

Highlights

Bayesian Optimisation using microscopic and integral measurements to infer nuclear data parameters

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Bayesian Optimisation using microscopic and integral measurements to infer nuclear data parameters

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Abstract

Abstract text.

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¹ 1. Introduction

² Nuclear data is considered the major source of uncertainty in several re-
³ actor observables, most notably the effective multiplication factor (k_{eff}). The
⁴ nuclear data available in evaluated nuclear data libraries, such as cross sec-
⁵ tions, neutron multiplicities, angular distributions, and fission neutron energy
⁶ spectra, are the result of a complex fitting procedure involving theoretical
⁷ models, microscopic experiments, and expert judgment. Integral experiments
⁸ are subsequently used to assess the performance of this nuclear data. In this
⁹ work, a Bayesian Optimization (BO) framework is proposed to consolidate
¹⁰ microscopic energy-dependent measurements with integral experiments for
¹¹ the estimation of nuclear data parameters.

12 The BO is performed using a Markov Chain Monte Carlo (MCMC) method,
13 in which surrogates are employed to evaluate the likelihoods. For the micro-
14 scopic energy-dependent measurements, the SAMMY v8.1.0 resonance fitting
15 tool [?] is employed, while SERPENT v2.2.2 [?], a Monte Carlo neutron
16 transport code, is used to quantify the integral response. Surrogates are
17 trained by evaluating random samples drawn in the input space using these
18 high-fidelity models. The methodology is tested on a case study involving
19 ^{53}Cr . Since microscopic experiments typically provide a dense set of data
20 points while integral experiments provide a single values integrated over sev-
21 eral nuclides/reactions/energies, special care is taken to analyze how different
22 assumptions regarding the likelihood evaluation and data correlation affect
23 the posterior distribution.

24 **2. Background and Mathematical Motivation**

25 *2.1. Bayesian Optimization Setup*

26 The main objective of this paper is to infer nuclear data parameter(s) from
27 a combined set of microscopic energy-dependent and integral experiments.
28 Microscopic energy-dependent measurements (hereafter referred to as micro-
29 scopic measurements) quantify single-energy neutron properties. These often
30 result from neutron Time-Of-Flight (nTOF) facilities, where the neutron en-
31 ergy is derived from the time of flight to a target. A characteristic of these
32 measurements is the high density of data points obtained. In contrast, in-
33 tegral measurements, such as criticality experiments, provide a single value
34 representative of a macroscopic group of nuclides, reactions, and energies.

35 According to Bayes' theorem, the posterior (updated) probability density

36 function (PDF), $P(\theta|\text{data})$, is proportional to the likelihood of observing the
 37 parameter(s) θ given the data, multiplied by the prior belief regarding the
 38 parameter(s):

$$P(\theta|\text{data}) \propto P(\text{data}|\theta) \cdot P(\theta) \quad (1)$$

39 For brevity, we refer to the likelihood as $\mathcal{L}(\theta) = P(\text{data}|\theta)$.

40 *2.2. Markov Chain Monte Carlo (MCMC)*

41 To calculate the posterior distribution, various techniques derived from
 42 Bayes' theorem can be employed, such as Generalized Linear Least Squares
 43 (GLLS) [?], Bayesian Monte Carlo (BMC) [?], and MOCABA [?]. In
 44 this paper, we select an algorithm belonging to the family of Markov Chain
 45 Monte Carlo (MCMC) techniques.

46 In most MCMC algorithms, the unnormalized posterior is evaluated for
 47 each sample as

$$P^*(\theta|\text{data}) = \mathcal{L}(\theta) \cdot P(\theta), \quad (2)$$

48 where $P^*(\theta|\text{data})$ represents the posterior up to a normalizing constant.
 49 The objective is to construct a Markov chain $\{\theta_0, \theta_1, \dots, \theta_N\}$ such that the
 50 stationary distribution of the chain converges to the posterior distribution
 51 $P(\theta|\text{data})$. Under the assumption of a Normally distributed prior ($\mathcal{N}(\theta_0, \Sigma)$)
 52 and likelihood ($\mathcal{N}(\mathbf{y}_{\text{true}}, \mathbf{A})$), the unnormalized posterior probability evalu-
 53 ated at θ can be rewritten as

$$\begin{aligned} P^*(\theta|\text{data}) &= \frac{1}{\sqrt{(2\pi)^m \det \mathbf{A}}} \exp \left[-\frac{1}{2} (\mathbf{f}(\theta) - \mathbf{y}_{\text{exp}})^T \mathbf{A}^{-1} (\mathbf{f}(\theta) - \mathbf{y}_{\text{exp}}) \right] \times \\ &\quad \frac{1}{\sqrt{(2\pi)^n \det \Sigma}} \exp \left[-\frac{1}{2} (\theta_0 - \theta)^T \Sigma^{-1} (\theta_0 - \theta) \right] \end{aligned} \quad (3)$$

