# PROBA

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# Lecture 1: Introduction

Wed 22 Sep

# 1 Some historical models

# 1.1 Laplace Model

# Definition 1 (Laplace Model)

 $\Omega$  finite set,  $|\Omega| = n$  is the set of outcomes.

We can observe whether  $E \subset \Omega$  happens, and we define it's probability

$$\mathbb{P}(E) = \frac{|E|}{|\Omega|}$$

# Question

Why should this have any meaning/content?

### Proposition 1

Consider laplace model for n coint tosses  $\Rightarrow$  every sequence has probability  $2^{-n}$ 

Denote by  $H_n$  the number of heads in n tosses

$$\mathbb{P}(|\frac{H_n}{n} - \frac{1}{2}| > \epsilon) \to 0$$

More generally

### Proposition 2

If you have a laplace model for some event E, and look at n repetitions, then

$$\forall \epsilon > 0 \mathbb{P}(|\frac{E_n}{n} - \mathbb{P}(E)| > \epsilon) \to 0$$

# Limitations of Laplace Model

- All outcomes have equal probability?
- Need  $|\Omega| < \infty$ , so what about infinite sets?

What next?

# Definition 2 (Intermediate model)

Let  $\Omega$  to be any set and  $P:\Omega\to[0,1], s.t.$   $\sum_{\omega\in\Omega}p(\omega)=1$ 

Event :  $E \subset \Omega$  and

$$\mathbb{P}(E) \coloneqq \sum_{\omega \in E} p(\omega)$$

- More freedom
- If you take  $\Omega$  finite,  $p(\omega) = \frac{1}{|\Omega|} \Rightarrow$  Laplace model
- Price? How to choose  $p:\Omega\to[0,1]\to \text{collect data, do statistics}$
- keeps many nice properties

- For contable sets, this is equivalent to the standard model.
- For uncountable  $\Omega$ ?
- Problem 1: There is no function s.t.

$$p(\omega) > 0 \forall \omega \in \Omega \text{ and } \sum p(\omega) = 1$$

This intermediate model is in essence only for countable sets.

### What about uncountable sets?

— What about a random point int [0,1] or  $[0,1]^n$ ? Intuitively, consider [0,1], then we can set

$$\mathbb{P}(A) = \text{length}(A)$$

# Definition 3 (Geometric probability)

Take  $f: \mathbb{R} \to (0, \infty)$  to be a riemann-integrable function with total mass 1. For any  $A \subset \mathbb{R}$ , s.t.  $1_A$  riemann-integrable, we set  $\mathbb{P}(A) = \int_A f(x) dx$ 

- In general quite  $\underline{ok}$  BUT
- You would expect there is one framework for uncountable and countable
- What about more complicated spaces (eg. space of continuous functions)
- $\mathbb{P}(\mathbb{Q})$  is undefined

# 2 Basic Formalism

# 2.1 Measure spaces: A notion of area

- Set + structure
- General setting to talk about area

# Definition 4 (Measure space)

 $(\Omega, \mathcal{F}, \mu)$  is called a measure space if :

- $\Omega$  is some set
- $\mathcal{F} \subset P(\Omega)$  called a  $\sigma$ -algebra
  - $-\emptyset \in \mathcal{F}$
  - $F \in \mathcal{F} \Rightarrow F^c \in \mathcal{F}$
  - $-F_1, F_2, \ldots, \in \mathcal{F}$ , then  $\bigcup_{i>1} F_i \in \mathcal{F}$  each F is called a measurable set.
- $-\mu: \mathcal{F} \to [0,\infty)$  called the measure
  - $-\mu(\emptyset) = 0$

— If  $F_1, \ldots$ , are disjoints sets of the  $\sigma$ -algebra, then

$$\mu(\bigcup_{i\geq 1} F_i) = \sum_{i\geq 1} \mu(F_i)$$

— Defined by Borel 1898 and Lebesgue 1901-1903

#### Probability spaces 2.2

Given by Kolmogorov in 1933

### Definition 5 (Probability space)

A triple  $(\Omega, \mathcal{F}, \mathbb{P})$  is called a probability space if it is a measure space and  $\mathbb{P}(\Omega) =$ 1

# Interpretation

- $\Omega$  state space/universe
- ${\mathcal F}$  is the set of events you can observe/have access to
- $\mathbb{P}(E)$  is the probability of E

