

# Formulae

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## Unit 1

### Point charge

$$D = \frac{Q}{4\pi r^2} a_r$$

### Line charge

$$E = \frac{-\rho_L}{4\pi\epsilon_o\rho} \int_{\alpha_1}^{\alpha_2} [\cos(\alpha)a_p + \sin(\alpha)a_z] d\alpha$$

- Where  $\alpha_1$  and  $\alpha_2$  are angles that the line subtends to the point
- Infinite line charge -

$$E = \frac{\rho_L}{2\pi\epsilon_o\rho} a_p$$

### Surface charge

- Electric field due to surface charge is

$$E = \int_S \frac{\rho_s dS}{4\pi\epsilon_0 R^2} a_R$$

- Substituting  $dS \rightarrow \rho d\phi d\rho$  and solving for **Infinite Sheet Charge**

$$E = \frac{\rho_s}{2\epsilon_0} a_n$$

- Where  $a_n$  is unit vector perpendicular to sheet

### Volume charge

- Electric field due to volume charge is

$$E = \int_S \frac{\rho_s dV}{4\pi\epsilon_0 R^2} a_R$$

- With  $a_R = \cos(\alpha)a_Z - \sin(\alpha)a_p$

$$E = \frac{Q}{4\pi\epsilon_o} z^2$$

$$Q = \rho_v \frac{4}{3} \pi a^3$$

## Electric Flux Density

Also known as Electric Displacement

$$D = \epsilon_o E$$

$$\psi = \int_S D \cdot dS$$

## Divergence

$$\nabla \cdot A = \lim_{\Delta V \rightarrow 0} \frac{\int_S A \cdot dS}{\Delta V}$$

### Cartesian

$$\nabla \cdot A = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z}$$

### Cylindrical

$$\nabla \cdot A = \frac{\partial A_\rho}{\partial \rho} + \frac{1}{\rho} \frac{\partial A_\phi}{\partial \phi} + \frac{\partial A_z}{\partial z}$$

### Spherical

$$\nabla \cdot A = \frac{\partial A_r}{\partial r} + \frac{1}{r} \frac{\partial A_\theta}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial A_\phi}{\partial \phi}$$

## Divergence Theorem

$$\int_S A \cdot dS = \int_V \nabla \cdot A dV$$

- Total outward flux of a vector field through closed surface S is same as volume integral of the divergence of A

## Gauss law

$$\Psi = \int_S D \cdot dS = Q_{enclosed} = \int_V \rho_v dV$$

- Applying divergence theorem

$$\int_S D \cdot dS = \int_V \nabla \cdot D dV$$

- Comparing the equations :- We get Maxwell's 1st equation

$$\rho_v = \nabla \cdot D$$

## Applying Gauss law

- Infinite line charge

$$\rho_L l = Q = \int_S D \cdot dS = D_\rho \int_S dS = D_\rho 2\pi \rho l$$

$$D_\rho = \frac{\rho_L l}{2\pi \rho l} \rightarrow D = \frac{\rho_L}{2\pi \rho} a_\rho$$

- Infinite sheet charge

$$\rho_S A = D_z(A + A) = 2D_z A$$

$$D = D_z a_z = \frac{\rho_s}{2} a_z \text{ (or) } E = \frac{\rho_s}{2\epsilon_0} a_z$$

- Uniformly charged sphere

$$D = \begin{cases} \frac{r}{3} \rho_o a_r & \text{if } 0 < r \leq a \\ \frac{a^3}{3r^2} \rho_o a_r & \text{if } r \geq a \end{cases}$$

## Electric Potential

$$V_{BA} = \frac{W}{Q} = - \int_A^B E \cdot dl$$

- Absolute potential - work done per charge to bring it from infinity to r

$$V = - \int_{\infty}^r E \cdot dl$$

## Relation b/w E and V

- For a closed loop:-

$$\int_L E \cdot dl = 0$$

 **Note**

### Stoke's Theorem

$$\int \int_S (\nabla \times \vec{B}) \cdot d\vec{S} = \oint_S \vec{B} \cdot d\vec{l}$$