54 The first term represents the probability of observing θ given the measurements,
55 where \mathbf{y}_{exp} is the vector describing the m measurement points, $\mathbf{f}(\theta)$
56 is the vector containing the model responses for the vector θ , and \mathbf{A} is the
57 covariance matrix describing the measurement points of size ($m \times m$). The
58 prior probability is calculated using the prior belief of the n parameters θ_0 ,
59 with a covariance matrix Σ of size ($n \times n$).

60 Standard algorithms, such as Metropolis-Hastings, propose a new state
61 θ' based on a proposal distribution $q(\theta'|\theta_t)$ and accept it with probability
62 α . However, as Metropolis-Hastings algorithms require tuning, we employ
63 the Affine Invariant Ensemble Sampler (AIES), as implemented in the *emcee*
64 code [?]. In this algorithm, an ensemble of K "walkers" is propagated in
65 parallel. The proposal step for a walker θ_k is based on the current position
66 of a complementary walker θ_j from the ensemble:

$$\theta'_k = \theta_j + Z(\theta_k - \theta_j) \quad (4)$$

67 where Z is a scaling variable drawn from a distribution $g(z) \propto 1/\sqrt{z}$ on the
68 interval $[1/a, a]$. This "stretch move" allows the algorithm to efficiently sample
69 distributions with strong correlations without requiring manual tuning of
70 the proposal covariance matrix.

71 2.3. Likelihood Formulation

72 The formulation of the likelihood function $\mathcal{L}(\theta)$ is one of the challenges
73 when combining integral and microscopic data. The quantity of data points
74 differs by orders of magnitude, which may dilute the effect of the integral
75 measurement. To better understand the extent to which microscopic measurements
76 might dilute these integral measurements, we analyze different

77 approaches to include the microscopic experiments.

78 Ideally, one would use the full experimental covariance matrix. However,
79 calculating experimental correlations between distinct integral experiments,
80 distinct microscopic, and between microscopic and integral experiments, is
81 inherently difficult and time consuming. We therefore currently introduce the
82 assumption that there are no correlations between microscopic and integral
83 experiments, nor between integral or microscopic experiments from different
84 facilities. This allows us to calculate the total likelihood $\mathcal{L}(\theta)$ for a set of
85 microscopic experiments J and integral experiments I :

$$\mathcal{L}(\theta) = \prod_{j \in J} \frac{1}{\sqrt{(2\pi)^{m_j} \det \mathbf{A}_j}} \exp \left[-\frac{1}{2} (\mathbf{f}_j(\theta) - \mathbf{y}_j)^T \mathbf{A}_j^{-1} (\mathbf{f}_j(\theta) - \mathbf{y}_j) \right] \times \\ \prod_{i \in I} \frac{1}{\sqrt{2\pi\sigma_i^2}} \exp \left[-\frac{(f_i(\theta) - y_i)^2}{2\sigma_i^2} \right] \quad (5)$$

86 Using the log-likelihood $\ln \mathcal{L}(\theta)$ for numerical stability:

$$\ln \mathcal{L}(\theta) = -\frac{1}{2} \sum_{j \in J} \ln [(2\pi)^{m_j} \det \mathbf{A}_j] - \frac{1}{2} \sum_{j \in J} [(\mathbf{f}_j(\theta) - \mathbf{y}_j)^T \mathbf{A}_j^{-1} (\mathbf{f}_j(\theta) - \mathbf{y}_j)] + \\ -\frac{1}{2} \sum_{i \in I} \ln [2\pi\sigma_i^2] - \frac{1}{2} \sum_{i \in I} \frac{(f_i(\theta) - y_i)^2}{\sigma_i^2} \quad (6)$$

87 We analyze two approximations regarding the microscopic data: (1) all mi-
88 croscopic measurement points behave fully independently, and (2) micro-
89 scopic points within a single experiment are fully correlated (correlation co-
90 efficient of 1) while remaining independent of other experiments.

