

Tensors:

i) Tensors - (p, q) -tensor $\rightarrow H^{\mu\nu} x^\mu x^\nu$

Remember that $\underbrace{V^\mu \quad V_\mu}_{\text{so}(1,3)} \Rightarrow \underbrace{V_\mu V^\mu}_{\tilde{r}^T r} = \text{invariant}$

$$V_\mu T^{\mu\nu} \rightarrow V_{\mu'} T^{\mu' \nu'}$$

Some tensors can be represented by matrices $V^\mu = \begin{bmatrix} \end{bmatrix} \quad V_\mu = \begin{bmatrix} \end{bmatrix}$

$T^{\mu\nu}$ two vector indices

T^μ_ν one vector index and one dual index

$T_{\mu\nu}$ two dual indices.

- $V^\mu \rightarrow V^{\mu'} = \Lambda^{\mu'}_\mu V^\mu$
 $V_\mu \rightarrow V_{\mu'} = \Lambda_{\mu'}^\mu V_\mu$

- The metric tensor: $g_{\mu\nu} V^\mu = V_\nu$
 $g^{\mu\nu} V_\nu = V^\mu \Rightarrow g^{\mu\nu} = (g_{\mu\nu})^{-1}$

$$g_{\mu\nu} \rightarrow g_{\mu'\nu'} = \Lambda_{\mu'}^\mu \Lambda_{\nu'}^\nu = g^{\mu\nu} \quad \text{in special relativity} \quad g_{\mu\nu} = \eta_{\mu\nu} = \begin{bmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Trace $\eta_{\mu\nu} \eta^{\mu\nu} = 4$

- Transformations $\Lambda^{\mu'}_\mu, \Lambda_{\mu'}^\mu = (\Lambda^{\mu'}_\mu)^T$

Index notation and matrices:

2D: $dx^\mu = \begin{pmatrix} dx \\ dy \end{pmatrix} \Rightarrow \begin{pmatrix} \cos\theta & \sin\theta \\ -\sin\theta & \cos\theta \end{pmatrix} \begin{pmatrix} dx \\ dy \end{pmatrix} = \begin{pmatrix} \cos\theta dx + \sin\theta dy \\ -\sin\theta dx + \cos\theta dy \end{pmatrix} = \begin{pmatrix} dx' \\ dy' \end{pmatrix}$

$$\Lambda^{1'}_1 = \cos\theta, \quad \Lambda^{1'}_2 = \sin\theta, \quad \Lambda^{2'}_1 = -\sin\theta, \quad \Lambda^{2'}_2 = \cos\theta$$

Λ^{row}
column

$$dx^\mu \rightarrow dx^{\mu'} = \Lambda^{\mu'}_\mu dx^\mu = \Lambda^{\mu'}_1 dx + \Lambda^{\mu'}_2 dy$$

$$dx^{1'} = \Lambda^{1'}_1 dx + \Lambda^{1'}_2 dy \quad \text{and} \quad dx^{2'} = \Lambda^{2'}_1 dx + \Lambda^{2'}_2 dy$$

• Note that:

$$dx^\mu \rightarrow dx^{\mu'} = \Lambda^{\mu'}_\mu dx^\mu = dx^\mu \Lambda^{\mu'}_\mu$$

• $\Gamma_{\mu\nu} = \Gamma_{\nu\mu}$ only with the metric in general $H_{\mu\nu} \neq H_{\nu\mu}$

Some important vectors:

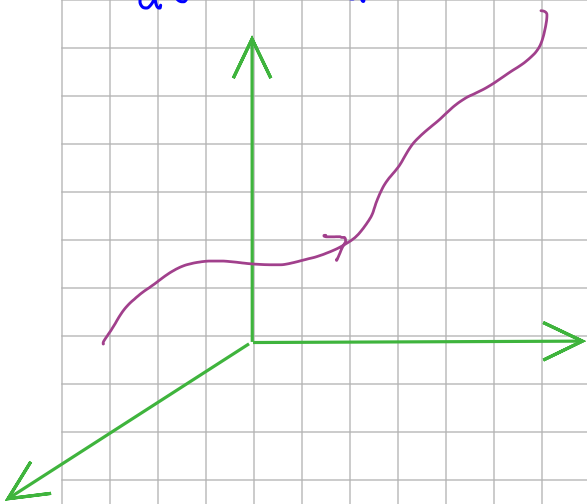
$$\partial_\mu = \left(\partial/\partial t, \partial/\partial x, \partial/\partial y, \partial/\partial z \right) \quad (0,1)\text{-tensor or dual tensor}$$

