Small data technique

Lecture 13

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Decision trees (DTs)

Recap: DNNs

Work well with enough data.

Otherwise, we may face: Overfitting problem

This motivates simplifying DNNs, being tailored for tasks of interest.

Recap: CNNs

A model specialized for image data

Two key building blocks:

- 1. Conv layer (mimicking neurons in visual cortex)
- 2. Pooling layer (mainly for reducing complexity)

Design principles: As a network gets deeper:

- 1. Feature map size gets smaller;
- 2. # of feature maps gets bigger.

Recap: RNNs

A model specialized for time series data

Two key building blocks:

- 1. Recurrent neurons
- 2. Memory cell

Basic RNNs: Trained via truncated BTTP;

Do not well keep memory.

LSTM: Offers great performance and fast training.

Recap: Tensorflow coding for RNNs

```
from tensorflow.keras.datasets import imdb
from tensorflow.keras.preprocessing.sequence import pad sequences
from tensorflow.keras.models import Sequential
from tensorflow.keras.layers import Embedding, SimpleRNN, Dense
from tensorflow.keras.layers import LSTM
(X train, y train), (X test, y test) = imdb.load data(num words=10000)
# Preprocessing
X train pad = pad sequences(X train, value=0, padding='post', maxlen=256)
# Basic RNN
model = Sequential()
model.add(Embedding(input dim=10000,output dim=100,input length=256))
model.add(SimpleRNN(128))
model.add(Dense(1, activation='sigmoid'))
# LSTM
model LSTM = Sequential()
model LSTM.add(Embedding(input dim=num words,output dim=100,input length=256))
model LSTM.add(LSTM(128))
model LSTM.add(Dense(1, activation='sigmoid'))
```

Questions

1. What if we still have unsatisfactory performances?

A better approach for the small data regime?

2. What about interpretability of DNNs?

Today's lectures

Will explore a technique that may enable a better performance for the small data regime, as well as offer model interpretability:

Random forests (RFs)

The most powerful ML algorithm in industry

Outline of today's lectures

Will study:

1. Decision trees (DTs):

Fundamental components of RFs

2. Ensemble learning:

A generic technique that includes RFs as a special case.

3. RFs in depth

Focus of Lecture 13

Will study:

1. Decision trees (DTs):

Fundamental components of RFs

2. Ensemble learning:

A generic technique that includes RFs as a special case.

3. **RFs** in depth

A motivating example

Iris plants classification:

Class: setosa versicolor virginica



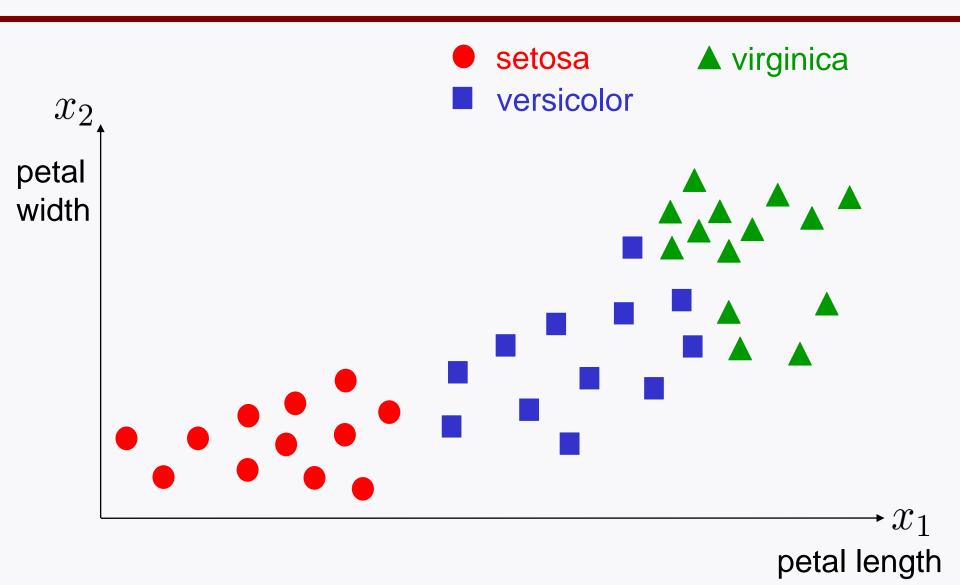




Two features x_1 : petal length

(out of 4): x_2 : petal width

Data distribution

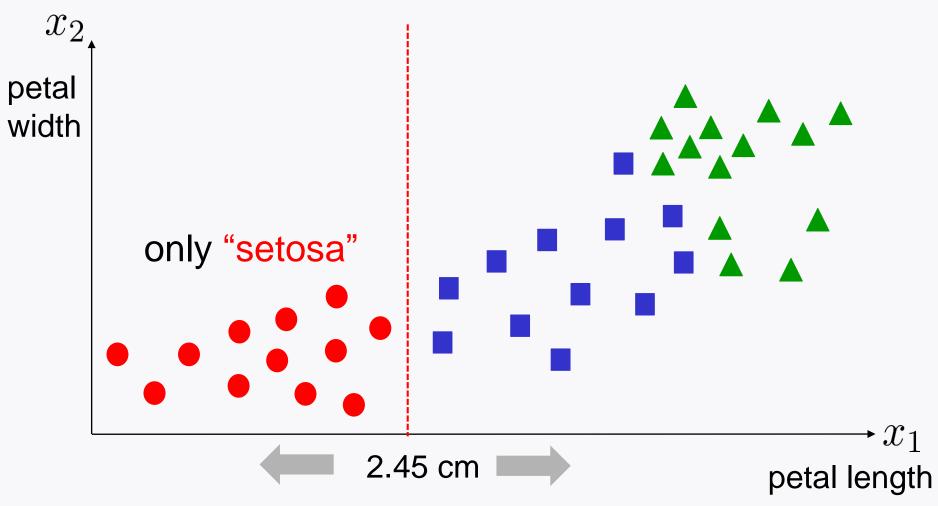


Observation

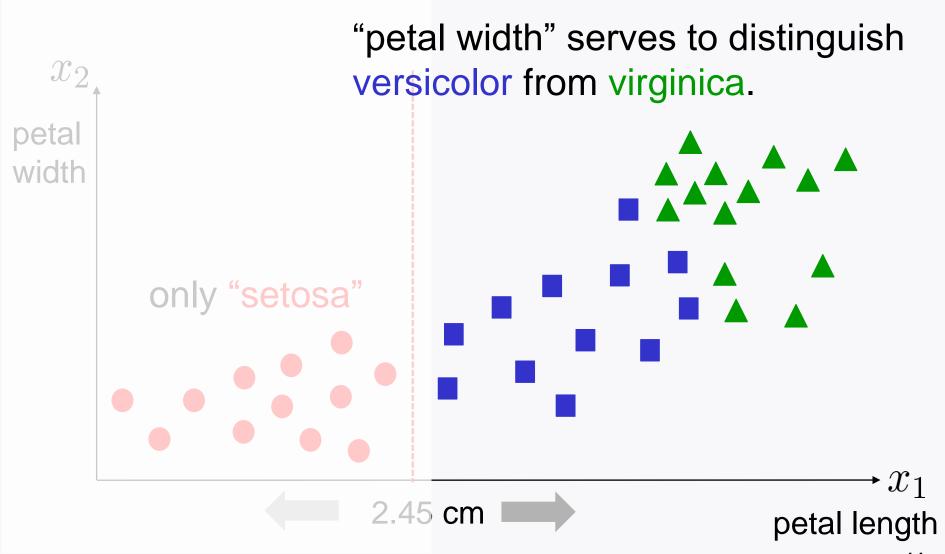
"petal length" plays a key role to distinguish setosa from versicolor & virginica. petal width