91 *2.3.1. Independent microscopic measurement points*

92 If all measurement points are independent, each microscopic point carries
93 the same weight as an integral experiment. Consequently, the integral exper-
94 iments are likely to be diluted and their influence on the posterior negligible.

95 This makes the inference overconfident in the microscopic experiments. The
 96 log-likelihood from Eq. ?? becomes:

$$\begin{aligned}\ln \mathcal{L}_J(\theta) &= -\frac{1}{2} \sum_{j \in J} \sum_{e \in E_j} \ln [2\pi\sigma_{j,e}^2] - \frac{1}{2} \sum_{j \in J} \sum_{e \in E_j} \left[\frac{(f_{j,e}(\theta) - y_{j,e})^2}{\sigma_{j,e}^2} \right] \\ &= C - \frac{1}{2} \sum_{j \in J} \chi_j^2\end{aligned}\quad (7)$$

97 where χ^2 is the standard goodness-of-fit. The logarithmic term is constant
 98 with respect to θ and is replaced by C .

99 2.3.2. Fully correlated microscopic measurement points

100 Conversely, if we assume microscopic points are fully correlated, we nor-
 101 malize by the degrees of freedom (N), which may be interpreted as taking
 102 the average. Eq. ?? then becomes

$$\begin{aligned}\ln \mathcal{L}_J(\theta) &= -\frac{1}{2} \sum_{j \in J} \frac{1}{N} \sum_{e \in E_j} \ln [2\pi\sigma_{j,e}^2] - \frac{1}{2} \sum_{j \in J} \frac{1}{N} \sum_{e \in E_j} \left[\frac{(f_{j,e}(\theta) - y_{j,e})^2}{\sigma_{j,e}^2} \right] \\ &= C - \frac{1}{2} \sum_{j \in J} \chi_{N,j}^2,\end{aligned}\quad (8)$$

103 where $\chi_{N,j}^2$ is the chi-squared per degree of freedom for microscopic exper-
 104 iment j . In this approximation, we are too conservative and do not trust
 105 the microscopic experiment sufficiently. Eventually, including the full exper-
 106 imental covariance matrix will result in a likelihood which is inbetween the
 107 result obtained by Eqs. ?? and ??.

108 2.4. Surrogate Modelling

109 The MCMC algorithm requires thousands of likelihood evaluations. Di-
 110 rectly executing high-fidelity codes (SAMMY and SERPENT) at each step

is computationally expensive. We therefore employ Gaussian Process (GP) regression as a surrogate model. A GP defines a probability distribution over all possible functions consistent with the observed data, providing both a predicted mean and an associated variance. This variance can then be included in the likelihood calculation and allows the MCMC sampler to avoid overconfidence in less explored regions of the input space.

To train the surrogates, a dataset is generated by drawing uniform random samples across the input space. For microscopic experiments, SAMMY calculates the χ^2 metric. For integral experiments, SERPENT calculates k_{eff} . The dataset is split 80/20 for training and testing. We utilize a Radial Basis Function (RBF) kernel for the integral experiments (as k_{eff} behaves smoothly) and a polynomial kernel of second degree for the microscopic χ^2 response (as χ^2 is inherently quadratic). A white noise kernel is added to account for Monte Carlo statistical uncertainty and to ensure positive definiteness.

2.5. Including Uncertainties of Other Nuclides

To limit the Bayesian Optimization from compensating for biases induced by other sources, next to the uncertainties introduced by material and geometry specifications, uncertainties from other nuclides should also be included. For criticality experiments, we estimate these using relative first-order sensitivity coefficients $S_{k,\sigma} = \frac{\partial k/k}{\partial \sigma \sigma}$ calculated via Generalized Perturbation Theory (GPT) as implemented in SERPENT-2 using the ECCO-33 multi-group energy structure [?].

Covariance matrices Σ_σ were generated using SANDY [?] (wrapping NJOY2016 [?]). The Sandwich formula [?] is used to propagate these

¹³⁵ uncertainties to k_{eff} , it is given by

$$\Sigma_k = S_{k,\sigma}^T \cdot \Sigma_\sigma \cdot S_{k,\sigma}, \quad (9)$$

¹³⁶ where Σ_k is the covariance matrix describing k_{eff} of the systems under con-
¹³⁷sideration and $S_{k,\sigma}$, the matrix containing the sensitivity vectors of each sys-
¹³⁸tem, is the relative first-order sensitivity coefficients describing how changes
¹³⁹in nuclear data affect k_{eff} . These nuclear data variances are then added to the
¹⁴⁰experimental variance. This ensures the adjustment does not falsely correct
¹⁴¹for other nuclear data biases. As a consequence, the integral experiments
¹⁴²(mostly criticality) become less informative, as they are heavily influenced
¹⁴³by uncertainties due to fissile nuclides.

