

Small data technique

Lecture 15

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Random forests (RFs)

Outline

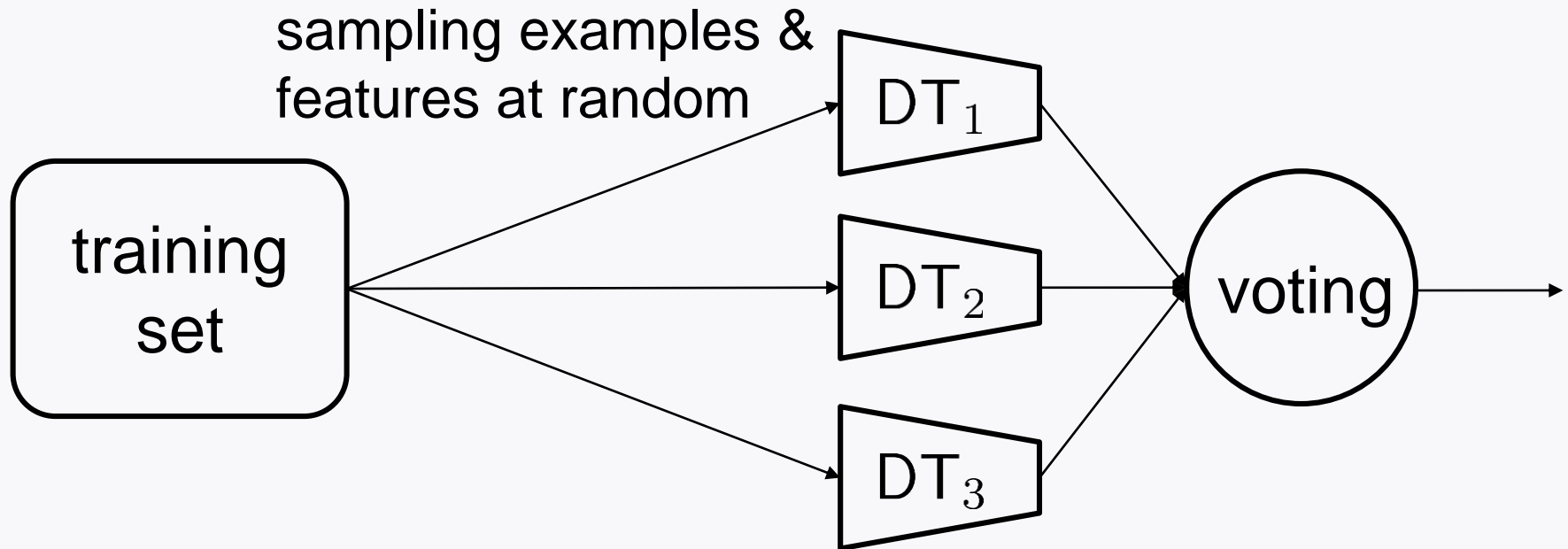
1. Investigate **hyperparameters**.
2. Study a key measure for model *interpretation*:

Feature Importance

Hyperparameters

Two types:

DT hyperparameters + additional hyperparameters



Hyperparameters

DT hyperparameters + **additional** hyperparameters

“max_depth”

“max_features”

“min_samples_split”

“n_estimators”

“min_samples_leaf”

“max_leaf_nodes”

Default parameters

DT hyperparameters + **additional** hyperparameters

“max_depth”	none	“max_features”	$\frac{\sqrt{n_features}}{n_features}$
“min_samples_split”	2	“n_estimators”	100
“min_samples_leaf”	1		
“max_leaf_nodes”	none		

Hyperparameters vs. regularization

DT hyperparameters **+** **additional** hyperparameters

“max_depth”



“max_features”



“min_samples_split”



“n_estimators”



“min_samples_leaf”



“max_leaf_nodes”



→ More regularized.

Hyperparameter search

Scikit-learn provides functions that ease search:

GridSearchCV

RandomizedSearchCV

Check details in PS.

A measure for model interpretation

RFs have a **measure** that captures **the relative importance of each feature**:

Feature Importance

Can serve model interpretation.

How to compute “feature importance”?

1. For each DT, compute “node importance”:

$$NI_j = G_j - \frac{m_{j,\text{left}}}{m_j} G_{j,\text{left}} - \frac{m_{j,\text{right}}}{m_j} G_{j,\text{right}}$$

→ Quantifies how well node j is split.

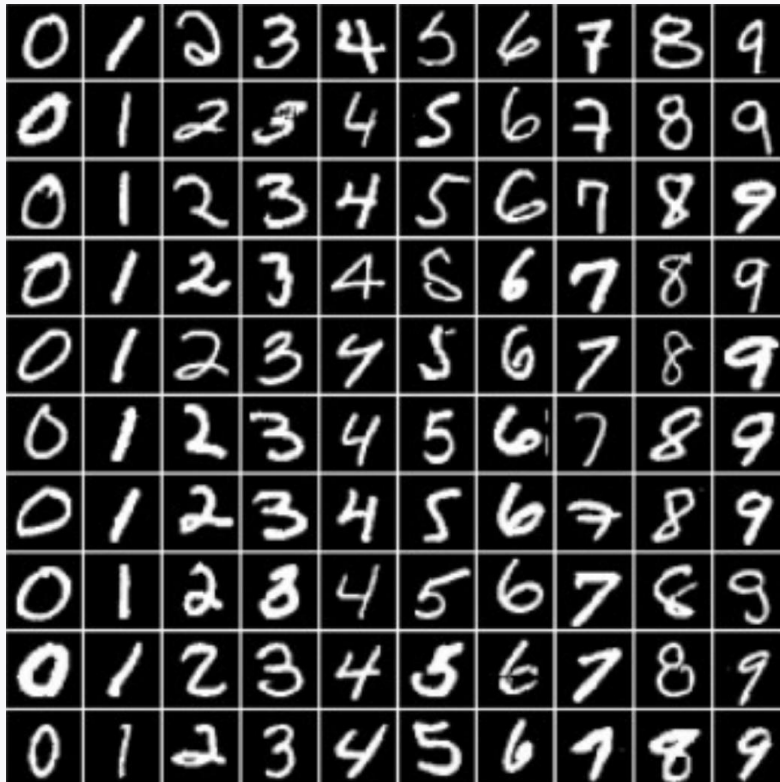
2. Compute “feature importance” based on NI_j :

$$FI_k = \frac{\sum_j NI_{j,k}}{\sum_j NI_j}$$

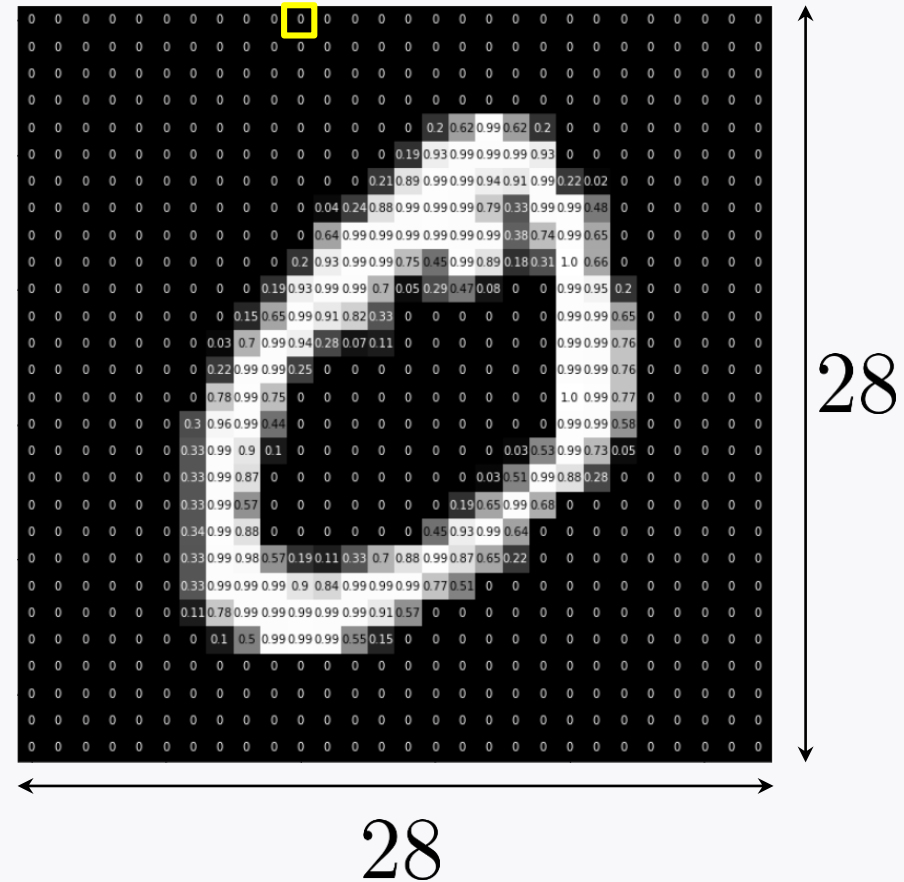
$$NI_{j,k} = NI_j \cdot \mathbf{1}\{k = \text{contributer of the node } j \text{ split}\}.$$

Average over all DTs.

