Mitigating manipulation in committees: Just let them talk!

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Abstract

Many decisions rest on the collective judgment of small groups like committees, boards, or teams. However, some group members may have hidden agendas and manipulate this judgment to sway decisions in their favor. Utilizing an incentivized experiment, I analyze how manipulation affects the objective accuracy and perceived trustworthiness of such group judgments depending on the format of group interaction.

I compare group judgments from unstructured face-to-face interactions, which are ubiquitous in real-world institutions, to group judgments from the scientifically endorsed, structured Delphi technique. To identify mechanisms underlying the accuracy differences, I use structural estimations and analyze emergent communication patterns.

Without manipulation, Delphi is more accurate than face-to-face interaction and indistinguishable from the Bayesian benchmark. Manipulation decreases accuracy for Delphi but not for face-to-face interaction. Thus, with manipulation, Delphi is less accurate than face-to-face interaction. With manipulation, sharing of (truthful) information decreases in Delphi but not in face-to-face interaction. The structural estimations further reveal that Delphi judgments likely exhibit more bias towards hidden agendas and less utilization of valuable information.

Perceived trustworthiness does not always match objective accuracy. Judgments from face-to-face interaction - unjustifiably - enjoy higher levels of trust without hidden agendas. Trustworthiness correctly decreases with hidden agendas for Delphi groups but - unjustifiably - also for face-to-face groups. With hidden agendas, face-to-face groups are simultaneously more accurate and trusted.

Keywords Committees · Manipulation · Face-to-face Communication · Delphi Technique JEL Classification D70, D71, D83

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1 Introduction

In many institutions, high-stake decisions are made based on the collective judgment of small groups, like (expert) committees or advisory boards that evaluate some decision-relevant criteria. Examples of such group judgments span diverse contexts: scientists evaluate the effectiveness of policy interventions to fight global pandemics (Haug et al., 2020), managers rate investment alternatives (Lovallo et al., 2020), and security experts assess terrorist activity (Friedman and Zeckhauser, 2014).

The question remains whether the widespread use of this practice implies its appropriateness. To optimally inform decisions, the accuracy and trustworthiness of group judgments are essential. However, some group members may have hidden agendas and manipulate this judgment in a particular direction to sway consequent decisions in their favor. Generating accurate and trusted collective intelligence in such a setting remains a challenge. Therefore, I analyze whether two common formats of group interaction may preserve accuracy and trustworthiness despite manipulation due to hidden agendas. In particular, I compare group judgments from unstructured face-to-face interactions, which are ubiquitous in real-world institutions, to group judgments from the scientifically endorsed, structured Delphi technique.

A way of extracting collective intelligence from groups that is both accurate and perceived as trustworthy has yet to be identified. Previous research in this context has focused on prediction markets and exogenously structured face-to-face interactions. While prediction markets appear accurate but not always trusted, structured face-to-face interactions are highly trusted but not always accurate. Prediction markets proved themselves as a robust tool to accurately elicit and aggregate dispersed information from a group of people (Wolfers and Zitzewitz, 2004; Arrow et al., 2008), which has also been successfully tested by large institutions such as Google and Ford (Cowgill and Zitzewitz, 2015). Such markets remain informative even if some participants act manipulatively. However, in

¹E.g., serving their career in the institution (Toma and Butera, 2009; Mattozzi and Nakaguma, 2022), serving other organizational units the individual is associated with (Pearsall and Venkataramani, 2015), benefiting their reputation (Visser and Swank, 2007), overstating chances of the political victory of favored parties (Hansen et al., 2004; Rothschild and Sethi, 2016), receiving bribes (Felgenhauer and Grüner, 2008) or downplaying security threat to reduce responsibility and effort for consequent duties (Amjahid et al., 2017).

response to manipulation, decision-makers observing the market lose trust and make even worse decisions, as if they had ignored the market completely (Choo et al., 2022).

Face-to-face interactions are a standard operating procedure in institutional decision-making. The particular variety of such interactions, that has been studied in hidden agenda settings, are nominal groups. These are groups interacting in an exogenously imposed estimate-talk-estimate format and have been found to enjoy high levels of trust among decision-makers.² Adversely, trustworthiness persists even if judgment accuracy deteriorates with manipulation (Maciejovsky and Budescu, 2020). Taken together, both prediction markets and nominal groups appear suboptimal and may lead to many objectively ill-informed decisions with high societal stakes. To address this problem, I extend previous investigations to two alternative formats of group interaction. On the one hand, I analyze commonly used face-to-face interaction (FTF) that is not exogenously bound to any structure, such as the protocol of nominal groups. On the other hand, I consider the scientifically endorsed Delphi technique (Delphi), where interaction is exogenously structured according to a specific protocol.³ I quantify the extent to which these interaction formats produce a collective intelligence that is simultaneously accurate and perceived as trustworthy. Further, I identify what drives robustness towards manipulation.

To measure the capabilities of Delphi and FTF, I developed a pre-registered, incentivized lab experiment.^{4,5} The experiment enables the isolation of the causal effects of hidden agendas and the format of group interaction on quantitative measures of objective accuracy and perceived trustworthiness. Conducting a lab experiment offers a unique opportunity to address the research questions by controlling for many factors that are not directly observable in real-world situations where group judgments are used. Hidden

²In nominal groups, group members first estimate individually, second talk with their group members, and finally estimate individually again.

³FTF and more broadly free-form deliberation of groups are ubiquitous in real-world institutional decision-making (Maciejovsky and Budescu, 2020) despite concerns about their performance (Sunstein, 2005; Armstrong, 2006). Though less common in practice, the Delphi technique is a group interaction format supported by empirical and theoretical research (Rowe and Wright, 1999; Graefe and Armstrong, 2011).

⁴Pre-registration files can be found via OSF https://osf.io/cv4md/

⁵The experiment was reviewed and approved by the Ethical Review Committee Inner City Faculties at Maastricht University (reference ERCIC_267_10_06_2021).

agendas, by their very nature, are covert to researchers. Moreover, group judgments potentially depend on many, not directly measurable factors, such as the expertise of group members, and are used in situations where the true answer is unknown.

The experiment comprises two parts: a group estimation experiment and a subsequent decision experiment. In the first part, the estimation experiment, I examine the objective accuracy of groups of four people who collaborate on a series of probabilistic judgment tasks in which they generate joint group judgments. The experiment follows a two-bytwo between-subject design with FTF and Delphi groups, each with and without hidden agendas. In the FTF treatments, groups interact via face-to-face conversation in a video call without any imposed structure. In the Delphi treatments, groups interact through an imposed, pseudonymous chat protocol. According to this protocol, group members first make individual quantitative and qualitative judgments, then review all members' pseudonymous judgments and reasonings before producing a second quantitative estimate individually. Across all treatments, I incentivize accuracy at the group level. In the hidden agenda treatments, I additionally induce manipulation incentives (hidden agendas) in half of the group members through individual, private side payments.

In the second part, the *decision experiment*, I elicit the perceived trustworthiness of the group judgments obtained from the estimation experiment. A new set of individual participants who did not participate in the estimation experiment states their individual, incentivized confidence intervals around group judgments.⁶ Each participant evaluates judgments from all four treatment conditions. This decision experiment allows for comparisons of the perceived trustworthiness of group judgments produced by FTF versus Delphi groups, each with and without hidden agendas, respectively.

I identify differences in objective accuracy by comparing absolute errors across conditions of the estimation experiment. Without hidden agendas, structured Delphi interaction produces more accurate judgments than FTF. This result reverses with manipulation, which does hamper accuracy in Delphi groups but not in FTF groups. To put accuracy into perspective, I compare Delphi and FTF groups against the best Bayesian benchmark based on the information available to the groups. Without hidden agendas, the best benchmark's accuracy is statistically indistinguishable from that of Delphi but sig-

⁶Intervals are incentivized through the incentive-compatible most likely interval technique (Schlag and van der Weele, 2015).

nificantly more accurate than FTF. Both interaction formats, Delphi and FTF, perform significantly better than a benchmark, which estimates all probabilities naïvely at 50%. In situations with hidden agendas, no interaction format reaches the best Bayesian benchmark. While FTF groups still outperform the naïve heuristic, Delphi falls behind this benchmark.

I identify differences in the perceived trustworthiness of group judgments by comparing the length of stated confidence intervals in the decision experiment across conditions of the estimation experiment. FTF group judgments are generally trusted more than Delphi group judgments. This holds regardless of the presence of hidden agendas and also in cases where it is not justified by objective accuracy.

All in all, FTF group judgments appear problematic in situations without hidden agendas. Here, they are objectively less accurate. Decision-makers fail to realize this and put relatively more trust in FTF judgments. This can be taken as evidence that FTF should be used less in institutional decision-making in situations without hidden agendas, which are arguably very rare. The Delphi technique seems to be a better alternative. However, in situations with hidden agendas, perceived trustworthiness is aligned with objective accuracy, as the relatively more accurate judgments from FTF groups are also trusted more than judgments from Delphi groups. This can be taken as evidence that FTF is an appropriate format for institutional decision-making in situations with hidden agendas, which are arguably very prevalent.

To explore the mechanisms underlying the differences in accuracy, I use structural estimations and analyze emergent communication patterns across conditions of the estimation experiment. In particular, I analyze the data from group estimation in the BIN modeling framework (Satopää et al., 2021) (Section 4.4.1). This allows me to decompose the estimation error in all conditions of the estimation experiment into: (i) bias (consistently producing too high or too low estimates), (ii) noise (coming to different conclusions given the same information), and (iii) the usage of valuable information. Delphi, as compared to FTF, generally exhibits less noise. However, with the introduction of hidden agendas, Delphi likely suffers from more bias, while FTF appears robust against this effect.

Complementing the results from the structural estimations, I analyze the degree and truthfulness of information sharing during group interaction. Transcribed and coded communication protocols of FTF and Delphi interactions reveal that hidden agendas lead

to less information sharing and decrease the truthfulness of shared information for Delphi groups. By contrast, in FTF groups, the amount of shared, truthful information increases with hidden agendas.

Condensed, FTF seems generally better suited for group judgments in situations with hidden agendas. Moreover, FTF appears to be the better choice in situations without hidden agendas where the perceived trustworthiness of group judgments is highly prioritized. The Delphi technique is preferable in situations without hidden agendas where accuracy is the highest priority.

2 Related literature

This work considers a broad range of interdisciplinary studies on collective intelligence. The most important works in relation to this study are those that compare multiple group interaction formats, investigate single group interaction formats in isolation, and those that study the effects of manipulation or lying behavior on group judgments. More broadly, this study builds on longstanding research on committee decision-making.

This study is most closely related to comparisons of group interaction formats concerning accuracy, trustworthiness, and robustness towards manipulation. Early studies in this area focus on comparing the accuracy of the Delphi technique to other formats of structured and unstructured direct interaction, as well as averaging individual judgments. This literature presents mixed results regarding the relative performance of the Delphi technique, but also acknowledges severe methodological limitations in early Delphi research (Woudenberg, 1991; Rowe and Wright, 1999). Notably, many studies used (over)simplified Delphi designs, which might have led to Delphi's capacity being understated (Rowe et al., 1991). Later, collective intelligence research focuses on prediction markets, and advances in software allowed more consistent implementation of structured interaction formats in the laboratory. Computerized Delphi groups were found to be the most accurate in a comparison against unstructured face-to-face groups, structured nominal groups, and groups trading in prediction markets to solve general knowledge questions in the laboratory (Graefe and Armstrong, 2011). Based on data from a geopolitical forecasting tournament, prediction markets outperform median estimates of interacting teams but lose to more sophisticated statistical aggregation (Atanasov et al., 2017). Previously mentioned studies consider situations without hidden agendas, and without the explicit

threat of manipulation. Maciejovsky and Budescu (2013) are the first to consider conflicts of interest that induce manipulation in structured nominal groups vs. prediction markets in a lab experiment. In contrast to nominal groups, prediction markets maintain knowledge sharing if the existence of conflicts of interest is commonly known. In a follow-up, Maciejovsky and Budescu (2020) additionally consider the trustworthiness of judgments. Without manipulation, nominal groups are more accurate than markets, but markets are more accurate than groups with manipulation. At odds with accuracy, nominal groups' judgment is perceived as more trustworthy overall, especially in manipulation treatments. This holds for trustworthiness as evaluated by group members themselves but also by external observers. Similarly, Choo et al. (2022) compare the accuracy of prediction markets without manipulative traders to markets where there is a certain probability that manipulators are active and markets where manipulators are active with certainty. The mere potential of manipulation hampers accuracy. Nevertheless, even with certain manipulation, markets still reveal valuable information. For decision-makers observing the market, the potential of manipulation and, more so, certain manipulation cause erosion of trust. Remarkably, while markets with manipulation still reveal objectively valuable information, erosion of trust prevents decision-makers from utilizing it. In fact, with certain manipulation, decisions are even worse, as if decision-makers had ignored the market entirely.

Extracting collective intelligence from groups in hidden agenda settings remains a challenge. Previous research, as summarized in Table 1, has not yet identified interaction formats that are simultaneously accurate and trusted. I build on and extend this body of literature by scrutinizing the accuracy and perceived trustworthiness of group judgments from Delphi groups as opposed to freely interacting face-to-face groups. To the best of my knowledge, I am first to compare these two interaction formats in a setting with hidden agendas. Further, I advance the methodology developed in previous method comparisons by combining experimentally induced, complementary expertise, and continuous as well as incentivized measures of accuracy and trustworthiness.

Focusing on a single group interaction format at a time, researcher further studied manipulation in prediction markets. Evidence is mixed, with some studies reporting that manipulation harms accuracy (Hansen et al., 2004; Gimpel and Teschner, 2014; Choo et al., 2022), while others find that prediction markets are robust against manipulation

Table 1: Comparisons of group judgment techniques in the literature

	$A_{Imstrong}^{Graefeand}$	$M_{aciejovsky}$ and $B_{udescu}\left(20_{I3} ight)$	$M_{aciejovsky}$ and B_{udescu} (2020)	C_{lloo} et al ; (2022)	T_{his} $stud_{\mathcal{V}}$
Interaction for					
$unstructured\\face-to-face$	\checkmark (4-6)	-	-	-	$\checkmark(4)$
$Delphi\\ technique$	\checkmark (4-6)	-	-	-	$\checkmark(4)$
$nominal\ group\\ technique$	√ (3-6)	$\checkmark(3)$	$\checkmark(3)$	-	-
$prediction\\ markets$	√ (4-7)	$\checkmark(3)$	$\checkmark(3)$	√ (8)	-
Assessed qualit	y measures				
accuracy	\checkmark	\checkmark	\checkmark	\checkmark	\checkmark
trust worthiness	-	-	\checkmark	✓	\checkmark
Features of the	group judgme	$nt \ task$			
$hidden \ agendas$	-	\checkmark	\checkmark	\checkmark	\checkmark
$induced \ expertise$	-	✓	✓	√	√
Sample					
$n\ judgment$	227	144	450	112	590
$\begin{array}{c} groups/\\ condition \end{array}$	11	16	15	7	15
$n\ trust$	-	-	224 + 358	56	2000

(Hanson et al., 2006; Hanson and Oprea, 2009; Teschner et al., 2017). Beyond markets, the Delphi technique appears manipulable by the Delphi administrators (Nelson, 1978), and Delphi estimates may generally be biased by the desirability of outcomes among Delphi group members (Ecken et al., 2011). Further, Wittrock (2023) discusses theoretically that Delphi group members may not report their true beliefs in order to affect the other Delphi participants and ultimately sway decisions tied to the Delphi result. Yet, explicit manipulation of Delphi estimates by group members has not been empirically investigated

prior to the present study.

