01: Functions & Calculus

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- Manifolds
- Differentiation
- Integration
- Calculus of Multiple Variables
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Functions

- Also known as maps
- Define a relationship between two sets
 - Domain
 - Range (aka Codomain)
- Given a value in the domain
- Assign a value in the range



Notation

• Most general:

$$f:Dom f \rightarrow Ran f$$

• More specific:

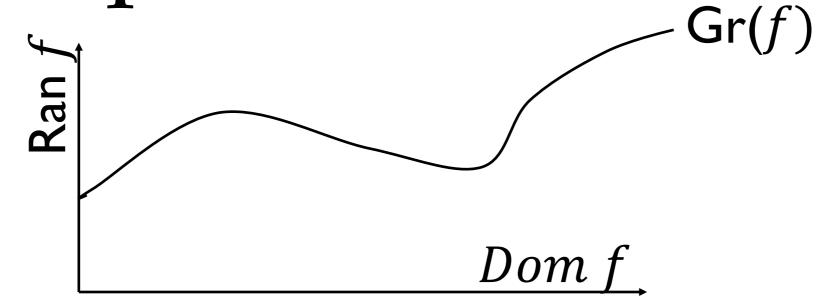
$$f \colon \mathbb{R} \to \mathbb{R}$$

• Explicit:

$$f(x) = x^{20} + \sin x$$



Graph of a Function



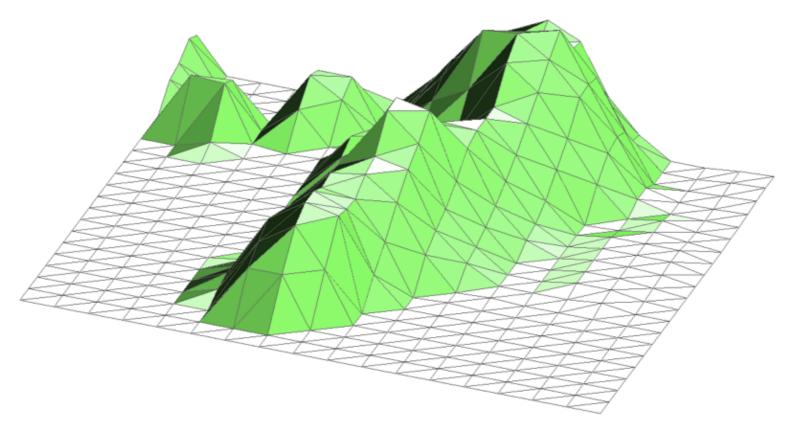
$$Gr(f) = \{(x, y) : x \in Dom f, y = f(x) \in Ran f\}$$

- Set of points defined by the function
- Notice we are now in 2-D
- The embedding space of the graph



 $f: \mathbb{R}^2 \to \mathbb{R}$:

Height Field

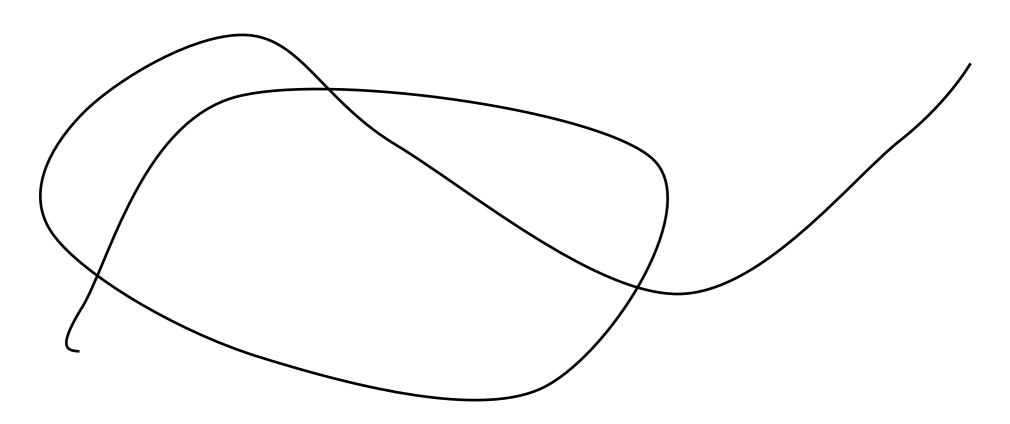


- For every point in the plane, define a height
- The graph is then a terrain
 - i.e. a surface in a 3D embedding space



 $f: \mathbb{R} \to \mathbb{R}^2$:

Planar Curve



- Also known as a parametric curve
- Assigns (x,y) coordinates to each t value
- Can self-intersect, &c.