¹⁴⁴ 3. Description of Cases

¹⁴⁵ 3.1. Chromium-53

¹⁴⁶ Chromium is a frequently used structural element in nuclear reactors,
¹⁴⁷here 11-26% of chromium is added to stainless steel in order to increase its
¹⁴⁸corrosion resistance. Due to the scattering and capture cross sections in
¹⁴⁹ ^{50}Cr , ^{52}Cr and ^{53}Cr , it is also important for criticality safety in some nuclear
¹⁵⁰systems [?]. A major isotope with relatively poor nuclear data is the 1-
¹⁵¹10 keV range of ^{53}Cr . Existing microscopic measurements, such as those
¹⁵²by Guber (2011) [?] and Stieglitz (1971) [?], are not consistent with
¹⁵³each other. Recently, Pérez-Maroto et al. (2025) performed new capture
¹⁵⁴yield measurements, it is seen as a possibility to include this experiment and
¹⁵⁵complement it with integral experiments to test the proposed methodology.

¹⁵⁶ To start, we selected two criticality experiments, i.e., PMI-002 and HMI-
¹⁵⁷001, due to their significant sensitivity in the 1-10 keV range (see Figure ??).

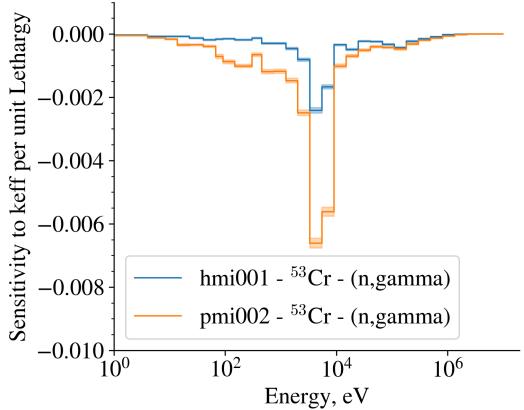


Figure 1: Sensitivity profiles for two criticality experiments sensitive to Cr-53 (n,γ)

158 These experiments use stainless steel as reflector in an intermediate spectrum.

159 They are available in the International Handbook of Evaluated Criticality

160 Safety Benchmark Experiments (ICSBEP) [?].

161 For this case study, we infer only the capture width Γ_γ at 4 keV, as it is

162 the parameter most sensitive to criticality in this range. E_r and Γ_n are not

163 perturbed as they are more easily derived from transmission measurements.

164 This serves as a simplified proof-of-concept and an extension to multiple

165 input parameters is possible. The perturbation of Γ_γ is shown in Figure

166 ???. Here, the capture yield (a) represents the connection to the microscopic

167 measurements performed by Pérez-Maroto et al., while (b) represents the

168 cross sections which have been incorporated into ACE files, ready for use in

169 the SERPENT-2 Monte Carlo code. For each of these curves, the SAMMY

170 and SERPENT codes were run with the goal of training a surrogate GP.

