

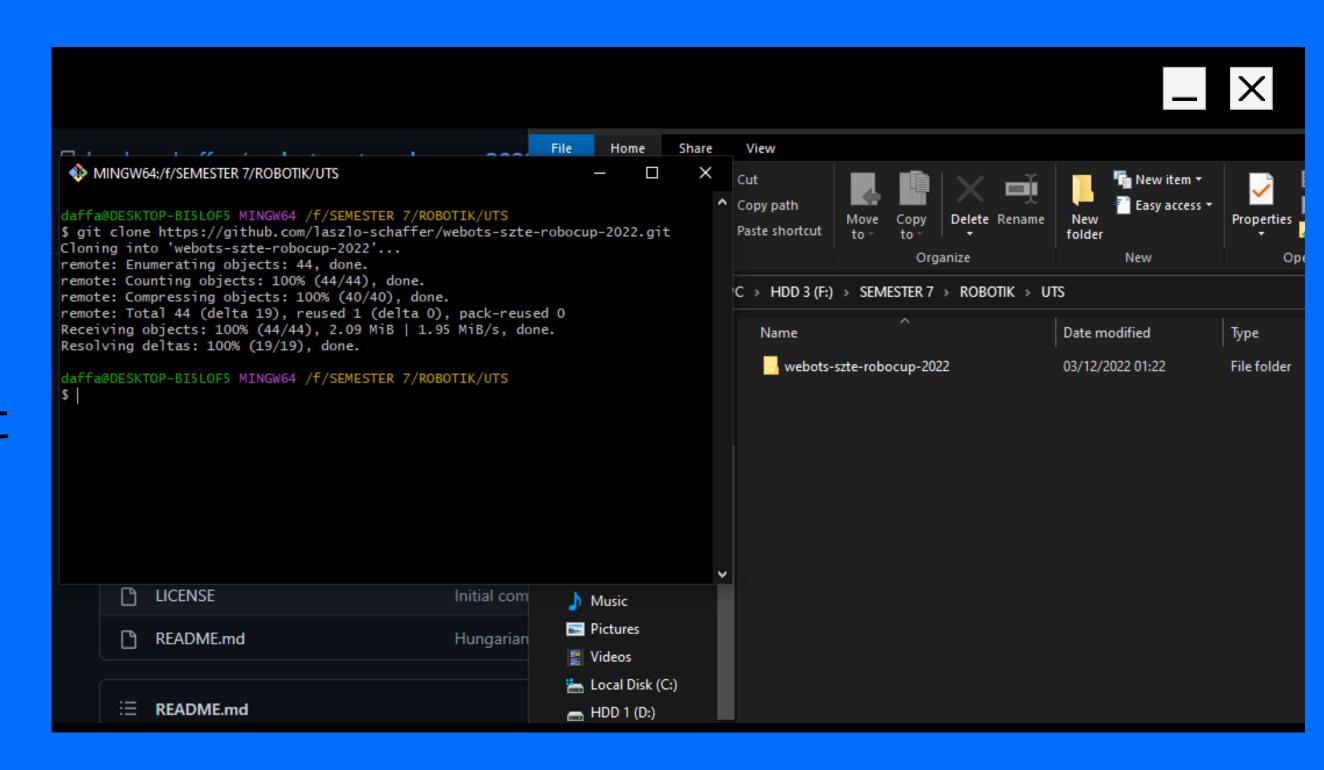
Clone File

webots-szte-robocup-2022

☐ laszlo-schaffer / webots-szte-robocup-2022 Public Wate Security ✓ Insights <> Code → ្រំ main ▼ Add file ▼ Go to file Codespaces (New) Local laszlo-schaffer Hungarian and english desc. ∑ Clone ③ Main files controllers Copy link yang akan SSH GitHub CLI Main files libraries kita clone Main files https://github.com/laszlo-schaffer/webots-szt protos Use Git or checkout with SVN using the web URL. worlds Main files LICENSE Initial commit Open with GitHub Desktop README.md Hungarian and english desc. Open with Visual Studio Download ZIP webots-szte-robocup-2022