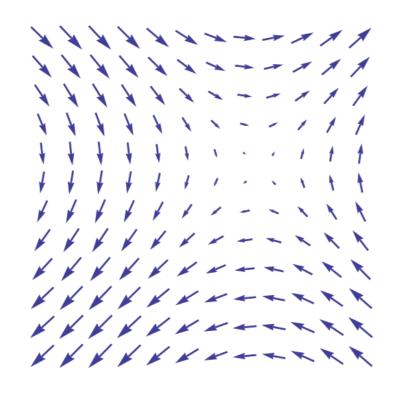
$$f: \mathbb{R} \to \mathbb{R}^3$$
:

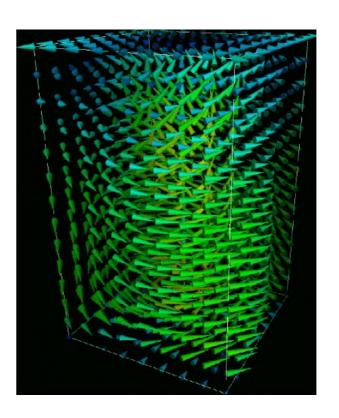
Space Curve

$$Helix = \left\{ \left(\cos t, \sin t, t\right) : 0 \le t \le \frac{5}{2}\pi \right\}$$



Vector Fields





- Fields whose output is a vector
- Range has same dimension as domain
- And there is added semantic meaning
- Frequently represents flow



Manifolds

- Generalisation of the idea of surfaces
- Sets that are *locally* equivalent to surfaces
- Defined for any dimension
 - 1-manifold a curve
 - 2-manifold a surface
 - 3-manifold a volume
- Always exist in an embedding space



Differential Calculus

- The *derivative* of a function
- Represents the *slope* of a function
 - Rate of change of f with respect to x
- Notation: f'(x) or $\frac{df}{dx}$ Definition: $f'(x) = \lim_{h \to 0} \frac{f(x+h) f(x)}{h}$
- Can be used to construct graph of function



Rules of Differentiation

- Constant:
- Addition:
- Multiplication:
- Power Rule:

- $\frac{d}{dx}c = 0$
- $\frac{\frac{d}{dx}}{\frac{d}{dx}}(f+g) = \frac{df}{dx} + \frac{dg}{dx}$ $\frac{\frac{d}{dx}}{\frac{d}{dx}}cf = c\frac{df}{dx}$ $\frac{\frac{d}{dx}}{\frac{d}{dx}}x^n = nx^{n-1}$

- Polynomials are easy:



More Rules

- Trigonometry:
- Exponential:
- Logarithmic:
- Product Rule:
- Quotient Rule:
- Chain Rule:

$$\frac{d}{dx}\sin x = \cos x, \&c.$$

$$\frac{\frac{dx}{dx}}{dx}e^{x} = e^{x}x$$

$$\frac{\frac{d}{dx}\ln x = \frac{1}{x}$$

$$(fg)' = f'g + g'f$$

$$\left(\frac{f}{g}\right)' = \frac{f'g - g'f}{g^2}$$

$$(f(g))' = f'(g)g'$$



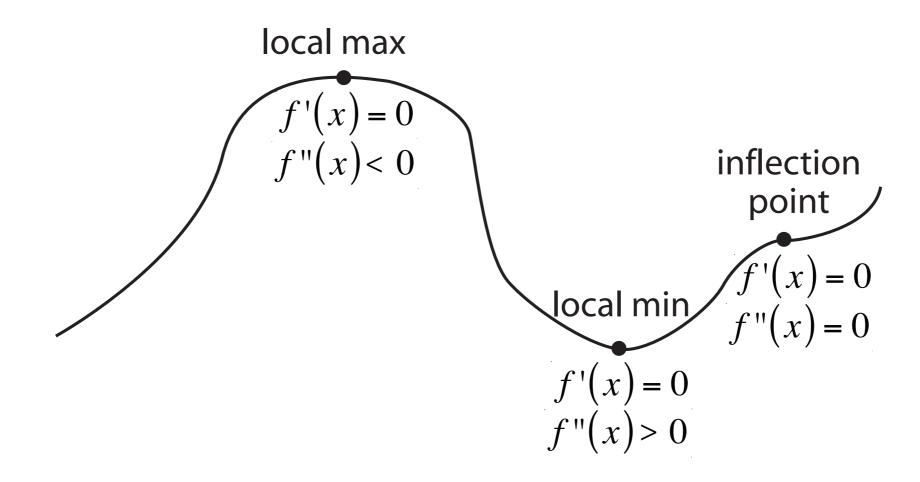
Higher Derivatives

• Notation: $f''(x), f'''(x), f^{(4)}(x), f^{(n)}(x)$ • Or: $\frac{d^2f}{dx^2}, \frac{d^3f}{dx^3}, \frac{d^4f}{dx^4}, \frac{d^nf}{dx^n}$

Obtained by repeated differentiation



Sketching A Function



- Partition graph into segments
- Defined by roots of derivatives

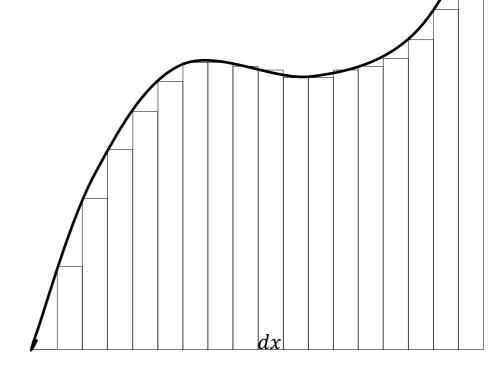


Integral Calculus

- The *integral* of a function
- Represents the area under a curve
- Notation:

$$\int_{a}^{b} f(x)dx = \lim_{n \to \infty} \sum_{i=0}^{n} f(x_{i})\delta x$$
$$x_{i} = a + i\delta x$$
$$\delta x = (b - a)/n$$





$$\frac{d}{dx} \int f(x) dx = f(x)$$



Rules of Integration

• Addition:

$$\int f + g \, dx = \int f dx + \int g \, dx$$

- Multiplication:
 - $\int a f(x) dx = a \int f(x) dx$

• Power Rule:

$$\int x^n dx = \frac{x^{n+1}}{n+1} + c$$

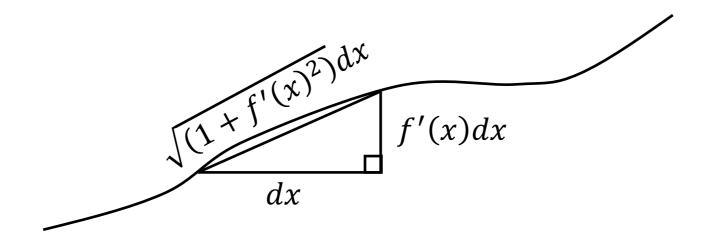
Polynomials:

$$\int 7x^3 + x^2 - 7dx = \frac{7}{4}x^4 + \frac{1}{3}x^3 - 7x + c$$

- Not all functions are easily integrated
 - Including most of the ones we want



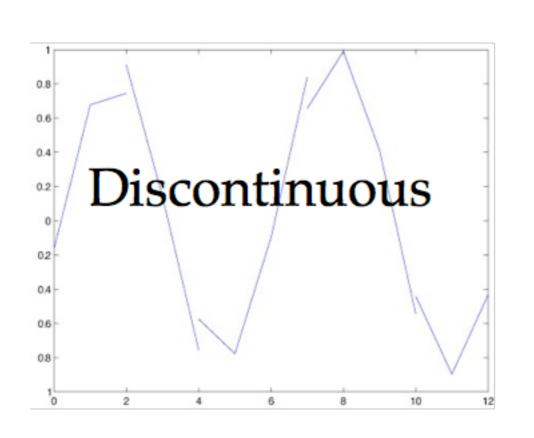
Arc-length Integral

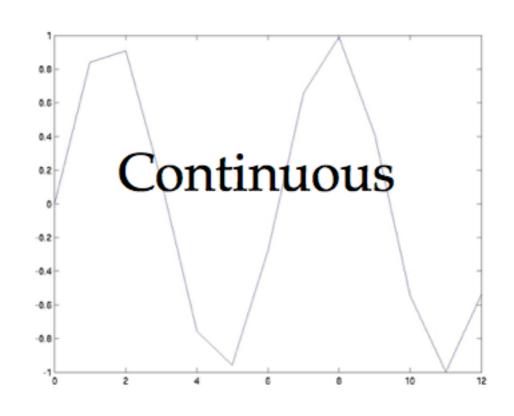


- Computes the length of a curve
 - $\bullet \int_a^b \sqrt{(1+f'(x)^2)} \, dx$
 - Derivative measures distortion
 - i.e. difference between curve & domain



Continuity





• A function f(x) is continuous at a if:

$$\lim_{x \to a^{-}} f(x) = f(a) = \lim_{x \to a^{+}} f(x)$$

Also known as C⁰ continuous



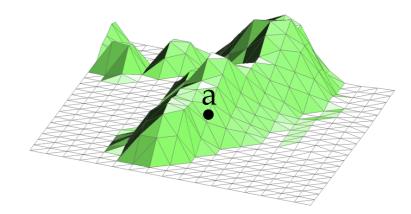
Higher-D Continuity

- We extend the idea of the limit
- The function is the same from any direction
- This leads to epsilon-delta proofs
- For our purposes, it generalises



Generalising Limits

- For $f: \mathbb{R} \to \mathbb{R}$, limits were left or right:
 - $\lim_{x \to a^{-}} f(x), \lim_{x \to a^{+}} f(x)$
- What about $f: \mathbb{R}^2 \to \mathbb{R}$?



- What does "left" or "right" mean?
- Hmm, let's take a step back
 - And have another look at $f: \mathbb{R} \to \mathbb{R}$

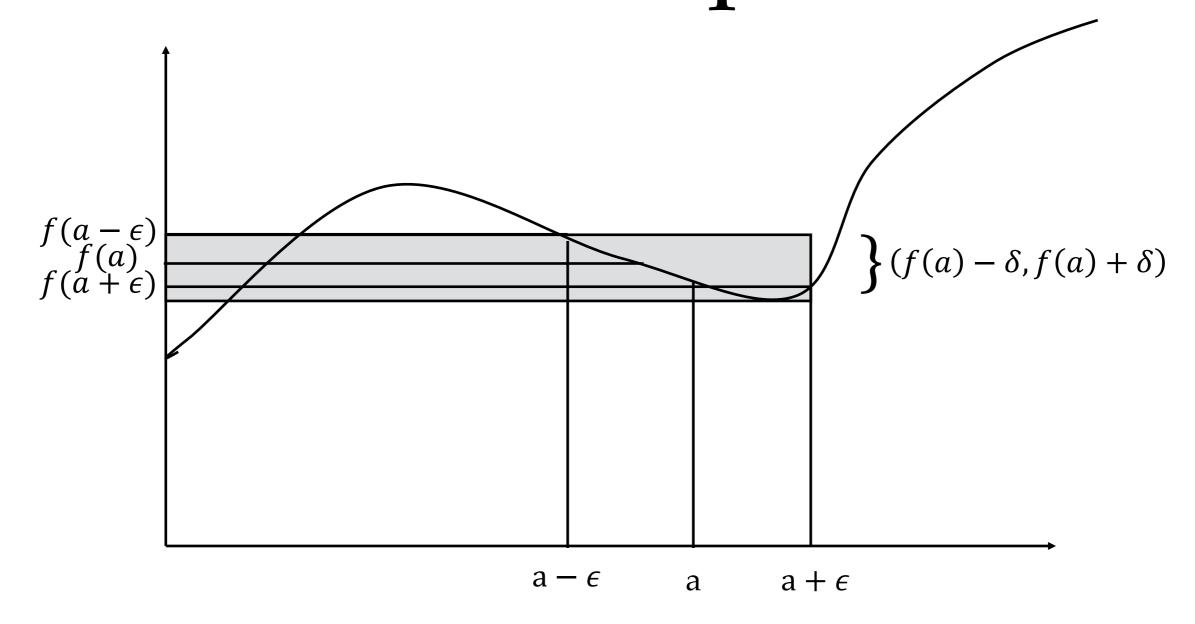


Epsilon Notation

- Limits are *really* about getting close to a point
- So why don't we pick how close
- And rewrite it in terms of the distance in x?
 - $\lim_{x \to a^+} f(x) = \lim_{\epsilon \to 0^+} f(a + \epsilon)$
- Now we can express both sides at once:
 - $\lim_{x \to a} f(x) = \lim_{\epsilon \to 0} f(a + \epsilon)$