To study the influence of manipulation, this work strongly builds on prior research on the **Delphi technique**, a structured interaction format to extract and aggregate human judgment from a group of experts. The format aims to strengthen the positive aspects of deliberation while minimizing the process loss of group interaction (Rowe and Wright, 2001). Two basic concepts form the foundation of Delphi's potential. First, according to the theory of errors, combining estimates from multiple judges will lead to a group judgment that is more accurate than the average individual's judgment (Dalkey, 1975). Second, throughout the interaction, relatively less accurate judges will update more than relatively accurate judges (Parenté and Anderson-Parenté, 1987), and relatively more accurate feedback has a stronger influence on such updating (Rowe et al., 2005; Bolger and Wright, 2011). Both concepts are also noted in the broader context of the "wisdom of crowds", i.e., aggregating independent, individual judgments is more accurate than the average individual (Galton, 1907). Second, through information exchange, individual judgments lose independence. However, accuracy may still increase (Mellers et al., 2014; Da and Huang, 2020), and combined group judgments improve if relatively stronger influence is exerted from more to less accurate individuals (Becker et al., 2017).

The Delphi technique dates back to research by the RAND Corporation in the late 1940s to improve expert forecasting on topics such as technological change. Subsequently, manifold research projects used the Delphi technique and investigated its performance and workings (as reviewed by Rowe et al. (1991); Woudenberg (1991); Rowe and Wright (1996, 1999); Bolger and Wright (2011)). In parallel, research from various disciplines has used the Delphi technique to generate estimates on transcontextual topics such as climate change mitigation measures (Griscom et al., 2017), biotechnologies improving health in developing countries (Daar et al., 2002) and geopolitical events (Wintle et al., 2012). Implementations of the Delphi technique often differ in their specific design. However, the vast majority exhibits four key characteristics: anonymity, controlled feedback, iteration, and statistical aggregation of final inputs (Rowe and Wright, 2001; Grime and Wright, 2016; Belton et al., 2019). Moreover, certain Delphi features empirically appeared as accuracy enhancing: feedback that also includes written rationales next to group members' estimates (Best, 1974; Rowe and Wright, 1996; Rowe et al., 2005; Bolger and Wright, 2011; Bolger et al., 2011) and group members with objective (complementary) expertise

(Jolson and Rossow, 1971; Rowe and Wright, 1996). The present study incorporates Delphi's four key characteristics, feedback including written rationales, and experimentally induced, complementary expertise in the Delphi interaction implemented in the estimation experiment.

In a broader context, this study builds on the literature on **committee and jury decision-making** going back to Condorcet (1785). A common focus of this research strand lies in groups of people, i.e., the jury or committee, that reaches a joint verdict, e.g., convict or acquit, by some voting procedure, which may be preceded by deliberation. Some jury members may follow strategic motives, as e.g., discussed by Feddersen and Pesendorfer (1998). This has common features with the given setting of groups deriving joint, probabilistic judgments but also exhibits apparent differences. For instance, the given setting does not explicitly study specific voting rules, nor is a decision made by the committee itself. Notably, a phase of communication preceding voting was found to counteract hidden agendas by inducing mostly truthful information sharing and less manipulative voting (Goeree and Yariv, 2011). However, making such deliberations public to non-committee members counteracts these positive effects (Fehrler and Hughes, 2018). Moreover, if committee members differ in competence, the voting behavior's transparency may counteract competent members' hidden agendas (Mattozzi and Nakaguma, 2022).

Furthermore, the effects of manipulation on collective intelligence are reflected in the literature on lying and deception. In contrast to the predictions of standard economic theory, many individuals tell the truth despite potential monetary gains from lying (Gneezy, 2005; Sutter, 2009). Further, many of those who do not tell the truth do not lie to the full extent (Mazar et al., 2008; Fischbacher and Föllmi-Heusi, 2013; Gneezy et al., 2018). Rather, they obfuscate the truth through vague messages (Serra-Garcia et al., 2011) or evasive lies (Khalmetski et al., 2017). The most plausible explanations for such (non-)lying behavior are preferences for being honest and being seen as honest (Abeler et al., 2019). Lying however, increases if individual responsibility is diffused, such as in team settings (Conrads et al., 2013), if the social distance between a liar and the person being lied to increases (Hermann and Ostermaier, 2018), if communication is computer-mediated (Marett and George, 2012) or if the truth that is twisted in a lie, is hard to observe by others (Fries et al., 2021; Hermann and Brenig, 2022). Switching perspectives, many people do not correctly detect if they are lied to (Bond and DePaulo,

2006). They are overconfident in their ability to do so, and share undetected lies as truth (Serra-Garcia and Gneezy, 2021). I compare these results to my analysis of (truthful) information revelation during group interaction across conditions of the estimation experiment.

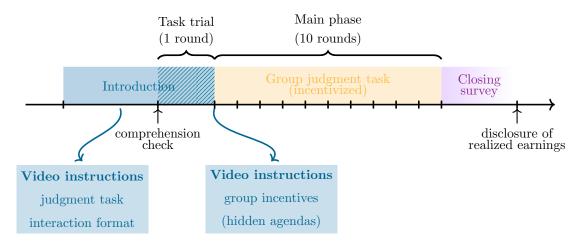
3 Experiment

This study comprises two complementary experiments: the estimation experiment, which examines the accuracy of group judgments, and the subsequent decision experiment, which elicits the trustworthiness of group judgments. All experiments were programmed in oTree (Chen et al., 2016) and were implemented onsite in the experimental economics laboratory BEElab at Maastricht University in 2022 and 2023. In total, 240 people participated in the estimation experiment, split into 60 groups of four, 15 groups per treatment condition. Subsequently, 50 participants individually evaluated group judgments in the decision experiment. All participants were recruited from the BEElab participant pool via ORSEE (Greiner, 2015) and followed a study program at the time of the experiment or in the past. Their backgrounds span the arts, as well as the social and natural sciences. There is a clear prevalence of participants with business and/or economics backgrounds (79.6%) in the estimation experiment and 74% of participants in the decision experiment). Most participants identified as female (56.3% in the estimation experiment and 64% of participants in the decision experiment). Many had at most one year of professional working experience (70.4\% in the estimation experiment and 76\% of participants in the decision experiment).

3.1 Estimation experiment

To determine the causal effect of group interaction format and hidden agendas on the accuracy of group judgments, I implemented the estimation experiment as a two-by-two between-subject design. In all treatment conditions, groups were asked to jointly generate a series of ten probabilistic group judgments in a group of four. Groups received incentives for doing so as accurately as possible. They interact in either FTF or Delphi format. In the hidden agenda treatments (HA), half of the group members additionally were given private, individual manipulation incentives that conflicted with and outweighed the group incentives for accuracy (see Appendix A.1.2 for details on incentives).

Figure 1: Timeline of the estimation experiment



The estimation experiment followed the same structure in all four conditions, as illustrated in Figure 1. First, participants received video instructions on the judgment task and the interaction format, followed by a comprehension check and a task trial to experience the judgment task and the interaction format. After the trial, before starting the main phase of the experiment, participants were informed about the incentive scheme and whether they would be interacting in a setting with hidden agendas. In settings with hidden agendas, participants were told their type (whether or not they had a hidden agenda) and that exactly two group members have a hidden agenda, while the remaining two do not. Thus, knowledge about their own type allowed participants to infer the distribution of types among the remaining group members. Types did not change during the experiment. Furthermore, in settings with hidden agendas, all participants were informed that hidden agendas may take one of two forms, driving estimates up or down. It was common knowledge that the direction of the hidden agendas was determined randomly per round of the judgment task and that it was the same among the two group members with hidden agendas in any given round. In a specific round, the two group members with a hidden agenda knew that their hidden agenda in this round was to drive estimates up (down). This information was not disclosed to the remaining two group members without a hidden agenda. Before starting the main phase, participants were prompted to ask any question to the experimenter that may have remained unanswered.

In the main phase of the experiment, participants went through 10 incentivized rounds of solving the probabilistic judgment task. Each round had a distinct underlying, objectively true answer against which the accuracy of group judgments could be evaluated.

At the beginning of each round, group members received individual, complementary information. Combining the individual pieces of information is generally advantageous to generate more accurate group judgments. In groups with hidden agendas, group members with hidden agendas also learned the round-specific direction (up or down) of their hidden agenda at the beginning of each round. No information on group accuracy or hidden agenda achievement was presented until the end of the experiment. Before earnings disclosure and payment, participants completed a questionnaire on socio-demographic characteristics and their subjective perception of the task.

3.1.1 Interaction formats

This paper focuses on the comparison of two interaction formats: free-form face-to-face interaction (FTF) without exogenously imposed structure, which is ubiquitous in real-world institutional decision-making (Maciejovsky and Budescu, 2020), and the Delphi technique, a group interaction format supported by empirical and theoretical research (Rowe and Wright, 1999). In a broader context, the general experimental framework provides a test bed that is well suited to investigating the accuracy and perceived trustworthiness of any group interaction format directed at generating quantitative group judgments.

Following Graefe and Armstrong (2011), I implemented a very simple form of face-to-face interaction in the **FTF** treatments, wherein groups were almost unrestricted in their interaction. For each round of the task, group members used a video call in which they could freely discuss the judgment task, their available information, and their strategy to form a joint group judgment.⁷ At the end of an interaction, each group member was prompted to enter the joint group estimate for that round. The experiment only proceeded after all group members entered the same estimate, thus enforcing consensus.⁸ As such, FTF is not anonymous and allows a free and unrestricted flow of information as well

⁷Video-conference interactions became a very popular medium for team interactions, latest during the COVID-19 pandemic. These formats enable information sharing and produce high-quality results that appear no different from those of physical face-to-face interactions (Jabotinsky and Sarel, 2020).

⁸To prevent extraordinarily long discussions, the interaction phase is limited to 10 minutes for the first incentivized round and 7:30 minutes for all later rounds. Groups that do not complete a given round in time do not earn any bonuses on this round. Out of 30 FTF groups, generating a total of 300 group judgments, the interaction on 10 group judgments exceeded the time limit.

as the full richness of communication (speech, body language, etc.). These details resemble typical real-world group interactions (Maciejovsky and Budescu, 2013). For further analysis, the video calls of all face-to-face interactions were recorded and transcribed.

In general, **Delphi** evolved to be an umbrella term for diverse forms of structured group interactions. This estimation experiment may only implement and analyze one particular variation of group interaction with Delphi features. To choose a meaningful design for this Delphi interaction, I followed two strategies: first, the design was as simple as possible while still comprising the most common Delphi features: anonymity, controlled feedback, iteration, and statistical aggregation of final inputs (Rowe et al., 1991; Woudenberg, 1991; Grime and Wright, 2016). Second, the design was similar to recent implementations of Delphi procedures in the field of collective intelligence (Becker et al., 2021; Belton et al., 2021).

In the experiment, Delphi group interactions followed a standardized, computer-mediated protocol. Participants did not directly discuss but rather interacted through a messaging interface. After receiving their information, group members first provided their numerical, individual estimates and corresponding reasoning in written form. Second, after all group members had completed their first input, everyone was presented with the inputs of the three remaining group members and their own input again. A, B, and C were used as pseudonyms associated with the same people throughout the experiment, and the feedback was shown as "the input of Person A, B, and C" and "your input." This prevented participants from being able to link the estimates and reasoning to a specific person. Next, group members were prompted to give a second estimate, which might, but did not have to be, a revision of their first estimate based on the feedback. After all group members completed their second estimate, the group judgment was calculated as the mean of all second estimates. Participants were presented with the group judgment and the underlying, second individual estimates before proceeding with the experiment. Again, this feedback is pseudonymous.

3.1.2 Judgment task

Inspired by (Peeters and Wolk, 2018, 2017), participants were asked to estimate the likelihood that a (biased), two-dimensional, discrete random walk would end above a threshold level after 10 steps. Specifically, the random walk started at 0 and comprised 10 steps

 $X_t = X_1, X_2, ..., X_{10}$. Each step X_t could take the values -1, 0 and 1. Independent draws from an identical distribution determined X_t . The task was repeated for 10 rounds. The distribution underlying the random walk varied from round to round of the judgment task. In each round, group members need to estimate $\mathbb{P}(\sum_{t=1}^{10} X_t > 0)$, i.e., the probability that the random walk would take a value larger than the threshold of 0 after ten steps. Throughout the 10 rounds, groups faced steps X_t from probability distributions corresponding to $\mathbb{P}(\sum_{t=1}^{10} X_t > 0) = \{0.1, 0.2, 0.3, 0.4, 0.45, 0.55, 0.6, 0.7, 0.8, 0.9\}$ in random order. The task was presented to participants as a computer-generated movement path (random walk) of a ladybird, which may or may not reach a target after 10 steps. Groups were asked to estimate the chance that the ladybird would reach the target. They were informed that the computer program would generate the movement paths by independently drawing the value per step from an underlying identical distribution, but the exact distribution was undisclosed. To learn about the underlying probabilities, each group member privately received a movement path generated by a distinct past execution of the computer program. In each round, group members first received their information and then entered a phase of interaction, which resulted in a group estimate (see Appendix A.1.1 for further details on the judgment task).

3.2 Decision experiment

This second experiment serves the purpose of evaluating the perceived trustworthiness of estimates generated by experts in the estimation experiment. Experimental participants (decision-makers) who were not involved in the estimation experiment took part in the decision experiment. Within-subject, each decision-maker stated their incentivized, personal confidence intervals around 40 estimates generated in the estimation experiment. They were given 10 randomly selected group judgments drawn from each of the four experimental conditions of the estimation experiment (FTF, FTF + HA, Delphi, Delphi +

⁹Incentives followed the most likely interval method (Schlag and van der Weele, 2015), as described in more detail in Appendix A.1.2.

HA).^{10,11} Decision-makers were also introduced to the judgment task. They were informed about the details of the interaction format and incentives in each of the four treatment conditions in the estimation experiment. Subsequently, decision-makers stated the lower and upper bound of an interval for each estimate, which they believed likely contained the true value estimated in the estimation experiment. The width of these stated most likely intervals can be seen as a measure of the perceived trustworthiness of group judgments generated in the estimation experiment; the narrower the intervals, the more trustworthy the group judgments, and vice versa.¹²

4 Analysis

4.1 Hypotheses

Initially focusing on the accuracy of group judgments, I test three pre-registered hypotheses. H1: Without hidden agendas, Delphi groups are more accurate than FTF groups. H2: Hidden agendas impair accuracy in Delphi and FTF groups. H3: The negative effect of hidden agendas is relatively smaller for Delphi groups. H1 and H3 relate to the theoretical and empirical arguments that Delphi extracts accurate group judgments by strengthening positive aspects of interaction while minimizing the process loss of group interaction (Rowe and Wright, 2001). H2 follows from the intuitive interpretation of hidden agendas as obstacles to accuracy.

Subsequently evaluating the trustworthiness of group judgments, I test three further pre-registered hypotheses. H4: Delphi groups enjoy the same level of trust as FTF groups in settings with and without hidden agendas, respectively. H5: Hidden agendas impair trust in Delphi and FTF groups. H6: The negative effect of hidden agendas on trustworthiness is the same for Delphi and FTF groups. Previous literature has focused on the

¹⁰This is an adjustment to pre-registration that allows all estimates of the estimation experiment to be evaluated in as balanced as possible: each estimate is evaluated at least three times and by three different decision-makers. The pre-registration outlines that each decision-maker faces all 10 group judgments made by one group in the estimation experiment.

¹¹The order in which group judgments from the four experimental conditions of the estimation experiment are evaluated is randomized across decision-makers.

