

Assume we have a curve

\mathbf{x} is a point in \mathbb{R}^2 or \mathbb{R}^3

$\mathbf{x}(t)$ is a function (i.e. a parametric description)

$$\mathbf{x}(t) : \mathbb{R} \rightarrow \mathbb{R}^d$$

t \mathbf{x} \mathbf{x}
 Dom Range
 Domain Range

A curve is the set of points mapped to by a parametric function from $\mathbb{R}^2 - \text{CoDom } \mathbf{x}$

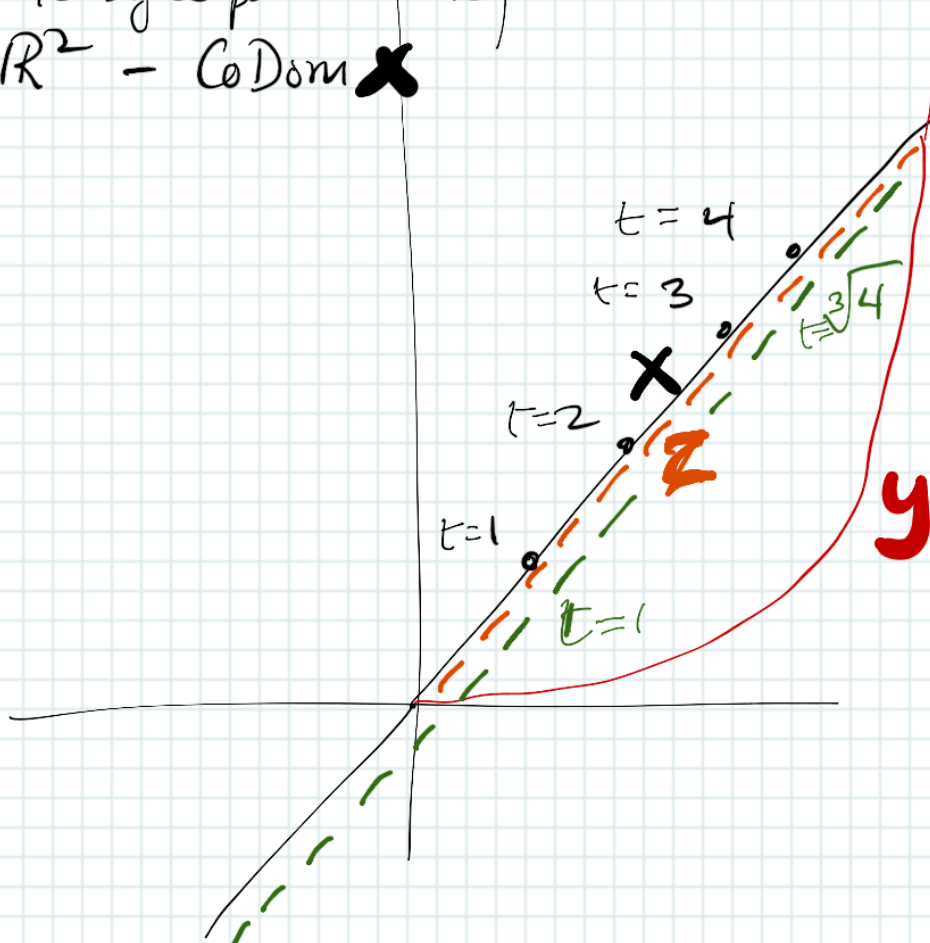
$$\mathbf{x}(t) = (t, t)$$

$$\mathbf{x}(t)$$

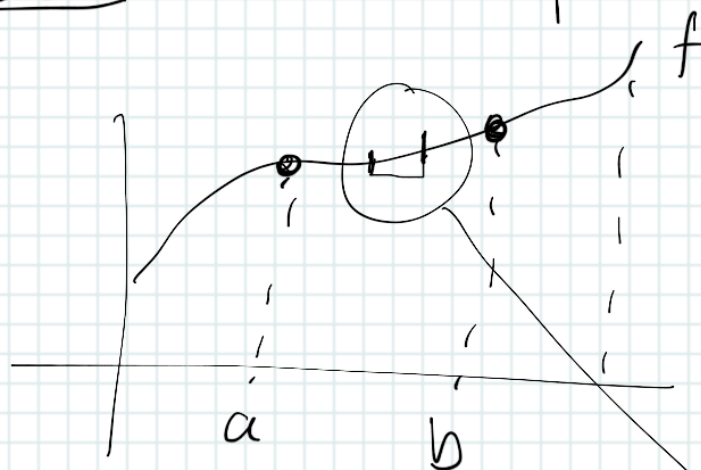
$$\mathbf{y}(t) = (t, t^2)$$

$$\mathbf{z}(t) = (t^2, t^2)$$

