Math 416 Lecture Note: Week 8

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1 Introduction to determinants

We define the determinant of a square matrix $A \in \mathcal{M}_{n \times n}(\mathbb{R})$ by the "(signed) volume" of the parallelogram spanned by the row vectors of A. For n = 1, it is natural to define $\det(A) = a$ where A = (a). In this section, we focus on the case n = 2.

Let $A \in \mathcal{M}_{2\times 2}(\mathbb{R})$. Let v, w be the row vectors of A, that is,

$$A = \begin{pmatrix} v \\ w \end{pmatrix} = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

where v = (a, b) and w = (c, d). We consider the determinant of A as a function from $\mathcal{M}_{2\times 2}(\mathbb{R})$ to \mathbb{R} . If the determinant represents the area of the parallelogram spanned by v, w, then it should satisfy the following:

- (i) $\det(I_2) = 1$.
- (ii) (multilinear) For any $u, v, w \in \mathbb{R}^2$ and $c \in \mathbb{R}$,

$$\det \begin{pmatrix} v \\ cu + w \end{pmatrix} = c \begin{pmatrix} v \\ u \end{pmatrix} + \begin{pmatrix} v \\ w \end{pmatrix}, \qquad \det \begin{pmatrix} cu + v \\ w \end{pmatrix} = c \begin{pmatrix} u \\ w \end{pmatrix} + \begin{pmatrix} v \\ w \end{pmatrix}.$$

(iii) (alternating) For any $v \in \mathbb{R}^2$,

$$\det \begin{pmatrix} v \\ v \end{pmatrix} = 0.$$

For each (z, w), the map

$$(x,y) \in \mathbb{R}^2 \mapsto \det \begin{pmatrix} x & y \\ z & w \end{pmatrix} \in \mathbb{R}$$

is linear, so that there exist constants T(z, w), S(z, w) depending on z, w such that

$$\det\begin{pmatrix} x & y \\ z & w \end{pmatrix} = T(z, w)x + S(z, w)y.$$

On the other hand, if x = 1 and y = 0, then the map

$$(z,w) \mapsto \det \begin{pmatrix} 1 & 0 \\ z & w \end{pmatrix} = T(z,w)$$

is linear. Similarly, S(z, w) is also linear. Thus, there exist $p, q, r, s \in \mathbb{R}$ such that T(z, w) = pz + qw and S(z, w) = rz + sw, which leads to

$$\det\begin{pmatrix} x & y \\ z & w \end{pmatrix} = (pz + qw)x + (rz + sw)y.$$

We determine the constants p, q, r, s using the property (i) and (iii). Indeed, we have

$$\det\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = q = 1, \qquad \det\begin{pmatrix} 1 & 0 \\ 1 & 0 \end{pmatrix} = p = 0$$

$$\det\begin{pmatrix} 0 & 1 \\ 0 & 1 \end{pmatrix} = s = 0, \qquad \det\begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} = q + r = 0.$$

Thus, if the determinant satisfy the above properties, it should be det(A) = ad - bc.

Definition 1.1. For $A \in \mathcal{M}_{2\times 2}(\mathbb{R})$, the determinant of A is defined by $\det(A) = ad - bc$.

Remark 1.2. One can check that $\det(A) = ad - bc$ indeed satisfy the property (i), (ii), and (iii). That is, the determinant is the unique alternating multilinear map from $\mathcal{M}_{2\times 2}(\mathbb{R})$ to \mathbb{R} with $\det(I_2) = 1$. For $n \geq 3$, the determinant can be defined in the same way. In general, there exists a unique alternating multilinear map from $\mathcal{M}_{n\times n}(\mathbb{R})$ to \mathbb{R} which maps I_n to 1. We call the map the determinant. We will not go over the uniqueness in this course. Next time, we construct the determinant for $n \geq 3$ and show that it is actually alternating and multilinear.

