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# OVERVIEW

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What is Kotlin?

2

Runnable  
Interface

3

Unsynchronized  
Run

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Synchronized  
Run

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Priorities Run

# What is Kotlin?

- Development started in 2010 by JetBrains – first stable release in 2016 and announced as preferred android language in 2019
- Runs on the JVM – transforms Kotlin source code into Java bytecode
- Amazon, Google, Cash App all implement Kotlin in their backend development



## **Kotlin pros**

- Statically Typed
- Concise
- Open Source
- IntelliJ IDEA is made for Kotlin

## **Kotlin Cons**

- Slower compilation
- Steep learning curve
- High potential complexity

# RUNNABLE INTERFACE

- The runnable interface gives each thread a task to complete
- Each task will print the thread name, priority, and an iteration of 0 - 5
- Runnable helps specify the code a thread should run via its run() method
- We MUST override the run function
- Separates task logic from thread management

```
3  class Twentylines(val name : String) : Runnable { 3 Usages
4   override fun run() { 3 Usages
5      println("$name running")
6      println("Thread priority: ${Thread.currentThread().priority}")
7      for (i in 0 ≤ .. ≤ 5) { println(i)
8      }
9  }
10 }
```

# UNSYNCHRONIZED RUN & LAMBDA FUNCTIONS

## *Unsynchronized Run*

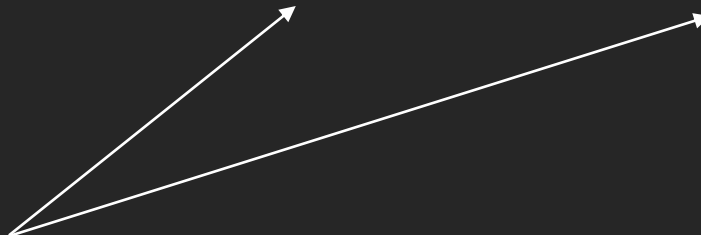
- No order to which thread enters CPU
- Each runs concurrently
- Threads start in the NEW state and then get moved to the RUNNABLE state
- When the threads are finished, they are TERMINATED

## *Lambda Functions*

- Instead of writing a full class or function, lambdas provide a shortcut
- It's an anonymous function
- Result implicitly returned

```
println("=====UNSYNC=====")
val tasks = ArrayList<Thread>()
repeat(5) { tasks.add(thread { Twentylines("Thread$it").run() }) }
```

Nested lambda  
Function



# SYNCHRONIZED RUN

## Reentrant Lock

- Is a mutual exclusion lock
- Thread holding the lock is allowed to execute the critical section
- Thread unlocks when finished
- When a thread acquires a lock, it remains in the RUNNABLE state and stays in the JVM Ready Queue

## Conditions

- Conditions set the state of the threads
- `await()` puts the threads in a WAITING state
- `.signalAll()` moves the threads from WAITING --> BLOCKED

```
println("====SYNC====")
val lock = ReentrantLock()
val condition = lock.newCondition()
var count = 0
repeat(times = 5) { i ->
    tasks.add(thread {
        lock.lock()
        try {
            while (count != i) {
                condition.await()
            }
            TwentyLines(name = "task $i").run(); count++; condition.signalAll()
        } finally {
            lock.unlock()
        }
    })
}
```

## Try / Finally

- If an exception occurs in our critical section, the lock is always released
- This prevents deadlock since some threads would be blocked forever

# CRITICAL SECTION

```
lock.lock()
try {
    while (count != i) {
        condition.await()
    }; Twentylines("task $i").run(); count++; condition.signalAll()
} finally {
    lock.unlock()
}
```

- The mutual exclusion lock ensures that only one thread can access the critical section at a time
- Checking the count, running our task, incrementing count, and signaling the threads all happen one at a time
- Without a mutual exclusion lock we are exposed to a race condition

# PRIORITY RUN

- Every thread has a set priority
- Priorities can be a range of integers from 1 – 10
- Default priority of any thread is 5
- Threads are in the NEW state until they are started, which puts them in the RUNNABLE state

```
35 tasks.clear()
36 println("====priorities====")
37 repeat( times = 5) { i ->
38     tasks.add(thread(start = false) { Twentylines( name = "Thread$i").run() })
39 }
40
41 tasks[0].priority = Thread.MIN_PRIORITY
42 tasks[1].priority = 3
43 tasks[2].priority = 5
44 tasks[3].priority = 8
45 tasks[4].priority = Thread.MAX_PRIORITY
46
47 tasks.forEach{ it.start() }
48 tasks.forEach{ it.join() }
49 }
```

- Priorities can be set using `x.priority = y`
- To obtain the current priority you can call, `Thread.currentThread().priority`
- *MAX\_PRIORITY = 10* , *NORM\_PRIORITY = 5* , *MIN\_PRIORITY = 1*

## Does setting priorities make a difference?

```
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7         for (i in 0 ≤ .. ≤ 5) { println(i)
8         }
9     }
10 }
```



# OUTPUTS

====UNSYNC====

Thread0 running  
Thread2 running  
Thread priority: 5  
Thread priority: 5  
Thread1 running  
Thread priority: 5  
Thread3 running  
Thread priority: 5  
Thread4 running  
Thread priority: 5

====SYNC====

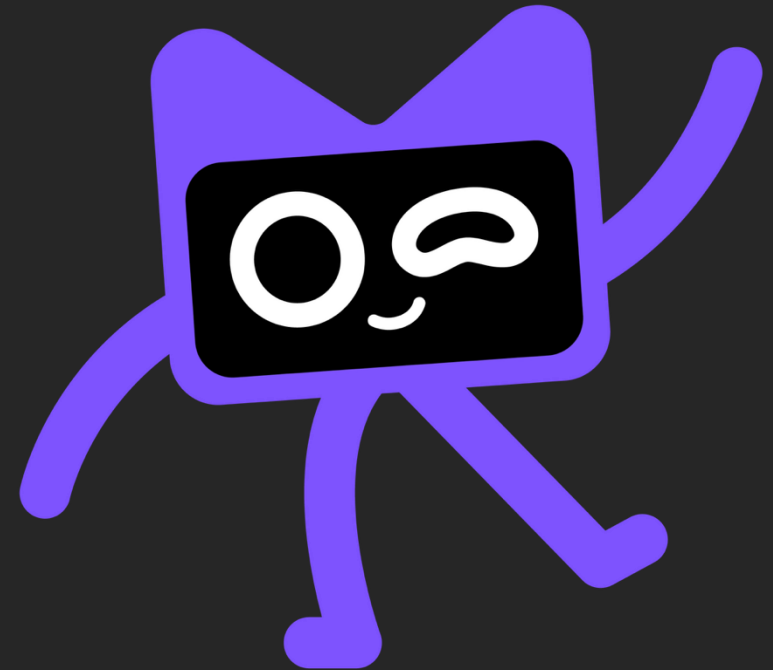
task 0 running  
Thread priority: 5  
task 1 running  
Thread priority: 5  
task 2 running  
Thread priority: 5  
task 3 running  
Thread priority: 5  
task 4 running  
Thread priority: 5

====priorities====

Thread0 running  
Thread priority: 1  
Thread1 running  
Thread priority: 3  
Thread3 running  
Thread priority: 8  
Thread2 running  
Thread priority: 5  
Thread4 running  
Thread priority: 10

# Problems & What We Learned

- **Kotlin basics**
- **MacOS**
- **Lambda Functions**
- **Priorities**
- **Critical Section**
- **Race Condition**



# CONCLUSION

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QUESTIONS?



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