¹²Judgments of FTF groups that were NA due to exceeding the time limit in the experiment were imputed by 0.5 (this applies to 10 judgments out of 300).

relative accuracy of Delphi and FTF but remains silent on their relative trustworthiness. As such, H4 and H6 can be seen as a result of an impartial prior about the interaction formats' trustworthiness. H5 follows from the intuitive interpretation of hidden agendas as obstacles to trustworthiness.

4.2 Evaluating the accuracy of estimates

To measure the causal effect of hidden agendas and interaction formats on accuracy, I compare group judgments across conditions of the estimation experiment. Based on the estimation experiment, Delphi groups appear more accurate than FTF groups without hidden agendas, supporting H1. Hidden agendas impair accuracy for Delphi groups, which is partly in line with H2. However, hidden agendas do not affect the accuracy of FTF groups, contradicting H3.

For the primary analysis, I quantify accuracy by juxtaposing group judgments with objectively true probabilities.¹³ I focus on absolute error (AE)¹⁴ as a simple, and illustrative corresponding metric:

$$AE_{g,r} = |p_{g,r} - p_r^*| \tag{1}$$

where $p_{g,r}$ is the group judgment, i.e., the estimated probability of group g in round r with r = 1, ..., 10, and p_r^* is the corresponding true probability. Absolute errors are bound by 0 (most accurate) and 1 (least accurate).¹⁵

¹³In the experiment setting, the objectively true probability is the probability of reaching the target, which is coded into the computer program that generates the movement paths of the ladybird. An alternative approach is comparing a group judgment to the outcomes drawn according to the underlying actual probability. In the experiment setting, the actual outcome is the outcome reached when the program is executed for the next time, i.e., the ladybird did (not) reach the target in this particular execution of the program. This alternative, however, is more complex than needed and a more noisy measure of accuracy, especially for relatively small numbers of distinct judgments.

¹⁴The reported main results 1-3 are robust towards considering squared errors and Brier scores (preregistered), as alternative metrics of accuracy (see Appendix B).

¹⁵An absolute error of 1, however, is only possible in two specific cases where the estimate was 0 (1) and the true probability was 1 (0), respectively. A realistic negative benchmark absolute error is 0.21, the average absolute error obtained if estimates were always 0.5, and the true probabilities are the same as in the experiment.

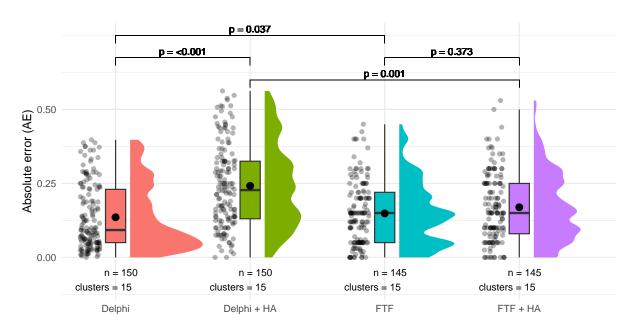


Figure 2: Absolute errors of group judgments across conditions of the estimation experiment

Notes: P-values from two-sided Wilcoxon rank sum tests (Rosner et al., 2003; Jiang et al., 2020). Bar in boxplot = median; dot in boxplot = mean.

The absolute errors in each experimental condition are summarized in Figure 2, leading to the three main results below. For comparisons between conditions, I report p-values of two-sided, non-parametric, adapted Wilcoxon Rank Sum tests that control for clustering of observations at the group level (Rosner et al., 2003; Jiang et al., 2020). ¹⁶

First, I focus on the baseline scenario of situations without hidden agendas.

Result 1: In line with H1, without hidden agendas, the absolute errors of judgments from structured Delphi interaction are significantly smaller (p = 0.037) than from unstructured face-to-face interaction.

Turning to situations with hidden agendas, FTF, however, performs quite well.

¹⁶Results 2 and 3 are robust to an even more conservative scenario, where the average absolute error over all ten judgments per group is considered as only independent observation per group as reported in Appendix B.

Result 2: Introducing hidden agendas leads to a significant increase (p < 0.001) in absolute errors of judgments from Delphi interactions but, in contrast to **H2**, not for judgments from unstructured face-to-face interactions (p = 0.373).

Result 2 also precludes that the negative effect of hidden agendas on accuracy is relatively smaller for Delphi groups. The negative effect of hidden agendas appears to be smaller in FTF than in Delphi interactions. This poses the new question: Which interaction format ultimately yields more accurate results in situations with hidden agendas?

Result 3: With hidden agendas, the absolute errors of judgments from unstructured face-to-face interactions are significantly smaller (p = 0.001) than from structured Delphi interaction.

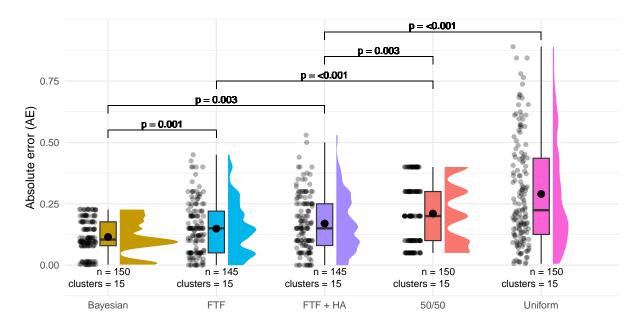
4.2.1 Accuracy benchmarks

To put Results 1 to 3 into perspective, I compare the absolute errors of actual group judgments to the theoretical benchmarks in Figures 3 and 4, respectively. On the positive side, I consider the perfect Bayesian benchmark (Bayesian). On the negative side, I consider first the naïve heuristic of always stating a "50/50" likelihood (50/50) and second reporting a random likelihood drawn from a uniform distribution (Uniform). Without hidden agendas, Delphi groups are statistically indistinguishable from the Bayesian benchmark on the positive side. FTF groups are in between positive and negative accuracy benchmarks. With hidden agendas, FTF remains more accurate than 50/50 and uniform, while Delphi is less accurate than 50/50.

The positive Bayesian benchmark (Bayesian) considers groups as if they had a uniform, i.e., uninformative prior, on the probabilities that a step in the movement path of the judgment task takes the values -1, 0, and 1, respectively. In other words, any combination of $\mathbb{P}(X_t = -1) + \mathbb{P}(X_t = 0) + \mathbb{P}(X_t = 1) \equiv 1$ is deemed a priori equally likely. Groups updated this prior based on the observed movement path and then calculated the probability of reaching the target $\mathbb{P}(\sum_{t=1}^{10} X_t > 0)$ based on their posterior.

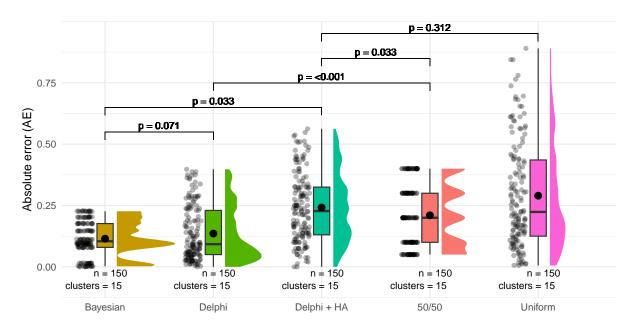
Result 1a: Without hidden agendas, the absolute errors of judgments from Delphi interactions are statistically indistinguishable (p = 0.071) from perfect Bayesian groups, but

Figure 3: Absolute errors of probability judgments from FTF groups against best and worst benchmarks



Notes: P-values from two-sided Wilcoxon rank sum tests (Rosner et al., 2003; Jiang et al., 2020). Bar in boxplot = median; dot in boxplot = mean. Observations of Bayesian, 50/50, and Uniform are simulated according to the underlying benchmark heuristic.

Figure 4: Absolute errors of probability judgments from Delphi groups against best and worst benchmarks



Notes: P-values from two-sided Wilcoxon rank sum tests (Rosner et al., 2003; Jiang et al., 2020). Bar in boxplot = median; dot in boxplot = mean. Observations of Bayesian, 50/50, and Uniform are simulated according to the underlying benchmark heuristic.

FTF groups are significantly less (p = 0.001) accurate than the Bayesian benchmark.

As the naïve 50/50 benchmark, I consider groups as if they always reported a 50% likelihood of reaching the target, irrespective of the task. Uniform constitutes an even stronger negative benchmark. It considers groups as if they consistently reported a random draw from a uniform distribution between 0 and 1, i.e., the infamous dart-throwing chimpanzee (Tetlock, 2005).

Result 1b: Without hidden agendas, both FTF (p < 0.001) and Delphi (p < 0.001) groups are more accurate than 50/50 and Uniform, respectively.

Result 2a: With hidden agendas, Delphi groups are less accurate (p = 0.033) than groups that would always report 50% as their group judgment but remain significantly more accurate (p = 0.006) than the Uniform benchmark. By contrast, FTF groups remain more accurate (p = 0.003) than 50/50 and Uniform, even with hidden agendas.

To summarize the findings on the accuracy, I borrow the generalist vs. specialist distinction from the field of ecology von Meijenfeldt et al. (2023). The Delphi technique appears to be a specialist that excels in a small niche or habitat (situations without hidden agendas), where it is perfectly adapted to environmental conditions. By contrast, FTF-based judgments are comparable to generalists. They never reach the same levels of accuracy as the specialist Delphi but appear way more robust and resilient to (unfavorable) changes in environmental conditions (hidden agendas).

4.2.2 Accuracy and hidden agenda achievement over time

The results presented in the previous section focus on the accuracy of group judgments, irrespective of whether the judgment results from the very first interaction of that group or from their interactions in later rounds. In this section, I zoom in on the time dimension to analyze whether accuracy changes over time. Note that participants did not receive any feedback between rounds. Nevertheless, a potential explanation for improving accuracy is that groups may learn to interact better and enhance their understanding of the task. In the same way, in groups with hidden agendas, those group members with hidden agendas

may learn how to achieve their hidden agenda over time, thus impairing accuracy. On the group level, I find no evidence for significant changes in the accuracy of judgments over time. Moreover, there is no time trend in how well group members with hidden agendas achieve their hidden agendas.

In Figure 5, I visualize accuracy and hidden agenda achievement over time by separating group judgments for the consecutive rounds 1,2, ..., and 10 of the judgment task. Based on a general overview, in most rounds, the distribution of absolute errors tends towards higher absolute errors for Delphi groups with hidden agendas towards lower absolute errors for Delphi groups, while the distribution of absolute errors for FTF groups with and without hidden agendas falls in between. This aligns with the general results on accuracy aggregated across rounds as depicted earlier in Figure 2. To identify potential trends over time, I regress the absolute error as the dependent variable on the round as the independent variable. This reveals no statistically significant association between these variables. The linear regression lines, accompanied by their 95%-confidence intervals, are included in Figure 5. None of them has a slope that is significantly different from zero.

To quantify the degree to which group members with hidden agendas achieve their hidden agendas, I define the hidden agenda achievement rate HAA, dependent on the hidden agenda HA and the group judgment p of group g in round r as follows:

$$HAA_{g,r} = 1 - |HA_{g,r} - p_{g,r}|,$$
 (2)

In this way, HAA = 1 corresponds to complete, i.e., 100%, achievement of the hidden agenda, while HAA = 0, indicates 0% achievement of the hidden agenda. HA = 1 if the hidden agenda was to drive group judgments up, and HA = 0 if the hidden agenda was to drive group judgments down. In most rounds, the distribution of hidden agenda achievement tends towards higher achievement rates for Delphi groups with hidden agendas and lower achievement rates for FTF groups with hidden agendas. This corroborates the general picture that FTF groups with hidden agendas are more accurate than Delphi groups with hidden agendas when aggregated over all rounds, as shown in Figure 2. As for accuracy, I find no statistically significant association between hidden agenda achievement and rounds.

I can extend the analysis to the individual level for Delphi groups. In any Delphi interaction, each group member provided a second individual judgment after observing

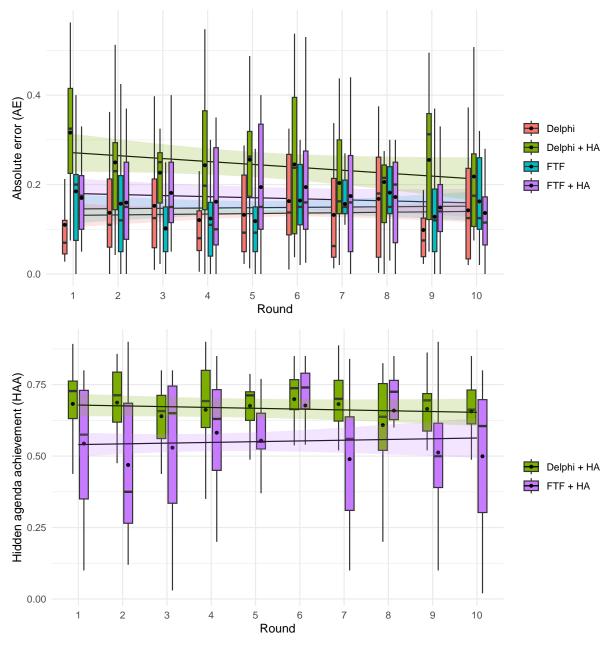
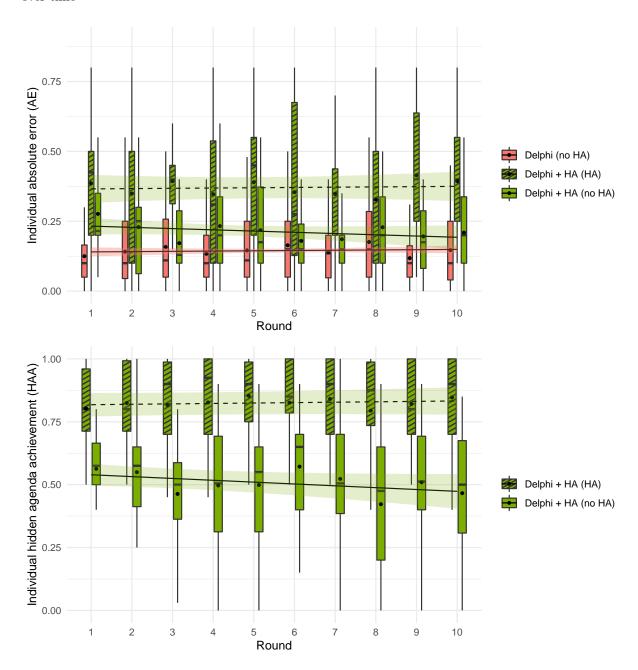


Figure 5: Accuracy of group judgments and hidden agenda achievement over time

Notes: Whiskers in the boxplots span observations larger than Q1 - 1.5 * IQR and smaller than Q3 + 1.5 * IQR. Regressions are OLS with standard errors clustered at the group level.

their group members' first individual judgments and reasonings. The group judgment was then calculated as the mean of all second, individual judgments. As previously done for the group estimates, I analyze whether these second individual judgments change accuracy over time and whether they converge more or less in the direction of hidden agendas. A priori, effects in multiple directions seem plausible. Group members with hidden agendas

Figure 6: Accuracy and hidden agenda achievement in second individual judgments in Delphi groups over time



Notes: In Delphi groups without hidden agendas (Delphi), all four individual group members have no hidden agenda (no HA). In Delphi groups with hidden agendas (Delphi + HA), two individual group members have a hidden agenda (HA), and the remaining two individual group members have no hidden agenda (no HA).