Theorem 1.3. Let $A, B \in \mathcal{M}_{2\times 2}(\mathbb{R})$.

- (i) det(AB) = det(A) det(B).
- (ii) A is invertible if and only if $det(A) \neq 0$. In this case, $det(A^{-1}) = (det(A))^{-1}$.

$$Proof.$$
 Exercise.

We will check that the determinant really measures the area of the parallelogram spanned by the row vectors.

Theorem 1.4. Let $A \in \mathcal{M}_{2\times 2}(\mathbb{R})$, then $|\det(A)|$ is the area of the parallelogram spanned by the row vectors of A.

Proof.

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}.$$

It is easy to see that

$$T_{\theta} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

rotates a vector by angle $\theta \in [0, 2\pi)$ counterclockwise. Let

$$\begin{pmatrix} p \\ q \end{pmatrix} = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix}, \qquad \begin{pmatrix} r \\ s \end{pmatrix} = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} c \\ d \end{pmatrix}.$$

Then, we have (using the transpose)

$$B = \begin{pmatrix} p & q \\ r & s \end{pmatrix} = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}.$$

Thus, we get

$$\det(B) = \det\begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix} \det(A) = \det(A).$$

By rotation, it is okay to assume that one of the row vectors is parallel to the x-axis. We assume that

$$B = \begin{pmatrix} p & 0 \\ r & s \end{pmatrix},$$

then det(A) = det(B) = ps. In this case the base of the parallelogram is |p| and the height is |s|, which completes the proof.

Remark 1.5. The sign of the determinant represents the orientation of the row vectors of a matrix. We say that $\{v, w\}$ is positively oriented if v can be rotated counterclockwise through $\theta \in (0, \pi)$ to coincide with w, and negatively oriented otherwise. Then, $\{v, w\}$ is positively oriented if and only if $\det(A) > 0$ where

$$A = \begin{pmatrix} v \\ w \end{pmatrix}.$$

2 Definition of determinants

Let $A \in \mathcal{M}_{n \times n}(\mathbb{R})$. Recall that $\det(A) = A_{11}$ for n = 1, and $\det(A) = A_{11}A_{22} - A_{12}A_{21}$ for n = 2. In this section, we define the determinant for $n \geq 3$. This definition also agrees with the previous ones for n = 1, 2.

Definition 2.1. For $A \in \mathcal{M}_{n \times n}(\mathbb{R})$, \widetilde{A}_{ij} is the $(n-1) \times (n-1)$ matrix obtained by deleting the *i*-th row and the *j*-th column of A.

Example 2.2. Consider $A = \begin{pmatrix} 1 & 2 & 3 \\ 1 & 0 & 2 \\ 2 & 1 & 1 \end{pmatrix}$. Then,

$$\widetilde{A}_{12} = \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix}, \qquad \widetilde{A}_{23} = \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix}, \qquad \widetilde{A}_{31} = \begin{pmatrix} 2 & 3 \\ 0 & 2 \end{pmatrix}.$$

Definition 2.3. Let $A \in \mathcal{M}_{n \times n}(\mathbb{R})$. The determinant of A is defined by

$$\det(A) = |A| = \sum_{j=1}^{n} (-1)^{1+j} A_{1j} \det(\widetilde{A}_{1j}).$$

The cofactor C_{ij} of A in row i and column j is defined by

$$C_{ij} = (-1)^{1+j} \det(\widetilde{A}_{ij}).$$

That is, the determinant can be written as

$$\det(A) = A_{11}C_{11} + A_{12}C_{12} + \dots + A_{1n}C_{1n}.$$

This formula is called the cofactor expansion along the first row of A.

Example 2.4. $det(I_n) = 1$.