Git Clone

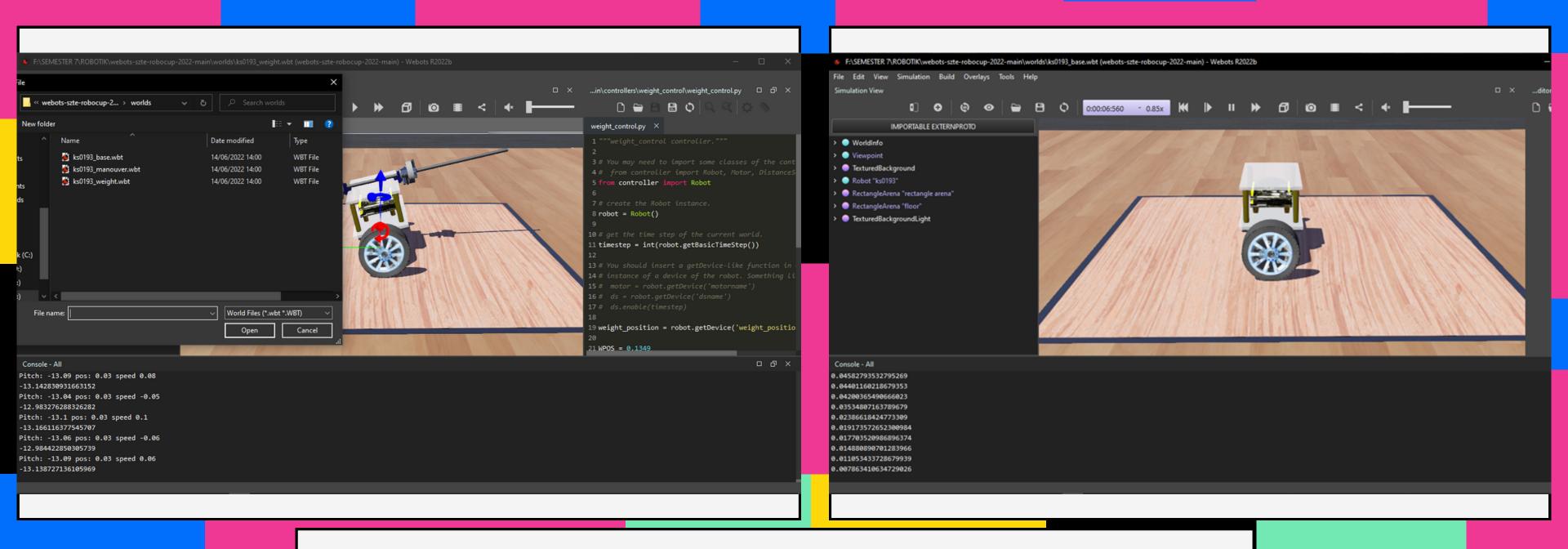
Buka Git Bash lalu Git Clone ke Folder yang sudah kita buat