Whiskers in the boxplots span observations larger than Q1 - 1.5 * IQR and smaller than Q3 + 1.5 * IQR. Regressions are OLS with standard errors clustered at the individual level. may, over time, distort their individual judgments more and more in the direction of the hidden agenda, as they care less about losing credibility in the decreasing number of future interactions with their group. Alternatively, they might distort less over time as they become more cautious not to repeatedly behave in an overly suspicious way. Group members without hidden agendas may, over time, update their suspicions about who has a hidden agenda and form beliefs about the direction of the hidden agenda. Accordingly, they may try to counteract by distorting their own individual judgments in the opposite direction. I find no evidence for either of the two trends.

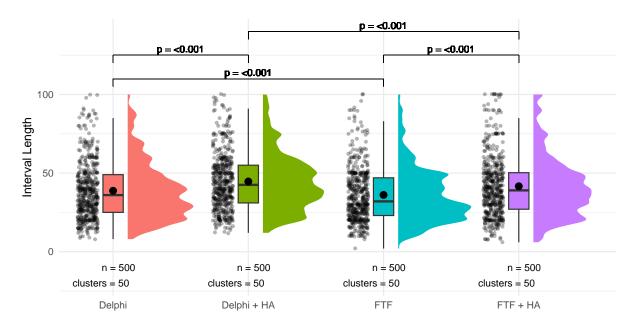
In Figure 6, I depict individual-level absolute errors and hidden agenda achievements over time. Overall, the distribution of absolute errors tends towards higher absolute errors for group members with hidden agendas in Delphi groups with hidden agendas and towards lower absolute errors for group members in Delphi groups without hidden agendas, while group members without hidden agendas in Delphi groups with hidden agendas are situated in between. This suggests that group members with hidden agendas do not only negatively influence the accuracy of Delphi group judgments but also the second individual judgments of members without hidden agendas in those groups. Further, in Delphi groups with hidden agendas, the individual judgments of group members with hidden agendas are plausibly shifted more in the direction of the hidden agenda than those of group members without hidden agendas. Focusing on the time dimension, I regress the individual-level absolute error and hidden agenda achievement rate on rounds. This reveals that individual accuracy and hidden agenda achievement are stable across rounds. All regression lines have a slope that is statistically indistinguishable from zero.

4.3 Evaluating trust in estimates

I measure the causal effect of hidden agendas and interaction formats on trust in group judgments by comparing confidence intervals in the decision experiment around group judgments from the estimation experiment. Based on the decision experiment, FTF groups always appear more trustworthy than Delphi groups, contradicting H4. In line with H5, hidden agendas impair trustworthiness, and the negative effect is of similar magnitude for FTF and Delphi, supporting H6.

I consider the width of confidence intervals to quantify the trustworthiness of group judgments. The narrower the confidence interval, the more trustworthy the group's judg-

Figure 7: Width of confidence intervals around group judgments from different treatment conditions in the estimation experiment



Notes: P-values from from clustered signed rank tests (Datta and Satten, 2008; Jiang et al., 2020). Bar in boxplot = median; dot in boxplot = mean.

ment. Confidence interval width has a most trusting upper bound at 0, or in other words; the decision-maker is certain that the group judgment is precisely equal to the actual value. The least trusting lower bound is 100, or in other words, the group judgments do not contain any information, and the decision-maker deems all possible values from 0 to 100 as equally likely to be true. Distributions of confidence interval length for judgments from each condition of the estimation experiment are summarized in Figure 7. For trustworthiness differences between conditions, I report p-values of non-parametric signed rank tests adapted for clustered paired data (Datta and Satten, 2008; Jiang et al., 2020).¹⁷

Result 4: In contrast to H4, FTF group judgments enjoy significantly higher (P < 0.001) levels of trust, i.e. narrower stated confidence intervals, than Delphi group judgments. This holds with and without hidden agendas.

Result 5: In line with H5, introducing hidden agendas leads to significantly lower (P <

¹⁷The Results 4 and 5 are robust towards averaging interval length across all 10 evaluated group judgments from the same condition of the estimation experiment, per evaluating decision-maker, and testing based on this average as only independent observation (compare Appendix B).

0.001) levels of trust, i.e., wider confidence intervals, for judgments from both Delphi and FTF interactions.

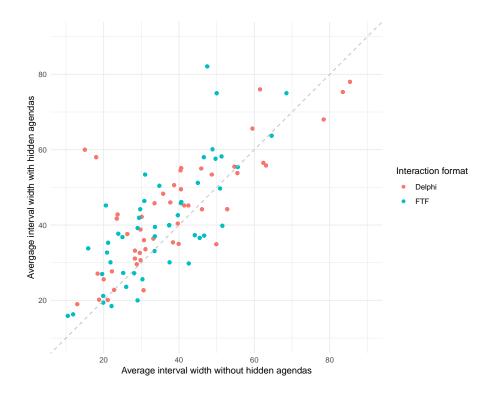
Zooming in on the size of the negative effect of hidden agendas on trustworthiness, I calculate the average confidence interval width for group judgments with and without hidden agendas evaluated by a specific decision-maker. Figure 8 depicts the average interval width per decision-maker, where each decision-maker is represented by two points, one for their evaluation of FTF groups and one for Delphi groups, each with (vertical axis) and without (horizontal axis) hidden agendas. The distance to the 45-degree line measures the difference in trustworthiness with and without hidden agendas. As such, points above the 45-degree line correspond to less trustworthiness with hidden agendas than without hidden agendas. In line with Result 5, we see that more points lie above the 45-degree lines, and many are further away from the line than points below the 45-degree line. Further, suppose the impact of hidden agendas on trustworthiness is similar for FTF and Delphi. In that case, we should see no clusters of points representing FTF and Delphi group judgments, e.g., Delphi points generally lie further above the 45-degree line than FTF points. In line with Result 6, points are scattered along the 45-degree line without clearly visible clusters.

Result 6: In line with H6, the size of the negative effect of hidden agendas on trust in judgments from FTF groups and Delphi groups is statistically not distinguishable (p = 0.6328).

Based on the results on accuracy and trustworthiness, the ultimate question is: Does perceived trustworthiness align with accuracy? In other words, do decision-makers correctly put more trust in the more accurate judgments and vice versa?

Result 7: Trustworthiness is aligned with accuracy in settings with hidden agendas; the objectively more accurate judgments from FTF interaction are trusted more. However, trustworthiness is misaligned with accuracy in settings without hidden agendas; the objectively less accurate judgments from FTF interaction are trusted more.

Figure 8: Average width of confidence intervals per decision-maker around judgments of estimation experiment groups with and without hidden agendas



Furthermore, the changes in trustworthiness are misaligned with changes in objective accuracy. While Delphi group judgments become relatively less accurate than FTF group judgments through the introduction of hidden agendas, trust in Delphi group judgments decreases just the same as trust in FTF group judgments.

4.4 BIN model

To formally disentangle the mechanisms behind accuracy differences between group interaction formats in settings with and without hidden agendas, I use the BIN model of forecasting (Satopää et al., 2021). This model distinguishes three determinants of the accuracy of probabilistic judgments or estimates: bias, information usage, and noise (BIN) as latent, i.e., not directly observable, variables of an estimating group. Bias resembles a group's tendency to produce too high or too low estimates consistently, noise leads to non-systematic variability in estimates unrelated to the event of interest, and finally, information usage characterizes the variability in group judgments, which is correlated with the event of interest. Bias and noise are detrimental, while information usage is beneficial to accuracy. Given the modeling framework, all three latent variables can be structurally

estimated based on group judgments and compared across conditions of the estimation experiment. Below, I briefly summarize the BIN model framework. Further, I outline the adaptions needed to accommodate the present setting of group judgments instead of individual forecasters in the original setting. For a more detailed discussion of the model, I refer the reader to the original paper (Satopää et al., 2021).

Let the binary event of interest of estimation be denoted as $Y \in \{0,1\}$, i.e. (not) reaching the target. Specifically, Y = 1 if $\sum_{t=1}^{10} X_t > 0$, i.e. the target is reached, and Y = 0 otherwise. Further, the model builds on two pillars: objective signals Z^* about Y and human estimates of the likelihood of Y based on the subjective interpretation of these signals Z. The outcome Y is considered to be determined by the entirety of all past and future objective signals, modeled as the continuous, normally distributed variable $Z^* \sim \mathcal{N}(\mathbb{E}[Z^*], Var(Z^*))$. In particular, the event is assumed to occur, i.e., the target area is reached, if the sum of all these signals is positive $Y = \mathbf{1}(Z^* > 0)$ where the indicator function $\mathbf{1}(E)$ equals 1 if E is true and 0 otherwise. Intuitively, this can be interpreted as an accumulation of evidence in favor of the event's occurrence. The model fixes the mean $\mathbb{E}[Z^*] = \mu^*$ and $Var(Z^*) = 1$, such that $\mathbf{P}(Z^* > 0) = p^*$, i.e. the expected frequency of the event happening based on Z^* is aligned with the true base rate $p^* \in (0,1)$.

Groups in a specific (experimental) condition i judge the likelihood of Y based on their interpretation of signals Z_i . AS with Z^* , Z_i is modeled as a normally distributed variable subject to three latent variables of group accuracy: bias, information usage, and noise (BIN). Intuitively, the closer the subjective Z_i is to the objective Z^* , the more accurate the group's judgments. Inaccuracy can take the form of bias as the difference in the means of Z^* and Z_i , or noise as the variability of Z^* that is uncorrelated with Z_i . Accuracy-enhancing information usage is described by the covariance of Z^* and Z_i . More formally, Z_i and Z^* follow the multivariate normal distribution:

$$\begin{pmatrix} Z^* \\ Z_i \end{pmatrix} = \mathcal{N} \left(\begin{pmatrix} \mu^* \\ \mu^* + \mu_i \end{pmatrix} \begin{pmatrix} 1 & \gamma_i \\ \gamma_i & \gamma_i + \delta_i \end{pmatrix} \right)$$
(3)

where the outcome and the latent variables are defined as:

$$Outcome: Y = \mathbf{1}(Z^* > 0) \tag{4}$$

$$Bias: \quad \mu_i = \mathbb{E}[Z_i] - \mathbb{E}[Z^*]$$
 (5)

Information:
$$\gamma_i = Cov(Z_i, Z^*)$$
 (6)

Noise:
$$\delta_i = Var(Z_i) - Cov(Z_i, Z^*),$$
 (7)

where the subscript i denotes a specific condition in the estimation experiment (FTF or Delphi interaction paired with (no) hidden agendas). For interpretation, perfectly accurate groups would be unbiased with $\mu_i = 0$, noise-free with $\delta_i = 0$, and exhibit $\gamma_i = 1 = Var(Z^*)$. Bias increases the further μ_i is from 0, noise increases the larger δ_i , and information usage decreases the further γ_i below 1.

Translating signals into probability judgments, the model considers groups as reporting their rational Bayesian belief of Y given Z_i :

$$\mathbb{E}[Y|Z_i] = \mathbb{P}[Z^* > 0|Z_i] \tag{8}$$

Groups are treated as if they report a judgment after they try their best to eliminate bias and noise. They are unaware of any remaining bias and noise in their interpretation of signals.¹⁸ Given this bounded rationality assumption, group judgments are given by:¹⁹

$$\mathbb{P}[Z^* > 0|Z_i] = \Phi\left(\frac{Z_i}{\sqrt{1 - \gamma_i}}\right),\tag{9}$$

where $\Phi(\cdot)$ is the cumulative distribution function (CDF) of the standard normal distribution.

I use this framework to compare the bias, information usage, and noise of groups across conditions of the estimation experiment. In this way, I can quantify the causal effect of the interaction format and hidden agendas on these three latent variables of accuracy. To this end, the estimation process of groups in the same condition is assumed to be subject to the

¹⁸This seems reasonable, as groups are incentivized through a proper scoring rule to produce the most accurate estimate possible.

¹⁹See Satopää et al. (2021) for the derivation of the conditional probability and a discussion of this assumption.

same bias, information usage, and noise. In other words, the estimation does not aim at the individual group level but treats any given group in a specific (experimental) condition as representative, i.e., as interchangeable with any other group in this condition. Further, outcomes and predictions across the ten rounds of the judgment tasks are assumed to be independent. Consequently, an estimate of, e.g., $\mathbb{P}[Y=1]=0.3$ in the first round of the judgment task says nothing about the estimate in the next round beyond the group's latent bias, information usage, and noise. As such, parameter estimates for bias, information usage, and noise can be seen as averages within a specific condition, e.g., the average bias of FTF groups with hidden agendas across the ten judgment tasks in the estimation experiment.

4.4.1 Estimates of bias, information usage, and noise

Following the econometric procedures of Satopää et al. (2021), I estimate the parameters in the framework of the BIN model using Bayesian statistics. To quantify the causal effects of interaction formats and hidden agendas on bias, information usage, and noise, I consider four binary comparisons of conditions in the estimation experiment. On the one hand, two comparisons juxtapose interaction formats within the same incentive scheme: FTF vs. Delphi and FTF with hidden agendas (FTF+HA) vs. Delphi with hidden agendas (Delphi+HA). On the other hand, two comparisons juxtapose incentive schemes within the same interaction format: FTF vs. FTF+HA and Delphi vs. Delphi+HA. For each binary comparison, I estimate posterior parameter distributions based on a uniform prior. In other words, a prior, I make the conservative assumption that all parameter configurations in the BIN model are equally likely across the two compared conditions.²⁰ To derive posterior distributions, parameter estimates are updated according to Bayes rule, taking observed group judgments, i.e., the data, into account. I modify the BINtools package (Satopää et al., 2022) to derive these parameter estimates by implementing Markov Chain Monte Carlo methods in R and Stan.²¹ Table 2 presents estimates of the BIN model

²⁰This prior is relatively uninformative. Hence, parameter estimates will largely be influenced by observed, actual group judgments.

²¹Prior to the estimation, I aligned all group judgments such that any hidden agenda points in the direction of driving group judgments up. This ensures that the estimates of bias can be consistently interpreted in relation to the direction of the hidden agenda. Positive estimates of bias indicate that

parameters and posterior probabilities. Further details on the estimation are outlined in Appendix C.1.

To structure results, I focus on two guiding questions consecutively: first, what is the likelihood of changes in accuracy that can be attributed to the mechanisms of bias, information usage, and noise? Second, what is the expected magnitude of changes in accuracy that can be attributed to each mechanism?

Table 2: Bayesian estimates of posterior inferences and BIN model parameters

	Interaction	Hidden Agendas		Interaction
Summary Statistic	FTF	FTF vs.	Delphi vs.	FTF+HA vs.
	vs. Delphi	FTF+HA	Delphi+HA	Delphi+HA
Posterior inferences				
Less bias in treatment: $\mathbb{P}(\mu_1 < \mu_0)$	0.737	0.506	0.187	0.149
Less noise in treatment: $\mathbb{P}(\delta_1 < \delta_0)$	0.997	0.598	0.75	0.993
More info in treatment: $\mathbb{P}(\gamma_0 < \gamma_1)$	0.221	0.288	0.177	0.158
Parameter estimates (with 95% CI)				
Outcome mean: μ^*	0.00	-0.01	0.00	0.00
	(-0.24; 0.23)	(-0.24; 0.23)	(-0.24; 0.23)	(-0.23; 0.23)
Bias (control): μ_0	-0.10	-0.11	-0.09	0.11
	(-0.72; 0.47)	(-0.76; 0.47)	(-0.53; 0.47)	(-0.48; 0.47)
Bias (treatment): μ_1	-0.09	0.11	0.44	0.43
	(-0.51; 0.31)	(-0.51; 0.31)	(0.09; 0.31)	(0.09; 0.31)
Diff in Bias: $ \mu_0 - \mu_1 $	0.06	0.01	-0.26	-0.18
	(-0.10; 0.29)	(-0.30; 0.29)	(-0.59; 0.29)	(-0.46; 0.29)
Information (control): γ_0	0.14	0.15	0.12	0.15
	(0.01; 0.40)	(0.01; 0.40)	(0.01; 0.40)	(0.01; 0.40)
Information (treatment): γ_1	0.10	0.12	0.07	0.07
	(0.01; 0.27)	(0.01; 0.27)	(0.00; 0.27)	(0.00; 0.27)
Diff in information: $\gamma_0 - \gamma_1$	0.05	0.03	0.05	0.08
	(-0.06; 0.17)	(-0.08; 0.17)	(-0.06; 0.17)	(-0.06; 0.17)
Noise (control): δ_0	0.94	0.96	0.29	0.83
	(0.19; 3.21)	(0.15; 3.21)	(0.01; 3.21)	(0.12; 3.21)
Noise (treatment): δ_1	0.31	0.90	0.18	0.17
	(0.02; 1.24)	(0.15; 1.24)	(0.02; 1.24)	(0.01; 1.24)
Diff in noise: $\delta_0 - \delta_1$	0.63	0.06	0.12	0.66
	(0.12; 2.10)	(-0.34; 2.10)	(-0.10; 2.10)	(0.05; 2.10)

Control: condition named on top, Treatment: condition named below CI: credible intervals

judgments are systematically distorted in the direction of hidden agendas and vice versa.