petal length

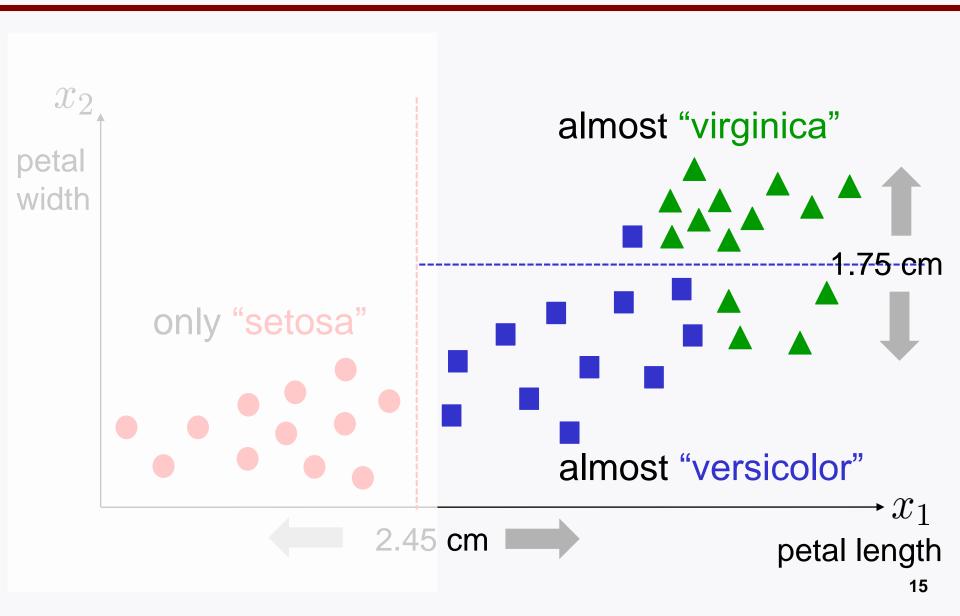
A natural attempt for classification



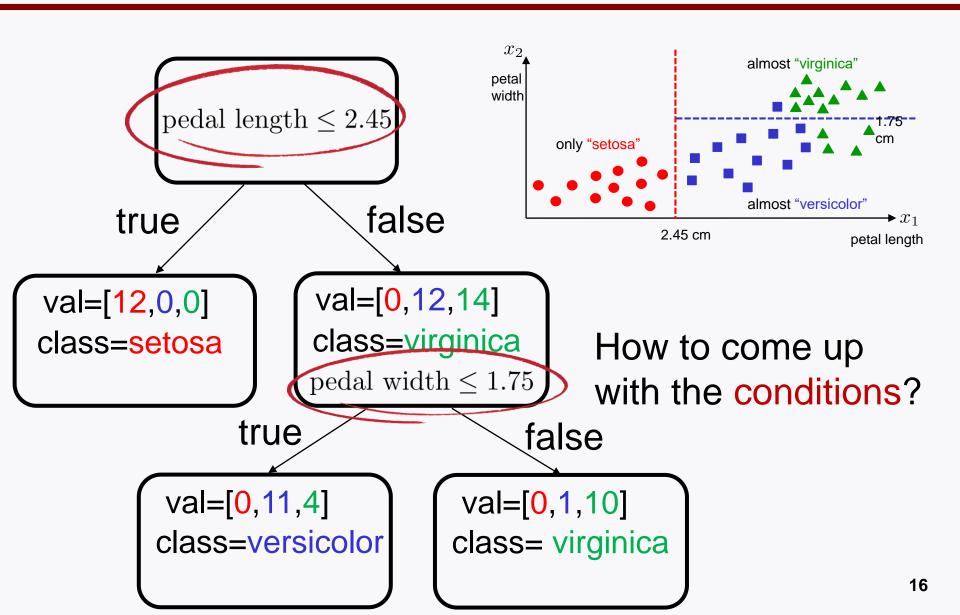
Another observation



A follow-up natural attempt



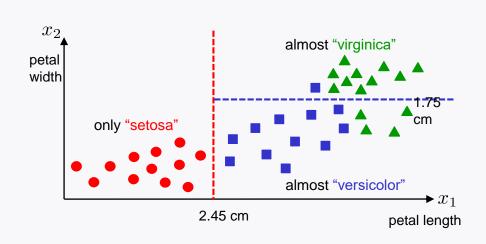
Decision Tree



CART (Classification And Regression Tree) algorithm

k: feature index

 t_k : threshold



Step 1: Find (k, t_k) such that $J(k, t_k)$ is minimized.

$$J(k,t_k) = \frac{m_{\rm left}}{m} G_{\rm left} + \frac{m_{\rm right}}{m} G_{\rm right} \quad {\rm smaller} \to {\rm more~pure}$$

impurity of the left split: Gini index (0~1)

$$G_{\text{left}} := 1 - \sum_{c=1}^{\infty} r_{\text{left},c}^2 = 1 - (\mathbf{1}^2 + \mathbf{0}^2 + \mathbf{0}^2) = 0$$

$$G_{\text{right}} = 1 - \left(\frac{0^2 + \left(\frac{12}{26}\right)^2 + \left(\frac{14}{26}\right)^2\right) = 0.497$$

CART (Classification And Regression Tree) algorithm

Step 1: Find (k, t_k) such that $J(k, t_k)$ is minimized.