Example 2.5. Consider $A = \begin{pmatrix} 1 & 2 & 3 \\ 1 & 0 & 2 \\ 2 & 1 & 1 \end{pmatrix}$. Then,

$$\det\begin{pmatrix} 1 & 2 & 3 \\ 1 & 0 & 2 \\ 2 & 1 & 1 \end{pmatrix} = 1(-1)^{1+1} \det\begin{pmatrix} 0 & 2 \\ 1 & 1 \end{pmatrix} + 2(-1)^{1+2} \det\begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix} + 3(-1)^{1+3} \det\begin{pmatrix} 1 & 0 \\ 2 & 1 \end{pmatrix} = 7.$$

Remark 2.6. We will see that this determinant is alternating multilinear, as we have seen for n=2 last time. It is well-known that such a map from $\mathcal{M}_{n\times n}(\mathbb{R})$ to \mathbb{R} is unique.

Theorem 2.7. Let $A, B, C \in \mathcal{M}_{n \times n}(\mathbb{R})$ and $k \in \mathbb{R}$. Let $r \in \{1, 2, \dots, n\}$ and u, v, w the r-th rows of A, B, C respectively. If A, B, C are the same except in row r where u = kv + w, then

$$\det(A) = k \det(B) + \det(C).$$

Proof. Use an induction on n. If n=1, it is trivial. Assume that n>1 and the theorem holds for n-1. If r=1, then $A_{1j}=kB_{1j}+C_{1j}$ and $\widetilde{A}_{1j}=\widetilde{B}_{1j}=\widetilde{C}_{1j}$ for all $j=1,2,\cdots,n$. Thus,

$$\det(A) = \sum_{j=1}^{n} (-1)^{1+j} A_{1j} \det(\widetilde{A}_{1j})$$

$$= k \sum_{j=1}^{n} (-1)^{1+j} B_{1j} \det(\widetilde{B}_{1j}) + \sum_{j=1}^{n} (-1)^{1+j} C_{1j} \det(\widetilde{C}_{1j})$$

$$= k \det(B) + \det(C).$$

Suppose r > 1, then \widetilde{A}_{1j} , \widetilde{B}_{1j} , \widetilde{C}_{1j} are the same except in row (r-1) where u' = kv' + w'. Here, u', v', w' are the (r-1)-th rows of \widetilde{A}_{1j} , \widetilde{B}_{1j} , \widetilde{C}_{1j} . By the induction hypothesis, we have

$$\det(\widetilde{A}_{1j}) = k \det(\widetilde{B}_{1j}) + \det(\widetilde{C}_{1j}).$$

Since $A_{1j} = B_{1j} = C_{1j}$, we have

$$\det(A) = \sum_{j=1}^{n} (-1)^{1+j} A_{1j} \det(\widetilde{A}_{1j})$$

$$= k \sum_{j=1}^{n} (-1)^{1+j} B_{1j} \det(\widetilde{B}_{1j}) + \sum_{j=1}^{n} (-1)^{1+j} C_{1j} \det(\widetilde{C}_{1j})$$

$$= k \det(B) + \det(C).$$

Corollary 2.8. Let $A \in \mathcal{M}_{n \times n}(\mathbb{R})$. If A has a row consisting of all zeros, then $\det(A) = 0$.

Theorem 2.9. Let $A \in \mathcal{M}_{n \times n}(\mathbb{R})$ and $i \in \{1, 2, \dots, n\}$, then

$$\det(A) = \sum_{j=1}^{n} (-1)^{i+j} A_{ij} \det(\widetilde{A}_{ij}).$$

Proof. This follow from the multi-linearity and [FIS, Lemma in p. 213]. See [FIS, Theorem 4.4 in p. 215].

Corollary 2.10. Let $A \in \mathcal{M}_{n \times n}(\mathbb{R})$ and $n \geq 2$. If A has two identical rows, then $\det(A) = 0$.