Install simple_pid for the base environment

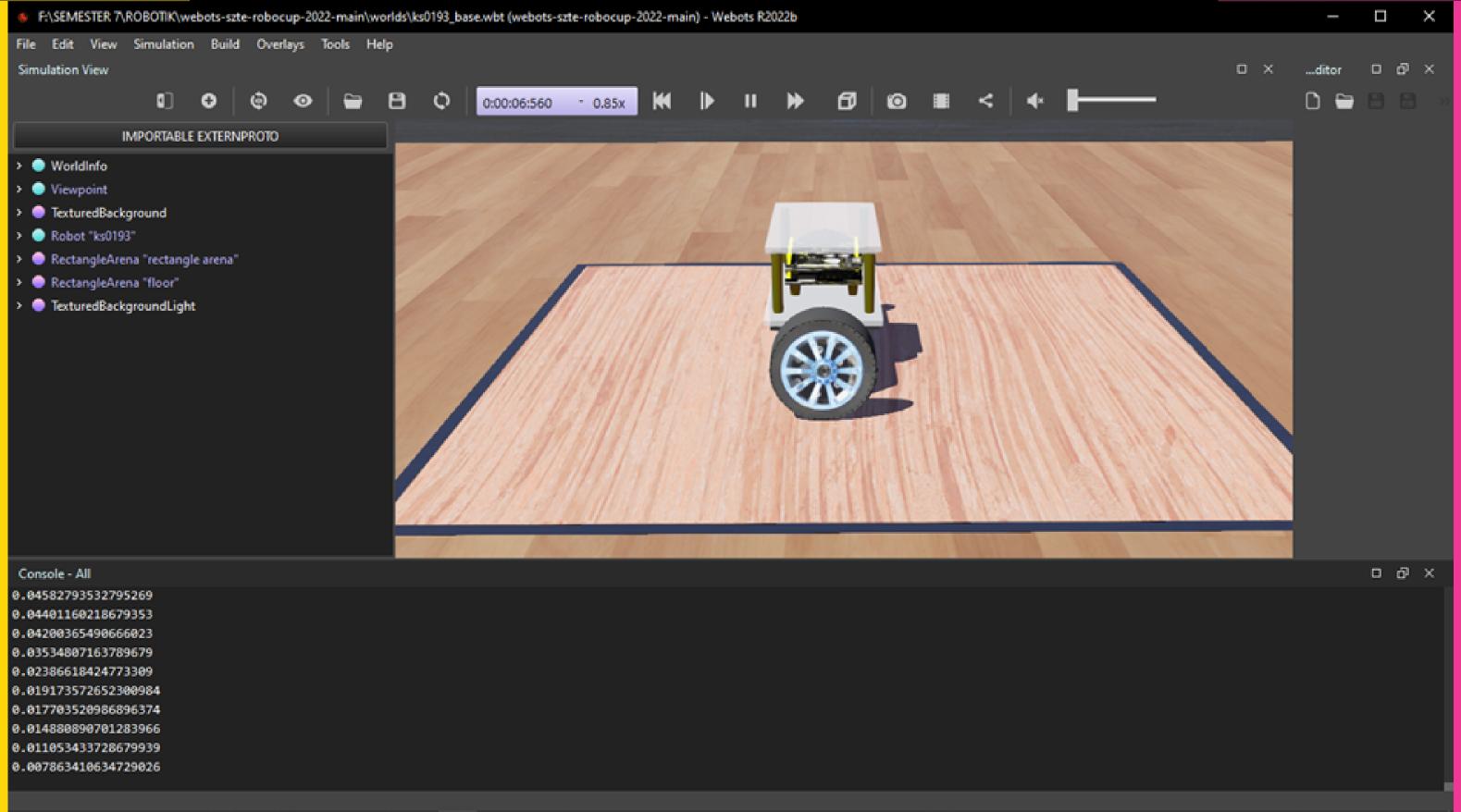
C:\Windows\system32\cmd.exe Microsoft Windows [Version 10.0.19044.2251] (c) Microsoft Corporation. All rights reserved. C:\Users\daffa>pip install simple-pid Requirement already satisfied: simple-pid in c:\python38\lib\site-packages (1.0.1) [notice] A new release of pip available: 22.3 -> 22.3.1 notice] To update, run: python.exe -m pip install --upgrade pip C:\Users\daffa> ketik "pip install simpel-pid" pada CMD

