Daeun Song

Computer Science and Engineering · Robotics

✉ daeun7250@gmail.com | ⌂ daeunSong.github.io | ⌨ daeunSong | 🔗 daeunSong

Research Interests

Robot Path and Motion Planning, Computational Geometry

Education

Ewha Womans University, Seoul, Korea

2017 - Current	**M.S. and Ph.D combined in Computer Science and Engineering** • Advisor : Professor Young J. Kim • Graduate student representative of CSE department in 2020

Ewha Womans University, Seoul, Korea

2013 - 2017	**B.S. in Computer Science and Engineering**

Experience

LAAS-CNRS, Toulouse, France

JUN 2019 - SEP 2019	**Gepetto Team, Summer Internship [C03]** • Worked on multi-contact planner for legged robots on uneven terrain, SL1M. • Implemented a module that generates a set of possible contact surfaces using a guide-path result from hpp-rbprm in Python.

Ewha Womans University, Seoul, Korea

JAN 2021 - Current	**"Large-scale Robotic Drawing System", ITRC** • Developing a large-scale robotic drawing system that draws a pen drawing on a large surface. • Implementing under ROS using KUKA LBR IIWA 7 R800 as a manipulator and Clearpath Robotics Ridgeback as a mobile platform. • Leading the team composed of two undergraduate students.
JAN 2016 - FEB 2017	**Computer Graphics Lab, Undergraduate Research [J01]** • Worked on rendering an astronaut model with the physics-based character animation under reduced gravity. • Developed under Motion Builder and 3dsMax with V-ray.
MAR 2016 - DEC 2016	**"SSK, the drawing robot", Graduation Project [W01], [P01], [H04, H05, H06]** • Developed a robotic application to reproduce the user's input drawing from a tablet PC on an arbitrary surface. Worked on the robot part. • Implemented under Sunrise Workbench in Java, using KUKA LBR IIWA 7 R800, manipulator. • Lead the team composed of three undergraduate students.

PUBLICATIONS

International Journals

[J02] **Daeun Song**, Pierre Fernbach, Thomas Flayols, Andrea Del Prete, Nicolas Mansard, Steve Tonneau, Young J. Kim, **"Solving Footstep Planning as a Feasibility Problem using L1-norm Minimization"**, IEEE Robotics and Automation Letters (RA-L)*****, (Accepted). ⌂ ▶ 🗋

[J01] Yun-Hyeong Kim, Taesoo Kwon, **Daeun Song**, Young J. Kim, **"Full-body Animation of Human Locomotion in Reduced Gravity using Physics-based Control"**, IEEE Computer Graphics and Applications (CG&A)*****, Vol. 37, No. 6, Nov/Dec 2017, pp.28-39 (Special issue on Modeling Virtual Humans). ⌂ ▶ 🗋

International Conference Papers

[C04] Jason Chemin, Pierre Fernbach, **Daeun Song**, Nicolas Mansard, Steve Tonneau, **"Learning to steer a locomotion contact planner"**, IEEE International Conference on Robotics and Automation (ICRA), May 2021. 🗋

[C03] Steve Tonneau, **Daeun Song**, Pierre Fernbach, Nicolas Mansard, Michel Taix, Andrea Del Prete, **"SL1M: Sparse L1-norm Minimization for contact planning on uneventerrain"**, IEEE International Conference on Robotics and Automation (ICRA), May 2020. ⌂ ▶ 🗋

[C02] **Daeun Song**, Young J. Kim, **"Distortion-free Robotic Surface-drawing using Conformal Mapping"**, IEEE International Conference on Robotics and Automation (ICRA), May 2019. ⌂ ▶ 🗋 **[H09]**

[C01] **Daeun Song**, Taekhee Lee, Young J. Kim, **"Artistic Pen Drawing on an Arbitrary Surface using an Impedance-controlled Robot"**, IEEE International Conference on Robotics and Automation (ICRA), May 2018. ⌂ ▶ 🗋 **[H07, H08]**

Workshops and Tutorials

[W02] **Daeun Song**, Young J. Kim, "Hi-fidelity Robotic Pen Drawing on a Bumpy Surface", IEEE International Conference on Robotics and Automation (ICRA) Robots and Art Forum, May 2018.

[W01] **Daeun Song**, Taekhee Lee, Jungmin Kim, Sungmin Sohn, Young J. Kim, "Artistic Pen Drawing on an Arbitrary Surface using an Impedance-controlled Robot", IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS) Workshop on Artistically Skilled Robots, Oct 2016.

* : SCI (Science Citation Index)-listed journals

PATENTS

[P01] Young J. Kim, **Daeun Song**, Jungmin Kim, "Robotic apparatus and method for artistic pen drawing on an arbitrary surface," Korean intellectual Property Office, 1019356400000

HONORS & AWARDS

[H10] **Solvay Korea Scholarship Award** | Outstanding Academic Performance (2019 - 2020)

[H09] **RAS Travel Award** | International Conference on Robotics and Automation (ICRA 2019)

[H08] **RAS Travel Award** | International Conference on Robotics and Automation (ICRA 2018)

[H07] **Best Paper Award** | The 13th Korea Robotics Society Annual Conference (KRoC 2018)

[H06] **Participation Award** | Hanium Expo Contest 2016

[H05] **Special Award** | Capston Awards (Engineering Education Festa 2016)

[H04] **1st Place** | Ewha Engineering Capstone Design Contest 2016

[H03] **1st Place** | Ewha Engineering Student Portfolio Contest 2016

[H02] **2nd Place** | Ewha Power ProgrammER(E-PPER) Contest 2016

[H01] **Excellence Award** | Excellent Tutee in Tutoring Program

Technical Skills

Programming Languages: C/C++, Python, Java, Matlab

Robotic Programming: ROS, Sunrise Workbench for KUKA

Robotic Planner and Simulator: OMPL, HPP, MoveIt!, Gazebo, CoppeliaSim

Robotic Hardware: KUKA iiwa 7 R800, Ridgeback mobile platform, Fetch mobile manipulator

Others: Experienced with OpenGL, OpenCV Gurobi, PCL

Activities

Academic

- **Summer School** | Participate, AI & Robotics Summer School 2020   *AUG 2020*
- **Tutorial** | Participate, Reinforcement Learning Tutorial   *JAN 2017*
- **Teaching Assistant** | Computer Programming Class   *Spring 2016*
- **Tutorial** | Participate, Arduino & IoT Sensing and Wireless Communication Control Tutorial   *JAN 2016*
- **Summer School** | Participate, EWHA-EPITA Sumer School, Paris, France   *JUL 2015*

Talks & Demos

- **TALK** | The 5th NZ/KOREA Workshop on HDI4D   *NOV 2017*
- **DEMO** | Drawing robot demo, Engineering Education Festa 2016   *NOV 2016*
- **DEMO** | Drawing robot demo, Hanium Expo 2016   *NOV 2016*