### Curl

$$\nabla \times \mathbf{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_x & F_y & F_z \end{vmatrix}$$

- Applying **stoke's theorem**

$$\int_L E \cdot dl = \int_S (\nabla \times E) \cdot dS = 0 \text{ (or) } \nabla \times E = 0$$

- Electric field is the gradient of V :-

$$E = -\nabla V$$

## Continuity Equation

$$I_{out} = \oint J \cdot dS = -\frac{dQ_{in}}{dt}$$

- With divergence theorem :-

$$\oint J \cdot dS = \int_v \nabla \cdot J \, dV$$

- Also

$$-\frac{dQ_{in}}{dt} = -\int_v \frac{\partial \rho_v}{\partial t} dV$$

- Therefore **Continuity Equation**

$$\nabla \cdot J = -\frac{\partial \rho_v}{\partial t}$$

#### Note

For DC current

$$\frac{\partial \rho_v}{\partial t} = 0$$

Therefore

$$\nabla \cdot J = 0$$

## Relaxation time

$$\rho_v = \rho_{vo} e^{-\frac{t}{T_r}} \text{ where } T_r = \frac{\epsilon}{\sigma}$$

## Poisson's Equation

$$\nabla^2 V = -\frac{\rho_v}{\epsilon_o}$$

#### Note

Laplacian operator :-

General Formula

$$\nabla^2 A = \frac{1}{h_1 h_2 h_3} \left[ \frac{\partial}{\partial a_1} \left( \frac{h_2 h_3}{h_1} \frac{\partial A}{\partial a_1} \right) + \frac{\partial}{\partial a_2} \left( \frac{h_1 h_3}{h_2} \frac{\partial A}{\partial a_2} \right) + \frac{\partial}{\partial a_3} \left( \frac{h_1 h_2}{h_3} \frac{\partial A}{\partial a_3} \right) \right]$$

