

## 1) Design Requirements:

$$V_A = 50V, P = 600W @ 1300 \text{ rpm}, T_{\text{stall}} = 1.55 T_{\text{Dop}}$$

$$(136.13 \text{ rad/s}) \quad T_{\text{fric}} = 0.07 T_{\text{Dop}}$$

$$a) T_{\text{Dop}} = \frac{P_{\text{Dop}}}{\omega_{\text{Dop}}} = \frac{0.600 \text{ kW}}{1300 \text{ rpm}} \left( 9.5488 \right) = 4.40 \text{ E-}3 \text{ Nm}$$

$$T_{\text{stall}} = 1.55 T_{\text{Dop}} = 1.55 (4.40 \text{ E-}3 \text{ Nm}) = 6.82 \text{ E-}3 \text{ Nm}$$

$$T_{\text{fric}} = 0.07 T_{\text{Dop}} = 0.07 (4.40 \text{ E-}3 \text{ Nm}) = 308 \text{ E-}6 \text{ Nm}$$

$$b) T_{\text{fric}} = c \omega_{\text{Dop}} \rightarrow c = \frac{T_{\text{fric}}}{\omega_{\text{Dop}}} = \frac{308 \text{ E-}6 \text{ Nm}}{136.13 \text{ rad/s}} = 2.26 \text{ E-}6 \frac{\text{Nm s}}{\text{rad}}$$

$$c) \omega_{\text{Dop}} = \frac{K V_A - R_A T_{\text{Dop}}}{c R_A + K^2} \quad \omega_{\text{stall}} = \frac{K V_A - R_A T_{\text{stall}}}{c R_A + K^2} = 0$$

$$\omega_{\text{Dop}} (c R_A + \omega_{\text{Dop}} K^2) = K V_A - R_A T_{\text{Dop}} \quad K V_A - R_A T_{\text{stall}} = 0$$

$$\omega_{\text{Dop}} K^2 - K V_A + \omega_{\text{Dop}} c R_A + R_A T_{\text{Dop}} = 0 \quad K V_A - R_A T_{\text{stall}} = 0$$

$$R_A = \frac{K V_A}{T_{\text{stall}}}$$

$$\omega_{\text{Dop}} K^2 - K V_A + (\omega_{\text{Dop}} c + T_{\text{Dop}}) \frac{K V_A}{T_{\text{stall}}} = 0$$

$$\omega_{\text{Dop}} K^2 + K V_A \left( \frac{\omega_{\text{Dop}} c + T_{\text{Dop}}}{T_{\text{stall}}} - 1 \right) = 0$$

$$\frac{K}{\omega_{\text{Dop}}} \left( K + \frac{V_A}{\omega_{\text{Dop}}} \left( \frac{\omega_{\text{Dop}} c + T_{\text{Dop}}}{T_{\text{stall}}} - 1 \right) \right) = 0$$

$$K = 0, -\frac{V_A}{\omega_{\text{Dop}}} \left( \frac{\omega_{\text{Dop}} c + T_{\text{Dop}}}{T_{\text{stall}}} - 1 \right)$$

$$K_T, K_b = \frac{-V_A}{\omega_{\text{Dop}}} \left( \frac{\omega_{\text{Dop}} c + T_{\text{Dop}}}{T_{\text{stall}}} - 1 \right)$$

$$R_A = \frac{-V_A^2}{T_{\text{stall}} \omega_{\text{Dop}}} \left( \frac{\omega_{\text{Dop}} c + T_{\text{Dop}}}{T_{\text{stall}}} - 1 \right)$$



$$K_T = K_b = -\frac{V_a}{\omega_{\text{dop}}} \left( \frac{\omega_{\text{dop}} C - T_{\text{dop}}}{T_{\text{stall}}} - 1 \right) = -\frac{50V}{136.13 \frac{\text{rad}}{s}} \left( \frac{(136.13 \frac{\text{rad}}{s})(2.26E-6 \frac{\text{Nm}\cdot\text{s}}{\text{rad}}) - (4.4E-3 \text{Nm})}{6.82E-3 \text{Nm}} - 1 \right)$$

