

■ Add identification! . . . . .	4
■ Add examples and complete notes for the last half hour of the class. . . . .	4

## Introduction

11/3/24

**Note** All vector spaces are real and finite dimensional unless otherwise stated.

**Definition 0.1** A bilinear form  $\Omega : V \times V \rightarrow \mathbb{R}$  on a vector space  $V$  is a *linear symplectic form* if it is

- (a) skew-symmetric, i.e.  $\Omega(v, w) = -\Omega(w, v) \quad \forall v, w \in V$ ;
- (b) non-degenerate, i.e.  $\Omega(v, w) = 0 \quad \forall v \in V \implies w = 0$ .

**Example 0.2**

- (1) Consider<sup>1</sup>  $V = \mathbb{R}^2, B = (e_1, e_2)$ . Then<sup>2</sup>  $[\Omega]_B^B = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$  represents a linear symplectic form on  $\mathbb{R}^2$ .
- (2) Consider  $V = \mathbb{R}^{2n}, B = (e_1, \dots, e_n, f_1, \dots, f_n)$ . Then

$$[\Omega]_B^B = \left( \begin{array}{c|c} 0 & I_n \\ \hline -I_n & 0 \end{array} \right)$$

represents a linear symplectic form on  $\mathbb{R}^{2n}$ . Moreover, we have that

$$\begin{aligned} \Omega(e_1, e_j) &= 0, \\ \Omega(f_i, f_j) &= 0, \\ \Omega(e_i, f_j) &= \delta_{ij} = -\Omega(f_j, e_i). \end{aligned} \tag{0.1}$$

**Definition 0.3** The pair  $(V, \Omega)$  is a (*real*) *symplectic vector space*. If it has a basis  $B = (e_1, \dots, e_n, f_1, \dots, f_n)$  satisfying the relations given by the equations in (0.1), we say that  $B$  is a *symplectic basis* of  $(V, \Omega)$ .

**Remark 0.4** If  $B$  is an ordered basis of  $V$ , then  $[\Omega]_B^B$  is antisymmetric and invertible.

**Example 0.5** Let  $W$  be a vector space with dual  $W^*$  and  $V = W \oplus W^*$ . Note there is an isomorphism of vector spaces  $W \oplus W^* \xrightarrow{\sim} W^* \oplus W, (w, f) \mapsto (f, -w)$ . Then,

$$\begin{aligned} \Omega : V \times V &\rightarrow \mathbb{R}, \\ ((w_1, f_1), (w_2, f_2)) &\mapsto f_2(w_1) - f_1(w_2) \end{aligned}$$

is a linear symplectic form on  $V$ .

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<sup>1</sup>Whenever order is needed for a basis, I write them as ordered bases (i.e. between parenthesis) instead of unordered sets, and this is important to me!

<sup>2</sup>The notation  $[\Gamma]_\alpha^\beta$  indicates the matrix representation of the bilinear form  $\Gamma$  which takes column vectors  $[w]_\alpha$  from the right represented, which are with an ordered basis  $\alpha$ , and row vectors  $([v]_\beta)^T$  from the left, which are represented with an ordered basis  $\beta$  and transposed, and computes  $\Gamma(v, w)$ .

**Lemma 0.6** If  $(V, \Omega)$  is a symplectic vector space, then  $\dim(V) \equiv 0 \pmod{2}$ .

*Proof.* If  $A$  represents  $\Omega$ , then

$$\begin{aligned}\det(A) &= \det(-A^T) \\ &= \det(-A) \\ &= (-1)^{\dim(V)} \det(A).\end{aligned}$$

□

**Definition 0.7** Let  $(V, \Omega)$  be a symplectic vector space. A linear subspace  $U \subseteq V$  is

- (a) *symplectic* if  $\Omega|_U$  is a linear symplectic form on  $U$  (non-degeneracy is sufficient);
- (b) *isotropic* if  $\Omega|_U = 0$ ;
- (c) *coisotropic* if  $\Omega(u, v) = 0 \quad \forall u \in U \implies v \in U$ ;
- (d) *Lagrangian* if it is both isotropic and coisotropic.