An Example



An interval in x ($a - \epsilon, a + \epsilon$) maps to an interval in ybut not necessarily ($f(a - \epsilon), f(a + \epsilon)$)



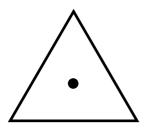
Epsilon-Delta Proofs

- Mathematicians can now generalise
 - You pick the desired $\delta > 0$
 - I choose a suitable $\epsilon > 0$
 - So that if $x \in (a \epsilon, a + \epsilon)$
 - I guarantee $f(x) \in (f(a) \delta, f(a) + \delta)$
- And this formalises "f(x) gets close to f(a)"
 - But in an entirely different way



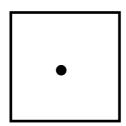
Generalising the Interval

- But how do we do this in 2-D?
- We generalise the idea of an interval first
- But which of the following is best?



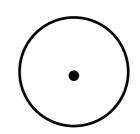
Triangle: Simplest Polygon

$$\alpha A + \beta B + \gamma C$$
, $\alpha, \beta, \gamma \in (0,1)$



Square: Product of Intervals

$$[a_{x} - \epsilon, a_{x} + \epsilon] \times [a_{y} - \epsilon, a_{y} + \epsilon]$$



Circle:
Defined
by Distance

 $\{x: dist(x, a) \le \epsilon\}$



The Neighbourhood

- Epsilon-delta proofs use a circle
 - You pick the desired $\delta > 0$
 - I construct a desired $\epsilon > 0$
 - So that if $dist(x, a) < \epsilon$
 - I guarantee $f(x) \in (f(a) \delta, f(a) + \delta)$
- More generally, we use a neighbourhood
- An arbitrary small open set near a point