Regarding the likelihood of changes, noise is the most likely mechanism driving accuracy differences between interaction formats. By contrast, differences between incentive schemes are most likely driven by the use of valuable information and bias. Estimates of the likelihoods are presented in Table 2 in the section on posterior inferences. Posterior probabilities are the Bayesian equivalent of p-values in frequentist statistics. The larger the posterior probability, the stronger the evidence in favor of the hypothesis, and vice versa.

Comparing FTF to Delphi group judgments, Delphi group judgments exhibit less noise with very high probabilities ($\mathbb{P} > 0.99$) in situations with and without hidden agendas. One potential reason may be that Delphi group judgments constitute an average of four individual judgments. In contrast, in FTF interactions, the group judgment constitutes a consensus judgment among the four group members.

Result 8: Noise is the most likely mechanism driving accuracy differences between interaction formats. Delphi group judgments are likely less noisy than FTF group judgments.

Comparing situations without and with hidden agendas within the same interaction format, less usage of valuable information is the most likely mechanism contributing to a decline in accuracy for FTF ($\mathbb{P} = 0.712$) and even more so for Delphi groups ($\mathbb{P} = 0.823$).

For Delphi groups with hidden agendas, an increase in bias is about as likely ($\mathbb{P} = 0.813$) as a decrease in the usage of valuable information. This is not mirrored in FTF groups, which are almost equally likely to exhibit less or more bias with hidden agendas compared to situations without. This points towards robustness against bias as differentiating mechanisms that may explain why FTF group judgments do not become significantly less accurate in situations with hidden agendas, while Delphi groups do. Nevertheless, posterior probabilities for the effect of hidden agendas are far from any usual significance level used when interpreting p-values in frequentist settings. Statements on the likelihood of information usage and bias driving accuracy differences between situations with and without hidden agendas should thus be interpreted cautiously.

Result 9: Less use of valuable information is the most likely mechanism for decreasing accuracy with hidden agendas irrespective of the interaction format.

Result 10: Increased bias likely decreases accuracy for Delphi group judgments in situations with hidden agendas. FTF group judgments appear robust against this effect.

In terms of magnitudes of changes, noise emerges as the only mechanism with a clear directional effect on accuracy differences between interaction formats. Estimates of the effect sizes of bias, information usage, and noise on accuracy are presented in the lower part of Table 2. Of particular interest are estimates for the difference in bias ($|\mu_1| < |\mu_0|$), information usage ($\gamma_0 - \gamma_1$), and noise ($\delta_1 - \delta_0$).

Result 10: Noise is the only mechanism to which a clear directional effect can be attributed. FTF group judgments exhibit more noise than Delphi group judgments.

Comparing FTF to Delphi group judgments, Delphi group judgments exhibit less noise in situations without ($\delta_0 - \delta_1 = 0.63$) and with hidden agendas ($\delta_0 - \delta_1 = 0.66$). The respective 95% credible intervals around the estimates of $\delta_0 - \delta_1$ do not include zero. The effects of information usage and bias are estimated with 95% credible intervals spanning zero. Thus, I cannot identify a clear directional effect of these mechanisms in the BIN model framework.

Comparing situations without and with hidden agendas within the same interaction format, bias, information usage, and noise can not be identified with a clear directional effect. The respective 95% credible intervals around the estimates span zero.

Wide credible intervals for magnitudes of expected effects can likely be attributed to the relatively small number of judgment tasks solved per group in the estimation experiment. Satopää et al. (2021) show that the width of credible intervals decreases substantially if the number of forecasts by the same person increases. This holds especially true for relatively low numbers of forecasts (below 50). While Satopää et al. (2021) use data from the Good Judgment Project, which comprises between 87 and 191 forecasts per person, the estimation experiment yields only 10 distinct judgments per group.²²

²²Using 10 distinct judgments per group ensured implementability in a controlled lab experiment. This presents clear advantages for analyzing the causal effects of group interaction formats and incentive schemes on accuracy and trust. Conversely, experimental control has been traded off against a higher number of observations, which might have allowed more precise estimates of mechanisms driving accuracy differences in the BIN model framework.

4.5 Communication Patterns

The BIN model estimates provide a good starting point to shed light on potential mechanisms underlying accuracy differences across conditions of the estimation experiment. Yet, essential differences might not be uncovered by structural estimations alone. I analyze the degree and truthfulness of information sharing during group interaction to complement the BIN model estimations. To this end, the communication of FTF and Delphi interactions with and without hidden agendas are transcribed and coded.²³ On a high level, the communication protocols reveal that hidden agendas cause less shared, truthful information in Delphi groups but not in FTF groups.

The probabilistic judgment task of the estimation experiment is generally designed such that the more information participants, i.e., group members, share with their group, the more accurately the group can solve the task. In increasing levels of detail, group members can reveal whether their individual movement path reached the target (target), the final level of their movement path after 10 steps (level), one or more individual steps of their movement path (some steps), and most comprehensively all 10 steps of their movement path (all step). Furthermore, group members may state their information truthfully or not truthful y for each level of detail. Withholding or not stating information truthfully may be a strategy to drive group estimates up or down according to one's hidden agenda.

In Figure 9, I summarize the frequencies of not stated (no), not truthfully stated (not truthfully), and truthfully stated (truthfully) information at the previously described four levels of d tail. I estimate corresponding linear probability models to identify the significance of differences in frequencies. Estimation results are presented in Appendix D.

Focusing first on whether information is shared at all, it becomes visible that in Delphi interactions with hidden agendas, significantly more group members choose not to reveal information when compared to Delphi interactions without hidden agendas. This holds at all levels of detail. Further, with hidden agendas, the frequency of shared non-truthful information is significantly higher, and the frequency of shared truthful information is significantly lower. Again, this holds at all levels of detail. This observation is intuitively aligned with the lower accuracy of Delphi groups with hidden agendas. Not only do

²³A detailed outline of the transcription and coding procedure can be found in Appendix D.

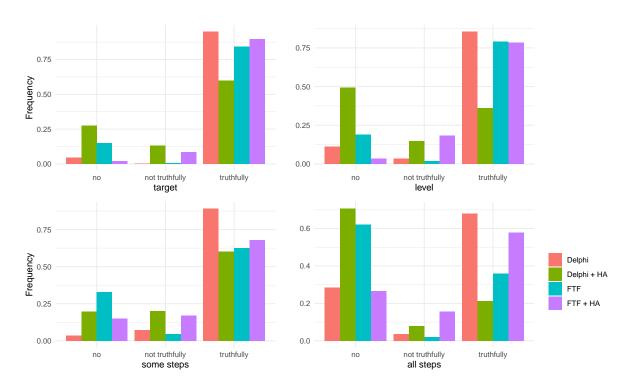


Figure 9: Revelation of information across conditions of the estimation experiment

hidden agendas lead to less information sharing, but they also decrease the truthfulness of shared information.

We see a vastly different pattern when comparing FTF groups with and without hidden agendas. With hidden agendas, significantly more group members choose to reveal information. This holds at all levels of detail. Just as for Delphi, in FTF groups with hidden agendas, the frequency of shared non-truthful information is significantly higher for all levels of detail. However, unlike Delphi, the frequency of shared truthful information is significantly higher for the target, some steps, and all steps. This observation suggests an intuitive explanation for the robust accuracy of FTF groups despite hidden agendas. While hidden agendas lead to more sharing of untruthful information, at the same time, the sharing of truthful information increases and potentially compensates for the negative effects of untruthful information sharing.

5 Conclusion and discussion

In this paper, I study whether commonly used face-to-face meetings and the scientifically supported Delphi technique are suitable interaction formats to generate and elicit accurate

and trustworthy group judgments. In particular, I consider situations where some group members have a hidden agenda, i.e., incentives to manipulate. Through two complementary experiments, I provide evidence supporting the widespread use of FTF meetings in real-world institutional decision-making. Hidden agendas are a potential threat to the accuracy and trustworthiness of group judgments. However, FTF emerges as capable of mitigating this threat. FTF interaction appears to be a resilient generalist capable of generating accurate and trusted group judgments even under adverse conditions with hidden agendas. By contrast, the Delphi technique appears to be a specialist adapted to one niche, capable of peak performance and outperforming FTF, but only without hidden agendas and only in terms of accuracy.

Using structural estimations in the Bayesian BIN model framework, I pinpoint increased bias as an accuracy-impairing mechanism that may explain differences between FTF and Delphi. While Delphi group judgments likely suffer from increased bias toward the direction of hidden agendas, FTF group judgments do not exhibit this effect. Robustness towards bias, thus, seems a relevant concern when determining and designing if and how decision-informing group judgments are generated and hidden agendas are likely. This study provides a building block of evidence from a controlled lab experiment that favors employing unstructured FTF group judgments in these situations. However, while FTF can be identified as relatively better than Delphi, it remains an open question whether unstructured FTF is the best among a wider set of interaction formats in situations with hidden agendas and whether the result holds in different contexts.

Further research may thus zoom in on identifying particular features of FTF underlying its robustness towards manipulation. This may deepen our understanding of why certain existing interaction formats work better than others, but it will ultimately also help to design new interaction formats to better extract accurate and trustworthy group judgments. To this end, the experimental setup of this study may serve as a test bed that is well suited to investigating the accuracy and trustworthiness of any group interaction format directed towards generating quantitative judgments in general. To isolate the effect of particular features of an interaction format, modifications of group interaction formats that vary by one detail at a time may be tested against each other. Furthermore, the present study investigates settings where the existence of hidden agendas is common knowledge. In institutional decision-making, however, it is more likely that one can only

suspect the presence of hidden agendas; hence, there is uncertainty about their presence. Future research could expand to such settings where hidden agendas may be present probabilistically. Beyond this, the investigation of the capabilities of group interaction to generate accurate and trustworthy judgments should also be extended to settings outside of the controlled lab environment and tested in the field. A potential stepping stone could be to investigate the presence and relevance of hidden agendas in forecasting tournaments such as the Good Judgment Project (Mellers et al., 2014).

Taken together, this study emphasizes that hidden agendas and potential manipulation matter and may harm the accuracy and trustworthiness of collective intelligence. It is vital to account for the existence of these hidden agendas to alleviate their threat to institutional decision-making. The presented evidence suggests that FTF is the preferable interaction format for generating accurate and trustworthy group judgments in situations with hidden agendas. The Delphi technique is preferable in situations without information where the accuracy of group judgments is of top priority. Practitioners involved in eliciting group judgments may refer to these results when structuring the interaction format of groups.

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A Experimental details

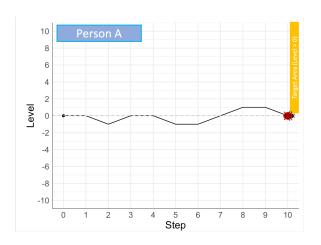
A.1 Estimation experiment

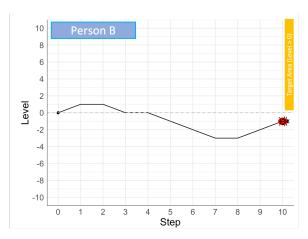
A.1.1 Judgment task

The judgment task is framed in a gamified story to ease understanding and increase the engagement of experimental participants. In particular, the movement path is framed to be generated by a computer program. Group members are told that the computer program generates the movement path of a ladybird on a map. They need to estimate the chance that the ladybird reaches the target area at the end of its path after ten steps. The chance is to be expressed in frequencies, such as 75 in 100, to facilitate better statistical reasoning (McDowell and Jacobs, 2017). As information, each sees a movement path generated by a distinct past execution of the program, compare Figure 10. For each round, group members are informed that a distinct computer program generates the movement paths, and consequently, the underlying probability of reaching the target might be different.

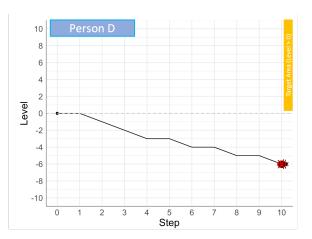
This judgment task amalgamates key features of the hidden-profile paradigm (Stasser and Titus, 1985), a benchmark task of group interaction in psychology, with additional aspects enabling more detailed analysis and broader real-world references. Common features comprise experimenter control over the information needed to solve the problem and its distribution across group members, i.e., participants resemble heterogeneous and complementary experts with the degree of expertise induced by the experiment. Consequently, the more private information is shared during group interaction, the more accuracy can be achieved in the group estimate. However, going beyond the standard hidden profile paradigm, this task incorporates uncertainty and requires probabilistic judgments. This comes with four major advantages. First, estimates can be evaluated based on a statistical measure of accuracy. Second, the statistical measure of accuracy enables incentives that continuously reward accuracy and hidden agenda achievement. Third, participants' behavior can be evaluated against theoretically optimal behavior given the information they have at hand. Finally, probabilistic judgment caters to real-world applications that go far beyond the motivating examples presented in the introduction.

Figure 10: Example of information received by group members (Person A, B, C, and D)









A.1.2 Incentives

All participants receive a show-up fee of €5 and performance-based remuneration for solving the task as accurately as possible. Additionally, to create a situation of hidden agendas, two group members can earn a supplementary individual bonus in the hidden agenda treatment arm by influencing the group's judgment in a particular direction.

For each of the ten rounds of the judgment task, all groups receive an accuracybased bonus, calculated based on the binarized quadratic scoring rule (Hossain and Okui, 2013). The group bonus is split equally among all four group members. This ensures that individuals are incentivized to pursue the most accurate group estimate irrespective of their risk preferences. Specifically, the group bonus in a given round amounts to €6 with a certain chance and €0 otherwise. The more accurate the group estimate, the greater the chance the group bonus is €6. To illustrate the calculation of the group bonus, let $Y_r \epsilon(0,1)$ be the binary event that the movement path does (not) reach the target in round r. $Y_r = 1$ if the movement path reaches the target in round r, i.e. $\sum_{t=1}^{10} X_t > 0$, and 0 otherwise. Moreover, p_r is the group estimate of the chance that the movement path reaches the target area in a particular round r. Following the binarized quadratic scoring rule, then the group bonus in round r is $\in 6$ if $Y_r = 1$ and a random number $Y \sim U(0,1) > (1-p_r)^2$ or if $Y_r = 0$ and a random number $Y \sim U(0,1) > p_r^2$.²⁴ By way of illustration, consider the true chance that the movement path reaches the target is $p^* = 0.7$, and the group estimated the chance at $p_r = 0.6$. In this case, 70% of actual realizations will reach the target, and 30% will not. Consequently, the chance of winning the group bonus is $0.7*(1-(1-0.6)^2)+0.3*(1-0.6^2)$, which is 0.7*0.84+0.3*0.64=0.78In other words, the chance of winning the group bonus is 78% in total, i.e. in expectation €4.68 group bonus or in other words €1.17 bonus per person.

In hidden agenda situations, in addition to the accuracy-based bonus, two out of four group members may each receive an **individual hidden agenda bonus** of €1.50 per round based on a binarized scoring. Their hidden agenda is to drive the group estimate to 1 or 0, i.e., up or down. Whether it is one or the other direction is determined randomly in each round. The direction of the hidden agenda is always the same for the two group members with a hidden agenda in a given round. The hidden agenda bonus is designed

²⁴The payoff relevant realizations of the movement path Y_r have been generated for all rounds r = 1, ..., 10 once before the experiment and are kept constant for all groups in the experiment.

such that it is always best for expected payoff-maximizing participants to follow their hidden agenda as much as possible. If following their hidden agenda, the decrease in the chance of earning the group bonus is overcompensated by gains in the chance of earning the individual hidden agenda bonus. Precisely, the chance of winning the hidden agenda bonus in round r is $(1-p_r)^2$ if the hidden agenda is to drive the estimate to 0, i.e., down, and p_r^2 if the hidden agenda is to drive the estimate to 1, i.e., up.

A.2 Decision experiment

A.2.1 Incentives

All participants in the decision experiment receive a show-up fee of $\in 10$ and performance-based remuneration depending on their stated confidence intervals. The latter follows the most likely interval method (Schlag and van der Weele, 2015), i.e., a stated confidence interval with lower bound L and upper bound U translates into a payment S:

$$S(L, U, p^*) = \begin{cases} 10(1 - \frac{U - L}{100}) & \text{if } 100p^* \in [L, U] \\ 0 & \text{otherwise,} \end{cases}$$
 (10)

depending on the respective true probability p^* . Note that estimates generated in the estimation experiment are naturally bounded by 0 and 100 in frequency terms. Further, the width of the stated confidence interval ranging from lower bound L to upper bound is U-L, which is at most 100. Consequently, the wider the stated confidence interval, the smaller the bonus paid in case the confidence interval contains $100p^*$, ultimately approaching 0 if the confidence interval spans the entire interval of possible values. I implement performance-based remuneration as a random lottery incentive, i.e., after participants stated their confidence intervals on all 40 estimates, one confidence interval is chosen at random for payout according to the above-mentioned most likely interval payment rule. This method is designed to encourage participants to treat each interval with equal, high care.

B Robustness checks

B.1 Accuracy

While the main analysis of accuracy focuses on absolute errors, accuracy can also be quantified using alternative metrics. Accordingly, I report test results based on squared errors (Figure 11) and Brier Scores (Figure 12). Furthermore, I report test results varying in the strictness of considering the dependence of judgments made within the same group. Two of the main results reported in Section 4 are robust in all alternative tests: First, hidden agendas decrease accuracy only for Delphi groups, and second with hidden agendas FTF groups are more accurate. Without hidden agendas, however, Delphi groups are no longer statistically more accurate than FTF groups in the robustness test, which is most strict concerning the potential dependence of observations.

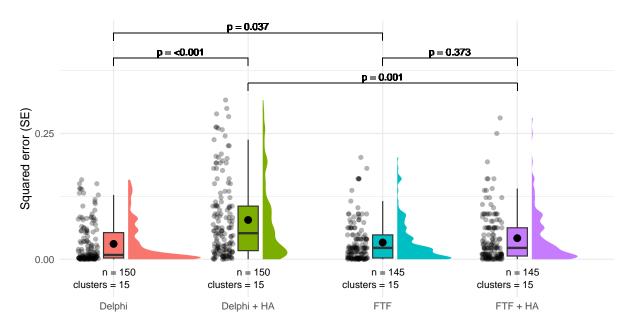


Figure 11: Squared errors of group judgments across experimental conditions

Notes: P-values from two-sided Wilcoxon rank sum tests (Rosner et al., 2003; Jiang et al., 2020). Bar in boxplot = median; dot in boxplot = mean.

Squared errors (SE), just like absolute errors juxtapose group judgments $(p_{g,r})$ to true probabilities (p_r^*) , but consider the squared difference:

$$SE_{g,r} = (p_{g,r} - p_r^*)^2 (11)$$

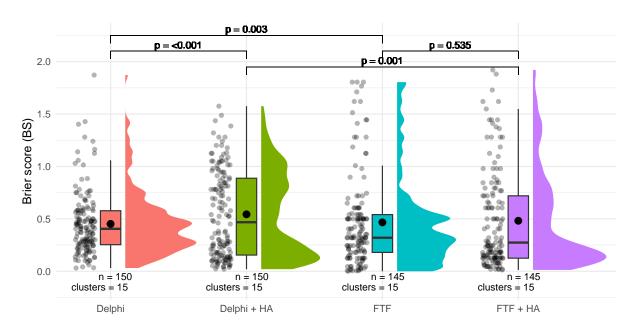


Figure 12: Brier Scores of group judgments across experimental conditions

Notes: P-values from two-sided Wilcoxon rank sum tests (Rosner et al., 2003; Jiang et al., 2020). Bar in boxplot = median; dot in boxplot = mean.

Consequently, the distribution of squared errors is narrower compared to absolute errors. However, the rank of observations remains unchanged. Therefore, test results are identical to those reported in Section 4.

Brier Scores (BS) are calculated based on group judgments $(p_{g,r})$ and actual outcomes (Y_r) , i.e., binary outcomes (0 or 1 for hit or missed target, respectively) drawn randomly according to the true underlying probabilities (p_r^*) :

$$BS_{g,r} = (Y_r - p_{g,r})^2 + ((1 - Y_r) - (1 - p_{g,r}))^2$$
(12)

Testing for differences in the distributions of Brier Scores across treatment conditions, I find the same results as with AEs and SEs. This is, however a stronger result, as Brier Scores are noisier than absolute and squared errors, which holds especially with a small number of distinct judgment tasks, like the ten different rounds in the estimation experiment. For illustration, consider that the underlying true probabilities are [0.1, 0.2, 0.3, 0.4, 0.45, 0.55, 0.6, 0.7, 0.8, 0.9] and the accordingly drawn actual outcomes, which are used to calculate Brier scores, are [0, 1, 0, 0, 1, 0, 1, 1, 1, 1].

Varying the strictness of considering the dependence of judgments made within the same group, I report results of Wilcoxon rank sum tests for average AE per group (most

Table 3: Wilcoxon rank sum tests on accuracy with different considerations of dependence of observations

	Interaction	Hidden	Interaction	
	FTF vs. Delphi	FTF vs. FTF^{HA}	Delphi vs. Delphi HA	FTF^{HA} vs. Delphi HA
Wilcoxon rank sum test on AE,	average per grou	p		
n	30	30	30	30
p-value	0.115	0.52	< 0.001	0.001
Clustered Wilcoxon rank sum to	est on AEs (Rosne	er, Glynn & Lee	2003)	
n	295	290	300	295
cluster	30	30	30	30
p-value	0.037	0.373	< 0.001	0.001

strict), in Table 3. The most strict scenario posits that groups make 10 judgments over the 10 rounds of the task, but in this way generate only one independent observation. Reporting test results only using average AE per group takes this into account. The clustered Wilcoxon rank sum tests reported in Section 4 are less strict. They actively control for the degree of dependence of observations within the same group. The most strict approach confirms the main results obtained through clustered Wilcoxon rank sum tests, except for Delphi groups being more accurate without hidden agendas. FTF and Delphi groups' accuracy becomes statistically indistinguishable in this case.

B.2 Trustworthiness

Similar to accuracy, I vary the strictness of considering the dependence of observations generated in the decision experiment. The main analysis reports results of clustered Wilcoxon signed rank tests that actively control for the dependence of confidence intervals stated by the same decision-maker. Obtained test results are robust towards considering the most strict scenario, positing that a decision-makers evaluating ten judgments from a given condition of the estimation experiment only generates one independent observation. Accounting for this, Table 4 reports results based on the average confidence interval width per decision-maker and condition in the estimation experiment.

Table 4: Wilcoxon signed rank tests on trust with different considerations of dependence of observations

	Interaction	Hidden Agendas		
	FTF vs. Delphi	FTF vs. FTF^{HA}	Delphi vs. Delphi ^{HA}	
Wilcoxon signed rank test on interval widths, av	erage per participan	t		
n	100	100	100	
test statistic	866	286.5	280	
p-value	0.028	0.001	0.001	
Clustered Wilcoxon signed rank test on interval	widths (Datta & Sat	tten 2008)		
n	1000	1000	1000	
cluster	50	50	50	
p-value	< 0.001	< 0.001	< 0.001	

C Modelling framework

C.1 BIN model estimation

The implementation of the BIN model largely follows the econometric procedures of Satopää et al. (2021). For details on these procedures, such as the underlying likelihood function, I refer the reader to the original paper and the documentation of the statistical companion package BINtools (Satopää et al., 2022). In the following, I focus on outlining adaptions to the original procedures I made to accommodate better the data from the estimation experiment of this study.

First, I exploit the fact that within my experimental design, the true probabilities for the ten distinct forecasts to be made by each group are known. In particular, each group faces judgment tasks with objectively true probabilities $\mathbb{P}(\sum_{t=1}^{10} X_t > 0) = \{0.1, 0.2, 0.3, 0.4, 0.45, 0.55, 0.6, 0.7, 0.8, 0.9\}$. With this knowledge, I can fix $\mu^* = 0$, i.e., the mean of the normal distribution from which actual true probabilities in the model are drawn. ²⁵ Second, I increase the numbers of iterations warmup and iter, and I set estimation control parameters for adapt_delta, stepsize, and max_treedepth according to

 $^{^{25}}$ The parameter is fixed in the Stan source code of the R BIN tools package by restricting $-0.01 < \mu^* < 0.01.$

Stan estimation feedback provided by BINtools. Third, I perform an iterative grid-search on the initial values of model parameters μ_0 , μ_1 , γ_0 , γ_1 , δ_0 , ρ_0 , δ_1 , ρ_1 , and ρ_{01} , to reduce the number of divergent transitions after warmup.

D Analysis of communication protocols

To analyze emergent communication patterns across conditions of the estimation experiment group and round specific transcripts were created. For Delphi groups, I extracted these from the written reasoning provided by group members alongside their first individual estimate. For FTF groups, research assistants who were unaware of the research questions underlying this paper, transcribed the video recordings of respective experimental sessions.²⁶ Subsequently, the transcripts were coded according to the coding scheme on characteristics of information sharing shown in Online Appendix E.²⁷

²⁶The research assistants used the automatically generated transcripts of the zoom video call as a starting point and corrected parts of the communication that had been incorrectly transcribed.

²⁷Coding and analysis of communication protocols according to the pregistered coding schemes on the general impression of group interaction and on quantifiable characteristics of group interaction have been postponed to future research.

Table 5: OLS estimation results for linear probability models on information revelation across conditions of the estimation experiment

	target	target_lie	target_truth	level	level_lie	level_truth
(Intercept)	0.047***	0.003	0.950***	0.112***	0.033**	0.855***
	(0.013)	(0.009)	(0.015)	(0.015)	(0.012)	(0.017)
delphi_ha	0.227***	0.127***	-0.353***	0.382***	0.113***	-0.495***
	(0.018)	(0.013)	(0.021)	(0.021)	(0.016)	(0.024)
ftf	0.103***	0.003	-0.107***	0.078***	-0.015	-0.063**
	(0.018)	(0.013)	(0.021)	(0.021)	(0.016)	(0.024)
ftf_ha	-0.027	0.082***	-0.055**	-0.078***	0.148***	-0.070**
	(0.018)	(0.013)	(0.021)	(0.021)	(0.016)	(0.024)
Num.Obs.	2400	2400	2400	2400	2400	2400

^{*} p < 0.05, ** p < 0.01, *** p < 0.001

	some_steps	some_steps_lie	some_steps_truth	all_steps	all_steps_lie	all_steps_truth
(Intercept)	0.035*	0.073***	0.892***	0.285***	0.035***	0.680***
	(0.015)	(0.013)	(0.018)	(0.019)	(0.010)	(0.019)
delphi_ha	0.162***	0.128***	-0.290***	0.422***	0.045**	-0.467***
	(0.021)	(0.019)	(0.026)	(0.027)	(0.015)	(0.027)
ftf	0.295***	-0.028	-0.267***	0.335***	-0.015	-0.320***
	(0.021)	(0.019)	(0.026)	(0.027)	(0.015)	(0.027)
ftf_ha	0.117***	0.097***	-0.213***	-0.020	0.122***	-0.102***
	(0.021)	(0.019)	(0.026)	(0.027)	(0.015)	(0.027)
Num.Obs.	2400	2400	2400	2400	2400	2400

^{*} p < 0.05, ** p < 0.01, *** p < 0.001

Notes: Each column represents a distinct dependent variable, a binary indicator of information revelation. (1) target: not revealing whether the target has been reached, (2) target_lie: misstating whether the target has been reached, (3) target_truth: correctly stating whether the target has been reached, (4) level: not revealing the final level of the movement path, (5) level_lie: misstating the final level of the movement path, (6) level_truth: correctly stating the final level of the movement path, (7) some_steps:, not revealing any particular steps of the movement path (8) some_steps_lie:, revealing one or more particular steps of the movement path, of which at least one is misstated (9) some_steps_truth: revealing one or more particular steps of the movement path, of which none is misstated, (10) all_steps: not revealing all ten particular steps of the movement path, (11) all_steps_lie: revealing all steps of the movement path, of which at least one is misstated, (12) all_steps_truth: revealing all steps of the movement path, of which none is misstated.

Online Appendix

E Coding scheme for video recordings

E.1 Preregistered coding scheme

Questions on the general impression of group interaction

- Did the group members follow a structure to discuss and generate a group estimate? (5-point Likert scale, strongly agree to strongly disagree)
 - Guidance: Did they take steps that were the same in multiple rounds? Steps could e.g., be an open discussion where everybody presents their arguments, a step where everybody presents their individual estimate, an aggregation step where individual estimates are averaged to generate a group estimate, etc.
 - Please briefly describe the structure followed by the group and the steps taken,
 if applicable. (open text)
- Please rate the overall influence of person A, B, C, and D throughout the group discussions. (5-point Likert scale, very influential to very uninfluential)
- Is there anything else you found striking about the group interaction? (open text)

Quantifiable characteristics of group interaction (coded for each of the 10 estimation rounds separately)

- Words spoken per person A, B, C, and D (extracted from automatically generated video conference transcripts)
- Number of numerical estimates uttered per person A, B, C, and D (extracted from automatically generated video conference transcripts)
 - Guidance: Numerical estimates could be in the form of frequencies, e.g. 10 in 100, the form of probabilities, e.g. 0.1, or the form of percentages, e.g. 10%.
- Number of qualitative/verbiage estimates uttered per person A, B, C, and D (extracted from automatically generated video conference transcripts)

- Guidance: Qualitative/verbiage estimates are e.g. very likely, very probable, impossible, almost certain, etc.
- Number of mentions of "hidden agendas" or "manipulation" per person A, B, C, and D (extracted from automatically generated video conference transcripts)
 - Guidance: Qualitative/verbiage estimates are e.g. very likely, very probable, impossible, almost certain, etc.
- Number of arguments uttered per person A, B, C, and D
 - Guidance: An argument usually entails a premise: e.g. My info indicates ...,
 and a conclusion: e.g. therefore I believe the chance to be ...
 - Repetitions are counted the same way as genuine arguments
- Number of confirmations uttered per person A, B, C, and D
 - Guidance: A confirmation could be: "I agree with the argument of ...", "I think the point of ... is true", etc.
- Number of confirmations from other persons received per person A, B, C, and D
 - Guidance: A confirmation could be: "I agree with the argument of ...", "I think the point of ... is true", etc.
- Number of qualifications uttered per person A, B, C, and D
 - Guidance: A qualification could be: "I do partly agree with ..., but I think ...", etc.
- Number of qualifications from other persons received per person A, B, C, and D
 - Guidance: A qualification could be: "I do partly agree with ..., but I think ...", etc.
- Number of direct rebuttals/attacks on other persons per person A, B, C, and D

- Guidance: A direct rebuttal/attack could be: "I do disagree with the argument of ...", "I think the point of ... cannot be true", etc.
- Number of direct rebuttals/attacks received per person A, B, C, and D
 - Guidance: A direct rebuttal/attack could be: "I do disagree with the argument of ...", "I think the point of ... cannot be true", etc.
- Please rate the state of agreement on the final group estimate. (5-point Likert scale, strong agreement to strong disagreement)

E.2 Coding scheme extension post data-collection

Characteristics of information sharing (coded for each of the 10 estimation rounds separately in Delphi and FTF treatments)

- Did person A, B, C and D state whether their movement path reached the target? (no, yes truthfully, yes but not truthfully)
- Did person A, B, C, and D reveal the final level of their movement path? (no, yes truthfully, yes but not truthfully)
- Did person A, B, C, and D reveal information on one or more values (-1,0,1) of individual steps of their movement path? (no, yes truthfully, yes but not truthfully)
 - Guidance: The answer is yes e.g. if person A states "The ladybird goes down in the first step ..." or "For me the last step is 0..."
- Did person A, B, C, and D reveal information on all 10 values (-1,0,1) of individual steps of their movement path truthfully? (no, yes truthfully, yes but not truthfully)
 - Guidance: The answer is yes e.g. if person B states "I have 4 ups, 3 downs and 3 straights..." or person B states "My ladybird goes -1,1,0,0,1,1,-1,0,-1,1
 ..." and this information matches the movement path seen by person in B in the given round

In cases of doubt, the following rules were applied. If there was doubt about whether a piece of information has or has not been revealed, it was considered as revealed. If there was doubt whether the revealed information was truthful or not, it was considered truthful. If the revealed information allowed to infer other information, the other information was considered revealed accordingly, e.g., a stated final level of 2 implies stating that the target has been reached.

F Experimental instructions

F.1 Estimation experiment

In the following, I provide screenshots of the estimation experiment and instructions provided to the participants. The screenshots follow the chronological order of the experiment. Where applicable, the screenshots and accompanying notes highlight differences across treatments.

F.1.1 Welcome information

Figure 13: Opening screen of the estimation experiment

Welcome to this study!



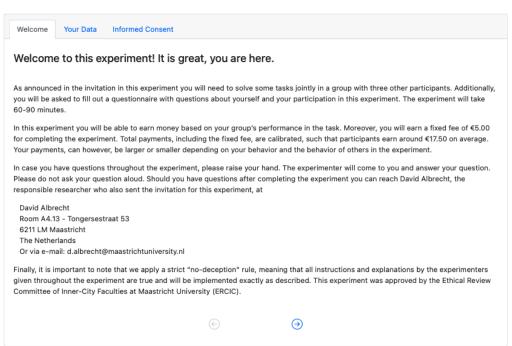
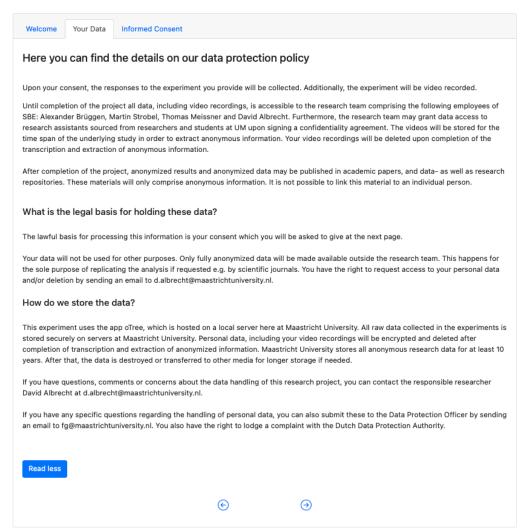


Figure 14: Information on data handling in the estimation experiment

Welcome to this study!





Notes: This screen is part of a face-to-face treatment, and participants are informed that the experiment will be video recorded. There is no video recording in the Delphi treatments, and the respective information is not displayed to participants.

Figure 15: Informed consent in the estimation experiment

Welcome to this study!



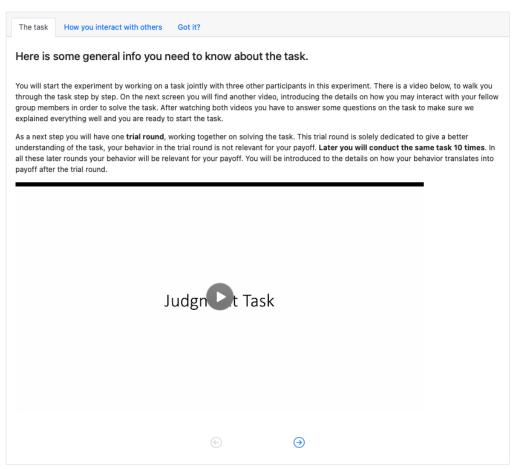


F.1.2 Introduction to the experiment

Figure 16: Introduction to the group judgment task

Introduction



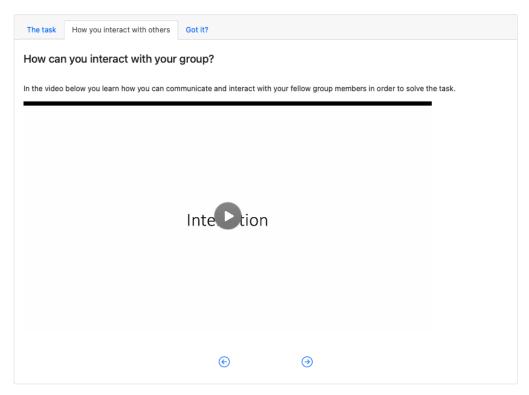


Notes: The introduction video on the judgment task can be found in the replication package.

Figure 17: Introduction to the group interaction format

Introduction





Notes: Depending on the treatment the video introduced FTF or Delphi interaction. Both respective introduction videos on the interaction format can be found in the replication package.

Figure 18: Check of understanding in FTF treatments

Introduction



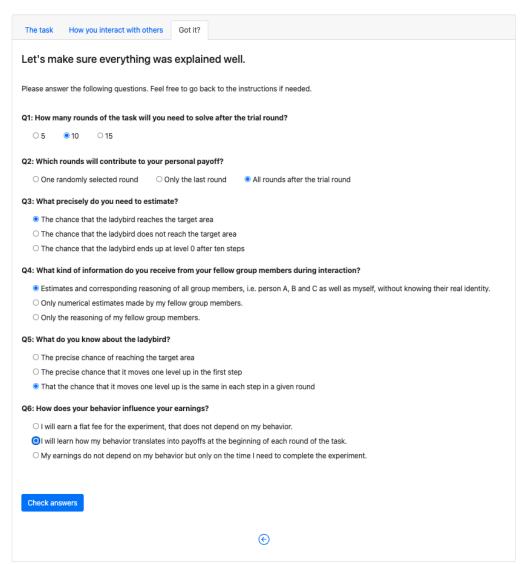
The task How you interact with others Got it?
Let's make sure everything was explained well.
Please answer the following questions. Feel free to go back to the instructions if needed.
Q1: How many rounds of the task will you need to solve after the trial round?
○ 5 ○ 10 ○ 15
Q2: Which rounds will contribute to your personal payoff?
One randomly selected round Only the last round All rounds after the trial round
Q3: What precisely do you need to estimate?
• The chance that the ladybird reaches the target area
The chance that the ladybird does not reach the target area
The chance that the ladybird ends up at level 0 after ten steps
Q4: How do you interact with your fellow group members?
⊙ Via video-conference
O Through a chat function which opens whenever we need to interact
By approaching my group members physically at their cubicle in the lab
Q5: What do you know about the ladybird?
○ The precise chance of reaching the target area
○ The precise chance that it moves one level up in the first step
• That the chance that it moves one level up is the same in each step in a given round
Q6: How does your behavior influence your earnings?
O I will earn a flat fee for the experiment, that does not depend on my behavior.
o I will learn how my behavior translates into payoffs at the beginning of each round of the task."
O My earnings do not depend on my behavior but only on the time I need to complete the experiment.
Check answers

Notes: Upon hitting the "Check answers" button, participants are informed which questions still contain incorrect answers. They can revisit the introduction videos and try to re-answer the questions. Only, after all questions are answered correctly participants may continue in the experiment. The number of attempts is recorded.

Figure 19: Check of understanding in Delphi treatments

Introduction





Notes: Upon hitting the "Check answers" button, participants are informed which questions still contain incorrect answers. They can revisit the introduction videos and try to re-answer the questions. Only, after all questions are answered correctly participants may continue in the experiment. The number of attempts is recorded.

F.1.3 Judgment task

Figure 20: Introduction / repetition of payment information in FTF treatment without hidden agendas

Time left to complete this page: 9:39 Your payoff Your info Solving the task This is how your behavior in the task translates into your payoff. Your group may earn a bonus of 6.00 for this round. The bonus will be split equally among group members, in other words you may earn et.50 for yourself. The chance of earning the group bonus depends on the accuracy of your group's estimate to the judgment task. The more accurate the larger the chance. In this way, it will always be best for your group to generate an estimate, which you believe is the most accurate given the information you have. Booles If you want to know all details about how the chance of earning the group bonus is calculated you can click here.

Figure 21: Introduction / repetition of payment information to participants without hidden agenda in FTF treatment with hidden agenda agendas

Round 1 out of 10



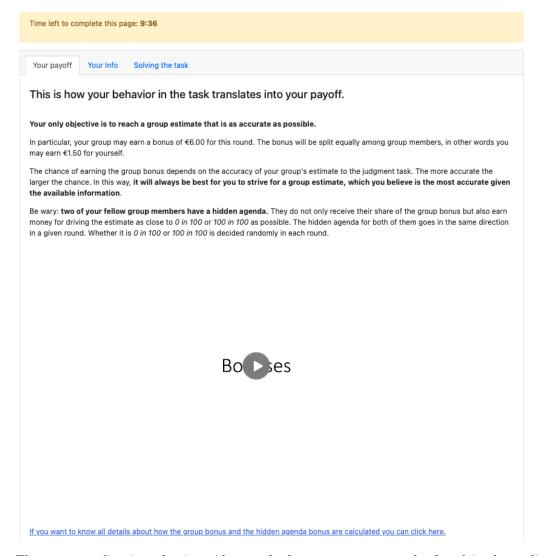


Figure 22: Introduction / repetition of payment information to participants with hidden agenda in FTF treatment with hidden agenda agendas

Round 1 out of 10



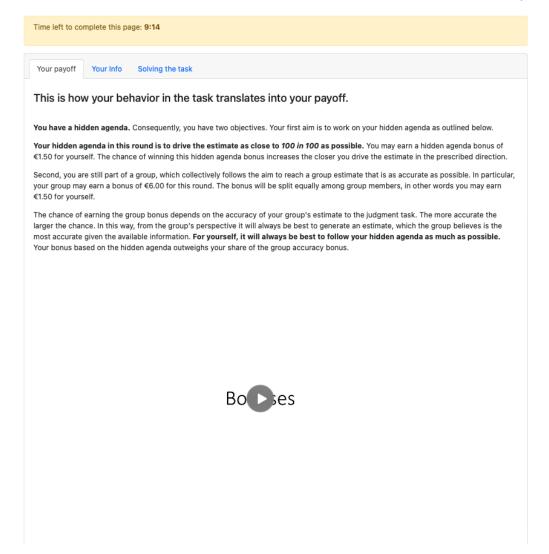


Figure 23: Introduction / repetition of payment information to participants without hidden agenda in Delphi treatment with hidden agenda agendas

Round 1 out of 10



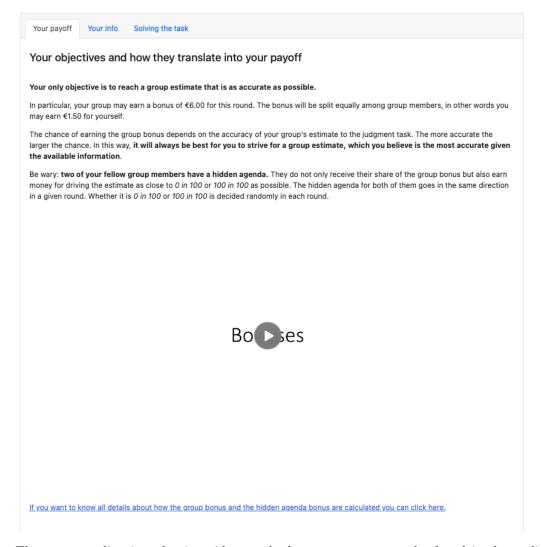
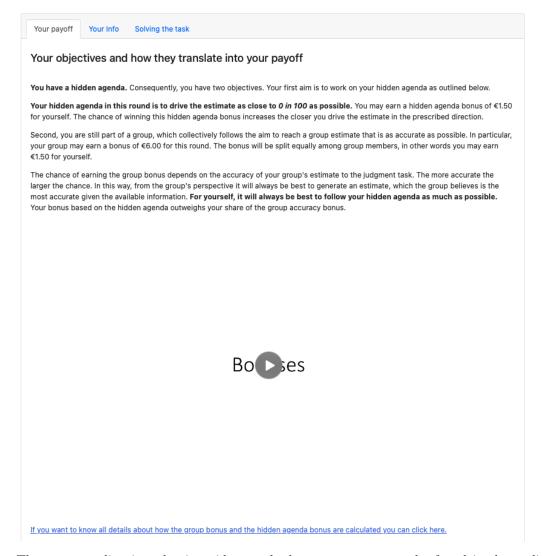


Figure 24: Introduction / repetition of payment information to participants with hidden agenda in Delphi treatment with hidden agenda agendas





Notes: The corresponding introduction video on the bonus payments can be found in the replication package.