$$J(k, t_k) = \frac{m_{\text{left}}}{m} G_{\text{left}} + \frac{m_{\text{right}}}{m} G_{\text{right}}$$

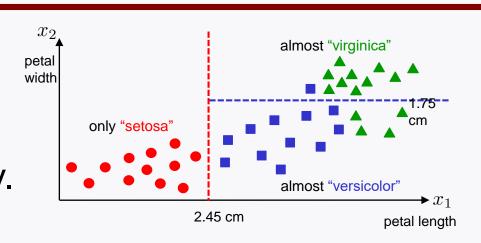
Step 2: Repeat Step 1 for each split:

$$G_{
m left}$$
 $G_{
m left,left}$ $G_{
m right}$ $G_{
m right,left}$ $G_{
m right,right}$

Stopping criteria?

Stopping criteria

1. Cannot find a split that further reduces impurity.



OR

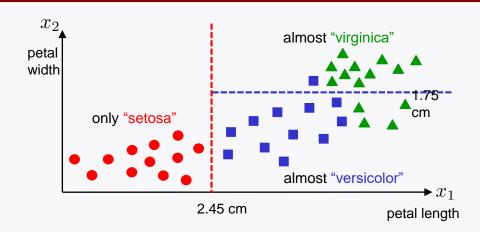
hyperparameter

2. Reach "max_depth" (maximum tree depth).

max_depth=2 (in the example)

Hyperparameters

1. "max_depth"



2. "min_samples_split"

Min # of samples a node must have prior to splitting.

3. "min_samples_leaf"

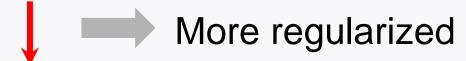
Min # of samples a leaf node must have.

4. "max_leaf_nodes"

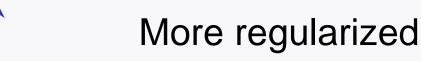
Max # of leaf nodes

Hyperparameters vs. regularization

1. "max_depth"



2. "min_samples_split"



Min # of samples a node must have prior to splitting.

3. "min_samples_leaf"



More regularized

Min # of samples a leaf node must have.

