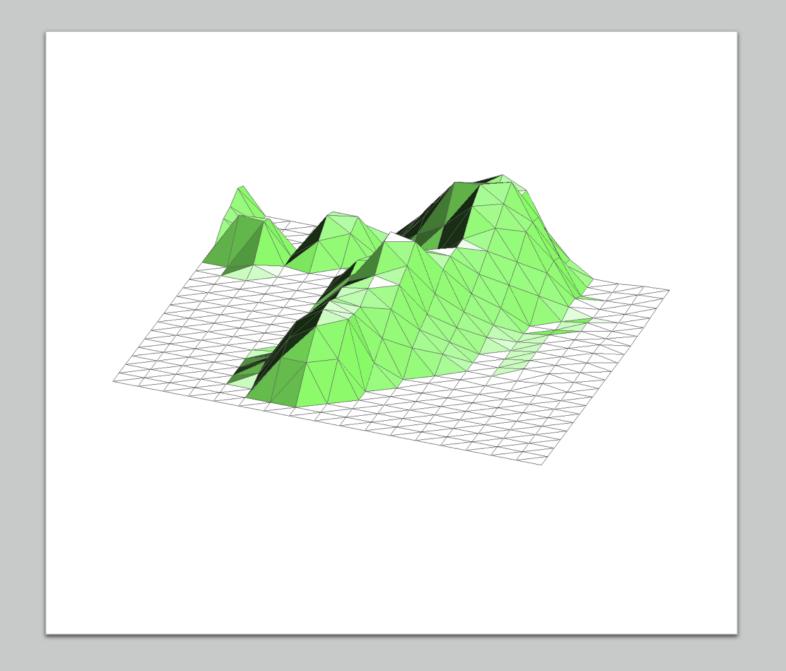
19- Volume Rendering

Dr. Hamish Carr & Dr. Rafael Kuffner dos Anjos



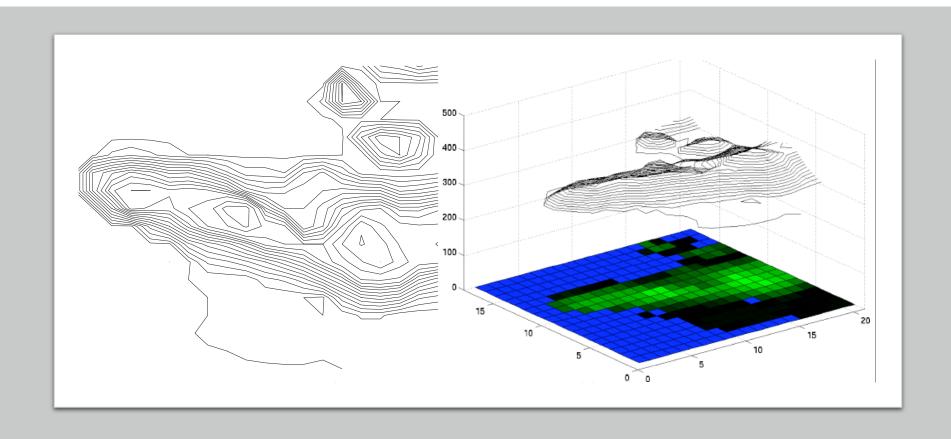
$f: \mathbb{R}^2 \to \mathbb{R}$: Height Field

- For every point in the plane, define a *height*
- The graph is then a *terrain*
 - i.e. a surface in a 3D embedding space

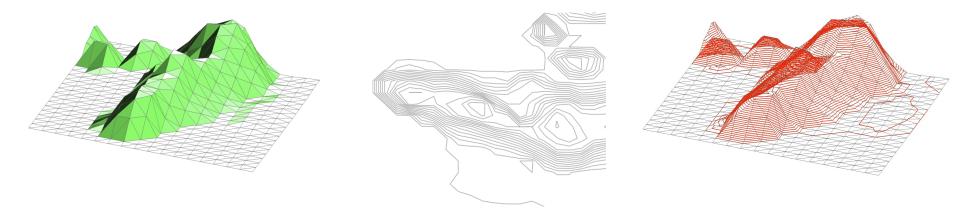


Contours

- We can define curves using contours
- Let an artist design the landscape
- Pick a threshold, generate a curve



Manifold Dimension



- f is a 2-manifold embedded in 3-D
- It's contours are 1-manifolds
 - embedded in 2-D
 - or in 3-D
- What happens if we add a dimension?