Buka Webots dan open file yang sudah di Git Clone



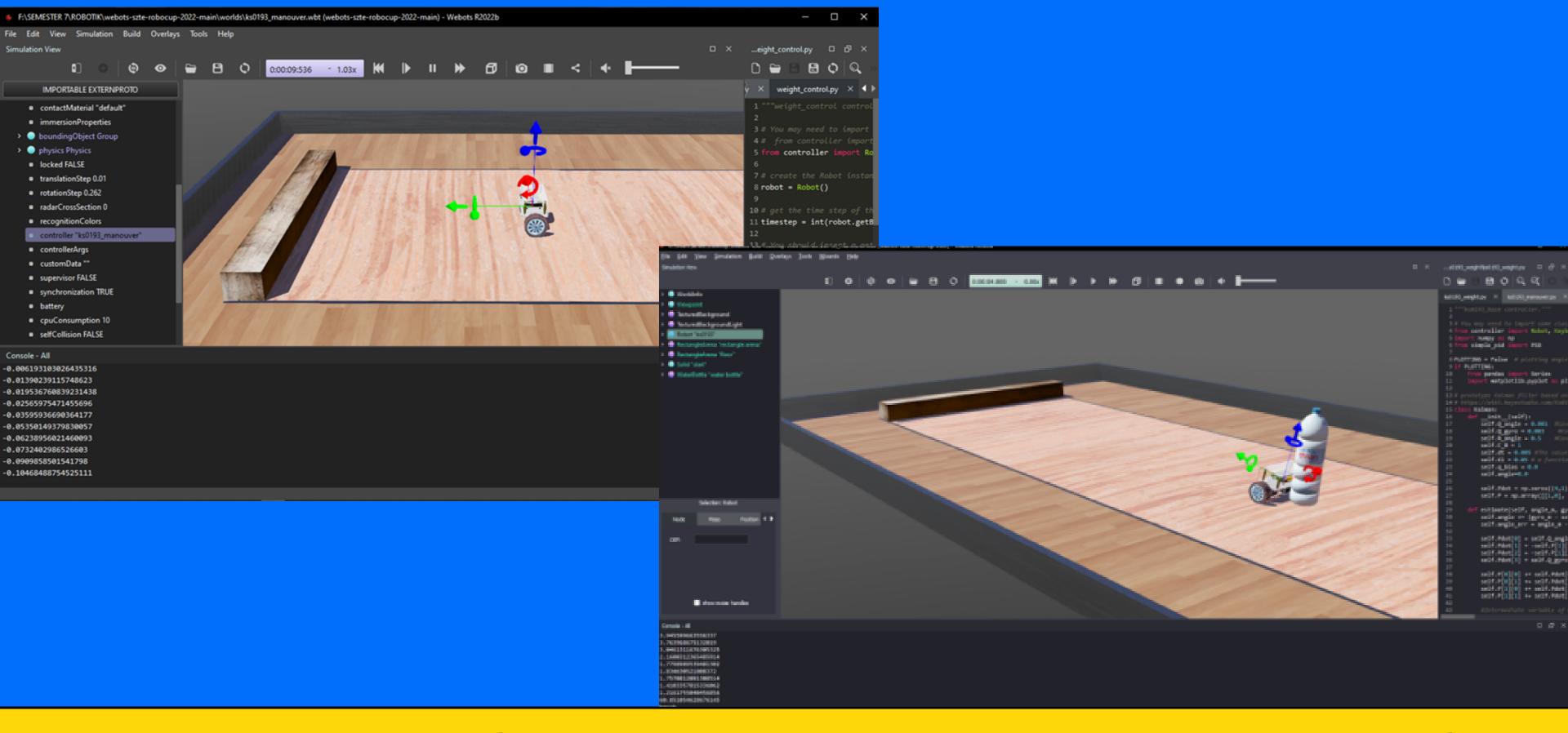
Berikut File World ksO193_base.wbt





Ketika robot tersebut dijalankan, Robot tersebut berdirii seimbang dan tidak terjatuh

Robot ks0193_manouver.wbt40



Robot tersebut akan berjalan dengan imbang dan akan menabrak sebuah objek yaitu botol

Robot ksO193_weight.wbt

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IMPORTABLE EXTERNIPROTO weight_control.py X Worldinfo Viewpoint Robot TexturedBackground TexturedBackgroundLight 5 from controller import Robot Robot "ks0193" tersebut RectangleArena "rectangle arena" 8 robot = Robot() RectangleArena "floor" 10 # get the time step of the current world. akan berdiri 11 timestep = int(robot.getBasicTimeStep()) 13 # You should insert a getDevice-like function in order to get the 14 # instance of a device of the robot. Something like: seimbang 17 # ds.enable(timestep) dan tidak 19 weight_position = robot.getDevice('weight_position') 21 WPOS = 0.1349terjatuh Console - All Pitch: -13.92 pos: 0.03 speed 0.07 -13.495742763294631 Pitch: -13.84 pos: 0.03 speed -0.14

F:\SEMESTER 7\ROBOTIK\webots-szte-robocup-2022-main\worlds\ks0193_weight.wbt (webots-szte-robocup-2022-main) - Webots R2022b

File Edit View Simulation Build Overlays Tools Help

Simulation View

-13.42412078770732

-13.238170296756195

-13.058855936513325

-12.839073345147794

Pitch: -13.62 pos: 0.03 speed -0.37

Pitch: -13.33 pos: 0.03 speed -0.52

Pitch: -12.98 pos: 0.03 speed -0.61

Repository

G G 🔛 M 👳 By * github.com/new 1103194083 Registr... 📵 odo 🌀 YouTube 🗤 BBRI 4080 🛦 +0.99... 🌇 Login QRIS InterAct... 🚱 https://memberne... 🧕 Dicoding Indonesia 💀 Test Coding 🥮 Quizizz Rock Search or jump to... Pull requests Issues Codespaces Marketplace Explore Create a new repository A repository contains all project files, including the revision history. Already have a project repository elsewhere? Import a repository. Owner * Repository name * Membuat Repository 🕕 daffajar 🕶 'UTS-ROBOTIK-TEL-U untuk menyimpan Great repository names Your new repository will be created as -UTS-ROBOTIK-TEL-U. | bug-free-tribble? Description (optional) project yang sudah kita kerjakan Anyone on the internet can see this repository. You choose who can commit. You choose who can see and commit to this repository Initialize this repository with: Skip this step if you're importing an existing repository. Add a README file This is where you can write a long description for your project. Learn more. Add .gitignore

Repository