Proof. Use induction on n. If n=2, we have seen this the last time. Suppose $n\geq 3$ and the result holds for n-1. Let rows r and s of A be identical for $r\neq s$. Let i be an integer such that $1\leq i\leq n,\ i\neq r,s$. Then \widetilde{A}_{ij} is an $(n-1)\times(n-1)$ matrix with two identical rows. By the induction hypothesis, $\det(\widetilde{A}_{ij})=0$ for all $j=1,2,\cdots,n$. Thus,

$$\det(A) = \sum_{j=1}^{n} (-1)^{i+j} A_{ij} \det(\widetilde{A}_{ij}) = 0.$$

Theorem 2.11. Let $A \in \mathcal{M}_{n \times n}(\mathbb{R})$. If A is not invertible (or, equivalently rank(A) < n), then $\det(A) = 0$.

Proof. If A is not invertible, then the set of the row vectors of A is linearly dependent. This means that one of the row vectors can be written as a linear combination of the others. Suppose

$$v_i = a_1 v_1 + \dots + a_{i-1} v_{i-1} + a_{i+1} v_{i+1} + \dots + a_n v_n$$

for some I, where v_1, \dots, v_n are the row vectors of A. Then, A can be written as

$$A = a_1 B_1 + \dots + a_{i-1} B_{i-1} + a_{i+1} B_{i+1} + \dots + a_n B_n$$

where B_i are $n \times n$ matrices having two identical rows. Also A and B_i differ only in one row. Thus, by the multilinearity and the alternating property, we have

$$\det(A) = a_1 \det(B_1) + \dots + a_{i-1} \det(B_{i-1}) + a_{i+1} \det(B_{i+1}) + \dots + a_n \det(B_n) = 0.$$

3 Determinants and row operations

Recall that there are three types of the row operations:

- (1) Swap two rows of M. $(R_i \leftrightarrow R_j)$
- (2) Multiply one row by a nonzero constant $c \in \mathbb{R}$. $(R_i \to cR_i)$
- (3) Add one row to another. $(R_i \to R_i + R_j)$.

We study how these operation affect on the determinant.

Theorem 3.1. Let $A \in \mathcal{M}_{n \times n}(\mathbb{R})$. If $B \in \mathcal{M}_{n \times n}(\mathbb{R})$ is obtained by $R_i \leftrightarrow R_j$, then $\det(B) = -\det(A)$.

Proof. Let R_i and R_j be the *i*-th and *j*-th row vectors of A, then

$$A = \begin{pmatrix} \vdots \\ R_i \\ \vdots \\ R_j \\ \vdots \end{pmatrix}, \qquad B = \begin{pmatrix} \vdots \\ R_j \\ \vdots \\ R_i \\ \vdots \end{pmatrix}.$$

By the linearity and the alternating property, we get

$$0 = \det \begin{pmatrix} \vdots \\ R_i + R_j \\ \vdots \\ R_i + R_j \\ \vdots \end{pmatrix} = \det \begin{pmatrix} \vdots \\ R_i + R_j \\ \vdots \\ R_i \\ \vdots \end{pmatrix} + \det \begin{pmatrix} \vdots \\ R_i \\ \vdots \\ R_j \\ \vdots \end{pmatrix} + \det \begin{pmatrix} \vdots \\ R_j \\ \vdots \\ R_j \\ \vdots \end{pmatrix} + \det \begin{pmatrix} \vdots \\ R_j \\ \vdots \\ R_j \\ \vdots \\ R_j \\ \vdots \end{pmatrix} + \det \begin{pmatrix} \vdots \\ R_j \\ \vdots \\ R_j \\ \vdots \\ R_j \\ \vdots \end{pmatrix} + \det \begin{pmatrix} \vdots \\ R_j \\ \vdots \\ R_j \\ \vdots \\ R_j \\ \vdots \end{pmatrix} = \det(A) + \det(B),$$

which completes the proof.

