## **PS21**

January 26, 2024

# 1 Mini-project #2 (RNN exercise)

- 1.1 Task: Weather prediction
- 1.2 Loading Jena climate dataset & propreprocessing

```
import pandas as pd
data = pd.read_csv('jena_climate_2009_2016.csv')

# fill up the missing entries with the mean
wv = data['wv (m/s)']
wv_missing_idx = (wv == -9999.00)
wv_mean = wv[-wv_missing_idx].mean()
wv[wv_missing_idx] = wv_mean

max_wv = data['max. wv (m/s)']
missing_idx = (max_wv == -9999.00)
max_wv_mean = max_wv[~missing_idx].mean()
max_wv[missing_idx] = max_wv_mean

# reumoe 'data time' column
data.pop('Date Time')

# downsampling
data = data[0::6] # m=70,092
```

C:\Users\chsuh\AppData\Local\Temp\ipykernel\_33720\391320505.py:8:
SettingWithCopyWarning:

A value is trying to be set on a copy of a slice from a DataFrame

See the caveats in the documentation: https://pandas.pydata.org/pandas-docs/stable/user\_guide/indexing.html#returning-a-view-versus-a-copy wv[wv\_missing\_idx] = wv\_mean

C:\Users\chsuh\AppData\Local\Temp\ipykernel\_33720\391320505.py:13:
SettingWithCopyWarning:

A value is trying to be set on a copy of a slice from a DataFrame

See the caveats in the documentation: https://pandas.pydata.org/pandas-docs/stable/user\_guide/indexing.html#returning-a-view-versus-a-copy

```
max_wv[missing_idx] = max_wv_mean
```

### 1.3 Normalization & splitting

```
[2]: features = data
     labels = data[['T (degC)']]
     # normalization
     from sklearn.preprocessing import StandardScaler
     std_scaler = StandardScaler()
     features = std_scaler.fit_transform(features)
     # 7:2:1 splitting
     from sklearn.model selection import train test split
     X_rest, X_test, y_rest, y_test = train_test_split(features,
                                                        labels,
                                                        test_size=0.1,
                                                        shuffle=False)
    X_train, X_val, y_train, y_val = train_test_split(X_rest,
                                                        y_rest,
                                                        test_size=2/9,
                                                        shuffle=False)
```

# 1.4 Time series data generation: Construct $\{(x_T^{(i)}, y_T^{(i)})\}_{i=1}^{m_T}$

```
[3]: T = 24
     batch_size = 16
     from tensorflow.keras.preprocessing import timeseries_dataset_from_array
     # Train batch dataset
     dataset_train = timeseries_dataset_from_array(X_train[:-T],
                                                    y_train[T:],
                                                    sequence_length = T,
                                                    sequence stride = 1,
                                                    batch_size = batch_size,
                                                    shuffle = True)
     # validation batch dataset
     dataset_val = timeseries_dataset_from_array(X_val[:-T],
                                                  y_val[T:],
                                                  sequence_length = T,
                                                  sequence_stride = 1,
                                                  batch_size=batch_size,
                                                  shuffle = False)
     # test batch dataset
     dataset_test = timeseries_dataset_from_array(X_test[:-T],
                                                   y_test[T:],
                                                   sequence_length = T,
```

```
sequence_stride = 1,
batch_size=batch_size,
shuffle = False)
```

#### 1.5 DNN model

```
[4]: from tensorflow.keras.models import Model
from tensorflow.keras.layers import Input,Flatten,Dense
from tensorflow.keras.optimizers import Adam
from tensorflow.keras.callbacks import EarlyStopping
from tensorflow.keras.callbacks import LearningRateScheduler
```

```
[5]: # DNN model construction
inputs = Input(shape=(T,14))
x = Flatten()(inputs)
x = Dense(units=32,activation='relu')(x)
outputs = Dense(units=1)(x)
dnn_model = Model(inputs=inputs,outputs=outputs)
dnn_model.summary()
```

Model: "model"

| Layer (type)         | Output Shape     | Param # |
|----------------------|------------------|---------|
| input_1 (InputLayer) | [(None, 24, 14)] | 0       |
| flatten (Flatten)    | (None, 336)      | 0       |
| dense (Dense)        | (None, 32)       | 10784   |
| dense_1 (Dense)      | (None, 1)        | 33      |
|                      |                  |         |

