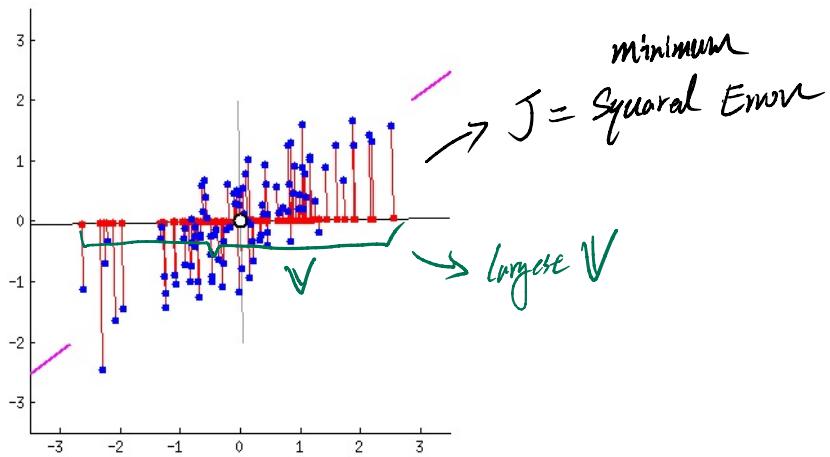
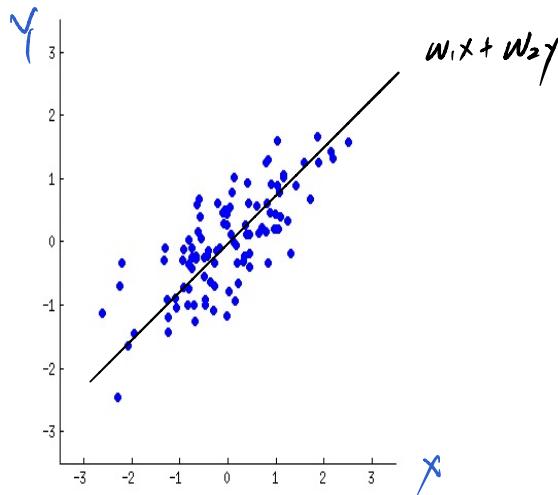
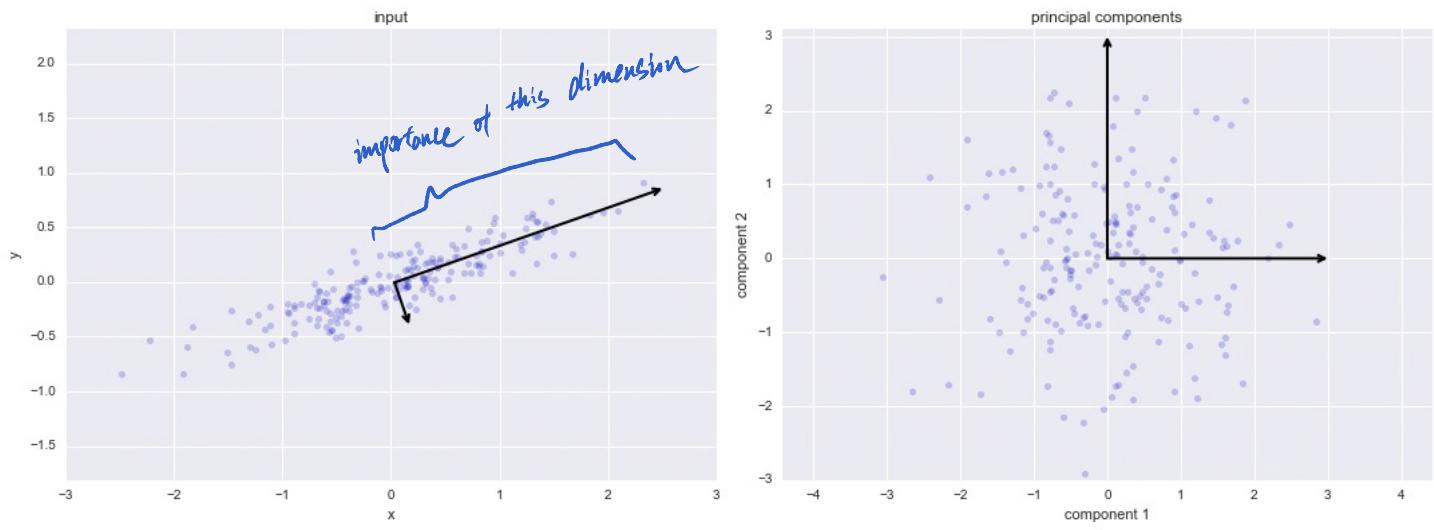


