

NENG 685, Fall 2017
Transport Solution Approaches
October 2, 2017

We've talked about the problem types that we can be faced with as nuclear engineers in the arena of national security. Now let's talk about approaches and what kinds of methods we use when.

Computational Methods

Inside the box of computational methods, we have two main categories:

- **Deterministic:** discretize all independent variables, obtain a set of coupled, linear, algebraic equations and develop a numerical method to solve them.
- **Probabilistic:** follow the history of each relevant particle based on the underlying probabilities for various types of interactions.

Each method has its own benefits and challenges. We'll talk a bit about **deterministic first**. Here, the discretization methods are a big part of the strategy, followed by parallelization.

The size of the problems (which impacts memory and parallelization performance) is governed by discretization. The quality and behavior of solutions is also governed by discretization. To get more accurate fluxes, typical transport problems today are three-dimensional, have up to thousands \times thousands \times thousands of mesh points, use up to ~ 150 energy groups, include accurate expansions of scattering terms, and are solved over many directions.

Table 1: Meaning and Range of Indices Used in Transport Discretization

Variable	Symbol	First	Last	Low	High
Energy	g	1	G	2	100s
Solid Angle	a	1	n	S_2	S_{16}
Space	n/a	n/a	n/a	1?	1e9
Legendre moment (P_N)	l	0	N	0	9

E.g. In 2012, a Pressurized Water Reactor (PWR)-900 with 44 groups, a $578 \times 578 \times 700$ mesh, using S_{16} level-symmetric quadrature, and with P_0 scattering was solved: 1.7 trillion unknowns.

With **Monte Carlo**, we sample the physics of every single interaction of every single particle until we have enough samples to assert that something is statistically valid. This requires lots and lots of samples, but is typically fairly easy to parallelize. Monte Carlo requires strategies and rules for sampling the physics—which can be complicated.

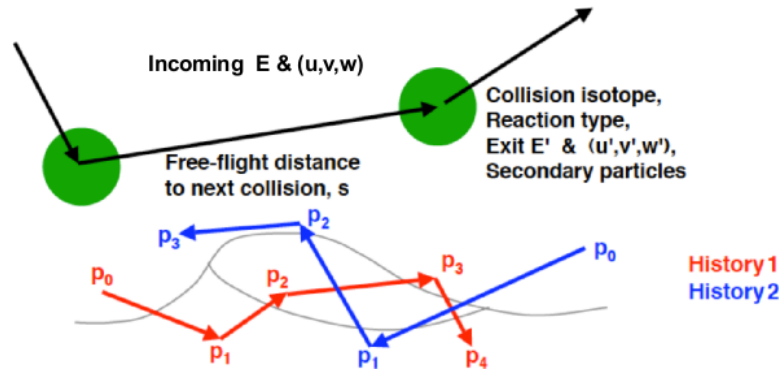


Figure 1: Monte Carlo particle tracking

Diffusion Equation

In this class we won't actually do much with the full BTE. Instead, we will use the diffusion equation, which simplifies the math a bit. The diffusion equation removes the angle dependence and gives only ϕ as a solution. Nuclear reactions and thus interaction rates only depend on the scalar flux, so maybe that's sufficient.

The diffusion equation is derived by starting with the transport equation and **integrating over all angles**. In the derivation we make the following assumptions

- the scattering term is azimuthally symmetric
- assume that scattering is at most linearly anisotropic [P_1 expansion]
- assume that the angular flux is at most linearly anisotropic [expand ψ in Legendre polynomials out to P_1]

We will work through this derivation in the coming weeks.

This equation *now includes several assumptions* that are **valid** when the solution is **not** near

- a void,
- boundary,
- source,
- or strong absorber.

While these requirements can be quite restrictive, the diffusion equation has been used frequently for analysis of nuclear systems throughout the history of the nuclear industry.

Comparison

In order of increasing accuracy *and* increasing runtime:

1. Diffusion Theory

- discretized and homogenized space
- linearly anisotropic direction
- discretized energy (few-group)

2. Deterministic

- discretized space
- discretized direction (discrete ordinates [S_N]) or functional expansion of direction (spherical harmonics)
- discretized energy (multi-group)

3. Monte Carlo

- continuous spatial resolution
- continuous direction representation
- continuous energy representation

	Monte Carlo	Deterministic
Strengths	<ul style="list-style-type: none"> * General geometry * Continuous Energy * Continuous in Angle * Inherently 3-D * Easy to parallelize on CPUs 	<ul style="list-style-type: none"> * Fast * Global Solution * Solution is of same quality everywhere * Inputs can be pretty simple
Weaknesses	<ul style="list-style-type: none"> * Slow * Might be memory intensive * Solutions have statistical error * Local solutions only * Must adequately sample phase space * Need efficient VR * Input can be extremely complicated 	<ul style="list-style-type: none"> * Variable discretization governs solution quality * Might be memory intensive * Solution contains truncation error * Constrained by what you can mesh * Ray Effects * Can be complicated to parallelize on CPUs

We tend to think of Monte Carlo as “benchmark quality” and highly flexible.

What is one major hazard of Monte Carlo?

What is the biggest challenge of using MC for detailed design?