\_\_\_\_\_\_

Total params: 10,817 Trainable params: 10,817 Non-trainable params: 0

```
[6]: # Early stopping & learning rate decay
es_callback = EarlyStopping(monitor='val_loss',patience=10)
def scheduler(epoch,lr):
    if epoch in [10,20,30]: lr = 0.1*lr
    return lr
lrs_callback = LearningRateScheduler(scheduler)
```

```
beta_2=0.999)
[8]: # Compile
    from tensorflow.keras.metrics import RootMeanSquaredError
    dnn_model.compile(loss='mean_squared_error',
                   metrics=RootMeanSquaredError(),
                    optimizer=opt)
[9]: # Training
    hist= dnn_model.fit(dataset_train,
                      epochs=30,
                      validation_data=dataset_val,
                      callbacks=[es_callback,lrs_callback])
   Epoch 1/30
   root_mean_squared_error: 2.0115 - val_loss: 0.9511 -
   val_root_mean_squared_error: 0.9752 - lr: 0.0010
   Epoch 2/30
   3064/3064 [============== ] - 14s 5ms/step - loss: 0.8718 -
   root_mean_squared_error: 0.9337 - val_loss: 0.6878 -
   val_root_mean_squared_error: 0.8294 - lr: 0.0010
   Epoch 3/30
   3064/3064 [============== ] - 13s 4ms/step - loss: 0.7640 -
   root_mean_squared_error: 0.8740 - val_loss: 0.6770 -
   val_root_mean_squared_error: 0.8228 - lr: 0.0010
   Epoch 4/30
   3064/3064 [============== ] - 13s 4ms/step - loss: 0.7125 -
   root_mean_squared_error: 0.8441 - val_loss: 0.7528 -
   val_root_mean_squared_error: 0.8676 - lr: 0.0010
   Epoch 5/30
   3064/3064 [============== ] - 14s 4ms/step - loss: 0.6894 -
   root_mean_squared_error: 0.8303 - val_loss: 0.6323 -
   val_root_mean_squared_error: 0.7952 - lr: 0.0010
   Epoch 6/30
   3064/3064 [============= ] - 13s 4ms/step - loss: 0.6596 -
   root_mean_squared_error: 0.8122 - val_loss: 0.6292 -
   val_root_mean_squared_error: 0.7932 - lr: 0.0010
   Epoch 7/30
   3064/3064 [============= ] - 14s 4ms/step - loss: 0.6408 -
   root_mean_squared_error: 0.8005 - val_loss: 0.5819 -
   val_root_mean_squared_error: 0.7628 - lr: 0.0010
   Epoch 8/30
   3064/3064 [============= ] - 13s 4ms/step - loss: 0.6311 -
   root_mean_squared_error: 0.7944 - val_loss: 0.5787 -
   val_root_mean_squared_error: 0.7607 - lr: 0.0010
```