## Laplace Equation

If there is no charge enclosed in the volume :-

$$\nabla^2 V = 0$$

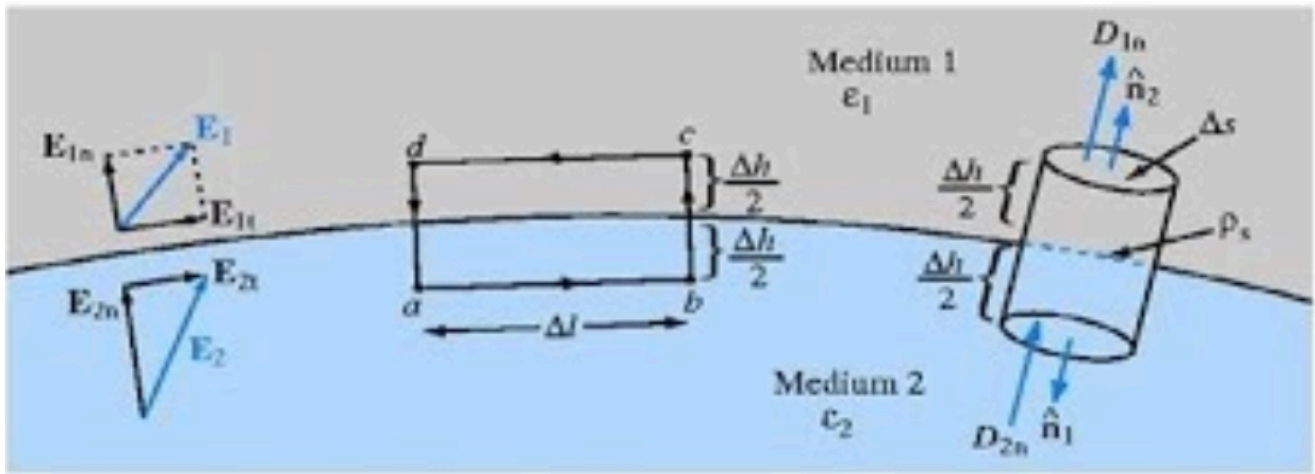
## Boundary conditions

Maxwell's Equations :-

$$\oint_S \vec{D} \cdot d\vec{S} = Q_{enc} \rightarrow 1^{st} \text{ Equation}$$

$$\oint_L \vec{E} \cdot d\vec{l} = 0 \rightarrow 2^{nd} \text{ Equation}$$

## Dielectric - Dielectric



$$\epsilon_1 = \epsilon_o \epsilon_{r1} \text{ (and) } \epsilon_2 = \epsilon_o \epsilon_{r2}$$

- For a closed path  $abcd$ . The tangential components of an electric field crossing the interface undergoes no change :-

$$E_{1t} = E_{2t}$$

- Or

$$\frac{D_{1t}}{\epsilon_1} = \frac{D_{2t}}{\epsilon_2}$$

- Similarly for cylindrical Gaussian surface

$$D_{1n} - D_{2n} = \rho_s$$

- Or when  $\rho_s = 0$  where  $\rho_s$  is charge density in the interface surface

$$\epsilon_1 E_{1n} = \epsilon_2 E_{2n}$$

- Refraction

$$\frac{\tan \theta_1}{\tan \theta_2} = \frac{\epsilon_1}{\epsilon_2} = \frac{\epsilon_{r1}}{\epsilon_{r2}}$$

- $\theta_1, \theta_2 \rightarrow$  angle of electric field with normal to surface in each medium

## Conductor - Dielectric

$$E_t = 0$$

$$D_n = \rho_s$$

## Conductor - Free space

$$D_t = \epsilon_o E_t = 0$$

$$D_n = \varepsilon_o E_n = \rho_s$$


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## Unit 2

### Drift velocity

$$v_e = -\mu_e \overline{E}$$

### Ohm's law

$$R = \frac{V}{I}$$

- Point form

$$\overline{J} = \sigma \overline{E}$$

### Resistance

$$R = \frac{l}{\sigma A}$$

### Conductivity

$$G = \frac{\sigma A}{l} = \frac{A}{\rho l}$$

### Joule's law

$$P(\text{power}) = \int_v \overline{J} \cdot \overline{E} dV$$

### Polarisation

$$\overline{D} = \varepsilon_o \overline{E} + \overline{P}$$

- P -> electric polarisation field

$$\overline{P} = \varepsilon_o \chi_e \overline{E}$$

$$\overline{D} = \varepsilon_o \overline{E} + \overline{P} = \varepsilon \overline{E}$$

$$\varepsilon_r = \varepsilon_o(1 + \chi_e)$$

- $\chi_e$  -> Susceptibility
- $\varepsilon_r$  -> relative permeability or dielectric strength

## Capacitance

$$C = \frac{Q}{V}$$

$$RC = \frac{\varepsilon}{\sigma}$$

## Parallel Plate

$$C = \frac{Q}{V} = \frac{\varepsilon S}{d}$$

$$W_E = \frac{1}{2} \int_v \varepsilon E^2 dv = \frac{1}{2} CV^2 = \frac{1}{2} QV = \frac{Q^2}{2C}$$

## Coaxial

$$E = \frac{Q}{2\pi\varepsilon L} \ln \frac{b}{a}$$

$$C = \frac{2\pi\varepsilon L}{\ln \frac{b}{a}}$$

## Spherical

$$C = \frac{4\pi\varepsilon}{\frac{1}{a} - \frac{1}{b}}$$

## Configurations

### Parallel

$$C = C_1 + C_2$$

### Series

$$\frac{1}{C} = \frac{1}{C_1} + \frac{1}{C_2}$$