$$\mathbf{w}(t) = (t^3, t^3)$$



Problem: Which description should we use for a curve?



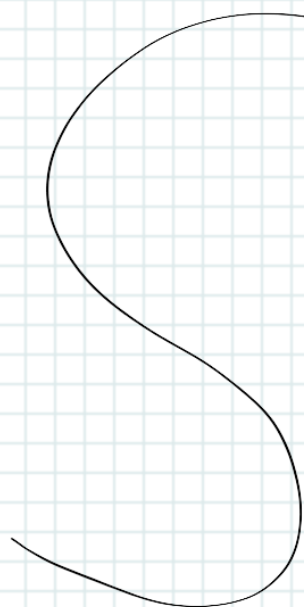
$$\text{Length} = \int_a^b \sqrt{1 + f'(x)^2} dx$$



$$\frac{h}{\Delta x} = \frac{\text{rise}}{\text{run}} = f'(x)$$

$$h = f'(x) \cdot \Delta x$$

$$d = \sqrt{\Delta x^2 + (f'(x) \Delta x)^2} \\ = \Delta x \sqrt{1 + f'(x)^2}$$



Rewrite $f(x)$ as $(t, f(t))$

$$\mathbf{f}(t) = (t, f(t))$$

& Then it's parameterized & I'm OK

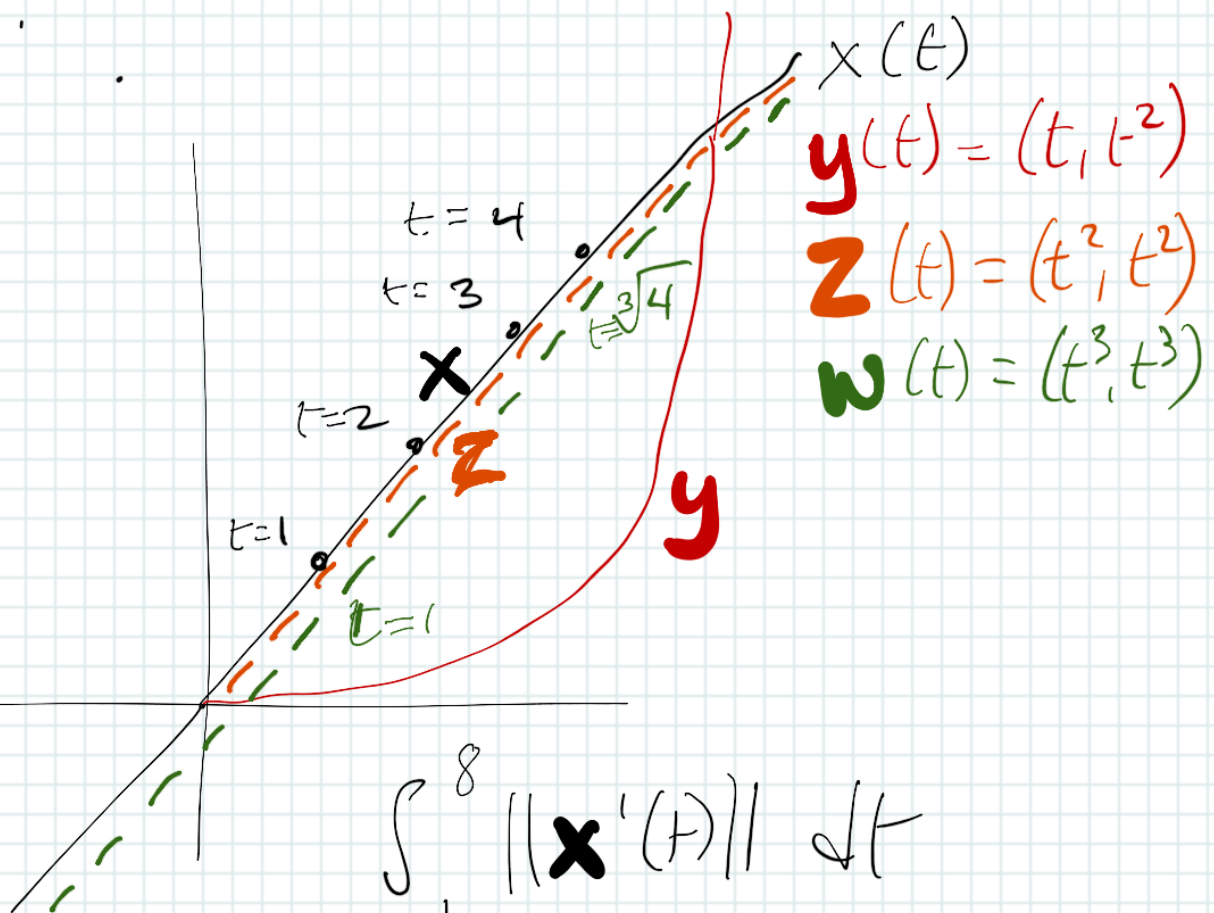
Consider $\frac{d}{dt} \mathbf{f}'(t) = (1, f'(t))$