$$= 0.5893 \frac{\text{Nm}}{\text{A}}$$

$$R_a = \frac{-V_a^2}{T_{\text{stall}} \omega_{\text{dop}}} \left( \frac{\omega_{\text{dop}} C - T_{\text{dop}}}{T_{\text{stall}}} - 1 \right)$$

$$= 4.32E3 \Omega$$

$$d) i_{\text{stall}} = \frac{V_a}{R_a} = \frac{50V}{4.32E3 \Omega} = 11.57 \text{ mA}$$

$$i_{\text{dop}} = \frac{c V_a + K_b T_{\text{dop}}}{c R_a + K_b K_T} = \frac{(50V)(2.26E-6 \frac{\text{Nm}\cdot\text{s}}{\text{rad}}) + (0.5893 \frac{\text{Nm}}{\text{A}})(4.4E-3 \text{Nm})}{(2.26E-6 \frac{\text{Nm}\cdot\text{s}}{\text{rad}})(4.32E3 \Omega) + (0.5893 \frac{\text{Nm}}{\text{A}})^2} = 7.58 \text{ mA}$$

$$e) \omega_{nl} = \frac{K_T V_a}{c R_a + K_b K_T} = \frac{(0.5893 \frac{\text{Nm}}{\text{A}})(50V)}{(2.26E-6 \frac{\text{Nm}\cdot\text{s}}{\text{rad}})(4.32E3 \Omega) + (0.5893 \frac{\text{Nm}}{\text{A}})^2} = 82.5 \text{ rad/s}$$

$$f) \eta = \frac{P_{\text{out}}}{P_{\text{in}}} = \frac{600W}{(50V)(7.58E-3A)} = 158; \quad (\text{known to be wrong but correct})$$

find computational mistakes

$$g) \Omega(s) = \frac{V_a(s) K_T}{(R_a I + c L_a)s + c R_a + K_b K_T} \rightarrow \dot{\omega} (R_a I + c L_a) + \omega (c R_a + K_b K_T) = V_a K_T$$

$$\dot{\omega} + \frac{(c R_a + K_b K_T)}{R_a I + c L_a} \omega = V_a K_T \rightarrow \tau = \frac{R_a I + c L_a}{c R_a + K_b K_T}; L_a \approx 0$$

$$\tau = \frac{R_a I}{c R_a + K_b K_T} \rightarrow I = \frac{\tau}{R_a} (c R_a + K_b K_T)$$

$$I = \frac{2.475s}{4.32E3 \Omega} \left( (2.26E-6 \text{Nm}\cdot\text{s})(4.32E3 \Omega) + (0.5893 \frac{\text{Nm}}{\text{A}})^2 \right)$$

$$I = 204.5E-6 \text{ s}^2 \text{ m}^2$$



2)

$$a) L_a I s^2 + (R_a I + c L_a) s + c R_a + K_b K_T = 0$$

$$240E-9 s^2 + (64E-6 + 3E-3 c) s + 0.8 c + 25E-6 = 0$$

$$b) c_1 = 0 \quad s_1 = -0.391, \quad s_2 = -266.27$$

$$c_2 = 0.01 \quad s_1 = -125.73, \quad s_2 = -265.9$$

$$c_3 = 0.1 \quad s_1 = -266.7, \quad s_2 = -1249.9$$

e)

$$\tau = \frac{R_a I + c L_a}{c R_a + K_b K_T}$$

$$c_1 = 0$$

$$\tau = 2.56 \text{ ms}$$

$$t_{ss} = 12.8 \text{ ms}$$

$$c_2 = 0.01$$

$$\tau = 11.7 \text{ ms}$$

$$t_{ss} = 58.5 \text{ ms}$$

$$c_3 = 0.1$$

$$\tau = 4.54 \text{ ms}$$

$$t_{ss} = 22.7 \text{ ms}$$

f)

The simulated models do not fully agree with calculations given that the larger  $c$  becomes, the lower  $t_{ss}$  becomes in the simulation but not the calculations.