**Example 0.8** Let  $V = \mathbb{R}^{2n}$ ,  $B = (e_1, \dots, e_n, f_1, \dots, f_n)$ .

- (1)  $\langle \{e_1, f_1\} \rangle$  is a symplectic subspace which is neither isotropic nor coisotropic (thus neither Lagrangian).
- (2)  $\langle \{e_1, \dots, e_n\} \rangle$  is a Lagrangian subspace which is not symplectic.
- (3)  $\{0\}$  and  $\langle \{e_1, \dots, \hat{e}_k, \dots, e_n\} \rangle$ , where  $\hat{e}_k$  indicates the exclusion of the  $k$ -th vector of the canonical ordered basis from the set, are isotropic subspaces which are not coisotropic, where the first one is trivially symplectic.
- (4) If  $I, J \subseteq \{1, \dots, n\}$  and  $\langle \{e_i\}_{i \in I} \cup \{f_j\}_{j \in J} \rangle$  is
  - symplectic if, and only if,  $I = J$ ;
  - isotropic if, and only if,  $I \cap J = \emptyset$ ;
  - coisotropic if, and only if,  $I \cup J = \{1, \dots, n\}$ <sup>3</sup>;
  - Lagrangian if, and only if,  $I = J^c$ .

## 12/3/24

**Remark 0.9** Let  $V$  be a real finite dimensional vector space with dual  $V^*$  and  $\Omega : V \times V \rightarrow \mathbb{R}$  a bilinear form. Then, we have the linear isomorphism<sup>4</sup>

$$\begin{aligned}\Omega^\# &= \tilde{\Omega} : V \rightarrow V^*, \\ v &\mapsto \Omega(v, \cdot).\end{aligned}$$

$\Omega$  is symplectic if and only if

- (1)  $\Omega^\#$  is antiselfdual, i.e.  $(\Omega^\#)^* = -\Omega^\#$ , and

<sup>3</sup>I'm pretty sure of this characterization. But keep this note until we get any kind of confirmation.

<sup>4</sup>I believe we need to ask for  $v \neq 0$ , although the professor didn't mention it.

(2)  $\Omega^\#$  is injective (or, equivalently, an isomorphism).

**Definition 0.10** Let  $(V, \Omega)$  be a symplectic vector space and  $U \subseteq V$  a linear subspace. The *symplectic orthogonal* or *symplectic annihilator* of  $U$  is

$$U^\Omega := \{v \in V \mid \Omega(u, v) = 0 \quad \forall u \in U\}.$$

**Proposition 0.11** Let  $(V, \Omega)$  be a symplectic vector space and  $U \subseteq V$  a linear subspace. Then,

$$\dim(U) + \dim(U^\Omega) = \dim(V) \quad \text{and} \quad (U^\Omega)^\Omega = U.$$

*Proof.* The first part follows from the fact that  $\Omega^\#$  is an isomorphism. Moreover, the inclusion  $U \subseteq (U^\Omega)^\Omega$  follows from Definition 0.10 and the equality follows by noticing their dimensions are equal.  $\square$

**Remark 0.12** Let  $U$  be a linear subspace of a symplectic vector space  $(V, \Omega)$ . Then  $U$  is

- symplectic if, and only if  $V = U \oplus U^\Omega$ ;
- isotropic if, and only if,  $U \subseteq U^\Omega$ ;
- coisotropic if, and only if,  $U \supseteq U^\Omega$ ;
- Lagrangian if, and only if,  $U = U^\Omega$ .

**Exercise 0.13** Prove that

- (1)  $U$  is symplectic if, and only if,  $U^\Omega$  is symplectic;
- (2)  $U$  is isotropic if, and only if,  $U^\Omega$  is coisotropic;
- (3)  $(U \cap W)^\Omega = U^\Omega + W^\Omega$ .

**Proposition 0.14** A symplectic vector space  $(V, \Omega)$  with  $\dim(V) = 2n$  has a symplectic basis.

*Proof.* We will prove this by induction, taking as basis  $\dim(V) = 2$ . Let  $e_1 \neq 0$ . Then there exists  $v \in V$  such that  $\Omega(e_1, v) \neq 0$ . By the Gram-Schmidt orthonormalization process, it follows that  $\{e_1, \frac{v}{\Omega(e_1, v)}\}$  is a symplectic basis.

Assume the Proposition holds for  $\dim(V) = 2n$ . Let  $v, v' \in V$  be such that  $\Omega(v, v') \neq 0$ . Then  $(S := \langle v, v' \rangle, \Omega|_S)$  is a symplectic space of dimension 2. Note that  $(S^\Omega, \Omega|_{S^\Omega})$  is a symplectic vector space of dimension  $2n$ . Since  $V = S \oplus S^\Omega$ , where both subspaces have symplectic bases due to the induction hypothesis, it follows that  $(V, \Omega)$  has a symplectic basis.  $\square$

**Remark 0.15** If  $L$  is a Lagrangian subspace of a symplectic vector space  $(V, \Omega)$ , then  $\dim(L) = \frac{\dim(V)}{2}$ .

**Proposition 0.16** (Lagrangian split) Let  $(V, \Omega)$  be a symplectic vector space. Then, there exist Lagrangian subspaces  $L, L'$  such that  $V = L \oplus L'$ .

*Proof.*

**Exercise 0.17** Write the proof; the idea is to show that you can find a maximal (with respect to dimension) isotropic subspace.  $\square$

**Remark 0.18** Recall that linear maps  $\varphi : V \rightarrow V$  induce a map between bilinear forms via

$$\varphi^*(\Omega(v, v')) = \Omega(\varphi(v), \varphi(v')).$$

The Lagrangian split  $V = L \oplus L'$  of Proposition 0.16 is canonical in the sense that there exists a canonical isomorphism  $\varphi : V \rightarrow L \oplus L'$  such that  $(\varphi^{-1})^*\Omega$  is the canonical symplectic form on  $L \oplus L'$ , i.e.

$$\Omega(v_1 + v'_1, v_2 + v'_2) = \Omega(v_1, v'_2) - \Omega(v_2, v'_1).$$

**Definition 0.19**  $M$  is a *topological manifold* if it is a topological space such that

- $\forall p \in M$ , there exists a neighborhood  $V$  of  $p$  that is homeomorphic to an open set in  $\mathbb{R}^n$ ;
- it is Hausdorff, i.e. for any two points we can find a neighbourhood for each such that they are disjoint;
- it satisfies the second countability axiom, i.e. there exists a countable basis.

**Example 0.20**

- (1) The torus  $T^2 = S^1 \times S^1$ , obtained via the identification

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- (2) The Klein bottle  $K^2$ , obtained via the identification  $(x, y) \sim (x + 1, y) \sim (1 - x, y + 1)$  in  $[0, 1] \times [0, 1] \subseteq \mathbb{R}^2$ .
- (3) The projective plane, obtained via the identification  $(x, y) \sim (x + 1, 1 - y) \sim (1 - x, y + 1)$  in  $[0, 1] \times [0, 1] \subseteq \mathbb{R}^2$ .

**Remark 0.21** Recall that  $M$  is a differential manifold if it is a topological manifold of dimension  $n$  with an atlas, which is a collection of charts  $\{U_\alpha, \varphi_\alpha\}_{\alpha \in A}$  such that

- (1)  $U_{\alpha \in A} \varphi_\alpha(U_\alpha) = M$ ,
- (2)  $W = \varphi_\beta(U_\beta) \cap \varphi_\alpha(U_\alpha) \neq \emptyset$ , where  $\varphi_\beta^{-1} \varphi_\alpha$  and  $\varphi_\alpha \varphi_\beta^{-1}$  are of class  $C^\infty$ ,
- (3)  $U_{\alpha \in A} \varphi_\alpha(U_\alpha)$  is maximal.

**Example 0.22**

Add examples and complete notes for the last half hour of the class.

**18/3/24**