Epoch 9/30

```
root_mean_squared_error: 0.7877 - val_loss: 0.5522 -
val_root_mean_squared_error: 0.7431 - lr: 0.0010
Epoch 10/30
3064/3064 [============= ] - 14s 4ms/step - loss: 0.5998 -
root mean squared error: 0.7745 - val loss: 0.6124 -
val_root_mean_squared_error: 0.7826 - lr: 0.0010
Epoch 11/30
root_mean_squared_error: 0.7109 - val_loss: 0.5235 -
val_root_mean_squared_error: 0.7235 - lr: 1.0000e-04
Epoch 12/30
root_mean_squared_error: 0.7069 - val_loss: 0.5214 -
val_root_mean_squared_error: 0.7221 - lr: 1.0000e-04
Epoch 13/30
3064/3064 [=============== ] - 14s 5ms/step - loss: 0.4980 -
root_mean_squared_error: 0.7057 - val_loss: 0.5211 -
val_root_mean_squared_error: 0.7219 - lr: 1.0000e-04
Epoch 14/30
3064/3064 [============== ] - 11s 4ms/step - loss: 0.4963 -
root_mean_squared_error: 0.7045 - val_loss: 0.5212 -
val_root_mean_squared_error: 0.7219 - lr: 1.0000e-04
Epoch 15/30
3064/3064 [============== ] - 12s 4ms/step - loss: 0.4947 -
root_mean_squared_error: 0.7033 - val_loss: 0.5221 -
val_root_mean_squared_error: 0.7226 - lr: 1.0000e-04
Epoch 16/30
root_mean_squared_error: 0.7028 - val_loss: 0.5209 -
val_root_mean_squared_error: 0.7217 - lr: 1.0000e-04
Epoch 17/30
3064/3064 [============== ] - 13s 4ms/step - loss: 0.4932 -
root_mean_squared_error: 0.7023 - val_loss: 0.5204 -
val_root_mean_squared_error: 0.7214 - lr: 1.0000e-04
Epoch 18/30
root_mean_squared_error: 0.7014 - val_loss: 0.5191 -
val_root_mean_squared_error: 0.7205 - lr: 1.0000e-04
Epoch 19/30
root_mean_squared_error: 0.7008 - val_loss: 0.5173 -
val_root_mean_squared_error: 0.7193 - lr: 1.0000e-04
Epoch 20/30
root_mean_squared_error: 0.7006 - val_loss: 0.5163 -
val_root_mean_squared_error: 0.7186 - lr: 1.0000e-04
Epoch 21/30
```

```
val_root_mean_squared_error: 0.7145 - lr: 1.0000e-05
    Epoch 22/30
    3064/3064 [============= ] - 13s 4ms/step - loss: 0.4790 -
    root mean squared error: 0.6921 - val loss: 0.5104 -
    val_root_mean_squared_error: 0.7144 - lr: 1.0000e-05
    Epoch 23/30
    root_mean_squared_error: 0.6919 - val_loss: 0.5103 -
    val_root_mean_squared_error: 0.7143 - lr: 1.0000e-05
    Epoch 24/30
    root_mean_squared_error: 0.6918 - val_loss: 0.5102 -
    val_root_mean_squared_error: 0.7143 - lr: 1.0000e-05
    Epoch 25/30
    root_mean_squared_error: 0.6917 - val_loss: 0.5101 -
    val_root_mean_squared_error: 0.7142 - lr: 1.0000e-05
    Epoch 26/30
    root_mean_squared_error: 0.6916 - val_loss: 0.5099 -
    val_root_mean_squared_error: 0.7141 - lr: 1.0000e-05
    Epoch 27/30
    3064/3064 [============== ] - 14s 5ms/step - loss: 0.4782 -
    root_mean_squared_error: 0.6915 - val_loss: 0.5098 -
    val_root_mean_squared_error: 0.7140 - lr: 1.0000e-05
    Epoch 28/30
    root_mean_squared_error: 0.6915 - val_loss: 0.5098 -
    val_root_mean_squared_error: 0.7140 - lr: 1.0000e-05
    Epoch 29/30
    3064/3064 [============= ] - 14s 5ms/step - loss: 0.4780 -
    root_mean_squared_error: 0.6914 - val_loss: 0.5098 -
    val_root_mean_squared_error: 0.7140 - lr: 1.0000e-05
    Epoch 30/30
    3064/3064 [============== ] - 14s 5ms/step - loss: 0.4779 -
    root_mean_squared_error: 0.6913 - val_loss: 0.5097 -
    val_root_mean_squared_error: 0.7139 - lr: 1.0000e-05
[10]: # Evaluate normalized RMSE
    eval rmse = dnn model.evaluate(dataset test)[1]
    eval_nrmse = eval_rmse/y_test.std()
    print(eval_nrmse)
    root_mean_squared_error: 0.7023
            0.089477
    T (degC)
    dtype: float64
```

