

Theorem (Expected value rule) Given a random variable X and a function $g: \mathbb{R} \rightarrow \mathbb{R}$, we construct the random variable $Y = g(X)$. Then

$$\sum_y y p_Y(y) = \mathbb{E}[Y] = \mathbb{E}[g(X)] = \sum_x g(x) p_X(x).$$

Remark (PMF of $Y = g(X)$) The PMF of $Y = g(X)$ is $p_Y(y) = \sum_{x: g(x)=y} p_X(x)$.

Remark In general $g(\mathbb{E}[X]) \neq \mathbb{E}[g(X)]$. They are equal if $g(x) = ax + b$.

Variance, conditioning on an event, multiple r.v.

Definition (Variance of a random variable) Given a random variable X with $\mu = \mathbb{E}[X]$, its variance is a measure of the spread of the random variable and is defined as

$$\text{Var}(X) \triangleq \mathbb{E}[(X - \mu)^2] = \sum_x (x - \mu)^2 p_X(x).$$

Definition (Standard deviation)

$$\sigma_X = \sqrt{\text{Var}(X)}.$$

Properties (Properties of the variance)

- $\text{Var}(aX) = a^2 \text{Var}(X)$, for all $a \in \mathbb{R}$.
- $\text{Var}(X + b) = \text{Var}(X)$, for all $b \in \mathbb{R}$.
- $\text{Var}(aX + b) = a^2 \text{Var}(X)$.
- $\text{Var}(X) = \mathbb{E}[X^2] - (\mathbb{E}[X])^2$.

Example (Variance of known r.v.)

- If $X \sim \text{Ber}(p)$, then $\text{Var}(X) = p(1 - p)$.
- If $X \sim \text{Uni}[a, b]$, then $\text{Var}(X) = \frac{(b-a)(b-a+2)}{12}$.
- If $X \sim \text{Bin}(n, p)$, then $\text{Var}(X) = np(1 - p)$.
- If $X \sim \text{Geo}(p)$, then $\text{Var}(X) = \frac{1-p}{p^2}$.

Proposition (Conditional PMF and expectation, given an event) Given the event A , with $\mathbb{P}(A) > 0$, we have the following

- $p_{X|A}(x) = \mathbb{P}(X = x|A)$.
- If A is a subset of the range of X , then:
$$p_{X|A}(x) \triangleq p_{X|\{X \in A\}}(x) = \begin{cases} \frac{1}{\mathbb{P}(A)} p_X(x), & \text{if } x \in A, \\ 0, & \text{otherwise.} \end{cases}$$
- $\sum_x p_{X|A}(x) = 1$.
- $\mathbb{E}[X|A] = \sum_x x p_{X|A}(x)$.
- $\mathbb{E}[g(X)|A] = \sum_x g(x) p_{X|A}(x)$.

Proposition (Total expectation rule) Given a partition of disjoint events A_1, \dots, A_n such that $\sum_i \mathbb{P}(A_i) = 1$, and $\mathbb{P}(A_i) > 0$,

$$\mathbb{E}[X] = \mathbb{P}(A_1) \mathbb{E}[X|A_1] + \dots + \mathbb{P}(A_n) \mathbb{E}[X|A_n].$$

Definition (Memorylessness of the geometric random variable)

When we condition a geometric random variable X on the event $X > n$ we have memorylessness, meaning that the “remaining time” $X - n$, given that $X > n$, is also geometric with the same parameter. Formally,

$$p_{X-n|X>n}(i) = p_X(i).$$

Definition (Joint PMF) The joint PMF of random variables X_1, X_2, \dots, X_n is

$$p_{X_1, X_2, \dots, X_n}(x_1, \dots, x_n) = \mathbb{P}(X_1 = x_1, \dots, X_n = x_n).$$

Properties (Properties of joint PMF)

- $\sum_{x_1} \dots \sum_{x_n} p_{X_1, \dots, X_n}(x_1, \dots, x_n) = 1$.
- $p_{X_1}(x_1) = \sum_{x_2} \dots \sum_{x_n} p_{X_1, \dots, X_n}(x_1, x_2, \dots, x_n)$.
- $p_{X_2, \dots, X_n}(x_2, \dots, x_n) = \sum_{x_1} p_{X_1, X_2, \dots, X_n}(x_1, x_2, \dots, x_n)$.

Definition (Functions of multiple r.v.) If $Z = g(X_1, \dots, X_n)$, where $g: \mathbb{R}^n \rightarrow \mathbb{R}$, then $p_Z(z) = \mathbb{P}(g(X_1, \dots, X_n) = z)$.

Proposition (Expected value rule for multiple r.v.) Given $g: \mathbb{R}^n \rightarrow \mathbb{R}$,

$$\mathbb{E}[g(X_1, \dots, X_n)] = \sum_{x_1, \dots, x_n} g(x_1, \dots, x_n) p_{X_1, \dots, X_n}(x_1, \dots, x_n).$$

Properties (Linearity of expectations)

- $\mathbb{E}[aX + b] = a\mathbb{E}[X] + b$.
- $\mathbb{E}[X_1 + \dots + X_n] = \mathbb{E}[X_1] + \dots + \mathbb{E}[X_n]$.