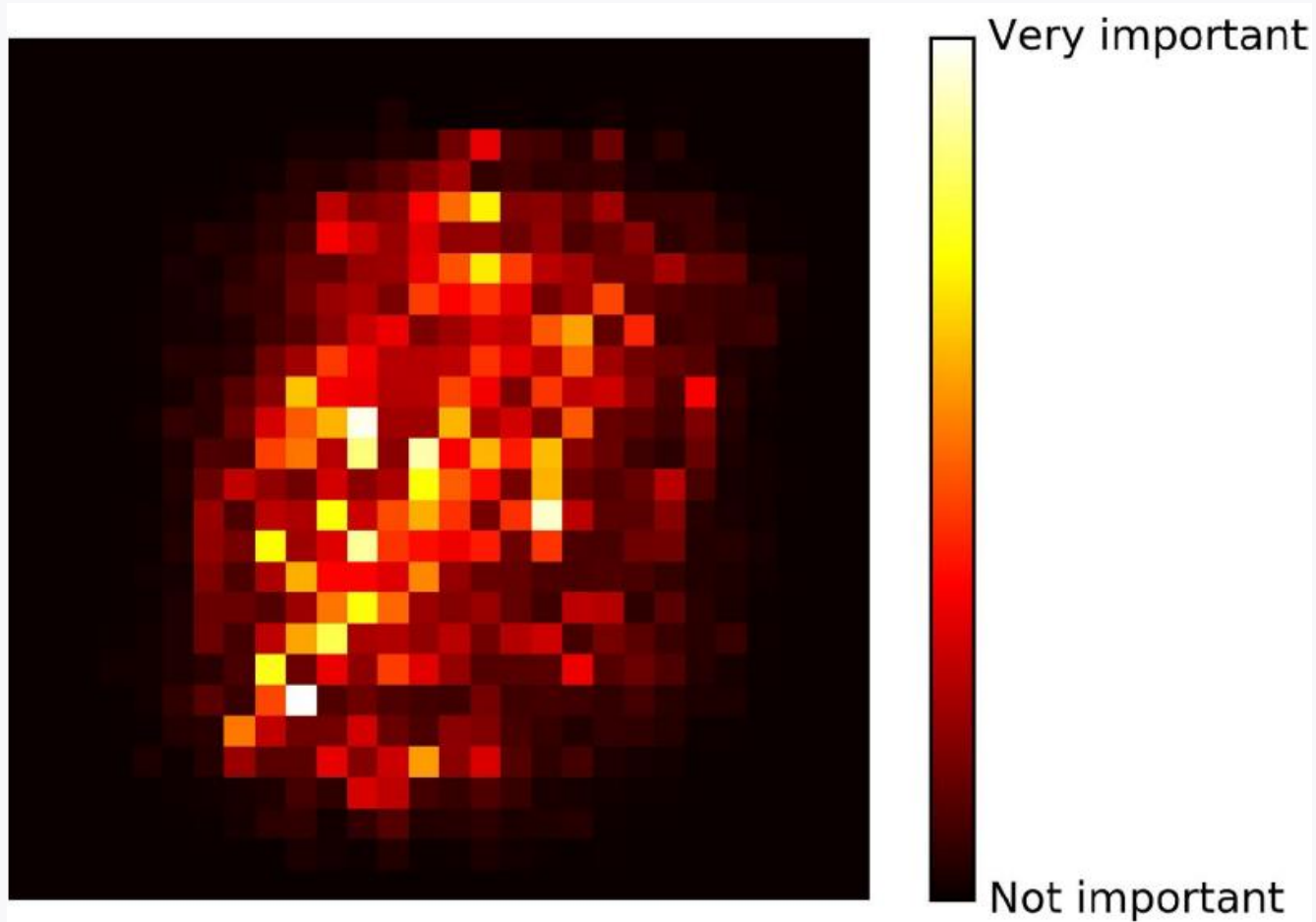
Example: MNIST



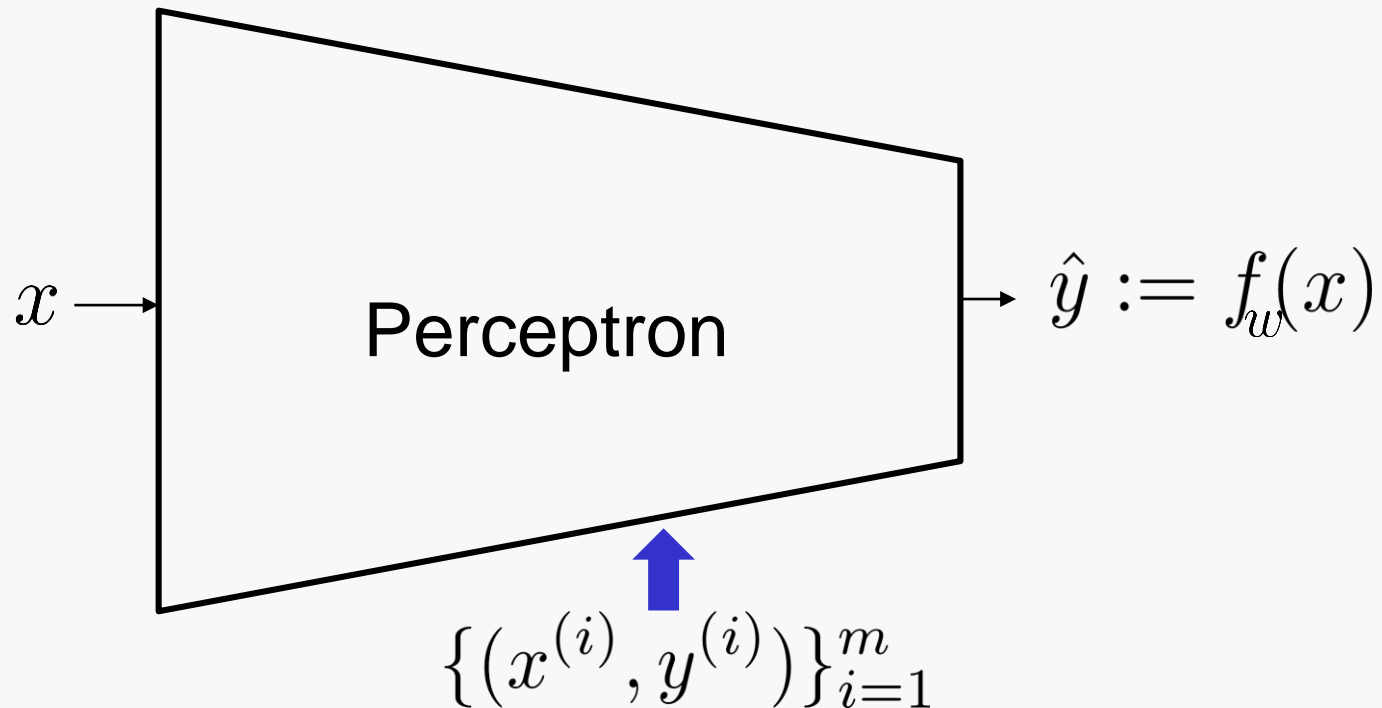
pixel value = feature



MNIST pixel importance



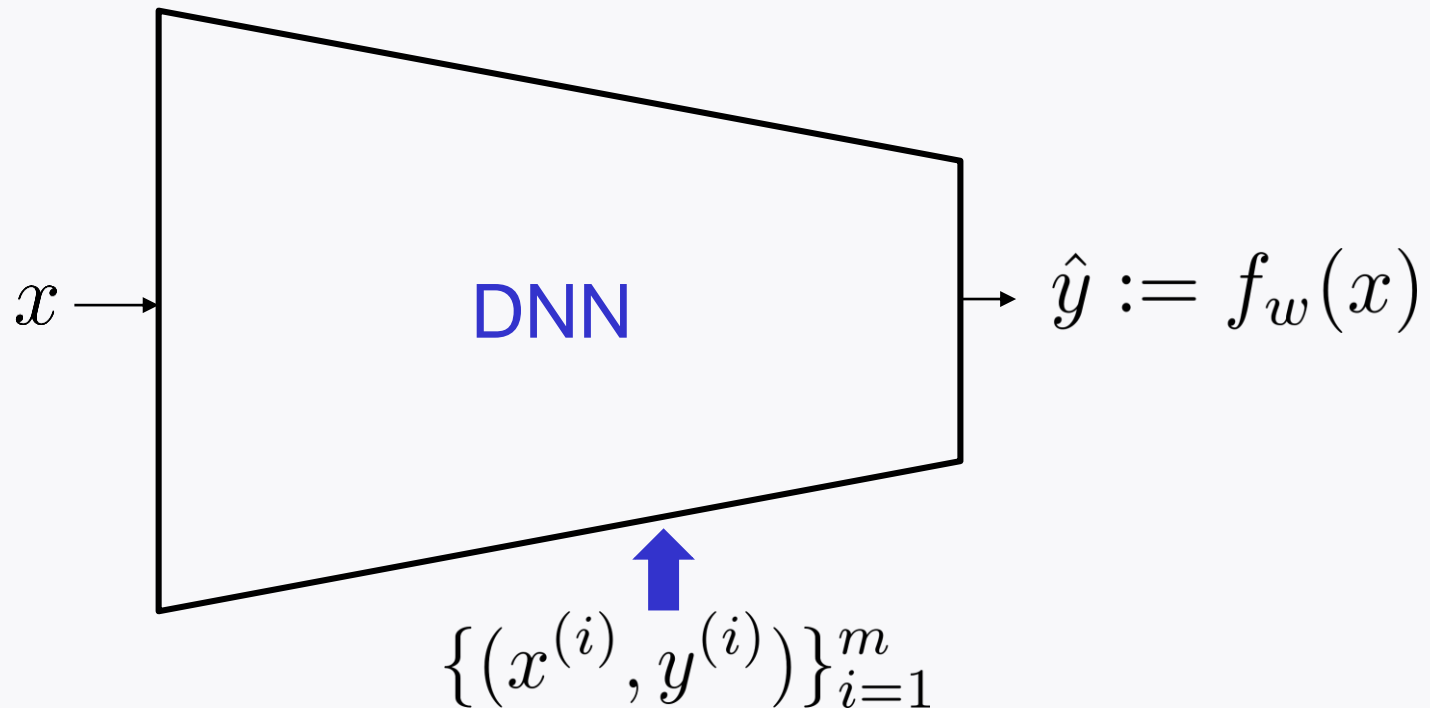