Principal Component Analysis and SVD

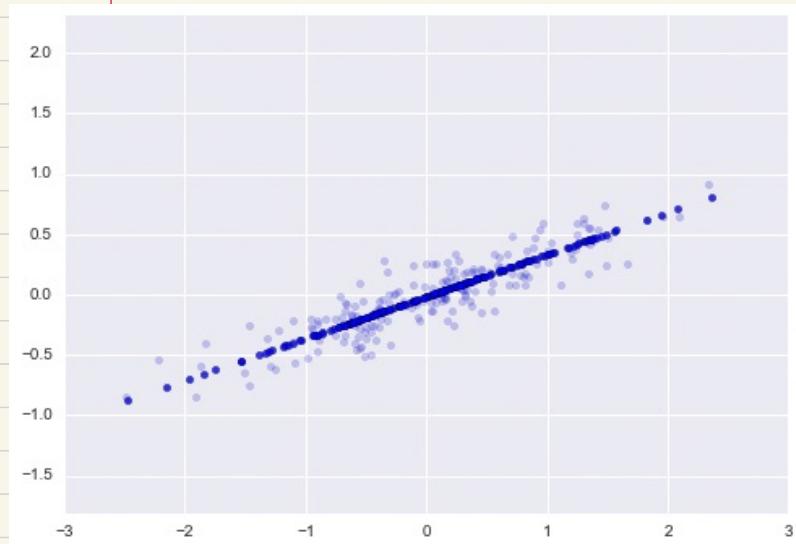
Dimensionality Reduction

Feb 7 2024
Coral Quant PCA Workshop
Da Gouy





Dimensionality Reduction



OLS

Eigen value & Eigen vector

$$AX = \lambda X \Rightarrow (\lambda I - A)X = 0$$

nxn scalar eigenvector

assume $X \neq 0 \Rightarrow \lambda I - A$ is not invertible

$$\Rightarrow \det(\lambda I - A) = 0$$

$$\text{e.g. } A = \begin{bmatrix} 5 & 2 \\ 7 & 4 \end{bmatrix} \text{ & } \det(\lambda I - A) = 0$$

$$\Rightarrow \det \left(A \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} - \begin{bmatrix} 5 & 2 \\ 7 & 4 \end{bmatrix} \right) = 0$$

$$\det \begin{bmatrix} \lambda+5 & -2 \\ 7 & \lambda-4 \end{bmatrix} = 0 \Rightarrow \lambda^2 + \lambda - 6 = 0$$

$$\Rightarrow \begin{cases} \lambda_1 = 2 \\ \lambda_2 = -3 \end{cases}$$

\Rightarrow find all $x \neq 0$ for each λ

$$\lambda=2: Ax=2x \Rightarrow \left(2 \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} - \begin{bmatrix} 5 & 2 \\ 7 & 4 \end{bmatrix} \right) \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow x_1 = \begin{bmatrix} 2 \\ 7 \end{bmatrix}$$

$$\lambda=-3: \Rightarrow x_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\text{e.g. } A = \begin{bmatrix} 0 & 2 \\ 2 & 3 \end{bmatrix} \Rightarrow x_1 = \begin{bmatrix} -0.89 \\ -0.44 \end{bmatrix} \quad x_2 = \begin{bmatrix} 0.44 \\ -0.89 \end{bmatrix}$$