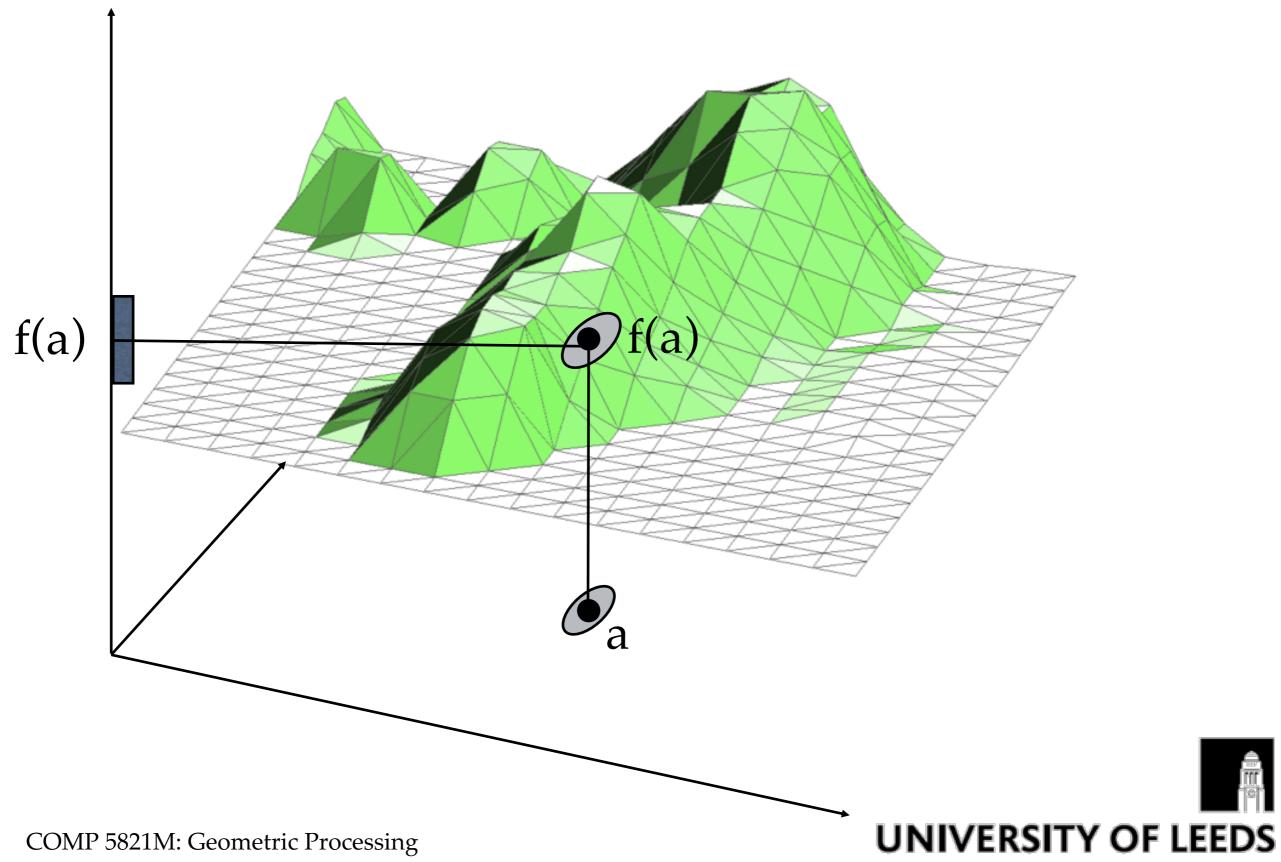


What does this Mean?

- Well, we needed limits to build calculus
- Limits express how "close" we are
- Which we are *always* interested in
- We can extend calculus to more dimensions
 - Using epsilon-delta proofs