velocity is $\mathbf{f}'(t)$, speed is $\|\mathbf{f}'(t)\|$

aka direction vector of the curve

distance travelled (length) = $\int_a^b \|\mathbf{f}'(t)\| dt$

$$\mathbf{x}(t) = (t, t)$$



$$\mathbf{y}(t) = (t, t^2)$$

$$\mathbf{z}(t) = (t^2, t^2)$$

$$\mathbf{w}(t) = (t^3, t^3)$$

$$\int_1^8 \|\mathbf{x}'(t)\| dt$$

$$= \int_1^8 \|(1, 1)\| dt$$

$$= \int_1^8 \sqrt{2} dt$$

$$= \sqrt{2}t \Big|_1^8 = 7\sqrt{2}$$

length is independent
of parameterization

$$\int_1^2 \|\mathbf{w}'(t)\| dt$$

$$= \int_1^2 \|(3t^2, 3t^2)\| dt$$

$$= \int_1^2 3\sqrt{2}t^2 dt$$

$$= \sqrt{2}t^3 \Big|_1^2 = 7\sqrt{2}$$

Define the arc-length parameterization of a curve (ALP) to be the parameterization where the arc length is the parameter, i.e. given

$$s(u) = \int_a^u \|X'(t)\| dt$$

\nwarrow the t -value where $u=0$

u is our new AL parameter

define $\mathbf{x}(s)$ to be the ALP s.t.

$$\int_a^s \|\mathbf{x}'(t)\| dt = s$$

i.e. the arc-length under ALP gives your parameter back.

In general, an ALP exists, but may be hard to construct.

The ALP is the parameterization of the curve where your speed is a constant of 1

i.e. $\|\mathbf{x}'(s)\| = 1$ unit direction vector
unit tangent vector

$$\|\mathbf{x}'(s)\| = \sqrt{\mathbf{x}'(s) \cdot \mathbf{x}'(s)} = 1$$

$$\mathbf{x}'(s) \cdot \mathbf{x}'(s) = 1$$

$$\mathbf{x}''(s) \cdot \mathbf{x}'(s) + \mathbf{x}'(s) \cdot \mathbf{x}''(s) = 0$$