Symmetric Matrix

$$x_1^\top \cdot x_2 = 0$$

„Python Example“

Example: A : Square Matrix

$A \cdot \vec{u} = \lambda \vec{u}$, λ is eigenvalue and
 \vec{u} is eigenvector, assume $\vec{u}^T \vec{u} = 1$

Suppose there are n solutions;

$(\lambda_1, u_1), (\lambda_2, u_2) \dots (\lambda_n, u_n)$

$$A \cdot \begin{bmatrix} u_1 & | & u_2 & | & \cdots & | & u_n \\ | & & | & & & & | \\ 1 & & 1 & & & & 1 \end{bmatrix} = \begin{bmatrix} \lambda_1 u_1 & | & \lambda_2 u_2 & | & \cdots & | & \lambda_n u_n \\ | & & | & & & & | \\ 1 & & 1 & & & & 1 \end{bmatrix}, \quad M = \begin{bmatrix} \lambda_1 & & & & 0 \\ 0 & \ddots & & & 0 \\ & & \ddots & & \\ & & & \ddots & \\ 0 & & & & \lambda_n \end{bmatrix}$$

$$A \cdot U = U \cdot A$$

If U is invertible, AKA, u_1, \dots, u_n span \mathbb{R}^n . (they are linearly independent)
orthogonal to each other

$$\Rightarrow A = U \cdot \Lambda \cdot U^{-1}$$

if A is symmetric and real $\Rightarrow \lambda \in \mathbb{R}$, $u^i = u^j$ ($u_i^T u_j = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{otherwise} \end{cases}$)

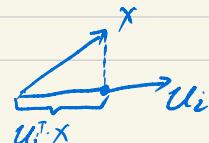
$$A = \begin{bmatrix} u_1 & u_2 & \cdots & u_n \end{bmatrix} \begin{bmatrix} \lambda_1 & & & \\ & \lambda_2 & & \\ & & \ddots & \\ & & & \lambda_n \end{bmatrix} \begin{bmatrix} -u_1^T & & & \\ & \vdots & & \\ & & u_n^T & \\ & & & \ddots \end{bmatrix}$$

$$\left[\begin{array}{cccc} 1 & | & \lambda_1 u_1 & \\ & | & \lambda_2 u_2 & \cdots \\ & | & \lambda_n u_n & \end{array} \right] \left[\begin{array}{c} -u_1^T - \\ | \\ -u_n^T - \end{array} \right]$$

$$= \sum_i \lambda_i u_i u_i^T$$

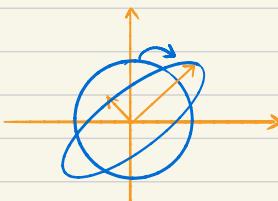
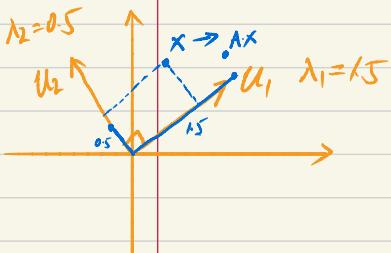
$$\Rightarrow Ax = \left(\sum_i \lambda_i \cdot u_i \cdot u_i^T \right) x = \sum_i \lambda_i \cdot u_i \cdot (u_i^T \cdot x)$$

this inner product is
projection of X on
 U_i



$$= \sum u_i (\lambda_i \cdot (u_i^T x))$$

↑
Scale by
 λ_i



Dimensionality Reduction

Kevin Murphy (20.1)

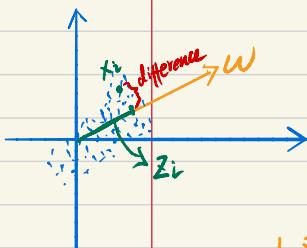
Principal Component Analysis

- a single vector w : vector of reconstruction z_i is scalar: Latent factor
 $d \times 1$

x_i is the true features of hypers

$$J = \sum_{i=1}^m \underbrace{(x_i - z_i w)^T (x_i - z_i w)}_{\text{squared error of difference}}, \quad x_i \text{ is given.}$$