Implicit (Blobby) Surfaces

- Define a function $f: \mathbb{R}^3 \to \mathbb{R}$
 - Often a sum of Gaussian distributions
 - It's a 3-manifold embedded in 4-D
 - It's contours are 2-manifolds in 3-/4-D
- Choose a threshold h
- Extract the level set / contours
 - They are guaranteed to be manifold



Implicit Surfaces

- We can use many types of functions:
 - CT/MRI scans
 - Numerical simulations
 - Mathematical models eg. sum of Gaussians
 - Distance fields
 - *any* property we can compute in 3-D
- In practice, we need to start with a 3-D mesh



Meshes in 3D

- In 2-D, we used triangles and squares
- In 3-D, we use tetrahedra and cubes
 - also pyramids, octahedra & triangular prisms
- Interpolation follows the same rules as in 2-D
 - geometric interpolation (meshes)
 - kernel filters (sampling theory)



Isosurfaces

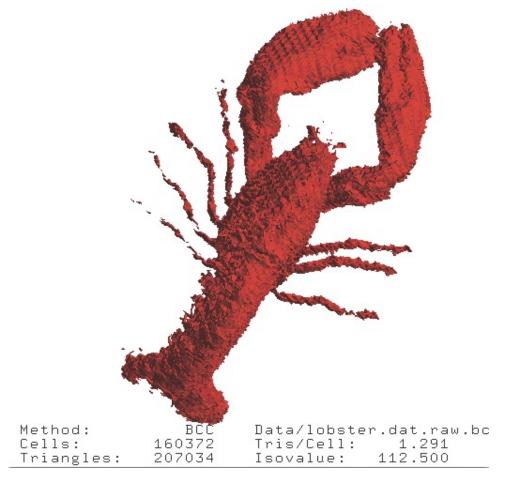
- Contours in 3D
- Basically the same as we saw in 2D

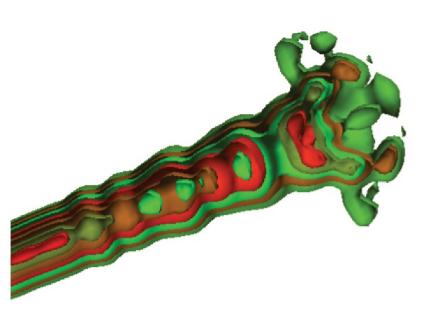
$$f^{-1}(h) = \{(x, y, z) : f(x, y, z) = h\}$$

- 2-manifolds embedded in 3 or 4 space
- But we can't usually show multiples
 - because we've run out of dimensions



Result



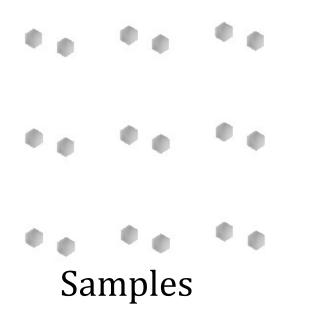


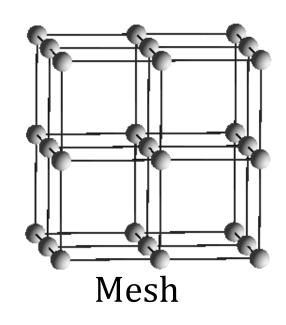
An Example





Cubic Meshes

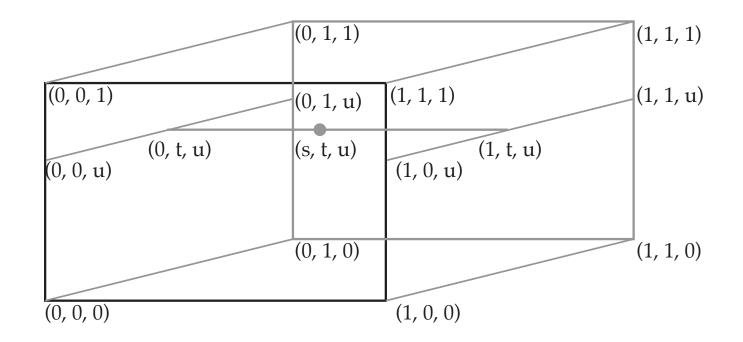




- By far the most common case
 - Generalisation of squares in 2-D



Trilinear Interpolation



Repeat linear interpolation in 3 dimensions



Trilinear Interpolation

$$f(x,y,z) = a \ xyz + b \ yz + c \ xz + d \ xy + ex + fy + gz + h$$

$$a = b_{111} - b_{110} - b_{101} - b_{011} + b_{100} + b_{010} + b_{001} + b_{000}$$