Conditioning on a random variable, independence

Definition (Conditional PMF given another random variable)

Given discrete random variables X, Y and y such that $p_Y(y) > 0$ we define

$$p_{X|Y}(x|y) \triangleq \frac{p_{X,Y}(x, y)}{p_Y(y)}.$$

Proposition (Multiplication rule) Given jointly discrete random variables X, Y , and whenever the conditional probabilities are defined,

$$p_{X,Y}(x, y) = p_X(x) p_{Y|X}(y|x) = p_Y(y) p_{X|Y}(x|y).$$

Definition (Conditional expectation) Given discrete random variables X, Y and y such that $p_Y(y) > 0$ we define

$$\mathbb{E}[X|Y = y] = \sum_x x p_{X|Y}(x|y).$$

Additionally we have

$$\mathbb{E}[g(X)|Y = y] = \sum_x g(x) p_{X|Y}(x|y).$$

Theorem (Total probability and expectation theorems)

If $p_Y(y) > 0$, then

$$p_X(x) = \sum_y p_Y(y) p_{X|Y}(x|y),$$

$$\mathbb{E}[X] = \sum_y p_Y(y) \mathbb{E}[X|Y = y].$$

Definition (Independence of a random variable and an event) A discrete random variable X and an event A are independent if $\mathbb{P}(X = x \text{ and } A) = p_X(x) \mathbb{P}(A)$, for all x .

Definition (Independence of two random variables) Two discrete random variables X and Y are independent if

$$p_{X,Y}(x, y) = p_X(x) p_Y(y) \text{ for all } x, y.$$

Remark (Independence of a collection of random variables) A collection X_1, X_2, \dots, X_n of random variables are independent if

$$p_{X_1, \dots, X_n}(x_1, \dots, x_n) = p_{X_1}(x_1) \dots p_{X_n}(x_n), \quad \forall x_1, \dots, x_n.$$

Remark (Independence and expectation) In general, $\mathbb{E}[g(X, Y)] \neq g(\mathbb{E}[X], \mathbb{E}[Y])$. An exception is for linear functions: $\mathbb{E}[aX + bY] = a\mathbb{E}[X] + b\mathbb{E}[Y]$.

Proposition (Expectation of product of independent r.v.) If X and Y are discrete independent random variables,

$$\mathbb{E}[XY] = \mathbb{E}[X] \mathbb{E}[Y].$$

Remark If X and Y are independent, $\mathbb{E}[g(X)h(Y)] = \mathbb{E}[g(X)] \mathbb{E}[h(Y)]$.

Proposition (Variance of sum of independent random variables) If X and Y are discrete independent random variables,

$$\text{Var}(X + Y) = \text{Var}(X) + \text{Var}(Y).$$

Continuous random variables

PDF, Expectation, Variance, CDF

Definition (Probability density function (PDF)) A probability density function of a r.v. X is a non-negative real valued function f_X that satisfies the following

- $\int_{-\infty}^{\infty} f_X(x) dx = 1$.
- $\mathbb{P}(a \leq X \leq b) = \int_a^b f_X(x) dx$ for some random variable X .

Definition (Continuous random variable) A random variable X is continuous if its probability law can be described by a PDF f_X .

Remark Continuous random variables satisfy:

- For small $\delta > 0$, $\mathbb{P}(a \leq X \leq a + \delta) \approx f_X(a) \delta$.
- $\mathbb{P}(X = a) = 0, \forall a \in \mathbb{R}$.

Definition (Expectation of a continuous random variable) The expectation of a continuous random variable is

$$\mathbb{E}[X] \triangleq \int_{-\infty}^{\infty} x f_X(x) dx.$$

assuming $\int_{-\infty}^{\infty} |x| f_X(x) dx < \infty$.

Properties (Properties of expectation)

- If $X \geq 0$ then $\mathbb{E}[X] \geq 0$.
- If $a \leq X \leq b$ then $a \leq \mathbb{E}[X] \leq b$.
- $\mathbb{E}[g(X)] = \int_{-\infty}^{\infty} g(x) f_X(x) dx$.
- $\mathbb{E}[aX + b] = a\mathbb{E}[X] + b$.

Definition (Variance of a continuous random variable) Given a continuous random variable X with $\mu = \mathbb{E}[X]$, its variance is

$$\text{Var}(X) = \mathbb{E}[(X - \mu)^2] = \int_{-\infty}^{\infty} (x - \mu)^2 f_X(x) dx.$$

It has the same properties as the variance of a discrete random variable.

Example (Uniform continuous random variable) A Uniform continuous random variable X between a and b , with $a < b$, ($X \sim \text{Uni}(a, b)$) has PDF

$$f_X(x) = \begin{cases} \frac{1}{b-a}, & \text{if } a < x < b, \\ 0, & \text{otherwise.} \end{cases}$$

We have $\mathbb{E}[X] = \frac{a+b}{2}$ and $\text{Var}(X) = \frac{(b-a)^2}{12}$.