Theorem 3.2. Let $A \in \mathcal{M}_{n \times n}(\mathbb{R})$ and $c \in \mathbb{R}$. If $B \in \mathcal{M}_{n \times n}(\mathbb{R})$ is obtained by $R_i \to cR_i$, then $\det(B) = c \det(A)$.

Proof. This follows from the linearity.

Theorem 3.3. Let $A \in \mathcal{M}_{n \times n}(\mathbb{R})$ and $c \in \mathbb{R}$. If $B \in \mathcal{M}_{n \times n}(\mathbb{R})$ is obtained by $R_i \to R_i + cR_j$, then $\det(B) = \det(A)$.

Proof. Let R_i and R_j be the *i*-th and *j*-th row vectors of A, then

$$A = \begin{pmatrix} \vdots \\ R_i \\ \vdots \\ R_j \\ \vdots \end{pmatrix}, \qquad B = \begin{pmatrix} \vdots \\ R_i + cR_j \\ \vdots \\ R_j \\ \vdots \end{pmatrix}.$$

By the linearity and the alternating property, we get

$$\det(B) = \det\begin{pmatrix} \vdots \\ R_i \\ \vdots \\ R_j \\ \vdots \end{pmatrix} + c \det\begin{pmatrix} \vdots \\ R_j \\ \vdots \\ R_j \\ \vdots \end{pmatrix} = \det\begin{pmatrix} \vdots \\ R_i \\ \vdots \\ R_j \\ \vdots \end{pmatrix} = \det(A).$$

These observations tell us how to compute the determinant using the row operations.

Theorem 3.4. If A is upper or lower triangular, then det(A) is the product of diagonal entries of A.

Proof. Suppose A is lower triangular. (The same argument works for the other case.) We use an induction on n. If n = 1, it is trivial. Suppose $n \ge 2$ and the result holds for n - 1. Let

$$A = \begin{pmatrix} A_{11} & 0 & 0 & \cdots & 0 \\ A_{21} & A_{22} & 0 & \cdots & 0 \\ \vdots & & \ddots & & 0 \\ A_{n1} & A_{n2} & A_{n3} & \cdots & A_{nn} \end{pmatrix}.$$

By the cofactor expansion of A along the first row, we get

$$\det(A) = A_{11} \det(\widetilde{A}_{11}).$$

Since \widetilde{A}_{11} is lower triangular, the result follows from the induction hypothesis.

Example 3.5.

$$A = \begin{pmatrix} 3 & -7 & 4 \\ 1 & -2 & 1 \\ 2 & -1 & -2 \end{pmatrix} \xrightarrow{R_1 \leftrightarrow R_2} \begin{pmatrix} 1 & -2 & 1 \\ 3 & -7 & 4 \\ 2 & -1 & -2 \end{pmatrix} \xrightarrow{R_2 \to R_2 - 3R_1} \begin{pmatrix} 1 & -2 & 1 \\ 0 & -1 & 1 \\ 2 & -1 & -2 \end{pmatrix}$$

$$\xrightarrow{R_3 \to R_3 - 2R_1} \begin{pmatrix} 1 & -2 & 1 \\ 0 & -1 & 1 \\ 0 & 3 & -4 \end{pmatrix} \xrightarrow{R_2 \to -R_2} \begin{pmatrix} 1 & -2 & 1 \\ 0 & 1 & -1 \\ 0 & 3 & -4 \end{pmatrix}$$

$$\xrightarrow{R_3 \to R_3 - 3R_2} \begin{pmatrix} 1 & -2 & 1 \\ 0 & 1 & -1 \\ 0 & 0 & -1 \end{pmatrix} = B.$$

Thus, det(A) = det(B) = -1.

References

- [FIS] Freidberg, Insel, and Spence, *Linear Algebra*, 4th edition, 2002.
- [Bee] Beezer, A First Course in Linear Algebra, Version 3.5, 2015.
- [Hol] W. H. Holzmann, http://www.cs.uleth.ca/holzmann/notes/reduceduniq.pdf

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