### Lemme 3

Let  $(\Omega, \mathcal{F}, \mu)$  be a measure space

- $-F_1, F_2 \in \mathcal{F} \Rightarrow F_1 \setminus F_2 \in \mathcal{F}$
- $-F_1,\ldots\in\mathcal{F}\Rightarrow\bigcap F_i\in\mathcal{F}$
- $-F_1, F_2, \ldots \in \mathcal{F} \Rightarrow \bigcap_{i \geq 1} F_i$

Let us compare this definition with the prior ones

- $\Omega$  finite set,  $\mathcal{F} = \mathcal{P}(\Omega), \mathbb{P}(F) = \frac{|F|}{|\Omega|}$  this is a probability space and a laplace model.
- For  $\Omega$  countable,  $\mathcal{F} = \mathcal{P}(\Omega), \mathbb{P}(E) = \sum_{\omega \in E} \mathbb{P}(\omega)$
- The really new part is  $\mathcal{F}$  which restricts the sets we can measure

Lecture 2: ...

Wed 29 Sep

# 2.3 Basic properties

 $-F_1, F_2, \ldots, \in \mathcal{F}$  disjoint

$$\mu(\bigcup F_i) = \sum \mu(F_i)$$

$$-F_1 \subset F_2 \in \mathcal{F} \ \mu(F_1) \le \mu(F_2)$$
$$-F_1 \subset F_2 \ldots \in \mathcal{F}$$

$$-F_1 \subset F_2 \ldots \in \mathcal{F}$$

$$\mu(F_n) \to \mu(\bigcup F_i)$$

$$-F_1, F_2, \ldots, \mathcal{F}$$

$$\mu(\bigcup F_i) \leq \sum \mu(F_i)$$

In addition, in probability spaces

$$--\mathcal{P}(F^c) = 1 - \mathcal{P}(F)$$

$$-F_1 \supset F_2 \supset \ldots \Rightarrow \mathcal{P}(F_n) \to \mathcal{P}(\bigcap F_i)$$

# 2.4 Measurable and measure preserving maps

#### Definition 6

Let  $(\Omega_1, \mathcal{F}_1, \mu_1), (\Omega_2, \mathcal{F}_2, \mu_2)$  two measure spaces.

 $f: \Omega_1 \to \Omega_2$  is called measurable if for every  $F \in \mathcal{F}_2$ ,  $f^{-1}(F) \in \mathcal{F}_1$ 

A measurable function  $f:(\Omega_1,\mathcal{F}_1)\to(\Omega_2,\mathcal{F}_2)$  is called measure preserving if  $\forall F\in\mathcal{F}_2\ \mu_1(f^{-1}(F))=\mu_2(F)$ .

# Lemme 4 (Push-Forward measure)

Let  $(\Omega_1, \mathcal{F}_1, \mathbb{P}_1), (\Omega_2, \mathcal{F}_2)$  be two measure spaces, and f measurable, then  $\mathbb{P}_2(F) = \mathbb{P}_1(f^{-1}(F))$  is a probability measure.

# 3 Probability spaces

- Discrete probability spaces :  $\Omega$  countable
- Continuous probability spaces :  $\Omega$  uncountable.

### 3.1 Discrete probability spaces

Does introducing a  $\sigma$ -algebra  $\mathcal{F}$  enlargen the generality?

# Proposition 5

If  $(\Omega, \mathcal{F}, \mathbb{P})$  is a discret probability space,  $\exists \Omega_2 \text{ countable}, \mathbb{P}_2 : \mathcal{P}(\Omega_2) \to [0, 1]$ s.t.  $(\Omega_2, P(\Omega_2), \mathbb{P}_2)$  is a probability space and  $\exists f : (\Omega_1, \mathcal{F}_1) \to (\Omega_2, \mathcal{F}_2)$  is measure preserving

Still  $\mathcal{F}$  is useful:

— can sequentially study a model/situation by taking  $\mathcal{F}_1 \subset \mathcal{F}_2 \dots$ 

### Lemme 6

There is no shift-invariant probability measure on  $(\mathbb{Z}, P(\mathbb{Z}))$ 

Preuve

$$\mathbb{P}(\mathbb{Z}) = \mathbb{P}(\bigcup_n \left\{n\right\}) = \sum \mathbb{P}(\left\{n\right\}) = \infty$$

 $\Rightarrow$  cannot treat everyone on an equal ground!