root\_mean\_squared\_error: 0.6927 - val\_loss: 0.5106 -

### 1.6 LSTM model

```
[11]: from tensorflow.keras.models import Model
     from tensorflow.keras.layers import Input, Flatten, Dense, LSTM
     from tensorflow.keras.optimizers import Adam
     from tensorflow.keras.callbacks import EarlyStopping
     from tensorflow.keras.callbacks import LearningRateScheduler
[12]: # LSTM model construction
     inputs = Input(shape=(T,14))
     x = LSTM(units=32,return_sequences=True)(inputs)
     x = LSTM(units=32)(x)
     outputs=Dense(units=1)(x)
     rnn_model = Model(inputs=inputs, outputs=outputs)
     rnn_model.summary()
     Model: "model_1"
     Layer (type)
                               Output Shape
     _____
      input_2 (InputLayer) [(None, 24, 14)]
     lstm (LSTM)
                                (None, 24, 32)
                                                        6016
     lstm_1 (LSTM)
                                (None, 32)
                                                         8320
      dense 2 (Dense)
                                (None, 1)
                                                         33
     Total params: 14,369
     Trainable params: 14,369
     Non-trainable params: 0
[13]: # Early stopping & learning rate decay
     es_callback = EarlyStopping(monitor='val_loss',patience=10)
     def scheduler(epoch,lr):
         if epoch in [10,20,30]: lr = 0.1*lr
         return lr
     lrs_callback = LearningRateScheduler(scheduler)
[14]: # Optimizer
     opt = Adam(learning rate=0.001,
               beta_1=0.9,
               beta_2=0.999)
[15]: # Compile
     from tensorflow.keras.metrics import RootMeanSquaredError
```

```
rnn_model.compile(loss='mean_squared_error',
                    metrics=RootMeanSquaredError(),
                     optimizer=opt)
[16]: # Training
     history = rnn_model.fit(dataset_train,
                       epochs=30,
                       validation_data=dataset_val,
                       callbacks=[es_callback,lrs_callback])
    Epoch 1/30
    3064/3064 [============== ] - 40s 11ms/step - loss: 7.4458 -
    root_mean_squared_error: 2.7287 - val_loss: 0.7951 -
    val_root_mean_squared_error: 0.8917 - lr: 0.0010
    Epoch 2/30
    3064/3064 [============= ] - 31s 10ms/step - loss: 0.6251 -
    root_mean_squared_error: 0.7906 - val_loss: 0.5424 -
    val_root_mean_squared_error: 0.7365 - lr: 0.0010
    Epoch 3/30
    3064/3064 [============= ] - 31s 10ms/step - loss: 0.5638 -
    root_mean_squared_error: 0.7509 - val_loss: 0.5172 -
    val_root_mean_squared_error: 0.7191 - lr: 0.0010
    Epoch 4/30
    3064/3064 [============== ] - 34s 11ms/step - loss: 0.5471 -
    root_mean_squared_error: 0.7397 - val_loss: 0.5013 -
    val_root_mean_squared_error: 0.7080 - lr: 0.0010
    Epoch 5/30
    3064/3064 [============= ] - 31s 10ms/step - loss: 0.5363 -
    root_mean_squared_error: 0.7323 - val_loss: 0.5083 -
    val_root_mean_squared_error: 0.7130 - lr: 0.0010
    Epoch 6/30
    3064/3064 [============= - - 33s 11ms/step - loss: 0.5289 -
    root_mean_squared_error: 0.7273 - val_loss: 0.5260 -
    val_root_mean_squared_error: 0.7253 - lr: 0.0010
    Epoch 7/30
    root_mean_squared_error: 0.7206 - val_loss: 0.4923 -
    val_root_mean_squared_error: 0.7016 - lr: 0.0010
    Epoch 8/30
    3064/3064 [============== ] - 34s 11ms/step - loss: 0.5124 -
    root_mean_squared_error: 0.7158 - val_loss: 0.4806 -
    val_root_mean_squared_error: 0.6932 - lr: 0.0010
    Epoch 9/30
    3064/3064 [============= ] - 33s 11ms/step - loss: 0.5062 -
    root_mean_squared_error: 0.7114 - val_loss: 0.4914 -
    val_root_mean_squared_error: 0.7010 - lr: 0.0010
    Epoch 10/30
```

3064/3064 [============== ] - 32s 11ms/step - loss: 0.5001 -

```
root_mean_squared_error: 0.7071 - val_loss: 0.5031 -
val_root_mean_squared_error: 0.7093 - lr: 0.0010
Epoch 11/30
3064/3064 [============== ] - 34s 11ms/step - loss: 0.4567 -
root mean squared error: 0.6758 - val loss: 0.4541 -
val_root_mean_squared_error: 0.6739 - lr: 1.0000e-04
Epoch 12/30
3064/3064 [============== ] - 33s 11ms/step - loss: 0.4514 -
root_mean_squared_error: 0.6719 - val_loss: 0.4521 -
val_root_mean_squared_error: 0.6724 - lr: 1.0000e-04
Epoch 13/30
3064/3064 [============== ] - 32s 11ms/step - loss: 0.4491 -
root_mean_squared_error: 0.6701 - val_loss: 0.4512 -
val_root_mean_squared_error: 0.6717 - lr: 1.0000e-04
Epoch 14/30
3064/3064 [============= - - 30s 10ms/step - loss: 0.4478 -
root_mean_squared_error: 0.6692 - val_loss: 0.4524 -
val_root_mean_squared_error: 0.6726 - lr: 1.0000e-04
Epoch 15/30
3064/3064 [============= ] - 32s 11ms/step - loss: 0.4464 -
root mean squared error: 0.6682 - val loss: 0.4510 -
val_root_mean_squared_error: 0.6716 - lr: 1.0000e-04
Epoch 16/30
3064/3064 [============== ] - 31s 10ms/step - loss: 0.4453 -
root_mean_squared_error: 0.6673 - val_loss: 0.4512 -
val_root_mean_squared_error: 0.6717 - lr: 1.0000e-04
Epoch 17/30
root_mean_squared_error: 0.6666 - val_loss: 0.4510 -
val_root_mean_squared_error: 0.6715 - lr: 1.0000e-04
Epoch 18/30
3064/3064 [============== ] - 31s 10ms/step - loss: 0.4437 -
root_mean_squared_error: 0.6661 - val_loss: 0.4511 -
val_root_mean_squared_error: 0.6716 - lr: 1.0000e-04
Epoch 19/30
root mean squared error: 0.6653 - val loss: 0.4508 -
val_root_mean_squared_error: 0.6714 - lr: 1.0000e-04
Epoch 20/30
3064/3064 [============= ] - 32s 10ms/step - loss: 0.4417 -
root_mean_squared_error: 0.6646 - val_loss: 0.4503 -
val_root_mean_squared_error: 0.6711 - lr: 1.0000e-04
Epoch 21/30
3064/3064 [============= ] - 32s 10ms/step - loss: 0.4364 -
root_mean_squared_error: 0.6606 - val_loss: 0.4491 -
val_root_mean_squared_error: 0.6702 - lr: 1.0000e-05
Epoch 22/30
3064/3064 [============== ] - 32s 10ms/step - loss: 0.4358 -
```