Summary of Day 1 lectures



Linear activation + squared error loss: **LS** classifier

Logistic acti. + cross entropy loss: **Logistic regression**

Summary of Day 1 lectures



ReLU (@hidden); **Logistic** (@output); Cross entropy loss

Algorithm: Gradient descent

Efficient method: **backprop**

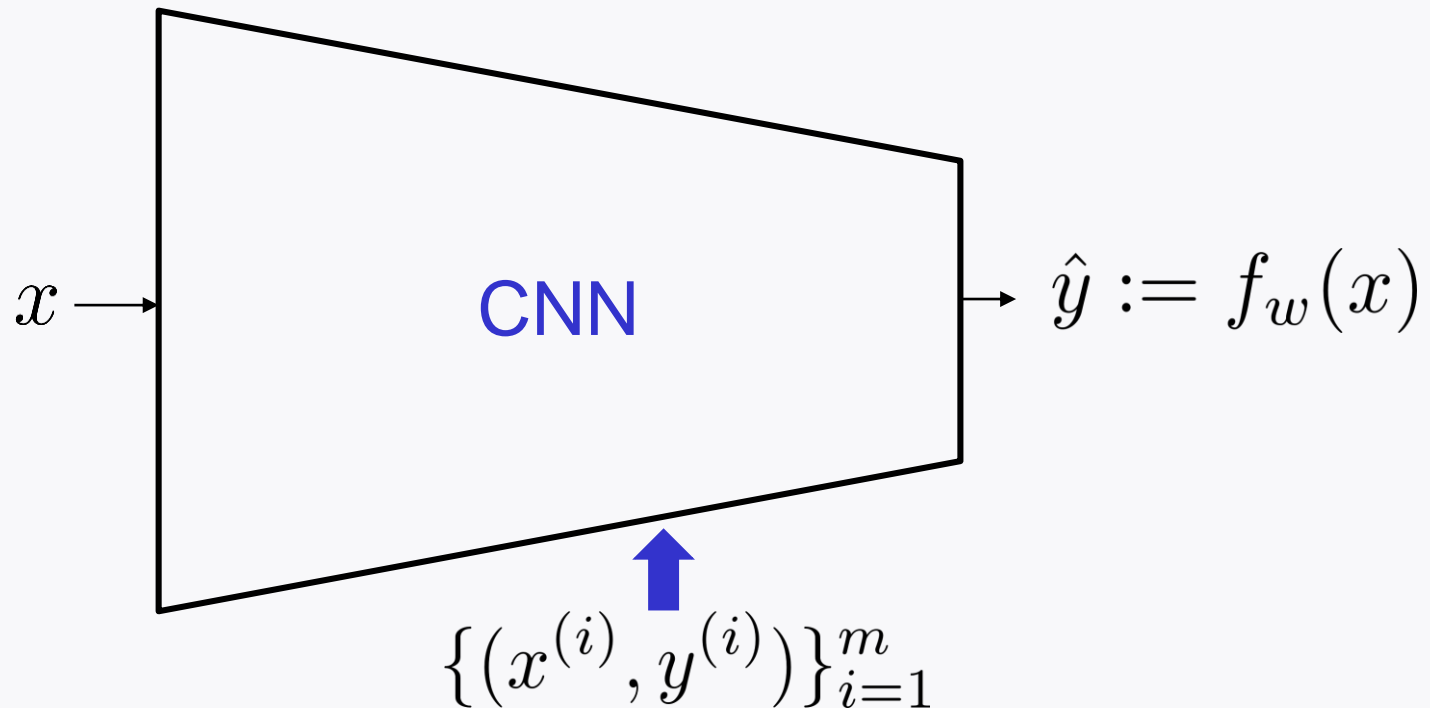
Practical variant: Adam optimizer

Summary of Day 2 lectures

Advanced techniques:

1. Data organization
2. Generalization techniques
3. Weight initialization
4. Techniques for training stability
5. Hyperparameter search
6. Cross validation

Summary of Day 3 lectures

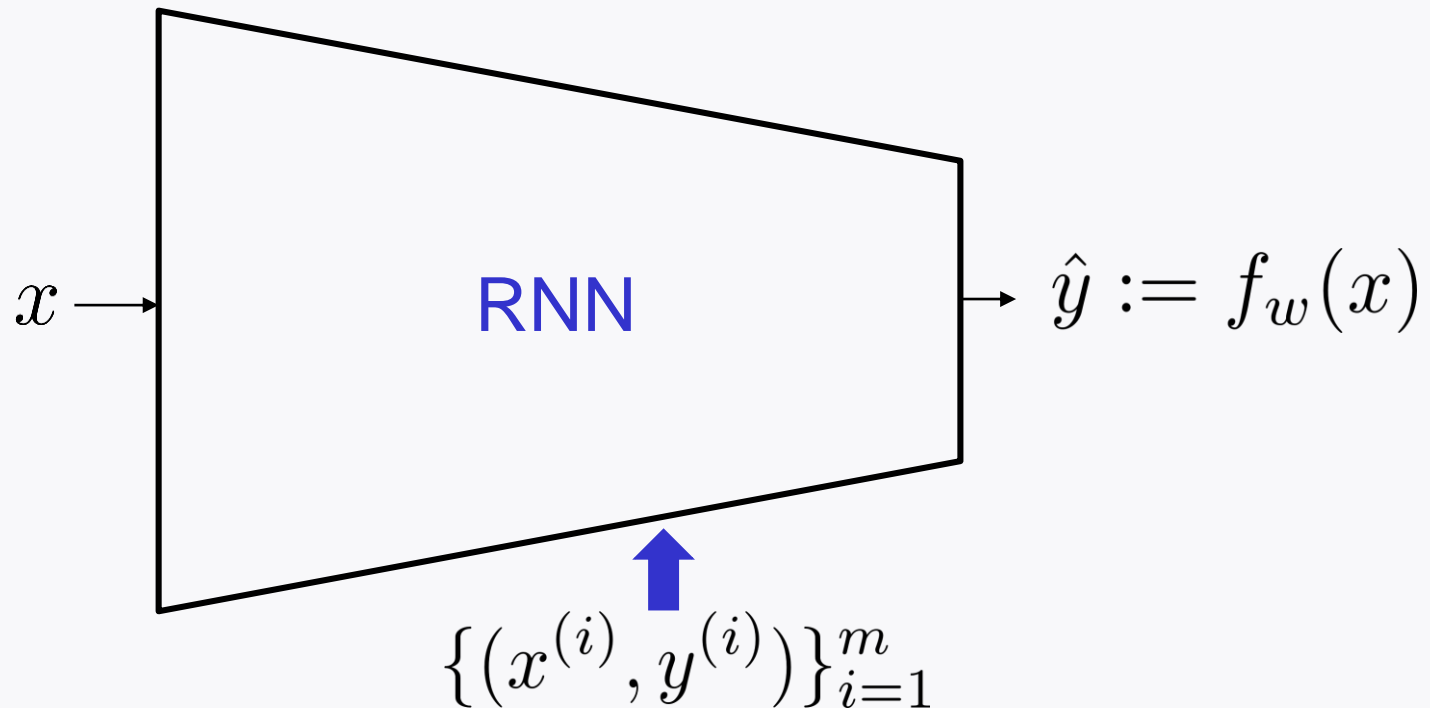


Two building blocks: Conv layer & Pooling layer

Design principles: As a network is deeper,

1. Feature map sizes gets smaller.
2. # of feature maps gets bigger.

Summary of Day 4 lectures



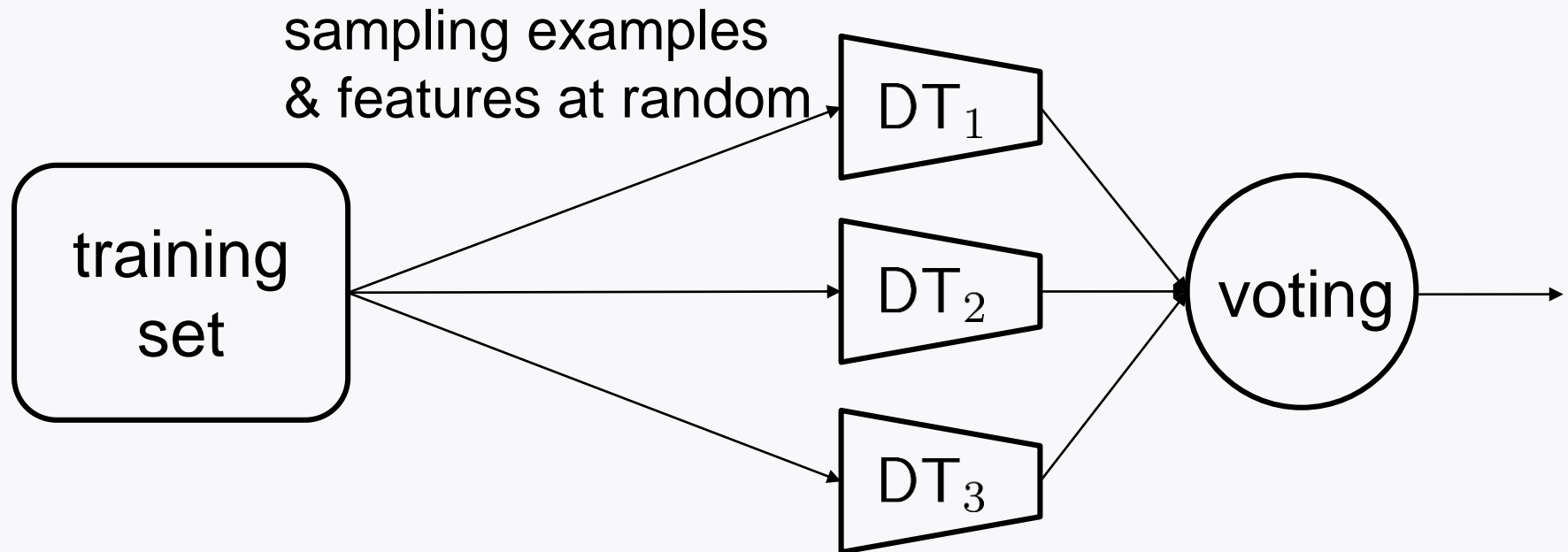
Two building blocks: Recurrent neurons & memory cell

Basic RNNs: Trained via truncated BTTP;
Memory fades quickly.

LSTM: Offers great performance and fast training.

Summary of today's lectures

RF: An ensemble of DTs, each trained on the random subspace method



A key hyperparameter: “**max_features**”

A measure for *interpretation*: **Feature importance**

Many remaining issues

What if labels are **not available**? $\{(x^{(i)}, \cancel{y^{(i)}})\}_{i=1}^m$

Unsupervised learning:

Clustering, anomaly detection

Principal component analysis (PCA), autoencoder

Generative Adversarial Networks (GANs)

Many remaining issues

Advanced small data techniques:

Semi-supervised learning

Transfer learning

Simulator-based learning