$$\partial_\mu \rightarrow \partial_{\mu'} = \Lambda^{\mu'}_\mu \partial_\mu \quad \begin{cases} 4 \text{ Gradient: } \partial_\mu \phi \rightarrow (0,1)\text{-tensor} \\ 4 \text{ Divergence: } \partial_\mu A^\mu \rightarrow (0,0)\text{ tensor.} \end{cases}$$

To naively generalize to 4D: $d\vec{r} \rightarrow dx^\mu = \begin{bmatrix} cdt \\ dx \\ dy \\ dz \end{bmatrix}$ (1,0) tensor

What is $\frac{dx^\mu}{dt}$?

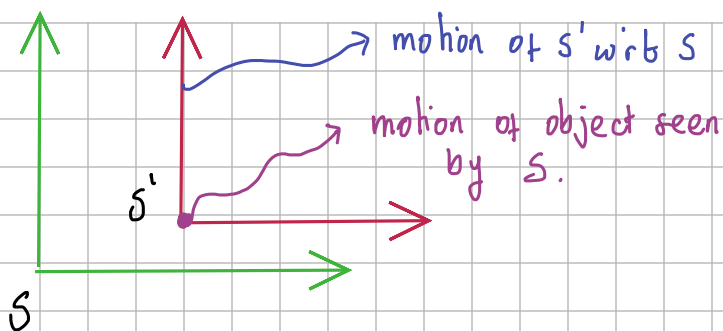
$$\frac{dx^\mu}{dt} \rightarrow \frac{dx^\mu}{dt} = \Lambda^{\mu'}_\mu \frac{dx^{\mu'}}{dt} \quad \text{But this one does not transform as a tensor.}$$



$$\frac{d}{dt} \Rightarrow \frac{d}{d\tau} \quad \text{where} \quad \tau = \int \sqrt{-ds^2}$$

$$ds^2 = -c^2 dt^2 + dx^2 + dy^2 + dz^2 = \text{Invariant.}$$

Now $u^\mu = c \frac{dx^\mu}{d\tau}$



As seen in S:

$$\begin{aligned} u^0 &= c^2 dt/d\tau \\ u^1 &= c dx/d\tau \\ u^2 &= c dy/d\tau \\ u^3 &= c dz/d\tau. \end{aligned}$$

For example: $u^1 = c \frac{dx}{dt} \frac{dt}{d\tau} = c V_x$ Something.

$$-ds^2 = d\tau^2 = c^2 dt^2 - dx^2 - dy^2 - dz^2 \rightarrow \frac{d\tau^2}{dt^2} = c^2 - v^2$$

$$\frac{dt^2}{d\tau^2} = \frac{1}{c^2 - v^2} = \frac{1}{c^2(1 - \beta^2)} = \frac{\gamma^2}{c^2} \quad \text{and} \quad \frac{dt}{d\tau} = \frac{\gamma}{c}.$$

In this case $u^\mu = \begin{bmatrix} \gamma c \\ \gamma \vec{v} \end{bmatrix}$

• **Momentum:** $p^\mu = m u^\mu = \begin{pmatrix} m c \gamma \\ m \gamma \vec{v} \end{pmatrix} \Rightarrow p_{\text{rest}}^\mu = \begin{pmatrix} m c \\ 0 \end{pmatrix}$