- Assume data are centered (data are subtract from mean)



$$J = \sum_{i=1}^m x_i^T x_i - 2 z_i x_i^T w + z_i^2 w^T w$$

$$\frac{\partial J}{\partial z_k} = 0 : 2 x_k^T w = 2 z_k w^T w, \quad \text{W.L.O.G assume } w^T w = 1 \quad (\text{length of } w \text{ is 1})$$

$$\Rightarrow x_k^T w = z_k, \quad \text{length of } x \text{'s projection on } w \text{ is } z_k$$

$$w^T x_k = x_k^T w = z_k$$

↑
Scalar

$$\Rightarrow J = \text{const} \sum_i -2 w^T x_i x_i^T w + w^T x_i \cdot x_i^T w$$

$J = \text{const} - \underbrace{w^T (\sum_i x_i x_i^T) w}_{\star}$, we wanna have J to be min which means x_i 's projection on w as large as possible.

and we know that, $\sum_i x_i x_i^T = m \cdot \hat{\Sigma}^{ML}$

So minimize J is equivalent to max $w^T \hat{\Sigma}^{ML} w$

$$\underset{\max}{\arg} L = w^T \hat{\Sigma}^{ML} w - \lambda (w^T w - 1), \lambda \text{ is Lagrange multiplier}$$

$$\nabla_w L = 0 : 2 \hat{\Sigma}^{ML} w - 2 \lambda w = 0 \Rightarrow \underbrace{\hat{\Sigma}^{ML} w}_{\star} = \lambda w$$

$$\Rightarrow w^T \hat{\Sigma}^{ML} w = w^T \lambda w = \lambda w^T w = \lambda \leftarrow \begin{array}{l} \text{Largest EigenValue} \\ \text{and associated} \\ \text{EigenVector!} \end{array}$$

- You should project on the largest eigenvector of $\hat{\Sigma}^{ML}$ (of centered data).

the empirical covariance matrix

what if, we don't want to use just one number to describe Hypo ??

$$\Rightarrow \min \sum_{i=1}^m \|x_i - (z_{i1} w_1 + z_{i2} w_2)\|_2^2 \quad \text{two dimensions.}$$

Result: $w_1 \sim$ eigenvector associate largest eigenvalue of $\hat{\Sigma}$

$w_2 \sim$ eigenvector associate second largest eigenvalue of $\hat{\Sigma}$

remind
Eigenvalue/vector

$$Z_{ii} = x_i^T w_1, \quad Z_{i2} = x_i^T w_2$$

General Result:

V are eigenvectors of $\hat{\Sigma}$:

$$\begin{bmatrix} | & | & & | \\ v_1 & v_2 & \cdots & v_d \\ | & | & & | \end{bmatrix}$$

$$W = \begin{bmatrix} | & | & \cdots & | \\ v_1 & v_2 & \cdots & v_k \\ | & | & & | \end{bmatrix} \quad k \leq d$$

$$\underbrace{Z}_{m \times k} = \underbrace{X \cdot W}_{m \times d \text{ by } d \times k}, \quad Z \text{ is projection } X \text{ on } W$$

1. W are directions for best squared error reconstruction
2. W are directions w/ largest empirical variances.

Cookbook:

Method 1

1. Central data: $x_i - \bar{x}_m \rightarrow x_i$

2. $\hat{\Sigma} = \underbrace{x^T x}_{\text{require a lot computational power}} \cdot \frac{1}{m}$

3. get eV of $\hat{\Sigma} \Rightarrow V \Rightarrow W \Rightarrow XW = Z$

method 2 (better way and faster and more stable)

1. Same

2. singular value decomposition *

diagonal matrix of singular values

$$X = U \cdot D \cdot V^T$$

matrix of orthogonal columns.

rowd
rowd
rowd
rowd

rowd
rowd
rowd
rowd

rowd
rowd
rowd
rowd

$$\Rightarrow \underline{X^T X} = \underline{V D U^T / U D V^T} = \underline{V D^2 V^T} \quad \begin{matrix} \nearrow \text{eigenvalue decomposition of } \\ X^T X \end{matrix}$$

So often get $X = U \cdot D \cdot V^T$, throw away U .