#### 3.1.1 Symmetric simple random walk

A simple walk of length n s.t.  $|s_n - s_{n-1}| = 1$ .

Let  $\Omega$  be the set of all walks of length n, and consider  $(\Omega, P(\Omega), \mathbb{P})$ .

What is the probability that S hits 0?

What does it look like, what is it's max?

# 3.2 Continuous probability spaces

Can we define a probability measure on  $S^1$  s.t.  $(S^1, P(S^1))$  that is rotation invariant?

Similarly to the countable case, but not the same as  $\Omega$  is uncountable and setting  $P(\{\omega\}) = 0$  gives no contradiction.

### Proposition 7

You can not.

#### Preuve

Idea: decompose  $S^1$  into countable many sets  $A_n$  st  $\bigcup A_n = S^1$ , they are disjoint and rotations of each other.

$$\forall x \in S^1, define S_x as \left\{ \dots, T^{-2}x, T^{-1}x, x, Tx, \dots \right\}.$$

Note that either  $S_x = S_y$  or  $S_x \cap S_y = \emptyset$ .

# Lecture 3: Measurable maps

Wed 06 Oct

# 3.3 Borel $\sigma$ -algebra

- Cannot define shift-invariant probability measure on  $([0,1], \mathcal{P}([0,1]))$ .
- What  $\sigma$ -algebra to choose on  $(X, \tau)$ ?
- Want to know the siize of all open-sets

#### Definition 7 (Borel sigma-algebra)

On  $(X, \tau)$  the borel  $\sigma$ -algebra  $\mathcal{F}_{\tau}$  is the smallest  $\sigma$ -algebra containing  $\tau$ .

This is well defined because, given a collection of  $\sigma$ -algebras, their intersection is too.

# Two nice properties

— Continuous functions on a Borel  $\sigma$ -algebra are also measurable.

#### Preuve

Suffices to check that  $f^{-1}(U) \in \mathcal{F}_{\tau_1}$  for  $U \in \tau_2$  but this is immediate since f is continuous.

In  $(\mathbb{R}^n, \tau_E)$ , the Borel  $\sigma$ -algebra  $\mathcal{F}_E$  is generated by  $(a_1, b_1) \times ... \times (a_n, b_n)$ .  $\mathcal{F}_E$  is the smallest  $\sigma$ -algebra containing open intervalls.

# 3.4 Probability Measures on $\mathbb{R}^n$

# Theorème 8 (Existence of Lebesgue-measure)

There exists a unique measure  $\lambda$  on  $(\mathbb{R}^n, \mathcal{F}_E)$  s.t.  $\lambda((a_1 \times b_1) \times \ldots \times (a_n, b_n)) = \prod_i |b_i - a_i|$ 

# Theorème 9 (Uniforme Measure)

There exists a unique  $\mathbb{P}$  measure on  $([0,1]^n, \mathcal{F}_E)$  with the same property.

Both  $\lambda$  and  $\mathbb P$  are shift-invariant in fact only shift invariant measures on  $\mathbb R$  ( up to a constant)

#### Preuve

Consider the case of  $(\mathbb{R}^n, \mathcal{F}_E)$  and  $f_r: x \to x + \tau, \tau \in \mathbb{R}^n$ .

- $-f_r \ continuous \Rightarrow measurable$
- $\tilde{\mathbb{P}}(A) = \mathbb{P}(f^{-1}(A))$  is a probability measure
- All boxes have the same measure

# 3.5 Probability measures on $(\mathbb{R}, \mathcal{F}_E)$

We saw that we can put a uniform measure on [0,1].

All probability measures on  $(\mathbb{R}, \mathcal{F}_E)$ 

- 1.  $\mathbb{P}: \mathcal{F}_E \to [0,1]$
- 2. These are actually only characterized by  $\mathbb{P}((-\infty, x))$

# Definition 8 (Cumulative distribution function)

 $F: \mathbb{R} \to [0,1]$  is called a c.d.f if

- F is non-decreasing
- $-F(x_n) \to 0 \text{ then } x_n \to -\infty$
- $-F(x_n) \rightarrow 1 \text{ if } x_n \rightarrow 1$
- F is right-continuous.