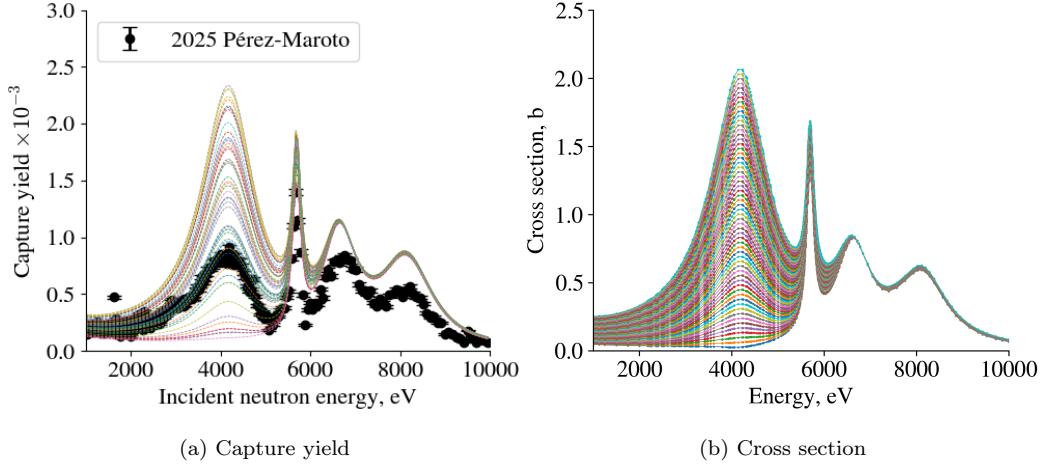


Figure 2: Random samples for capture yield (a) and cross section (b).

¹⁷¹ 4. Results and Discussions

¹⁷² 4.1. Chromium-53

¹⁷³ The validation of the Gaussian Process is shown in Figure ??, in (a) the
¹⁷⁴ data points and the GP for the Pérez-Maroto data set is shown, while in
¹⁷⁵ (b) it is shown for PMI-002. The GP corresponds well with the predicted
¹⁷⁶ responses obtained from SAMMY and SERPENT, obviously since they were
¹⁷⁷ trained on them. Nevertheless, the tests performed on the 20% of data points
¹⁷⁸ which were not included in the assimilation were also in good agreement with
¹⁷⁹ the GP prediction.

¹⁸⁰ We analyze several scenarios: integral experiments only, microscopic ex-
¹⁸¹ periments only, and combinations using the independent vs. fully correlated
¹⁸² assumptions. The results are summarized in Table ??.

¹⁸³ To confine the effect of including some experiments, various scenarios are
¹⁸⁴ simulated. In case 1, to experiments are included, which corresponds to the
¹⁸⁵ prior input parameters taken from JEFF-4.0, but with an increased relative

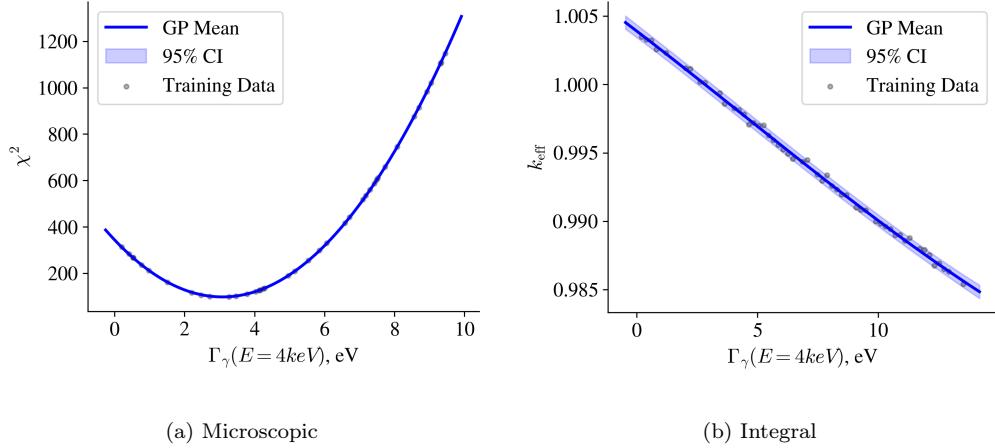


Figure 3: GPs for microscopic (a) and integral (b) experiment.

Table 1: Overview of posterior mean and uncertainty for different combinations of experiments included.

| Case | PMI002 | HMI001 | ntof | Γ_γ , eV | σ_Γ (%) | Comment |
|------|--------|--------|------|----------------------|---------------------|-------------------------|
| 1 | | | | 4.14 | 20 | Prior |
| 2 | ✓ | ✓ | | 4.16 | 19.7 | |
| 3 | | | ✓ | 3.14 | 6 | |
| 4 | ✓ | ✓ | ✓ | 3.15 | 6 | Fully correlated |
| 5 | ✓ | ✓ | ✓ | 3.09 | 2 | Independent |
| 6 | ✓ | ✓ | | 5.52 | 13 | No other ND uncertainty |
| 7 | | | ✓ | 3.09 | 2 | Independent |

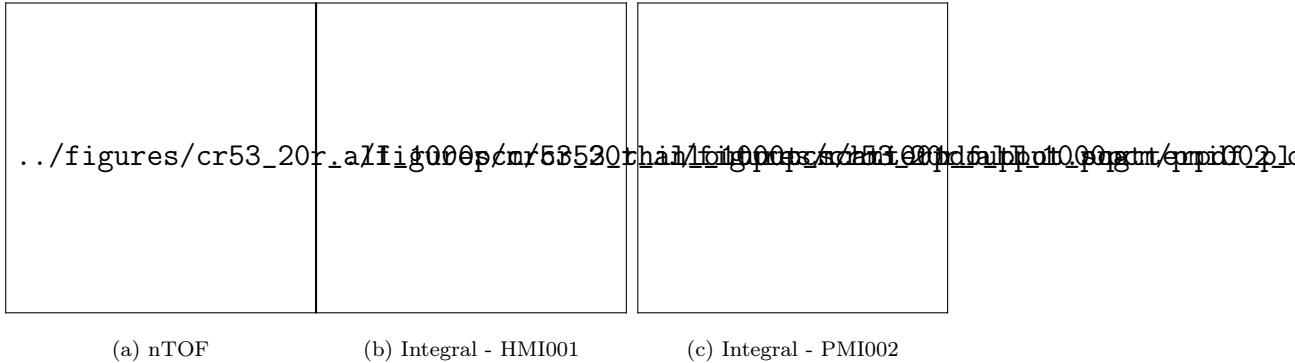


Figure 4: Scatter plots for microscopic (a) and integral (b and c) experiments showing the prior and posterior responses as a function of the input variable for Case 4.

uncertainty to make the prior less informative. Then, as a baseline Eq. ?? is used unless otherwise noted. In case two, both integral experiments are included and the mean shifts only slightly and the posterior uncertainty is also not improved much. This can be attributed to the large uncertainty due to other nuclear data uncertainties in comparison to the rather limited sensitivity to the first Γ_γ of ^{53}Cr . In contrast, when these other nuclear data uncertainties are neglected, as can be seen in case 6, the bias shifts by about 30%, while the uncertainty is reduced by 7%.

Now, the influence of fully correlated and independent microscopic measurement points is compared. In case 3, only the microscopic experiment from Pérez-Maroto is included with the assumption of fully correlated measurement points. Then, the posterior is optimized to be consistent with only this measurement and the Γ_γ moves down. This is in contradiction with the adjustment proposed by case 6, but cannot be rejected by the posterior in case 2 where the other nuclear data uncertainties are included. The posterior uncertainty is then reduced to 6%. Now, when the assumption of fully inde-

202 pendent microscopic data points is used, such as in case 7 or also in Figure
203 **??**. Here the posterior seems to be confident in the prediction of Γ_γ with a
204 posterior uncertainty of 2%.

205 In Figure **??**, corresponding to case 4 is depicted. Here the two inte-
206 gral experiments PMI-002 and HMI-001 as well as the microscopic dataset
207 (regarded as fully correlated) from Pérez-Maroto are included. The poste-
208 rior prediction of k_{eff} moves away from the calculated integral response for
209 PMI-002, but remains well within the uncertainty bounds imposed by exper-
210 imental and other nuclear data sources. It appears that the included integral
211 experiments contribute negligibly to the uncertainty reduction in the Γ_γ pa-
212 rameter at 4 keV. In order to be able to include integral experiments into this
213 mix, several things are needed. First, the nuclear data uncertainties of other
214 sources should be kept to a minimum, either by experimental design, or by
215 reducing them using data assimilation with integral experiments that are sen-
216 sitive to the most important other nuclear data uncertainties. Nevertheless,
217 it seems criticality experiments are not sufficiently sensitive to the Γ_γ -width
218 of ^{53}Cr at 4 keV. A possible route to increase the sensitivity is to design
219 experiments specifically sensitive to this energy range, e.g. pile-oscillation
220 experiments with a significant portion of the spectrum in this energy range.
221 On the other hand, nuclides which are more important for k_{eff} , such as ^{238}U /
222 ^{235}U or ^{239}Pu might be more suitable candidates for testing as a much larger
223 suite of highly sensitive integral experiments are available.

224 Finally, we simulate a hypothetical scenario with highly sensitive integral
225 experiments (experimental uncertainty reduced to 10 pcm and other nuclear
226 data uncertainties neglected). As seen in Figure **??**, under these ideal and

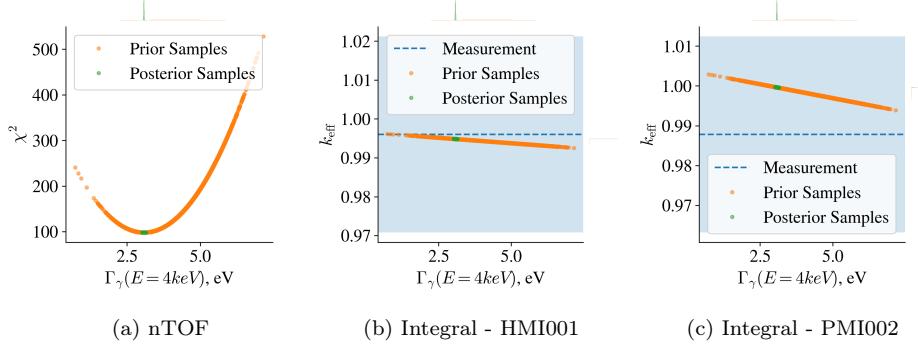


Figure 5: Scatter plots for Case 5 (Independent assumption).

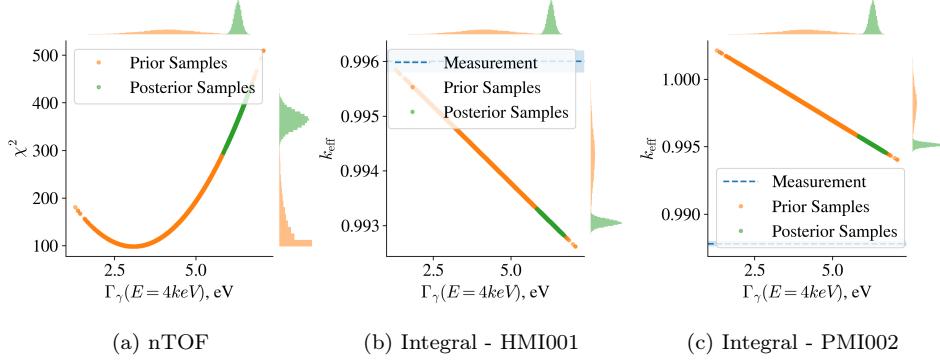


Figure 6: Scatter plots for the hypothetical high-sensitivity scenario.

unrealistic conditions, integral experiments provide significant guidance to the posterior. Although we know the integral experiments are subjected to larger uncertainties of other nuclides, it shows that when experiments with a lower uncertainty in comparison to the sensitivity are used, they can be combined with microscopic experiments under the conservative assumption that microscopic data points behave as one.

233 **5. Conclusions and Future Work**

234 In this work, a Bayesian Optimization framework was implemented to
235 infer nuclear data parameters by consolidating microscopic and integral ex-
236 periments. The methodology coupled SAMMY and SERPENT with Gaus-
237 sian Process surrogates and an MCMC sampler, allowing for more efficient
238 exploration of the posterior distribution.

239 The case study on ^{53}Cr highlighted the critical challenge of weighting
240 different data sources. We demonstrated that the assumption regarding cor-
241 relations in microscopic data fundamentally alters the posterior. Treating
242 microscopic points as independent results in an overconfident reduction of
243 uncertainty in which integral experiments become negligible. On the other
244 side, when microscopic data is treated as fully correlated (per experiment)
245 and uncertainties for other nuclides are also included, the criticality experi-
246 ments currently available for ^{53}Cr provide negligible information gain. They
247 are dominated by the uncertainties due to fissile nuclides.

248 The results indicate that for integral experiments to be valuable in this
249 framework, either the experiments must be chosen such that the parameter
250 to infer is sufficiently sensitive in comparison to other nuclear data, or the
251 uncertainties of other nuclear data must be significantly reduced using a-
252 priori data assimilation techniques.

253 Future work should be devoted to including a realistic experimental co-
254 variance matrix to assess the validity of the assumptions regarding indepen-
255 dent / fully correlated data samples. Second, since the case study on ^{53}Cr
256 did not yield significant results, the framework could be applied to a realis-
257 tic scenario involving for example ^{238}U , where many highly sensitive integral

258 experiments are available. Some points that still should be addressed in-
259 clude implementing correlations between experiments and including the GP
260 prediction uncertainty in the loglikelihood of the microscopic experiment.
261 Although the latter is not expected to influence the results since SAMMY
262 is deterministic, therefore the prediction uncertainty attributed to the GP
263 response is negligible.

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