For $\frac{v}{c} \ll 1$ $\gamma = 1 + \frac{1}{2} \frac{v^2}{c^2} + \dots \Rightarrow p^\mu = \begin{pmatrix} \frac{1}{c} (m c^2 + \frac{1}{2} m v^2 + \dots) \\ m v \end{pmatrix}$

and $p^\mu = \begin{pmatrix} \frac{1}{c} \text{Energy relativistic} \\ \vec{p}_{\text{relativistic}} \end{pmatrix} \quad E_{\text{rest}} = m c^2$

Since p^μ is a vector, $p_\mu p^\mu$ is a scalar.

$$p_\mu = (-m \gamma c, m \gamma \vec{v}).$$

In particular $p_\mu p^\mu = -m^2 c^2 = \frac{E^2}{c^2} - p^2$, and finally we get:

$$E^2 - p^2 c^2 = m^2 c^4$$

$$p_\mu p^\mu \begin{cases} < 0 & m^2 > 0 \\ = 0 & m^2 = 0 \\ > 0 & m^2 < 0. \end{cases}$$

Collisions:

$$p_i^\mu = p_f^\mu$$

• **Scattering Matrix:** $S = \lim_{t \rightarrow \infty} T \left[\exp \left(i \int_{-\infty}^{\infty} dt' H_I(t') \right) \right]$

• Wick: $T[\phi(x_1) \phi(x_2)] = : \phi(x_1) \phi(x_2) : + \overline{\phi(x_1) \phi(x_2)}$

Remember that:

• $\phi(x_1) \phi(x_2) = i D_F(x_1 - x_2) = \int \frac{d^4 p}{(2\pi)^4} \frac{1}{p^2 - m^2 + i\epsilon} e^{-ip(x_1 - x_2)}$

• $\psi(x_1) \bar{\psi}(x_2) = i S_F(x_1 - x_2) = i \int \frac{d^4 p}{(2\pi)^4} \frac{\not{p} \gamma_5 + m \gamma_5}{p^2 - m^2 + i\epsilon}$

• $A_\mu(x_1) A_\nu(x_2) = i D_{\mu\nu}^F(x_1 - x_2) = \int_p \frac{-i(\eta_{\mu\nu} - (3-1) p_\mu p_\nu / p^2)}{p^2 + i\epsilon}$

QFT (Quantum electrodynamics):

→ Fermions $(\bar{\psi}, \psi)$ $\mathcal{L} = i \bar{\psi} \gamma^\mu \partial_\mu \psi - m \bar{\psi} \psi$

If we propose the changes: $\psi \rightarrow \psi' = e^{i\theta} \psi$
 $\bar{\psi} \rightarrow \bar{\psi}' = e^{-i\theta} \bar{\psi}$

$g = e^{i\theta} \in U(1)$ (Circle rotations)

Using this in the Lagrangian: $\mathcal{L}' = i \bar{\psi}' \gamma^\mu \partial_\mu \psi' - m \bar{\psi}' \psi'$

$\mathcal{L}' = i e^{-i\theta} \bar{\psi} \gamma^\mu \partial_\mu e^{i\theta} \psi - m e^{-i\theta} \bar{\psi} e^{i\theta} \psi$

$\mathcal{L} = i \bar{\psi} \gamma^\mu \partial_\mu \psi - m \bar{\psi} \psi$

• **Noether theorem:** Global symmetry → Quantity conserved.

Conserved current: $J^\mu = \frac{\partial \mathcal{L}}{\partial(\partial_\mu \psi)} \Delta \psi + T^\mu{}_\nu \Delta x$

- $\pi(x) = \frac{\partial \mathcal{L}}{\partial(\dot{\psi})}$

$$\psi' = e^{i\theta} \psi = (1+i\theta) \psi = \psi + i\theta \psi$$

$$\frac{\partial \mathcal{L}}{\partial(\partial_\mu \psi)} = i \bar{\psi} \gamma^\mu \implies J^\mu = i \bar{\psi} \gamma^\mu \psi$$

Conserved Current: $J^\mu = ie \bar{\psi} \gamma^\mu \psi$.

Local: $\psi \rightarrow e^{i\theta(x)} \psi$; $\bar{\psi} \rightarrow e^{-i\theta(x)} \bar{\psi}$