### Theorème 10

Given a probability measure  $\mathbb{P}$  on  $(\mathbb{R}, \mathcal{F}_E)$ , then  $f(x) \coloneqq \mathbb{P}((-\infty, x))$  is a c.d.f

Given a c.d.f, there exists a unique probability measure s.t.  $\mathbb{P}(-\infty, x) = F(x)$ 

### Preuve

Given  $\mathbb{P}$  on  $(\mathbb{R}, \mathcal{F}_E)$ .

Let's show that  $F(x) = \mathbb{P}((-\infty, x))$  is a c.d.f.

$$-x < y$$
  $F(x) = \mathbb{P}((-\infty, x)) \le \mathbb{P}(-\infty, y) = F(y)$ 

$$-x_n \to -\infty$$
  $F(x_n) = \mathbb{P}(-\infty, x_n) \to \mathbb{P}(\bigcap_n (-\infty, x_n)) = 0$ 

$$-x_n \to \infty \Rightarrow F(x_n) \to 1 \text{ is similar}$$

— Also for right continuous  $x_n \to x$ , we have that  $[x_n, \infty) \subset [x_{n+1}, \infty)$ 

How do we construct  $\mathbb{P}$  given F?

Trick using push-forward measure.

Define  $f:(0,1)\to\mathbb{R}$ , define

$$f(x) = \inf_{y \in \mathbb{R}} \left\{ F(y) \ge x \right\}$$

Define  $\mathbb{P}(A) := \mathbb{P}_U(f^{-1}(A)) \forall A \in \mathcal{F}_E$  Why is f measurable? If f is increasing  $\Rightarrow f$  is measurable

### Lecture 4: ...

Wed 13 Oct

Each c.d.f gives rise to a unique  $\mathbb{P}$ .

A priori  $\mathbb{P}_1 = \mathbb{P}_2$  means  $\forall F \in \mathcal{F}_E \mathbb{P}_1(F) = \mathbb{P}_2(F)$ .

We show that it suffices to show that  $\mathbb{P}_1((-\infty, x]) = \mathbb{P}_2((-\infty, x]) \forall x \in \mathbb{R}$ .

#### Lemme 11

Given  $(\mathbb{R}, \mathcal{F}_E, \mathbb{P})$  then  $\forall B \in \mathcal{F}_E, \forall \epsilon > 0$  one can find disjoint intervals  $I_1, \ldots, I_n$  s.t.  $\mathbb{P}(B\Delta(I_1 \cup \ldots \cup I_n)) < \epsilon$ 

#### Preuve

Consider the collection H of all subsets  $H \in \mathcal{F}_E$  s.t. the property above holds.

We know that H contains all intervalls, hence  $\sigma(H) = \mathcal{F}_E$ .

So we only need to show that H is a  $\sigma$ -algebra

1. 
$$\emptyset \in H : Know that \forall x(-\infty, x] \in H$$

2. If 
$$B \in H \Rightarrow B^C \in H$$
.

Given  $\epsilon > 0$ , choose  $I_1, \ldots, I_n$  s.t.  $\mathbb{P}(B\Delta(I_1 \cup \ldots)) < \epsilon$ , but  $(B\Delta A) = B^C \Delta A^C$ , hence

$$\mathbb{P}(B^C \Delta(I_1 \cup \ldots)) < \epsilon$$

3.  $H_1, \ldots \in H$ , we want  $\bigcup_i H_i \in H \exists n \in \mathbb{N}$ 

$$\mathbb{P}((\bigcup_{i=0}^{m} H_i)\Delta(\bigcup_{i} H_i)) < \frac{\epsilon}{2}$$

 $\forall i = 1, \ldots, m$ , we have disjoint  $I_{i,1}, \ldots, I_{i,m_i}$  s.t.

$$\mathbb{P}(H_i\Delta(I_{i,1}\cup\ldots))<\frac{\epsilon}{2m}$$

Now use that

$$(\bigcup_{i=1}^{m} H_i) \Delta(\bigcup_{i=1}^{m} \bigcup_{j=1}^{m_i} I_{i,j}) \subseteq \bigcup_{i=1}^{m} (H_i \Delta \bigcup_{j=1}^{m_i} I_{i,j})$$

Finally, we can write a finite union of disjoint intervals

#### Corollaire 12

 $\mathbb{P}_1, \mathbb{P}_2$  probability measure on  $(\mathbb{R}, \mathcal{F}_E)$ , then  $\mathbb{P}_1 = \mathbb{P}_2$  as soon as

$$\mathbb{P}_1((-\infty, x]) = \mathbb{P}_2((-\infty, x])$$

or

$$\mathbb{P}_1(x,y) = \mathbb{P}_2(x,y)$$

#### Preuve

Notice  $(-\infty, x)$  can be written as

$$(-\infty, x) = (\bigcup_n (x, x+n))^C$$

So it suffices to prove the first point.

Observe, for all intervalls  $\mathbb{P}_1(I) = \mathbb{P}_2(I)$  since

$$\mathbb{P}_i(y,x) = \mathbb{P}_i(-\infty,x) - \mathbb{P}_i(-\infty,y)$$

The condition holds for B if  $\forall \epsilon > 0$ , we can pick  $I_1, \ldots, I_n$  s.t.

$$\mathbb{P}_1(B\Delta(I_1\cup\ldots))<\epsilon$$

and

$$\mathbb{P}_2(B\Delta(I_1 \cup \ldots)) < \epsilon$$

So we need to check again that this is a  $\sigma-$  algebra and we are done. Now we can conclude that

$$|\mathbb{P}_1(B) - \mathbb{P}_1(I_1 \cup \ldots)| = |\mathbb{P}_1(B) - \mathbb{P}_2(I_1 \cup \ldots)| < \epsilon$$

and

$$|\mathbb{P}_2(B) - \mathbb{P}_1(I_1 \cup \ldots)| = |\mathbb{P}_2(B) - \mathbb{P}_2(I_1 \cup \ldots)| < \epsilon \qquad \Box$$

An abstract uniqueness result follows from a similar strategy.

### Theorème 13 (Dynkin)

 $\mathbb{P}_1$  and  $\mathbb{P}_2$  two probability measures on  $(\Omega, \mathcal{F})$ , suppose  $\mathbb{P}_1(H) = \mathbb{P}_2(H)$  for all  $H \in \mathcal{H} \subset \mathcal{F}$  and

$$--\sigma(H)=\mathcal{F}$$

$$- H_1 \in \mathcal{H}, H_2 \in \mathcal{H} \Rightarrow H_1 \cap H_2 \in \mathcal{H}$$

Then  $\mathbb{P}_1 = \mathbb{P}_2$ 

# 3.6 Probability measures on $\mathbb{R}^n$

### Definition 9 (Joint c.d.f.)

$$F: \mathbb{R}^n \to [0,1]$$

- F non-decreasing in each coordinate
- $-F(x_1,\ldots,x_n)\to 1 \text{ if all } x_i\to -\infty$
- $-- right\hbox{-}continuous$

#### Theorème 14

Joint c.d.f  $\iff$   $\mathbb{P}$  on  $(\mathbb{R}^n, \mathcal{F}_E)$ 

# 3.7 Product probability measures on $\mathbb{R}^n, \mathbb{R}^{\mathbb{N}}$

- Related to independence
- Natural mathematically

# 2 steps

- product  $\sigma$ -algebra
- product measure

### 3.7.1 Product $\sigma$ -algebra

## Definition 10 (Product algebra)

Let  $(\Omega_i, \mathcal{F}_i)_{i\geq 1}$  measurable spaces, then the product  $\sigma$ -algebra  $\mathcal{F}_{\pi}$  on  $\prod_i \Omega_i$  is the  $\sigma$ -algebra generated by sets  $F = E_1 \times \ldots \times E_n \times \Omega_{n+1} \times \ldots$ ,  $E_i \in \mathcal{F}_i$ 

# Remarque

- Projections are measurable
- In fact, product  $\sigma$ -algebra s.t. all projections are measurable

Notice on  $\mathbb{R}^n$ , we now have two ways to define a  $\sigma$ -algebra.

- Take  $(\mathbb{R}^n, \tau_E)$  and induce a Borel  $\sigma$ -algebra
- Take n copies of  $(\mathbb{R}, \mathcal{F}_E)$  and consider  $\mathcal{F}_{\pi}$  on  $\mathbb{R}^n$