4. "max_leaf_nodes"



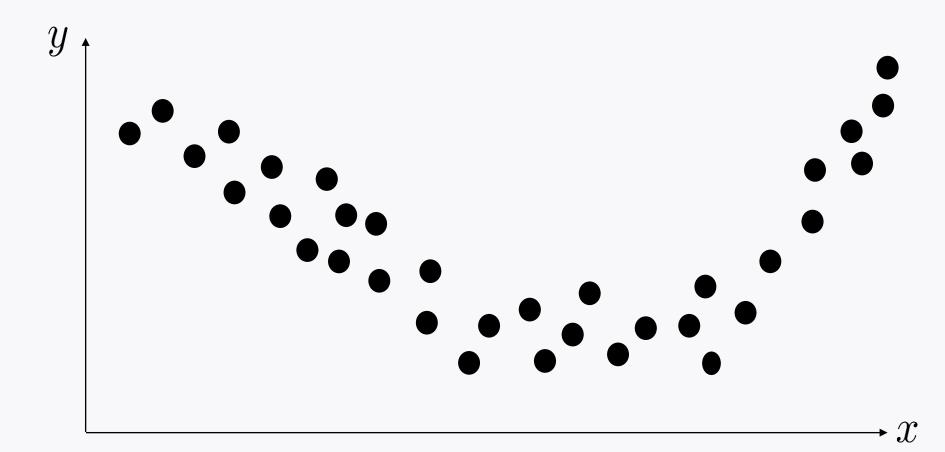
More regularized

Max # of leaf nodes

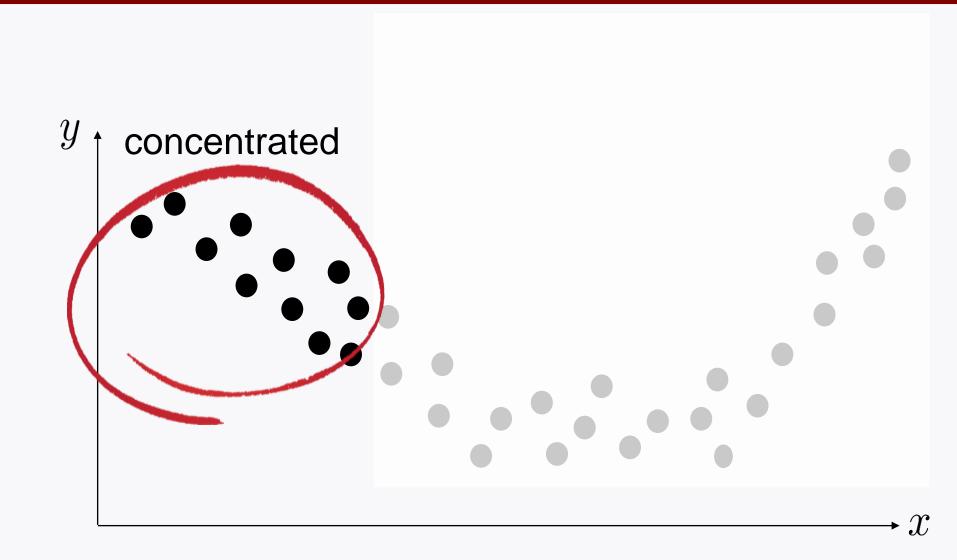
DTs for regression

A motivating example

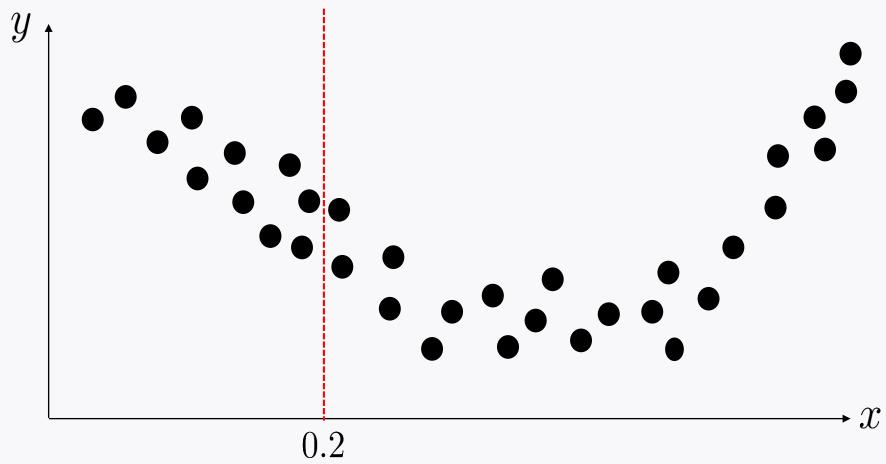
$$x \in \mathbf{R} \quad y \in \mathbf{R}$$