Product Rule
 $(fg)' = f'g + g'f$

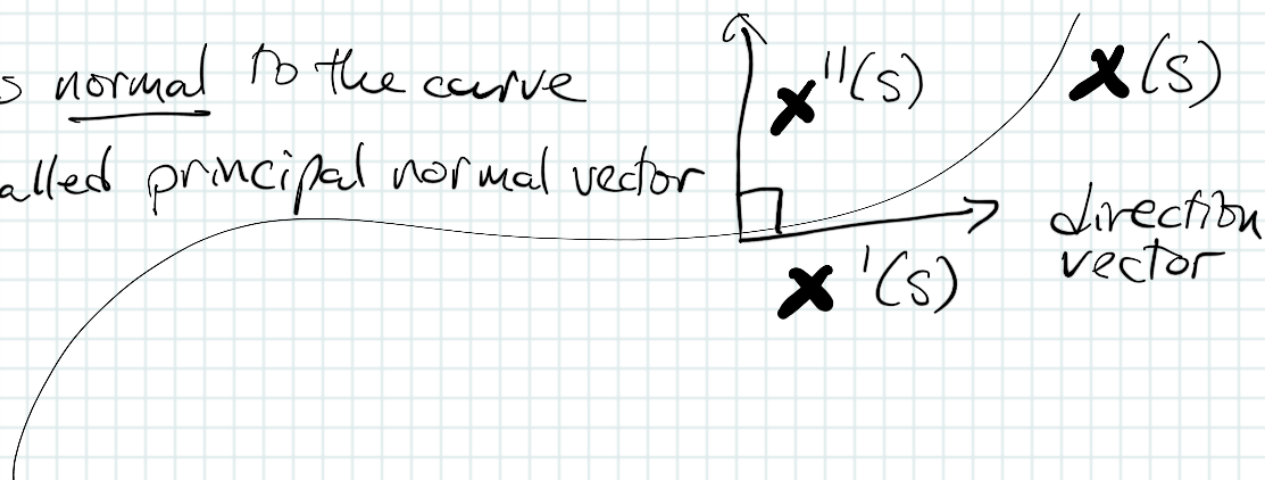
OR

$$\cancel{x''(s) \cdot x'(s)} = 0$$

$$x''(s) \perp x'(s)$$

$x''(s)$ is normal to the curve

& is called principal normal vector



$x(s)$ arc length parameterization

$x'(s)$ direction vector

$x''(s)$ principal normal vector

Can we have $\|x''(s)\| = 0$?

Consider $v(t) = (\frac{1}{\sqrt{2}}t, \frac{1}{\sqrt{2}}t)$ the ALP of $y=x$

$$v(s) = (\frac{1}{\sqrt{2}}s, \frac{1}{\sqrt{2}}s)$$

$$v'(s) = (\frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}})$$

$$v''(s) = (0, 0)$$

as required

When is $\|\mathbf{x}''(s)\| = 1$?

p.5

$$\text{let } \mathbf{x}(s) = (\sin s, \cos s) \quad \|\mathbf{x}(s)\| = 1$$

$$\mathbf{x}'(s) = (\cos s, -\sin s) \quad \|\mathbf{x}'(s)\| = 1$$

$$\mathbf{x}''(s) = (-\sin s, -\cos s) \quad \|\mathbf{x}''(s)\| = 1$$

A circle has a constant length p.n.v. of 1 p

How about a circle of radius 2?

The magnitude of the p.n.v. $\mathbf{x}''(s)$ is the radius of the tangent circle at s , and is known as the curvature

$$\text{if you have } \mathbf{x}(t), \quad \mathbf{x}'(s) = \frac{\mathbf{x}'(t)}{\|\mathbf{x}'(t)\|}$$

you can find $\mathbf{x}''(t)$

if we do have ALP, then take $\mathbf{n} = \mathbf{x}'(s) \times \mathbf{x}''(s)$
normalize them & you get a coord. system or frame
in particular, the Frenet frame for every point on the curve

$$\text{if we have } \mathbf{x}(t), \quad \text{take } \mathbf{n} = \mathbf{x}'(t) \times \mathbf{x}''(t)$$

$$\frac{\mathbf{x}''(s)}{\|\mathbf{x}''(s)\|} = \frac{\mathbf{n}}{\|\mathbf{n}\|} \times \frac{\mathbf{x}'(t)}{\|\mathbf{x}'(t)\|}$$