UTS

ROBOT AUTONOMY I

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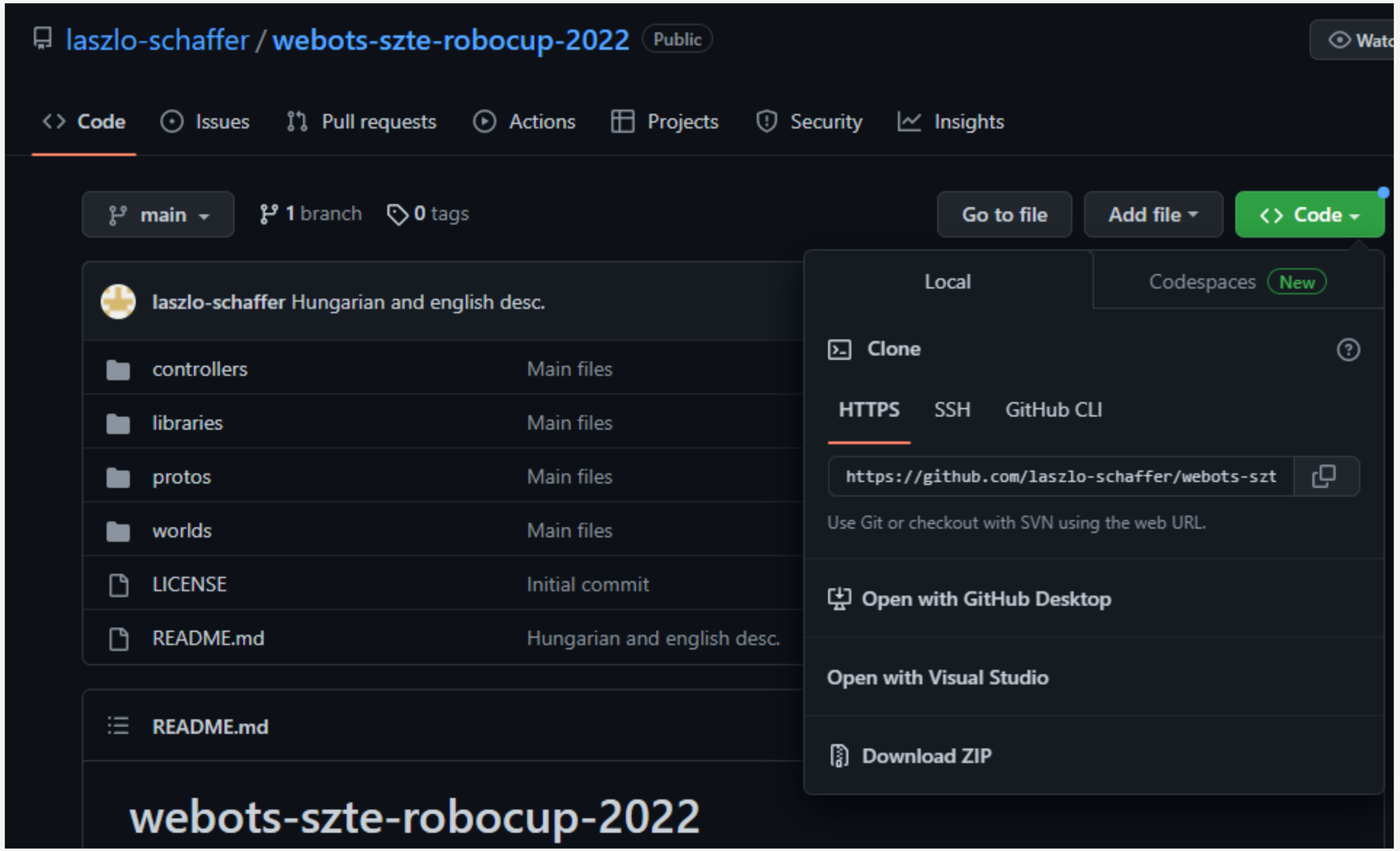
Clone File