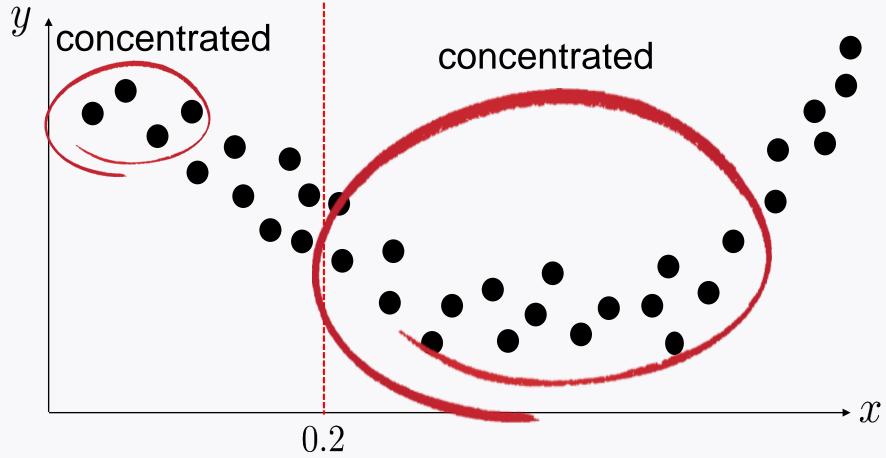
Observation



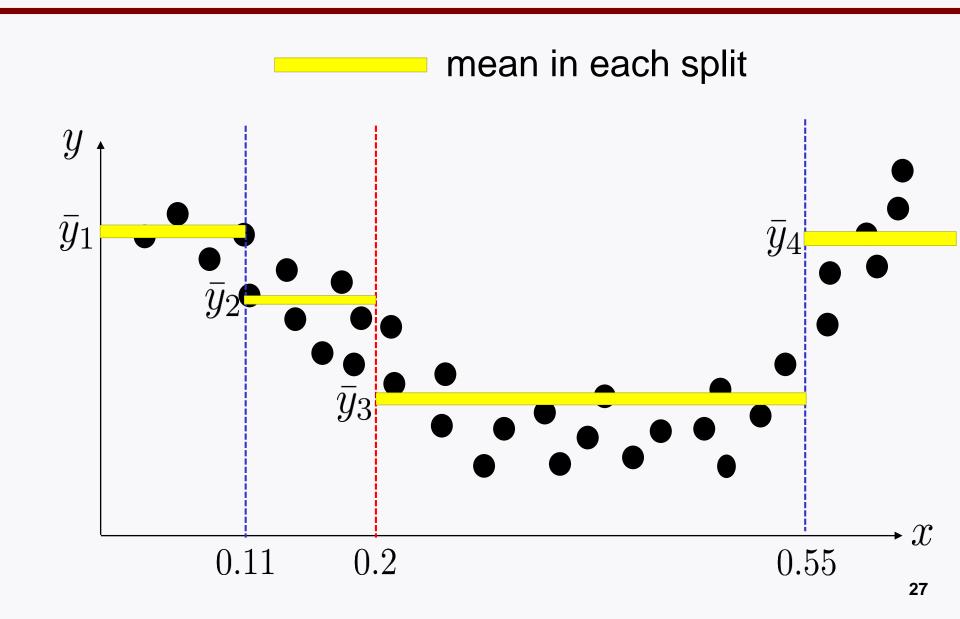
A natural attempt for separation



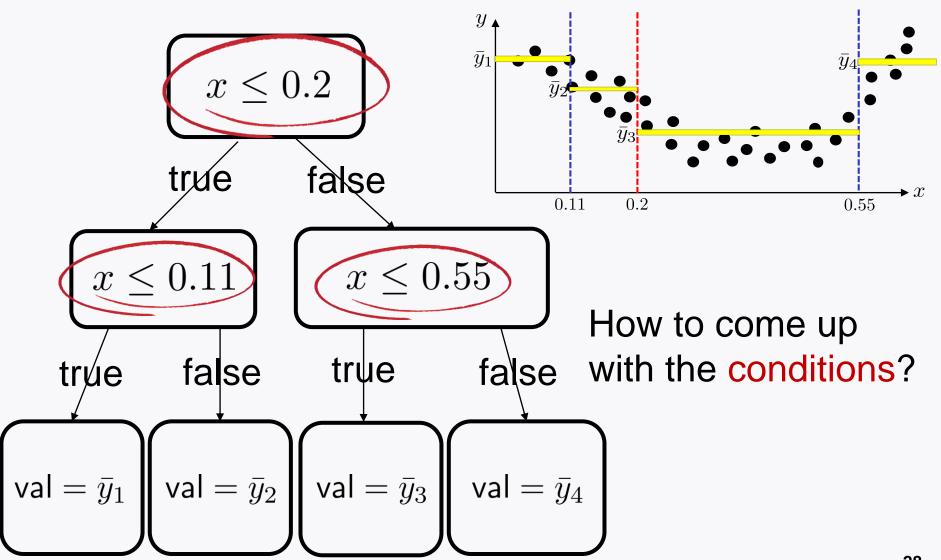
Observation in each split



A follow-up natural attempt



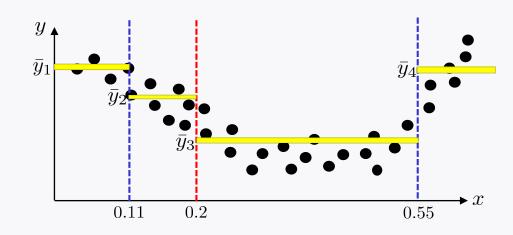
Decision tree



CART algorithm

k: feature index

 t_k : threshold



Step 1: Find (k, t_k) such that $J(k, t_k)$ is minimized.

$$J(k,t_k) = \frac{m_{\mathrm{left}}}{m} \mathrm{MSE}_{\mathrm{left}} + \frac{m_{\mathrm{right}}}{m} \mathrm{MSE}_{\mathrm{right}}$$

$$\mathsf{MSE}_{\mathsf{left}} := \frac{1}{m_{\mathsf{left}}} \sum_{i \in \mathsf{left}} (y^{(i)} - \bar{y}_{\mathsf{left}})^2 \quad \bar{y}_{\mathsf{left}} = \frac{1}{m_{\mathsf{left}}} \sum_{i \in \mathsf{left}} y^{(i)}$$

CART algorithm

Step 1: Find (k, t_k) such that $J(k, t_k)$ is minimized.

$$J(k,t_k) = \frac{m_{\text{left}}}{m} \text{MSE}_{\text{left}} + \frac{m_{\text{right}}}{m} \text{MSE}_{\text{right}}$$

Step 2: Repeat Step 1 for each split:

$$MSE_{left} \underbrace{ MSE_{left,left} }_{MSE_{left,right}} \underbrace{ MSE_{right},left}_{MSE_{right,right}}$$

Stopping criteria & hyperparameters are the same as those of classification.

Look ahead

1. Investigate a challenge that arises in DTs.

2. Explore a way to address the challenge:

Ensemble learning