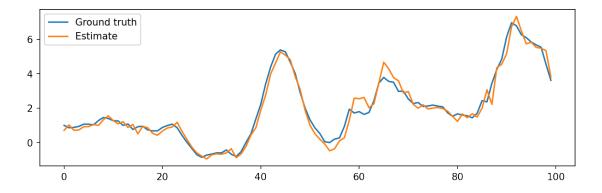
```
val_root_mean_squared_error: 0.6702 - lr: 1.0000e-05
    Epoch 23/30
    3064/3064 [============= ] - 32s 10ms/step - loss: 0.4356 -
    root mean squared error: 0.6600 - val loss: 0.4493 -
    val_root_mean_squared_error: 0.6703 - lr: 1.0000e-05
    Epoch 24/30
    3064/3064 [============== ] - 32s 10ms/step - loss: 0.4354 -
    root_mean_squared_error: 0.6599 - val_loss: 0.4493 -
    val_root_mean_squared_error: 0.6703 - lr: 1.0000e-05
    Epoch 25/30
    3064/3064 [============== ] - 32s 10ms/step - loss: 0.4353 -
    root_mean_squared_error: 0.6598 - val_loss: 0.4494 -
    val_root_mean_squared_error: 0.6704 - lr: 1.0000e-05
    Epoch 26/30
    3064/3064 [============= ] - 32s 10ms/step - loss: 0.4352 -
    root_mean_squared_error: 0.6597 - val_loss: 0.4494 -
    val_root_mean_squared_error: 0.6704 - lr: 1.0000e-05
    Epoch 27/30
    3064/3064 [============= ] - 31s 10ms/step - loss: 0.4351 -
    root_mean_squared_error: 0.6596 - val_loss: 0.4494 -
    val_root_mean_squared_error: 0.6704 - lr: 1.0000e-05
    Epoch 28/30
    3064/3064 [============== ] - 33s 11ms/step - loss: 0.4349 -
    root_mean_squared_error: 0.6595 - val_loss: 0.4495 -
    val_root_mean_squared_error: 0.6704 - lr: 1.0000e-05
    Epoch 29/30
    root_mean_squared_error: 0.6594 - val_loss: 0.4495 -
    val_root_mean_squared_error: 0.6704 - lr: 1.0000e-05
    Epoch 30/30
    3064/3064 [============= ] - 32s 10ms/step - loss: 0.4348 -
    root_mean_squared_error: 0.6594 - val_loss: 0.4495 -
    val_root_mean_squared_error: 0.6705 - lr: 1.0000e-05
[17]: # Evaluate normalized RMSE
     eval_rmse = rnn_model.evaluate(dataset_test)[1]
     eval_nrmse = eval_rmse/y_test.std()
     print(eval_nrmse)
    root_mean_squared_error: 0.6633
              0.084508
    T (degC)
    dtype: float64
[18]: import matplotlib.pyplot as plt
     plt.figure(figsize=(10,3), dpi=150)
```

root\_mean\_squared\_error: 0.6601 - val\_loss: 0.4492 -

```
plt.plot(y_test[T:100+T].values)
estimated = rnn_model.predict(dataset_test)
plt.plot(estimated[:100])
plt.legend(['Ground truth', 'Estimate'])
```

436/436 [============ ] - 3s 5ms/step

### [18]: <matplotlib.legend.Legend at 0x2176e043c10>



[]: