

# Tutorial 1

Some notes about the tutorials

- Attendance is not mandatory, but encouraged
- Feel free to make topic suggestions on Canvas
- TAs will make a post on Fridays asking for suggestions on topics to revisit
- If there's time left from the tutorial session after covering the suggested topics, it will be used as office hours

# Frequency Response

## From Lecture 5 slides

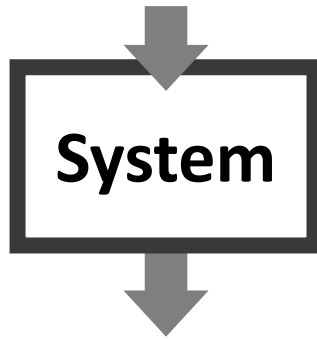
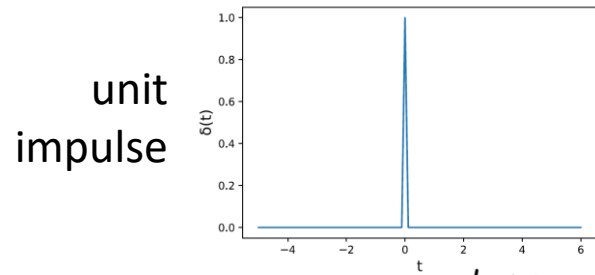
And we know that these complex exponential signals are eigenfunctions of LTI systems:

$$\begin{aligned}x(t) \rightarrow y(t) &= \sum_{k=-\infty}^{\infty} c_k H(jk\omega) e^{jk\omega t} \\x[n] \rightarrow y[n] &= \sum_{k=0}^{N-1} c_k H(e^{jk\omega}) e^{jk\omega n}\end{aligned}$$

In general,  $H(s)$  is called the **system function**; when we are limiting to  $H(j\omega)$  we term this the **frequency response**.

In other words, when we input a complex exponential signal at a particular frequency, how does the system respond?

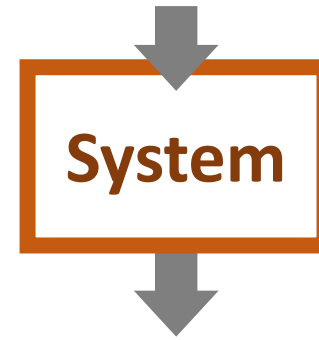
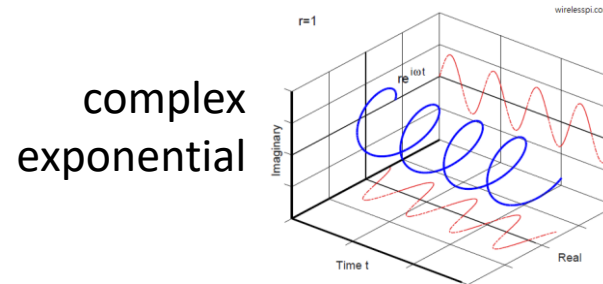
to know how a system will  
behave to any given signal



$$h(t)$$

impulse response

to know how a system will  
**behave to any given frequency**



$$H(j\omega)$$

**frequency response**

# Frequency Response

Three steps:

1. Determine the Fourier coefficients of the signal
2. Determine the frequency response
3. Use 1 and 2 to obtain Fourier coefficients of the output signal

# 1. Determine Fourier coefficients of input signal

Using an example from Quiz 2

## Quiz 2 Fourier coefficients

The continuous-time Fourier series of a periodic function is defined as  $x(t) = \sum_{k=-\infty}^{\infty} c_k e^{jk\omega t}$ .

Consider the function below:  $x(t) = 2 + 2 \sin(\omega t) + 2 \cos(2\omega t)$

What are the real and imaginary parts of the first 3 Fourier coefficients? (Hint:  $1/j = -j$ .)

- Expand to complex exponentials

$$x(t) = 2 + 2 \frac{1}{2j} (e^{j\omega t} - e^{-j\omega t}) + 2 \frac{1}{2} (e^{2j\omega t} + e^{-2j\omega t})$$

When dealing with periodic signals such as these, calculating  $C_k$  is a straight forward process

$$x(t) = 2 - j(e^{j\omega t} - e^{-j\omega t}) + (e^{2j\omega t} + e^{-2j\omega t})$$

Helpful to remember:

$$\begin{aligned}\cos \theta &= \frac{1}{2} (e^{i\theta} + e^{-i\theta}) \\ \sin \theta &= \frac{1}{2i} (e^{i\theta} - e^{-i\theta}) \\ \frac{1}{j} &= -j\end{aligned}$$



$$\begin{aligned}C_0 &= 2 \\ C_1 &= \frac{1}{j} = -j; \quad C_{-1} = C_1^* = j \\ C_2 &= C_{-2} = 1\end{aligned}$$

## 2. Determine frequency response

Consider the impulse response function

$$h(t) = e^{-t}u(t)$$

We obtain the frequency response of the system as follows

$$\begin{aligned} H(j\omega) &= \int_0^{\infty} e^{-\tau} e^{-j\omega\tau} d\tau = \int_0^{\infty} e^{-\tau(1+j\omega)} d\tau \\ &= \frac{-1}{1+j\omega} e^{-\tau(1+j\omega)} \Big|_0^{\infty} \end{aligned}$$

For  $\tau = \infty$ ,  $e^{-\tau(1+j\omega)} \rightarrow 0$ , whereas for  $\tau = 0$ ,  $e^{-\tau(1+j\omega)} = 1$

So, it follows that the frequency response is

$$H(j\omega) = \frac{1}{1+j\omega}$$

Helpful to remember:

Since  $u(t)$  will be 0 for any  $t < 0$ , the lower limit of the integral can be modified to reflect that, i.e., making the lower limit 0 instead of  $-\infty$ .

### 3. Calculate the new coefficients for the signal

Original coefficients

$$\begin{aligned}C_0 &= 2 \\C_1 &= \frac{1}{j} = -j; \quad C_{-1} = C_1^* = j \\C_2 &= C_{-2} = 1\end{aligned}$$

Frequency response

$$H(j\omega) = \frac{1}{1 + j\omega}$$

New coefficients can be calculated using

$$y(t) = \sum_{k=-\infty}^{\infty} C_k H(jk\omega) e^{jk\omega t}$$

Where

$$\tilde{C}_k = C_k H(jk\omega)$$

New coefficients

$$\begin{aligned}\tilde{C}_0 &= 2 \left( \frac{1}{1 + j\omega(0)} \right) = 2 \\ \tilde{C}_1 &= \tilde{C}_{-1}^* = -j \left( \frac{1}{1 + j\omega(1)} \right) = \frac{-j}{1 + j\omega} \\ \tilde{C}_2 &= \tilde{C}_{-2} = 1 \left( \frac{1}{1 + j\omega(2)} \right) = \frac{1}{1 + 2j\omega}\end{aligned}$$

# The Real and Imaginary parts of $C_k$

In order to separate the real and imaginary parts of the coefficients, we multiply and divide by the conjugate of the denominator.

E.g.

$$\tilde{C}_1 = \tilde{C}_{-1}^* = \frac{-j}{(1+j\omega)} \frac{(1-j\omega)}{(1-j\omega)} = \frac{-\omega-j}{1+\omega^2}$$
$$\Re(\tilde{C}_1) = \frac{-\omega}{1+\omega^2}, \quad \Im(\tilde{C}_1) = \frac{-j}{1+\omega^2}$$

and

$$\tilde{C}_2 = \tilde{C}_{-2} = \frac{1}{(1+2j\omega)} \frac{(1-2j\omega)}{(1-2j\omega)} = \frac{1-2j\omega}{1+4\omega^2}$$
$$\Re(\tilde{C}_2) = \frac{1}{1+4\omega^2}, \quad \Im(\tilde{C}_2) = \frac{-2j\omega}{1+4\omega^2}$$



# Another example

## 1. Coefficients of $x(t)$

$$x(t) = 1 + \cos(\omega t) + 3 \cos(3\omega t)$$

$$x(t) = 1 + \frac{1}{2}(e^{j\omega t} + e^{-j\omega t}) + \frac{3}{2}(e^{3j\omega t} + e^{-3j\omega t})$$

$$C_0 = 1; \quad C_1 = C_{-1} = \frac{1}{2}; \quad C_3 = C_{-3} = \frac{3}{2}$$

## 2. Frequency response of $h(t) = \frac{1}{2}e^{-\frac{t}{6}}u(t)$

$$H(j\omega) = \int_0^{-\infty} \frac{1}{2} e^{-\tau/6} e^{-j\omega\tau} d\tau = \frac{-1}{2\left(\frac{1}{6} + j\omega\right)} e^{-\tau\left(\frac{1}{6} + j\omega\right)} \Big|_0^{\infty}$$

$$H(j\omega) = \frac{1}{2\left(\frac{1}{6} + j\omega\right)}$$

# Another example (continuation)

3. New coefficients  $\tilde{C}_k$

$$\tilde{C}_0 = 3$$

$$\tilde{C}_1 = \tilde{C}_{-1} = \frac{1}{\frac{2}{3} + 4j\omega} = \frac{\frac{2}{3}}{\frac{4}{3} + 16\omega^2} - \frac{4j\omega}{\frac{4}{3} + 16\omega^2}$$

$$\tilde{C}_3 = \tilde{C}_{-3} = \frac{3}{\frac{2}{3} + 12j\omega} = \frac{2}{\frac{4}{9} + 144\omega^2} - \frac{36j\omega}{\frac{4}{9} + 144\omega^2}$$