

Assignment 3 - SOEN 331 Section U-UB

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Safety Critical System

The EFSM of the Safety Critical System is the tuple $S = (Q, \Sigma_1, \Sigma_2, q_0, V, \Lambda)$, where

$Q = \{\text{dormant}, \text{safe_shutdown}, \text{init}, \text{idle}, \text{monitoring}, \text{error_diagnosis}\}$

$\Sigma_1 = \{\text{kill}, \text{sleep}, \text{start}, \text{init_ok}, \text{begin_monitoring}, \text{idle_rescue}, \text{idle_crash}, \text{retry_init}, \text{monitor_crash}, \text{monitor_rescue}, \text{init_crash}, \text{shutdown}\}$

$\Sigma_2 = \{\text{broadcast idle_err_msg}, \text{retry++}, \text{broadcast moni_err_msg}, \text{broadcast init_err_msg}, \text{system clean up}\}$

$q_0 : \text{dormant}$

$V : \text{retry} : \mathbb{N}_0; \text{inlockdown} : \text{Boolean}.$

$\Lambda : \text{Transition specifications}$

1. $\rightarrow \text{dormant}$
2. $\text{dormant} \xrightarrow{\text{kill}} \text{exit}$
3. $\text{dormant} \xrightarrow{\text{start} / \text{retry} = 0} \text{init}$
4. $\text{init} \xrightarrow{\text{init_ok}} \text{idle}$
5. $\text{init} \xrightarrow{\text{init_crash} / \text{broadcast init_err_msg}} \text{error_diagnosis}$
6. $\text{idle} \xrightarrow{\text{begin_monitoring} / \text{inlockdown} = \text{false}} \text{monitoring}$
7. $\text{idle} \xrightarrow{\text{idle_crash} / \text{broadcast idle_err_msg}} \text{error_diagnosis}$
8. $\text{monitoring} \xrightarrow{\text{monitor_crash} [\text{not}(\text{inlockdown})] / \text{broadcast moni_err_msg}} \text{error_diagnosis}$
9. $\text{error_diagnosis} \xrightarrow{\text{retry_init} [\text{retry} < 3] / \text{retry++}} \text{init}$
10. $\text{error_diagnosis} \xrightarrow{\text{idle_rescue}} \text{idle}$
11. $\text{error_diagnosis} \xrightarrow{\text{moni_rescue}} \text{monitoring}$
12. $\text{error_diagnosis} \xrightarrow{\text{shutdown} [\text{retry} \geq 3] / \text{system clean up}} \text{safe_shutdown}$
13. $\text{safe_shutdown} \xrightarrow{\text{sleep}} \text{dormant}$

init

The EFSM of the init state is the tuple $S = (Q, \Sigma_1, \Sigma_2, q_0, V, \Lambda)$, where

$Q = \{\text{boot_hw}, \text{senchk}, \text{tchk}, \text{psichk}, \text{ready}\}$

$\Sigma_1 = \{\text{hw_ok}, \text{senok}, \text{t_ok}, \text{psi_ok}\}$

$\Sigma_2 = \{\}$

$q_0 : \text{boot_hw}$

$V = \{\}$

Λ : Transition specifications

1. $\rightarrow \text{boot_hw}$
2. $\text{boot_hw} \xrightarrow{\text{hw_ok}} \text{senchk}$
3. $\text{senchk} \xrightarrow{\text{sen_ok}} \text{tchk}$
4. $\text{tchk} \xrightarrow{\text{t_ok}} \text{psichk}$
5. $\text{psichk} \xrightarrow{\text{psi_ok}} \text{ready}$

lockdown

The EFSM of the lockdown state is the tuple $S = (Q, \Sigma_1, \Sigma_2, q_0, V, \Lambda)$, where

$Q = \{\text{prep_vpurge}, \text{alt_temp}, \text{alt_psi}, \text{risk_assess}, \text{safe_status}\}$

$\Sigma_1 = \{\text{initiate_purge}, \text{tcyc_comp}, \text{psicyc_comp}\}$

$\Sigma_2 = \{\text{lock_doors}, \text{unlock_doors}\}$

$q_0 : \text{prep_vpurge}$

$V : \text{risk: percentage}$

Λ : Transition specifications

1. $\rightarrow \text{prep_vpurge}$
2. $\text{prep_vpurge} \xrightarrow{\text{initiate_purge/lock_doors}} \text{alt_temp}$
3. $\text{prep_vpurge} \xrightarrow{\text{initiate_purge/lock_doors}} \text{alt_psi}$
4. $\text{alt_temp} \xrightarrow{\text{tcyc_comp}} \text{risk_assess}$
5. $\text{alt_psi} \xrightarrow{\text{psicyc_comp}} \text{risk_assess}$
6. $\text{risk_assess} \xrightarrow{[\text{risk} \geq 1\%]} \text{prep_vpurge}$
7. $\text{risk_assess} \xrightarrow{[\text{risk} < 1\%]} \text{safe_status}$
8. $\text{safe_status} \rightarrow \text{exit}$

error_diagnosis

The EFSM of the error_diagnosis state is the tuple $S = (Q, \Sigma_1, \Sigma_2, q_0, V, \Lambda)$, where

$Q = \{\text{error_rcv}, \text{applicable_rescue}, \text{reset_module_data}\}$

$\Sigma_1 = \{\text{apply_protocol_rescues}, \text{reset_to_stable}\}$

$\Sigma_2 = \{\}$

$q_0 : \text{error_rcv}$

$V : \text{err_protocol_def} : \text{Boolean}$

$\Lambda : \text{Transition specifications}$

1. $\rightarrow \text{error_rcv}$
2. $\text{error_rcv} \xrightarrow{[\text{err_protocol_def}]} \text{applicable_rescue}$
3. $\text{error_rcv} \xrightarrow{[\text{err_protocol_def}]} \text{reset_module_data}$
4. $\text{reset_module_data} \xrightarrow{\text{reset_to_stable}} \text{exit}$
5. $\text{applicable_rescue} \xrightarrow{\text{apply_protocol_rescues}} \text{exit}$

monitoring

The EFSM of the monitoring state is the tuple $S = (Q, \Sigma_1, \Sigma_2, q_0, V, \Lambda)$, where

$Q = \{\text{monidle}, \text{regulate_environment}, \text{lockdown}\}$

$\Sigma_1 = \{\text{no_contagion}, \text{after_100ms}, \text{purge_succ}, \text{contagion_alert}\}$

$\Sigma_2 = \{\text{inlockdown} = \text{false}, \text{broadcast FACILITY_CRIT_MMSG and inlockdown} = \text{true}\}$

$q_0 : \text{monidle}$

$V = \{\}$

$\Lambda : \text{Transition specifications}$

1. $\text{monidle} \xrightarrow{\text{no_contagion}} \text{regulate_environment}$
2. $\text{monidle} \xrightarrow{\text{contagion_alert} / \text{broadcast FACILITY_CRIT_MMSG and inlockdown} = \text{true}} \text{lockdown}$
3. $\text{regulate_environment} \xrightarrow{\text{after_100ms}} \text{monidle}$
4. $\text{lockdown} \xrightarrow{\text{purge_succ} / \text{inlockdown} = \text{false}} \text{monidle}$