$$b = b_{011} - b_{010} - b_{001} + b_{000}$$

$$c = b_{101} - b_{100} - b_{001} + b_{000}$$

$$d = b_{110} - b_{100} - b_{010} + b_{000}$$

$$e = b_{100} - b_{000}$$

$$f = b_{010} - b_{000}$$

$$g = b_{001} - b_{000}$$

$$h = b_{000}$$

Computing Normal

- Normal vector is based on gradient
 - always perpendicular to contours
 - describes steepest ascent
 - but outside is typically low-valued
 - use *negative* gradient as normal

$$\vec{n} = -\nabla f(x)$$

$$= (-\frac{\delta f}{\delta x}, -\frac{\delta f}{\delta y}, -\frac{\delta f}{\delta z})$$



Central Differencing:

• Approximation of gradient:

$$ec{n}_{i,j,k} pprox (-rac{f(x_{i+1},y_j,z_k)-f(x_{i-1},y_j,z_k)}{2}, -rac{f(x_i,y_{j+1},z_k)-f(x_i,y_{j-1},z_k)}{2}, -rac{f(x_i,y_j,z_{k+1})-f(x_i,y_j,z_{k-1})}{\delta z})$$

- Compute at vertices of cell
- Interpolate along edges



Direct Volume Rendering



Created with 3D doctor

courtesy T. Möller, SFU

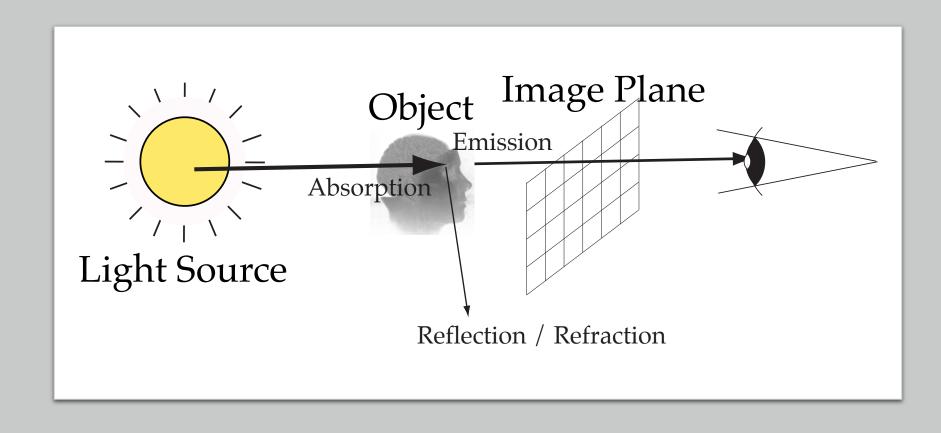
Direct Volume Rendering

- 3D equivalent of colour mapping
- Define a transfer function:
 - maps from data to colour opacity
- Then compute light transport through data
 - i.e. a computational X-ray
- Or think of it as luminous jelly



Modelling Transmission

- No longer modelling *surfaces*
- Modelling diffuse internal reflection
- We get light added and subtracted





Density Clouds

- Photons are blocked by absorption
- Probability depends on density of material
 - i.e. how many particles are in the way
- Measured as optical density
 - # of particles / mm
 - E.g. 5mm of lead might block 90% of photons
 - How much would 10mm block?



