

1 a) In the G-S algorithm, each man will propose at least once, and in the order of their preference list.

Thus,  $m_1$  will at some point propose to  $w_1$ , since it's his top preference.  $w_1$  will accept, because  $m_1$  is ranked higher than any other man (except  $m_2$ , who will propose to  $w_2$  before  $w_1$ ).

Similarly,  $m_2$  will propose to  $w_2$ , who will accept, since she prefers  $m_2$  to any other man (except  $m_1$ , who will propose to  $w_1$  before  $w_2$ ).

Once the matching  $(m_1, w_1), (m_2, w_2)$  is made, they will never unmatch, since  $w_1$  won't accept any other proposals unless from  $m_2$ , and  $w_2$  won't accept proposals from any man except  $m_1$ . However, neither  $m_1$  nor  $m_2$  will propose to another  $w$  since they will not lose their partner. Thus,  $(m_1, w_1)$  and  $(m_2, w_2)$  will remain matched.

b) Proof by Contradiction!

Let's assume a stable matching where  $m_1$  is matched to some  $w_k$  (not  $w_1$  or  $w_2$ ) and  $w_1$  is matched to some  $m_k$  (not  $m_1$  or  $m_2$ ).

By their preference list, we know  $m_1$  prefers  $w_1$  to  $w_k$ , and similarly,  $w_1$  prefers  $m_1$  to  $m_k$ . Thus, since both  $m_1$  and  $w_1$  prefer each other over their current match, this is by definition an unstable match, and a contradiction.

Similarly, for any matching where  $m_1, m_2, w_1, w_2$  are not matching is an unstable match, since each  $m_{n \in 1,2}$  prefers either  $w_{k \in 1,2}$  to any other outside  $w$ , and vice-versa.

2a) There exists the following example:

$$m_1: w_2 > w_1 > w_3$$

$$m_2: w_1 > w_2 > w_3$$

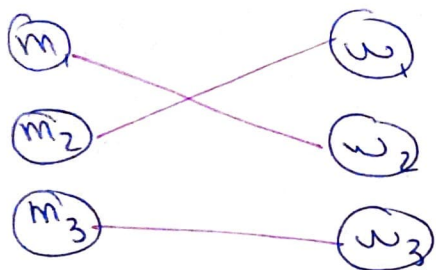
$$m_3: w_1 > w_3 > w_2$$

$$w_1: m_1 > m_2 > m_3$$

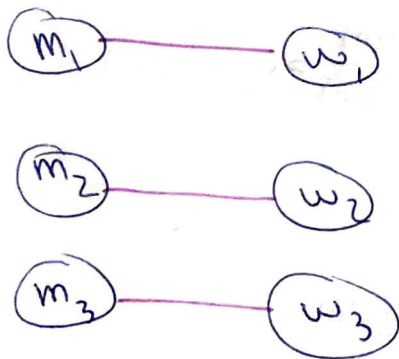
$$w_2: m_2 > m_1 > m_3$$

$$w_3: m_3 > m_2 > m_1$$

With this "truthful" preference list, running G-S algorithm results in following matching:



Let us now create an "untruthful" preference list, where  $w_1$  claims to prefer  $m_3$  to  $m_2$ . We update  $w_1$ 's preference list as follows:  $w_1: m_1 > m_3 > m_2$  (Notice the swapped  $m_2$  and  $m_3$ ). Now running G-S algorithm, we get following matching:



Notice in the "truthful" (original) matching,  $w_1$  ends up with  $m_2$ . In "untruthful" (modified) matching, she ends up with  $m_1$ , whom she truly prefers to  $m_2$ . Thus, the untruthful switch leads  $w_1$  to ~~have~~ have a better partner.  $\square$

3a)  $f(n) = O(g(n))$  implies  $\exists c, s.t. \quad c \cdot g(n) > f(n)$   
for  $n > \text{some } n_1$ .

Thus, exponentiate both sides,

$$2^{(c \cdot g(n))} > 2^{f(n)} \quad \text{for } n > n_1,$$

$$2^c \cdot 2^{g(n)} > 2^{f(n)} =$$

let  $C = 2^c$ . Thus,  $C \cdot 2^{g(n)} > 2^{f(n)}$ . Thus, by definition  
 $2^{f(n)} = O(2^{g(n)})$ .  $\square$ .

3b) Test  $n^n = \Theta(n!)$

Use limit check:  $\lim_{n \rightarrow \infty} \frac{n!}{n^n} = \frac{1 \times 2 \times 3 \times \dots \times n}{n \times n \times n \times \dots \times n} = 0$

(Note: this limit can be solved using squeeze theorem, but I decided to use a limit calculator.)

Thus, by the limit check, if  $\lim_{n \rightarrow \infty} \frac{f(n)}{g(n)} = 0$ , then

$$f(n) = \Omega(g(n)) \text{ and } f(n) \neq \Theta(g(n)).$$

$$\text{Thus, } n! = \Omega(n^n) \text{ and } n! \neq \Theta(n^n).$$

$$\text{We know if } f(n) = \Theta(g(n)) \Leftrightarrow g(n) = \Theta(f(n)).$$

Thus, since  $n! \neq \Theta(n^n)$ , we know

$$n^n \neq \Theta(n!) \quad \square.$$

$$3c) \quad f(n) = O(g(n))$$

$$\exists c_1 \text{ s.t. } c_1 \cdot g(n) > f(n) \quad \text{for } n > \text{some } n_1$$

Multiply both sides by  $g(n)$ .

$$c_1 \cdot g(n) \cdot g(n) > f(n) \cdot g(n) \quad \text{for } n > \text{some } n_1$$

$$c_1 (g(n)^2) > f(n) \cdot g(n) \quad =$$

Thus, by definition of big-O,

$$f(n) \cdot g(n) = O(g(n)^2) \quad \square.$$



4). Idea: use both max-heap and min-heap.

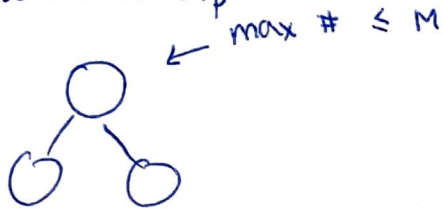
For a range of numbers  $A$ , and  $\text{median}^*(A) = m$ ,

Store a left-heap, which is a max-heap of numbers in  $A \leq m$ .

Store a right-heap, which is a min-heap of numbers in  $A \geq m$ .

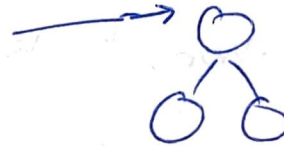
### Medium Heap.

left-heap



right-heap

min #  
≥ M



Define algorithm  $\text{push}(n)$ :

let  $m = \text{find-medium}$

if  $(n < m)$  ~~push~~ left-heap.push(n)  $\leftarrow O(\log n)$  by specification

else right-heap.push(n)  $\leftarrow O(\log n)$  by design of max- or min-heap

if (left-heap.size() > right-heap.size() + 1)  $\leftarrow$  size should be  $O(1)$  as heap can store internal size var.

let node = left-heap.pop()  $\leftarrow O(\log n)$ , since removal is  $O(\log n)$

right-heap.push(node)  $\leftarrow O(\log n)$

else if (right-heap.size() > left-heap.size() + 1)

let node = right-heap.pop()

left-heap.push(node)

Since all operations in  $\text{push}(n)$  are  $O(\log n)$ , and do not occur more than once, push is  $O(c \cdot \log n)$ , or just  $O(\log n)$ ,  $n$  being the number of elements.

Define algorithm find-medium:

if (left-heap.size() == right-heap.size() + 1) size is  $O(1)$   
return left-heap.first() getting root of heap is  $O(1)$   
else if (right-heap.size() == left-heap.size() + 1)  
return right-heap.first()  
else  
return (left-heap.first() + right-heap.first()) / 2

Since all operations in find-medium are  $O(1)$  and occur at-most once, find-medium is  $O(c \cdot 1) = O(1) = O(\log n)$ .

5) Define function  $\text{find\_i}(A, i)$

let  $n = A.\text{size}()$

let  $\text{left} = 0$

let  $\text{right} = n$

while ( $\text{left} < \text{right}$ )

let  $i = \text{left} + (\text{right} - \text{left}) / 2$

if ( $i == A[i]$ ) return True

else if ( $i < A[i]$ )  $\text{right} = i$

else if ( $i > A[i]$ )  $\text{left} = i$

return False

Notice in every iteration we split the input array  $A$  in 2, and continue iterating until there are no elements left. Since we divide by 2 on each iteration, we will iterate  $\log_2(n)$  times, where  $n = |A|$ . Thus,  $\text{find\_i}$  is  $O(\log n)$ .

Since  $A$  is sorted, distinct elements, for any element index  $i$ , every element will be strictly greater to the right, and strictly less on the left. Thus, if  $A[i] > i$ , then every element  $j > i$  (to the right of  $i$ ) will also have property  $A[j] > j$ , since each element is greater than previous. Similarly, if  $A[i] < i$ , every element to its left will also have  $A[j] < j$ . By this rule we can eliminate half

of the array every time until we find a match or exceed the array.