initialize K-means

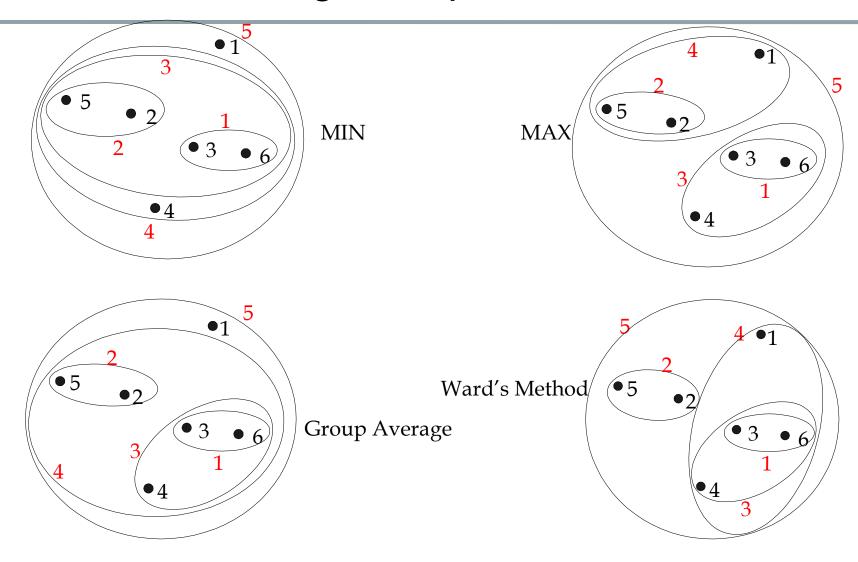
## Hierarchical Clustering: Ward's method



**Nested Clusters** 

Dendrogram

## Hierarchical Clustering: Comparison



### Hierarchical Clustering: Time and Space requirements

- O(N<sup>2</sup>) space since it uses the proximity matrix.
  - N is the number of points.
- O(N³) time in many cases.
  - There are N steps and at each step the proximity matrix (size N²) must be updated and searched.
  - By being careful, the complexity can be reduced to O(N<sup>2</sup> log N) time for some approaches.

## Hierarchical Clustering: Problems and Limitations

- Once a decision is made to combine two clusters, it cannot be undone.
- No objective function is directly minimized.
- Different schemes have problems with one or more of the following:
  - Sensitivity to noise and outliers.
  - Difficulty handling different sized clusters and convex shapes.
  - Breaking large clusters.