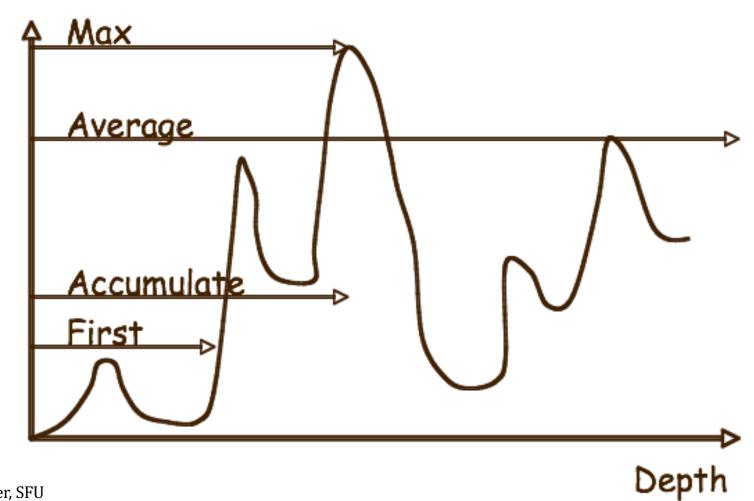
Volume Rendering Integral

$$I_{\lambda}(x,r) = \int_0^L C_{\lambda}(s)m(s)e^{-\int_0^2 m(t)dt} ds$$

- Due to Kajiya, Sabella, Max (1986) (3 papers!)
 - λ is the wavelength of light
 - $x + \vec{r}t$ is a ray of length L through pixel x
 - $C_{\lambda}(s)$ is the colour contribution at point s
 - m(s) is the mass density at s



