

$$\boxed{\dot{X} + X = 0} \quad \text{sol. gral. } X(t) = Ce^{-t}$$

$$\boxed{\begin{array}{l} \dot{X} + \lambda X = 0 \\ X(0) = C_0 \end{array}} \quad \begin{array}{l} \text{sol. gral. } X(t) = Ce^{-\lambda t} \\ \Rightarrow Ce^{-0(1)} = C_0 \Rightarrow C = C_0 \Rightarrow X(t) = C_0 e^{-\lambda t} \text{ es sol. part.} \end{array}$$

$$\boxed{\begin{array}{l} \dot{X}_1 + \lambda_1 X_1 = 0 \\ \dot{X}_2 + \lambda_2 X_2 = 0 \end{array}} \quad \begin{array}{l} \text{sol. gral. } \begin{pmatrix} X_1(t) \\ X_2(t) \end{pmatrix} = \begin{pmatrix} C_1 e^{-\lambda_1 t} \\ C_2 e^{-\lambda_2 t} \end{pmatrix} \end{array} \quad A\vec{X} = \vec{\dot{X}} \quad \begin{pmatrix} -\lambda_1 & 0 \\ 0 & -\lambda_2 \end{pmatrix} \begin{pmatrix} X_1 \\ X_2 \end{pmatrix} = \begin{pmatrix} \dot{X}_1 \\ \dot{X}_2 \end{pmatrix}$$

↖ sistema desacoplado

$$\boxed{\begin{array}{l} \dot{X}_1 + \lambda_1 X_1 = 0 \\ \vdots \\ \dot{X}_n + \lambda_n X_n = 0 \end{array}} \quad \begin{pmatrix} X_1(t) = C_1 e^{-\lambda_1 t} \\ \vdots \\ X_n(t) = C_n e^{-\lambda_n t} \end{pmatrix} \quad \begin{pmatrix} -\lambda_1 & 0 & \dots & 0 \\ 0 & -\lambda_2 & 0 & \dots & 0 \\ \vdots & & \ddots & & \vdots \\ 0 & \dots & 0 & -\lambda_n \end{pmatrix} \begin{pmatrix} X_1 \\ X_2 \\ \vdots \\ X_n \end{pmatrix} = \begin{pmatrix} \dot{X}_1 \\ \dot{X}_2 \\ \vdots \\ \dot{X}_n \end{pmatrix}$$

$$A = [T]_{\beta}$$

$$\vec{\dot{X}} = A\vec{X} \quad \begin{pmatrix} \dot{X}_1 \\ \dot{X}_2 \end{pmatrix} = \begin{pmatrix} 1 & 2 \\ 3 & 2 \end{pmatrix} \begin{pmatrix} X_1 \\ X_2 \end{pmatrix} \quad \det(A - \lambda I) = 0 = \begin{vmatrix} 1-\lambda & 2 \\ 3 & 2-\lambda \end{vmatrix} = (1-\lambda)(2-\lambda) - 6$$

$$\Rightarrow \lambda^2 - 3\lambda - 4 = 0 = (\lambda - 4)(\lambda - (-1)) \Rightarrow \lambda_1 = 4, \lambda_2 = -1. \quad [\vec{v}_1]_{\beta} = \begin{pmatrix} 2 \\ 3 \end{pmatrix}$$

$$(A - \lambda_1 I) \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow \begin{pmatrix} -3 & 2 \\ 3 & -2 \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow \begin{array}{l} -3u_1 + 2u_2 = 0 \\ 3u_1 - 2u_2 = 0 \end{array} \Rightarrow u_1 = \frac{2}{3}u_2 \Rightarrow \begin{pmatrix} \frac{2}{3}u_2 \\ u_2 \end{pmatrix}$$

$$(A - \lambda_2 I) \begin{pmatrix} w_1 \\ w_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow \begin{pmatrix} 2 & 2 \\ 3 & 3 \end{pmatrix} \begin{pmatrix} w_1 \\ w_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \Rightarrow \begin{array}{l} 2w_1 + 2w_2 = 0 \\ 3w_1 + 3w_2 = 0 \end{array} \Rightarrow w_1 = -w_2 \Rightarrow \begin{pmatrix} -w_2 \\ w_2 \end{pmatrix} \Rightarrow [\vec{v}_2]_{\beta} = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

$$\mathcal{B} = (\vec{v}_1, \vec{v}_2) \text{ es b.o. de } \mathbb{R}^2. \quad \begin{pmatrix} -4 & 0 \\ 0 & 1 \end{pmatrix} = [T]_{\mathcal{B}} = [I]_{\beta}^{\mathcal{B}} [T]_{\beta} [I]_{\mathcal{B}}^{\beta}$$

$$\left. \begin{array}{l} y_1 = C_1 e^{4t} \\ y_2 = C_2 e^{-t} \end{array} \right\} \vec{X} = \begin{pmatrix} 2 & -1 \\ 3 & 1 \end{pmatrix} \begin{pmatrix} C_1 e^{4t} \\ C_2 e^{-t} \end{pmatrix} \Rightarrow \begin{array}{l} X_1 = 2C_1 e^{4t} - C_2 e^{-t} \\ X_2 = 3C_1 e^{4t} + C_2 e^{-t} \end{array} \quad \downarrow \begin{pmatrix} 2 & -1 \\ 3 & 1 \end{pmatrix}$$