view_frames Result Recorded at time: 4924.159 map Broadcaster: /ekf_localization Average rate: 150.301 Buffer length: 4.99 Most recent transform: 4924.124 Oldest transform: 4919.134 base_link Broadcaster: /robot_state_publisher Average rate: 10000.0 Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 chassis_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher | Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher ` Average rate: 10000.0 Average rate: 10000.0 Average rate: 10000.0 Average rate: 50.202 Average rate: 10000.0 Average rate: 10000.0 Average rate: 50.202 Average rate: 50.202 Average rate: 50.202 Buffer length: 0.0 Buffer length: 0.0 Buffer length: 4.96 Buffer length: 4.96 Buffer length: 0.0 Buffer length: 4.96 Buffer length: 0.0 Buffer 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