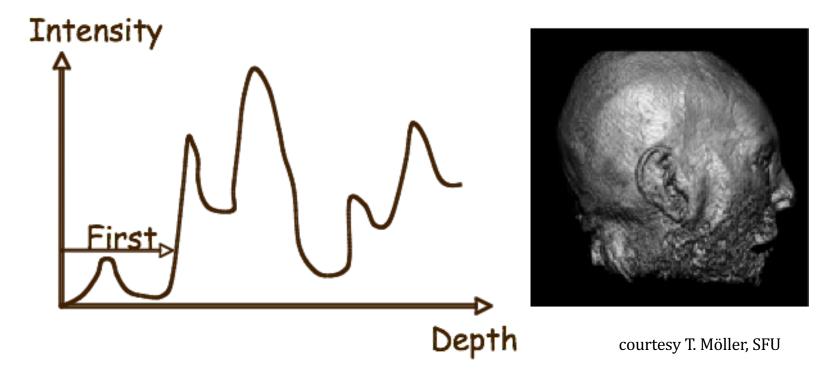
TF Design



courtesy T. Möller, SFU



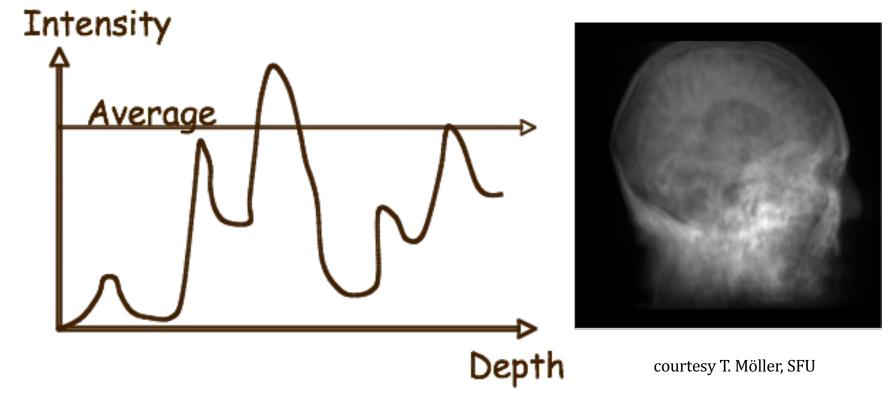
First Intersection



- Equivalent to an Isosurface (Tuy&Tuy, 1984)
- 100% opacity at chosen isovalue



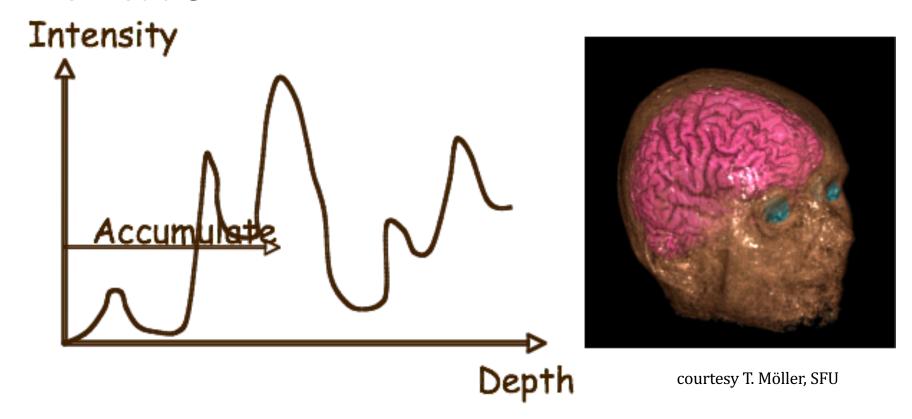
Average Intensity



- Constant Opacity throughout volume
- Equivalent to an x-ray

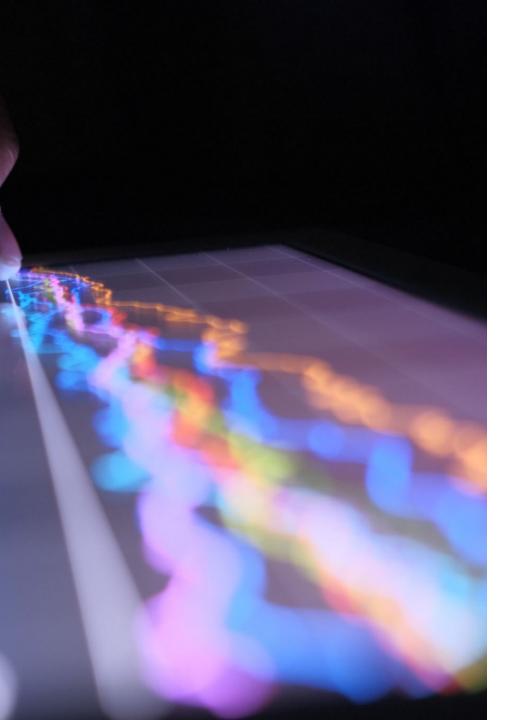


Accumulate



- Use TF to highlight structures
- Levoy, 1988



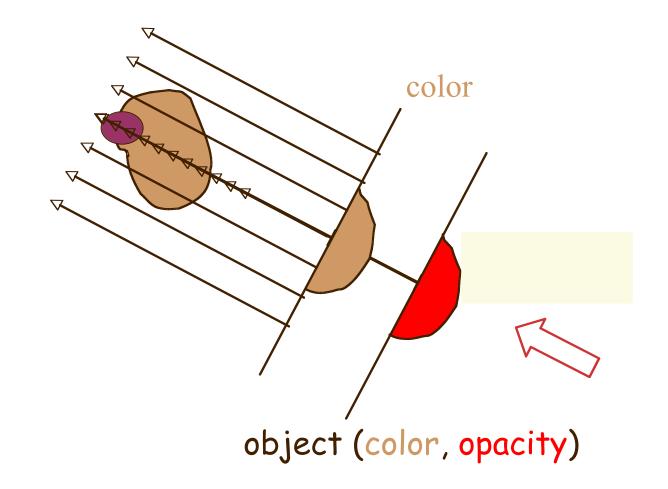


DVR Ray-tracing

- For each pixel
- Compute corresponding ray in volume
- Walk along ray in small increments
- Computing contribution to integral
- Then display as image
- This makes regular raytracing look cheap!
 - So sci. vis. has *many* hacks/speedups



Example





Pseudocode

```
// loop through all pixels
for (x = 0; x < width; x++)
  for (y = 0; y < height; y++)
    { // for each pixel
    // start with 0 intensity
    float totalIntensity = 0.00;
    // choose two points along the ray
    Point p = unProject(x, y, -1);
    Point q = unProject(x, y, -2);
    // compute the vector for the line
    Vector v = q - p;
    // take very small steps
    tStep = 0.01;
    // iterate along the ray until we get to the other side
    for (t = 0.0; t < maxThicknessOfData; t+=tStep)</pre>
      { // for t
      // compute where this point is
      Point r = p + v*t;
      // look up the value, then use that to find opacity
      alpha = TF alpha(r,tStep);
      // also use it to look up intensity
      intensity = TF intensity(r);
      // compute the opacity & update
      totalIntensity = totalIntensity * (1-alpha) + intensity * alpha;
      } // for t
    // when we're done, save the pixel intensity
    setPixel(x,y,totalIntensity);
    } // for each pixel
```

Volume rendering algorithm

- This is tracking the integration from the back forwards
- If you want to have a lightsource at the side,
- Modify to account for the reflection of the particles.
- And for that you will need everything we talked about before, and a normal vector.
- Scattering, montecarlo etc...

Applications to Rendering

- Mist
- Fog
- Smoke
- Explosions
- Particle Systems
- X-rays
- Visualisation in general