An Example



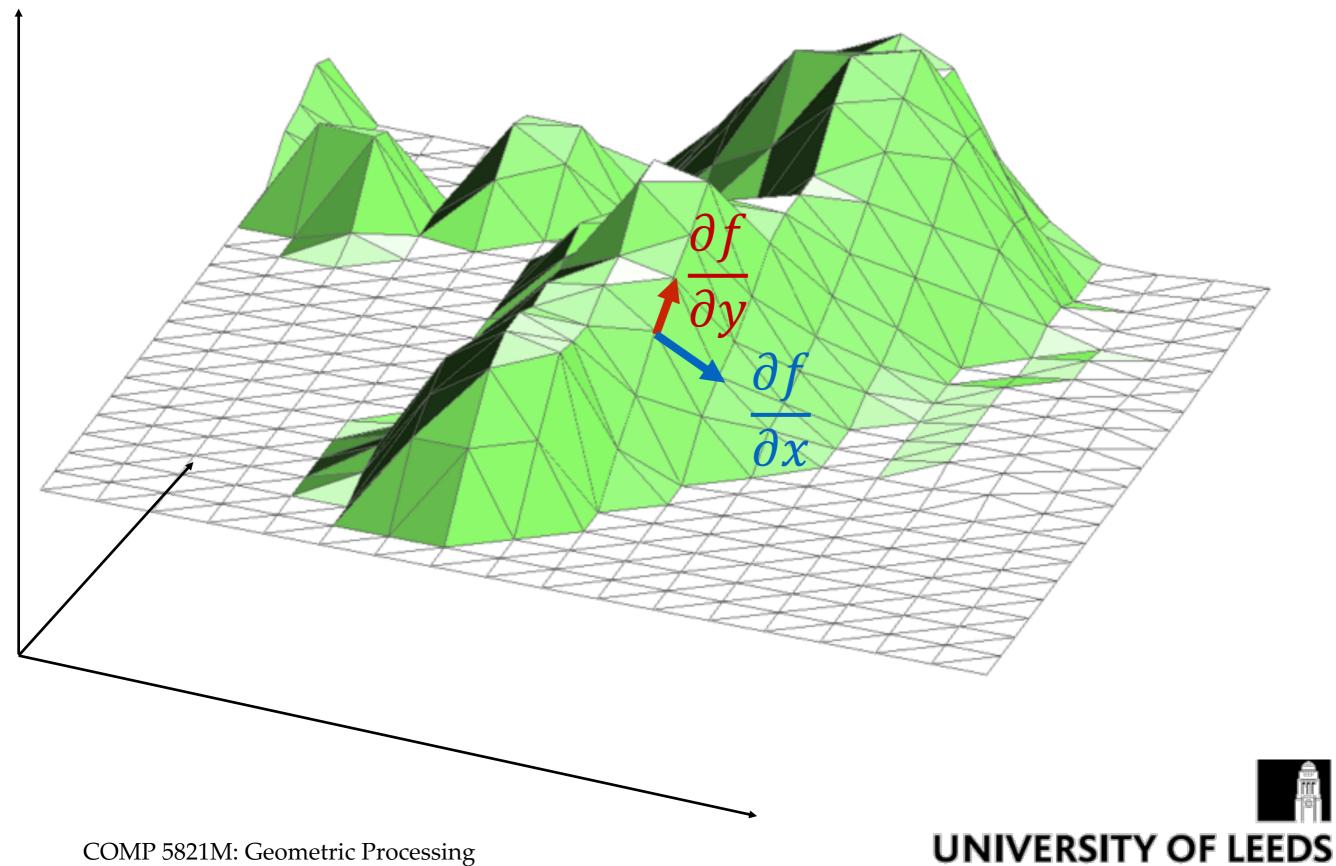
Multi-D Derivatives

- Slope & rate of change become ambiguous
- We define them with respect to a variable
- I.e. rate of change of *f* as *x* changes:
 - Notation: $\frac{\partial f}{\partial x}$, $\frac{\partial f}{\partial y}$, $\frac{\partial f}{\partial z}$
- Derived by *fixing* other variables:

 - $\frac{\partial}{\partial x}(x^2y + y^3z xyz) = 2xy yz$ $\frac{\partial}{\partial y}(x^2y + y^3z xyz) = x^2 + 3y^2z xz$ $\frac{\partial}{\partial z}(x^2y + y^3z xyz) = y^3 xy$



An Example



Gradient Vector

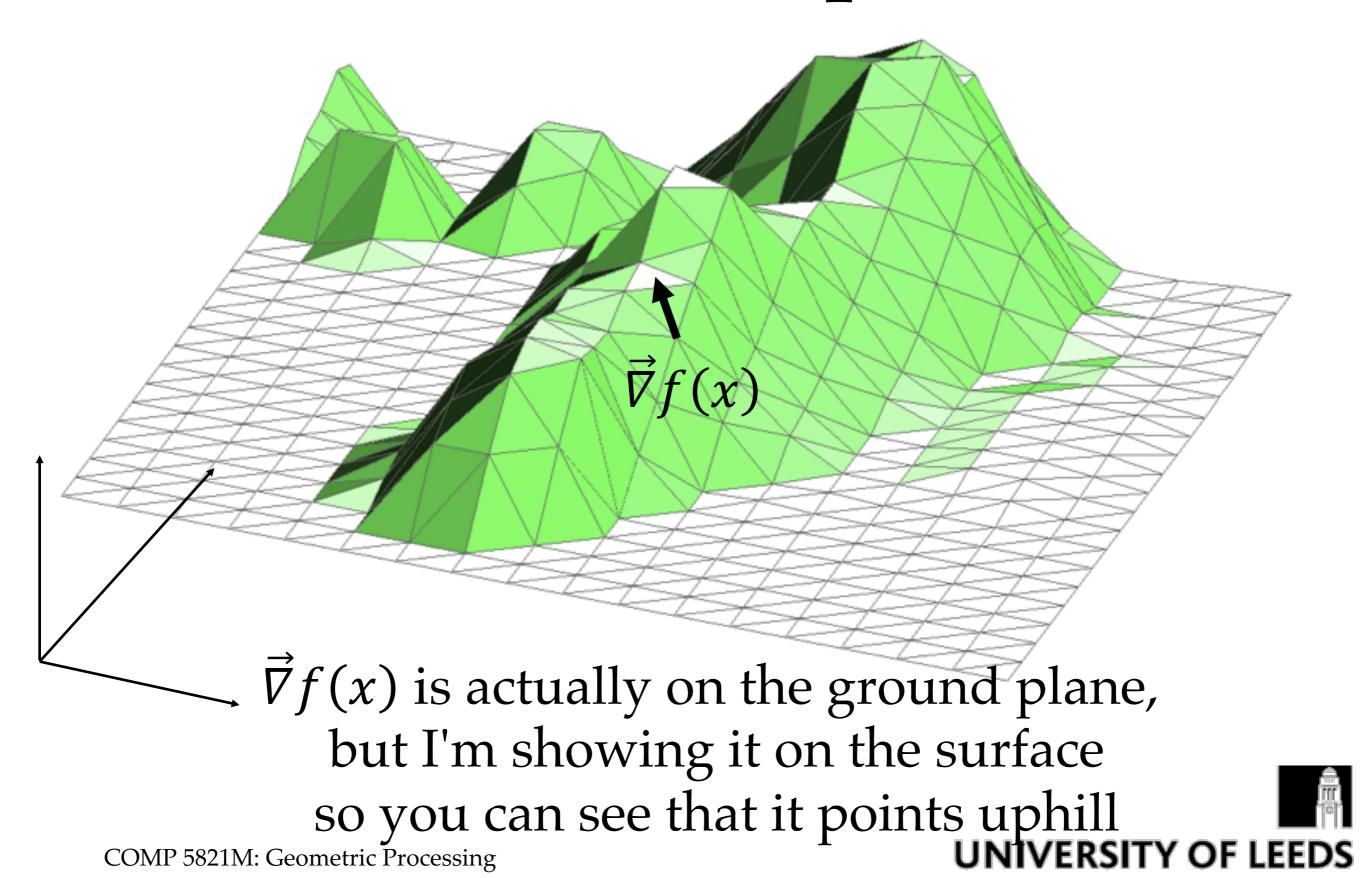
• A vector made of the partial derivatives:

$$\vec{\nabla} f(x) = \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z}\right)$$

- Defines a vector field
- Direction & rate of steepest ascent
 - So the idea of slope is still with us
 - As is the idea of distortion



An Example



COMP 5821M: Geometric Processing

Higher-Order Partials

- Notation specifies order of differentiation:
 - \bullet $\frac{\partial^2 f}{\partial x^2}$ $\frac{\partial^2 f}{\partial x^2}$ $\overline{\partial x^2}$, $\overline{\partial x \partial y}$
 - $f(x,y) = x^2y + y^{17} \sin xy$



Multiple Integrals

- Integration can also be done repeatedly
 - $\int_a^b \left(\int_c^d f(x,y) dx \right) dy$
- Summation is now over a small rectangle
 - \bullet $A = [a, b] \times [c, d]$
- And can be rewritten:

$$\int_{A} f(x,y)dx = \lim_{n \to \infty} \sum_{i=0}^{n} \sum_{j=0}^{n} f(x_{i,j}) \delta x \delta y$$
$$x_{i,j} = (a + i\delta x, c + j\delta y)$$
$$\delta x = (b - a)/n, \delta y = (d - c)/n$$





Numerical Calculus

- Most of our functions will *not* be integrable
- We will approximate them numerically
- There are a number of methods:
 - Taylor Series
 - Numerical Integration
 - Table Lookup



Taylor Series

• For any function f(x)

$$f(x) = f(a) + \frac{f'(a)(x-a)}{1!} + \frac{f''(a)(x-a)^2}{2!} + \dots + \frac{f^{(n)}(a)(x-a)^n}{n!} + \dots$$

- We choose an easy value for a.
- For example, look at cosine, with a=0

$$\cos(x) = \cos(0) + \frac{-\sin(0)(x-0)}{1!} + \frac{-\cos(0)(x-0)^2}{2!} + \frac{\sin(0)(x-0)^3}{3!} + \dots$$

$$= 1 + \frac{-0x}{1} + \frac{-1x^2}{2} + \frac{0x^3}{6} + \dots$$

Many functions converge slowly



Numerical Integration

• We just go back to our summation:

$$\int_{a}^{b} f(x)dx = \lim_{n \to \infty} \sum_{i=0}^{n} f(x_{i})\delta x$$

- And choose a small δx
- The rest is standard numerical computation



Table Lookup

- A lot of computations are reused
 - e.g., sin, cos, logarithm
- And we may not need high accuracy
- So store a lookup table
 - an array with (e.g.) 1024 values
- Then just take the closest value
- This runs a *lot* faster