V is the same V in method 1.

$\frac{D^2}{m}$ is the eigenvalue of $\hat{\Sigma}$ in method 1.

$$x = \begin{bmatrix} x_1, x_2, \dots, x_m \end{bmatrix}_{n \times m}^T = U \sum V^T = \begin{bmatrix} u_1, u_2, \dots, u_n \end{bmatrix}_{n \times n} \begin{bmatrix} b_1, b_2, \dots, b_m \end{bmatrix}_{m \times m}^T \begin{bmatrix} v_1, v_2, \dots, v_m \end{bmatrix}_{m \times m}$$

↑ left S. Val ↑ S. Value ↑ right S. Val

1 million pixels in 1 vector

n=1 million

$$UU^T = U^T U = I_{n \times n} \quad VV^T = V^T V = I_{m \times m} \quad \text{Diagonal}, \quad b_1 \geq b_2 \geq \dots \geq b_m \geq 0$$

$$\begin{bmatrix} u_1, u_2, \dots, u_n \end{bmatrix}_{n \times n}$$

often, double # of cols of x

mixture of all orientations

$$V^T = \begin{bmatrix} v_1^T, v_2^T, \dots \end{bmatrix}_{m \times m}$$

$$\begin{bmatrix} u_1, u_2, \dots, u_n \end{bmatrix}_{n \times n} \begin{bmatrix} b_1, b_2, \dots, b_m \end{bmatrix}_{m \times m}^T \begin{bmatrix} v_1, v_2, \dots, v_m \end{bmatrix}_{m \times m}^T = \tilde{U} \sum \tilde{V}^T$$

"economy SVD"

n > m

$$= b_1 u_1 v_1^T + b_2 u_2 v_2^T + \dots + b_m u_m v_m^T + 0$$

$$= b_1 \left[\begin{array}{c|c} u_1 & v_1^T \\ \hline \end{array} \right] + \dots + b_m \left[\begin{array}{c|c} & \\ \hline & \end{array} \right]$$

truncate at Rank r

$$\approx \tilde{U} \sum \tilde{V}$$

$$\tilde{U}^T \tilde{U} = I_{n \times n} \quad \tilde{V} \tilde{V}^T = I_{m \times m}$$

correlation matrix (COV)



$$X^T X = \begin{matrix} \text{---} \\ m \times m \end{matrix}$$

$$\begin{matrix} | & | & & | \\ x_1 & x_2 & \cdots & x_m \\ | & | & & | \\ n \times m \end{matrix} = \begin{bmatrix} x_1^T x_1 & x_1^T x_2 & \cdots & x_1^T x_m \\ x_m^T x_1 & x_m^T x_2 & \cdots & x_m^T x_m \end{bmatrix}$$

↑ similar
↑ → traces

$$x_i^T x_j = \langle x_i, x_j \rangle$$

$$X^T X = V \sum_{i=1}^n \hat{\lambda}_i^2 \hat{U}^T \hat{U} \sum_{i=1}^n \hat{\lambda}_i V^T = V \sum_{i=1}^n \hat{\lambda}_i^2 V^T$$

$$\Rightarrow \underbrace{X^T X}_{\text{eigen vec}} \cdot V = V \cdot \underbrace{\sum_{i=1}^n \hat{\lambda}_i^2}_{\text{eigen val}}$$

• PCA

$$B = X - \bar{X} \quad C = B^T B$$

$$CV = V \cdot D$$

$$T = BV$$

↑
principal
components

$$\lambda = \sigma^2$$

$$\frac{\text{captured by PCA}}{V} = \frac{\sum_{k=1}^n \lambda_k}{\sum_{k=1}^n \lambda_k}$$