Figure 25: Individual information on the judgment task in FTF treatments





Figure 26: Individual information on the judgment task in Delphi treatments



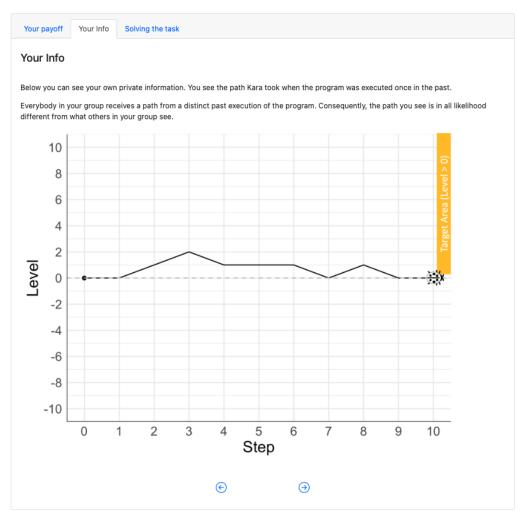
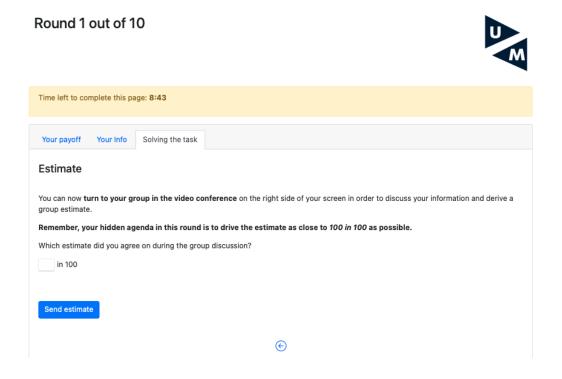


Figure 27: Input screen for group judgments in FTF treatments for participants without hidden agendas

Time left to complete this page: 9:00 Your payoff Your Info Solving the task Estimate You can now turn to your group in the video conference on the right side of your screen in order to discuss your information and derive a group estimate. Which estimate did you agree on during the group discussion? in 100 Send estimate

Figure 28: Input screen for group judgments for participants with hidden agenda in FTF treatment with hidden agendas



 $\label{thm:conditional} Figure~29:~Input~screen~for~first~individual~judgments~for~participants~without~hidden~agenda~in~Delphi~treatments$



Your payoff Your In	Solving the task
irst estimate	
	our group will give their individual estimate of the chance that Kara will reach the target area, when the program is ne. What is your estimate?
in 100	re. What is your estimate:
	may also outline your reasoning behind the estimate in a brief text. Both your estimate and the reasoning will be to your fellow group members in the next step. What is your reasoning?
esented anonymously	
esented anonymously	to your fellow group members in the next step. What is your reasoning?
esented anonymously	to your fellow group members in the next step. What is your reasoning?
esented anonymously y estimate is based or	to your fellow group members in the next step. What is your reasoning? the following line of thought
esented anonymously	to your fellow group members in the next step. What is your reasoning? the following line of thought

Figure 30: Input screen for first individual judgments for participants with hidden agenda in Delphi treatments with hidden agendas



Your payoff Your Ir	Solving the task
First estimate	
	your group will give their individual estimate of the chance that Kara will reach the target area, when the program is me. What is your estimate?
Remember, your hidde	n agenda in this round is to drive the estimate as close to 0 in 100 as possible.
in 100	
presented anonymously	may also outline your reasoning behind the estimate in a brief text. Both your estimate and the reasoning will be to your fellow group members in the next step. What is your reasoning? In the following line of thought
Send estimate and rea	soning
	€

Figure 31: Feedback screen after first individual judgments for participants without hidden agenda in Delphi treatments



Your payoff Your Info Solving the task	
Feedback and second estimate	
You and all your fellow group members completed their i	nput. Below you can see all the estimates and corresponding reasoning.
Your own input	
Estimate: 50 in 100. Reasoning: Lorem ipsum dolor sit amet, consectetur ad enim ad minim veniam, quis nostrud exercitation ullamod	piscing elit, sed do eiusmod tempor incididunt ut labore et dolore magna aliqua. Ut laboris nisi ut aliquip ex ea commodo consequat.
Input of your fellow group members	
Person A Estimate: 50 in 100. Reasoning: Duis aute irure dolor in reprehenderit in volu cupidatat non proident, sunt in culpa qui officia deserun	ptate velit esse cillum dolore eu fugiat nulla pariatur. Excepteur sint occaecat mollit anim id est laborum.
Person B Estimate: 20 in 100. Reasoning: Lorem ipsum dolor sit amet, consectetur ad	piscing elit, sed do eiusmod tempor incididunt ut labore et dolore magna aliqua.
Person C Estimate: 15 in 100. Reasoning: Pharetra vel turpis nunc eget. Arcu non sodi morbi.	ales neque sodales. Scelerisque varius morbi enim nunc. Sit amet porttitor eget dolor
Now that you have seen the estimates by the other grou What is your new estimate?	o members, and their reasoning you have the chance to revise your own estimate.
in 100	
Send estimate	
	⊙

Figure 32: Feedback screen after first individual judgments for participants with hidden agenda in Delphi treatments with hidden agendas



Your payoff Your Info	Solving the task
Feedback and sec	ond estimate
You and all your fellow grou	up members completed their input. Below you can see all the estimates and corresponding reasoning.
Your own input	
Estimate: 15 in 100. Reasoning: Pharetra vel tu morbi.	rpis nunc eget. Arcu non sodales neque sodales. Scelerisque varius morbi enim nunc. Sit amet porttitor eget dolor
Input of your fellow group	members
enim ad minim veniam, quis Person B Estimate: 50 in 100. Reasoning: Duis aute irure	lolor sit amet, consectetur adipiscing elit, sed do eiusmod tempor incididunt ut labore et dolore magna aliqua. Ut s nostrud exercitation ullamco laboris nisi ut aliquip ex ea commodo consequat. dolor in reprehenderit in voluptate velit esse cillum dolore eu fugiat nulla pariatur. Excepteur sint occaecat nt in culpa qui officia deserunt mollit anim id est laborum.
Person C Estimate: 20 in 100. Reasoning: Lorem ipsum d	lolor sit amet, consectetur adipiscing elit, sed do eiusmod tempor incididunt ut labore et dolore magna aliqua.
Now that you have seen the What is your new estimate?	e estimates by the other group members, and their reasoning you have the chance to revise your own estimate.
Remember, your hidden a	genda in this round is to drive the estimate as close to $\it 0$ in $\it 100$ as possible.
Send estimate	
	€

Figure 33: Feedback screen after second individual judgments for participants in Delphi treatments



Your payoff Your Info Solving the task
Done!
You completed round 1.
Below you can see your aggregated group estimate, and the second estimates of yourself and your fellow group members.
Please click the blue button to continue.
Aggregate group estimate
21.25 in 100
Your own estimate
0 in 100
Estimates of your fellow group members
Person A: 45 in 100 Person B: 35 in 100 Person C: 5 in 100
© Continue to next round

F.1.4 Closing survey

Figure 34: Closing survey - personal characteristics

Closing Survey



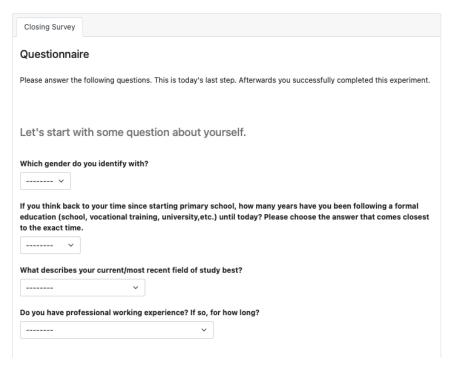


Figure 35: Closing survey - honesty module

Questionnaire
Now, please read the following statements and indicate how much you agree with each of them.
If I want something from a person I dislike, I will act very nicely toward that person in order to get it.
strongly disagree o o o strongly agree
If I knew that I could never get caught, I would be willing to steal a million euros.
strongly disagree o o o strongly agree
I wouldn't use flattery to get a raise or promotion at work, even if I thought it would succeed.
strongly disagree o o o strongly agree
I would be tempted to buy stolen property if I were financially tight.
strongly disagree OOOOO strongly agree
If I want something from someone, I will laugh at that person's worst jokes.
strongly disagree o o o strongly agree
I would never accept a bribe, even if it were very large.
strongly disagree o o o strongly agree
I wouldn't pretend to like someone just to get that person to do favors for me.
strongly disagree o o o strongly agree
I'd be tempted to use counterfeit money, if I were sure I could get away with it.
strongly disagree o o o strongly agree

Figure 36: Closing survey - experience during experiment

	aire
Finally, pleatoday's exp	ase answer some questions about the task you worked on throughout periment.
How would you	rate your own understanding of the task?
very wea	k o o o o very good
How reliable, d	o you think, are the final estimates your group produced?
very unre	eliable o o o very reliable
How satisfying	did you perceive the overall process and the interaction with your fellow group members?
very satis	sfying o o o very unsatisfying
	describe how you tried to solve the task in the experiment: aluate your information and how did you transform it into an estimate?
I used my inform	nation in the following way
What was your :	strategy for communicating your information to others?
	strategy for communicating your information to others?
I communicated	
I communicated	d in the following way
I communicated	d in the following way see the input of others into account?
How did you tak	d in the following way see the input of others into account?
How did you tak	the the input of others into account? In input of others in the following way In the input of others in the following way In the input of others in the following way In the input of others in the following way In the input of others in the following way
How did you tak I considered the	the the input of others into account? In input of others in the following way In the input of others in the following way In the input of others in the following way In the input of others in the following way In the input of others in the following way

F.2 Decision experiment

In the following I provide screenshots of the decision experiment and instructions provided to the participants. The screenshots follow the chronological order of the experiment.

F.2.1 Welcome information

Figure 37: Opening screen of the decision experiment

Welcome to this study!



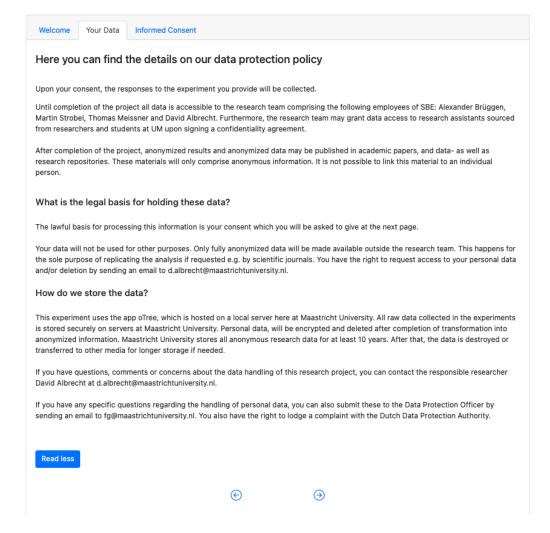


Figure 38: Information on data handling in the estimation experiment

Welcome to this study!



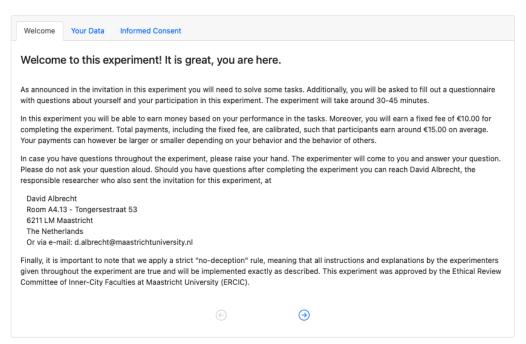
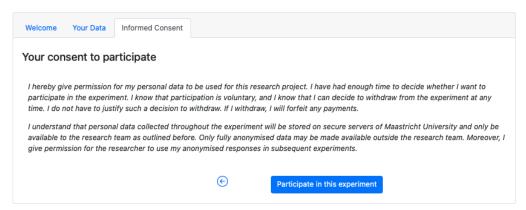


Figure 39: Informed consent in the estimation experiment

Welcome to this study!





F.2.2 Introduction to the experiment

Figure 40: Introduction to the decision task

Introduction



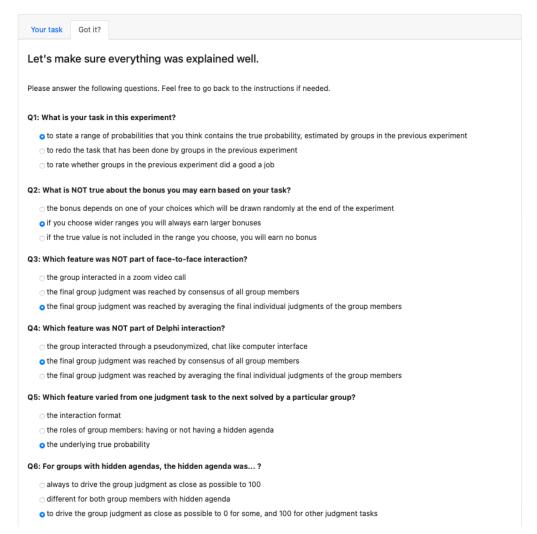


Notes: The introduction video on the decision task can be found in the replication package.

Figure 41: Check of understanding

Introduction





Notes: Upon hitting the "Check answers" button, participants are informed which questions still contain incorrect answers. They can revisit the introduction video and try to re-answer the questions. Only, after all questions are answered correctly participants may continue in the experiment. The number of attempts is recorded.

Figure 42: Prompt to ask any question that may have remained unanswered after the introduction

Questions



F.2.3 Decision task

Figure 43: Decision task screen for evaluating group judgments from FTF groups without hidden agendas



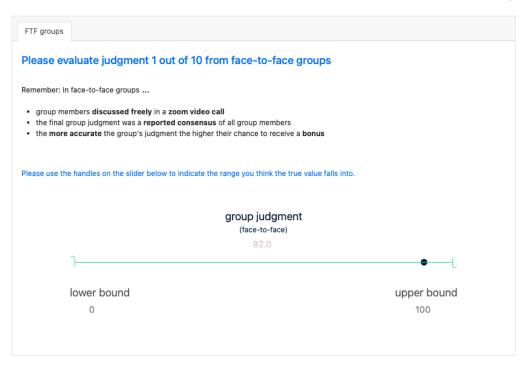


Figure 44: Decision task screen for evaluating group judgments from FTF groups with hidden agendas



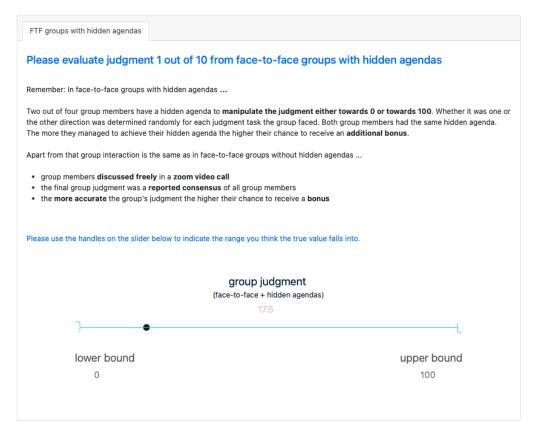


Figure 45: Decision task screen for evaluating group judgments from Delphi groups without hidden agendas





Figure 46: Decision task screen for evaluating group judgments from Delphi groups with hidden agendas





F.2.4 Closing survey

Figure 47: Closing survey - personal characteristics

Closing Survey



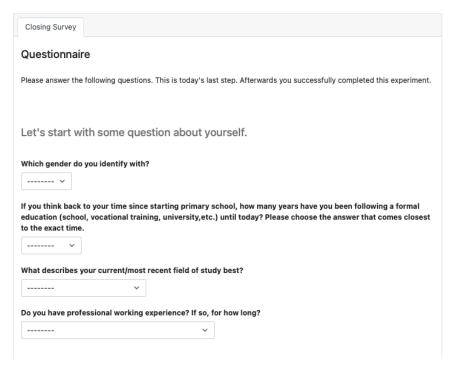


Figure 48: Closing survey - experience during experiment

Questionnaire
Now, please read the following statement and state how well it describes you as a person.
As long as I am not convinced otherwise, I assume that people have only the best intentions.
does not describe me at all
Finally, please answer some questions about the task you worked on throughout today's experiment.
How would you rate your own understanding of the task?
very weak o o o very good
Please, briefly describe how you tried to solve the task in the experiment: How did you come up with a range around the group judgments, based on the information your were given?
I used my information in the following way
Did you evaluate group judgments from groups with hidden agendas differently? How?
When hidden agendas were present
Finally, if you wanted to get the judgment of a group of people, of which some have a hidden agenda, how would you like that group to interact?
It would be great if
Once you answered all questions, please click the blue button in order to continue to the final page, where you will see
your earnings from this experiment.
Continue