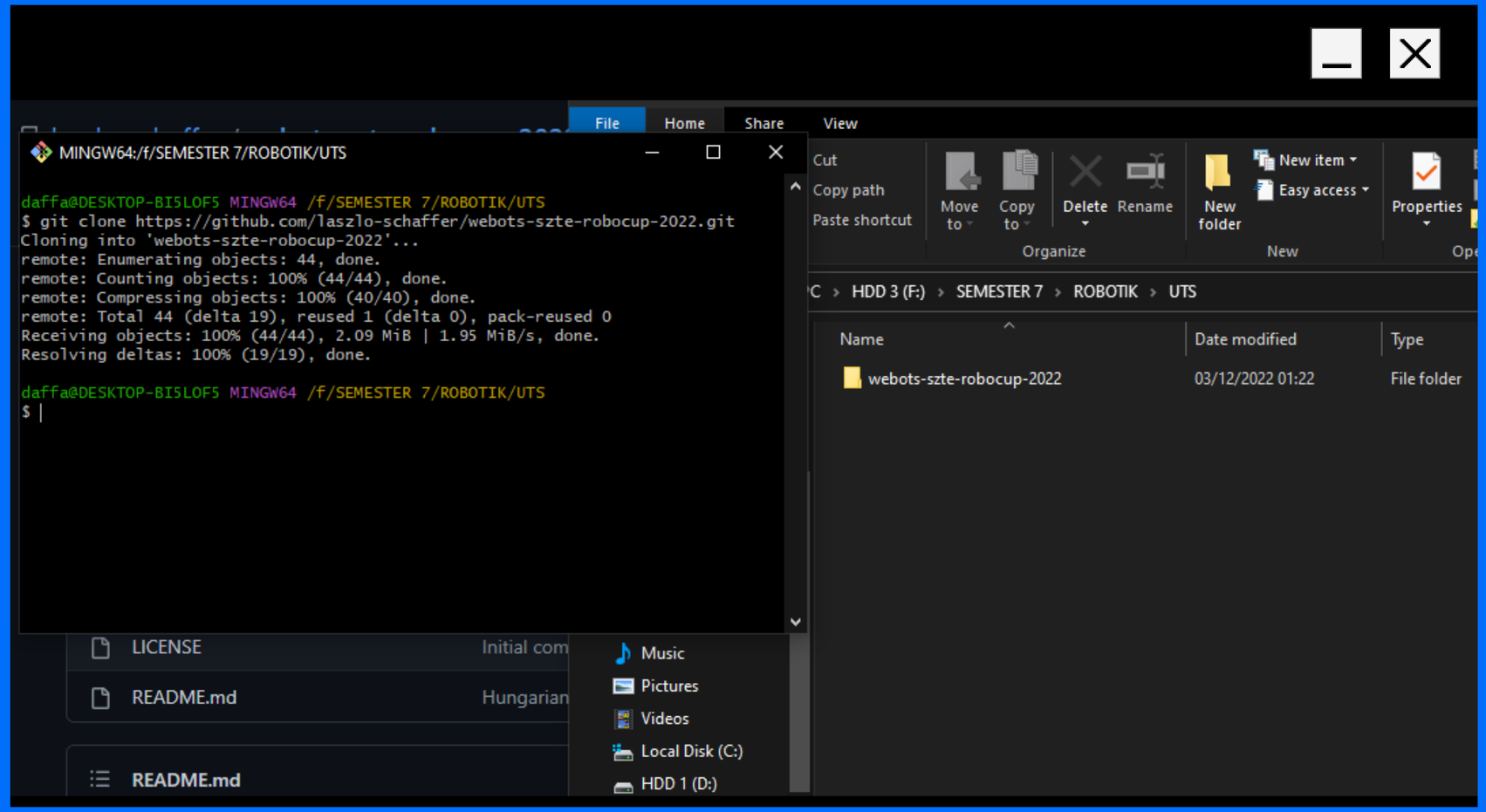
webots-szte-robocup-2022

Copy link yang akan kita clone



Git Clone

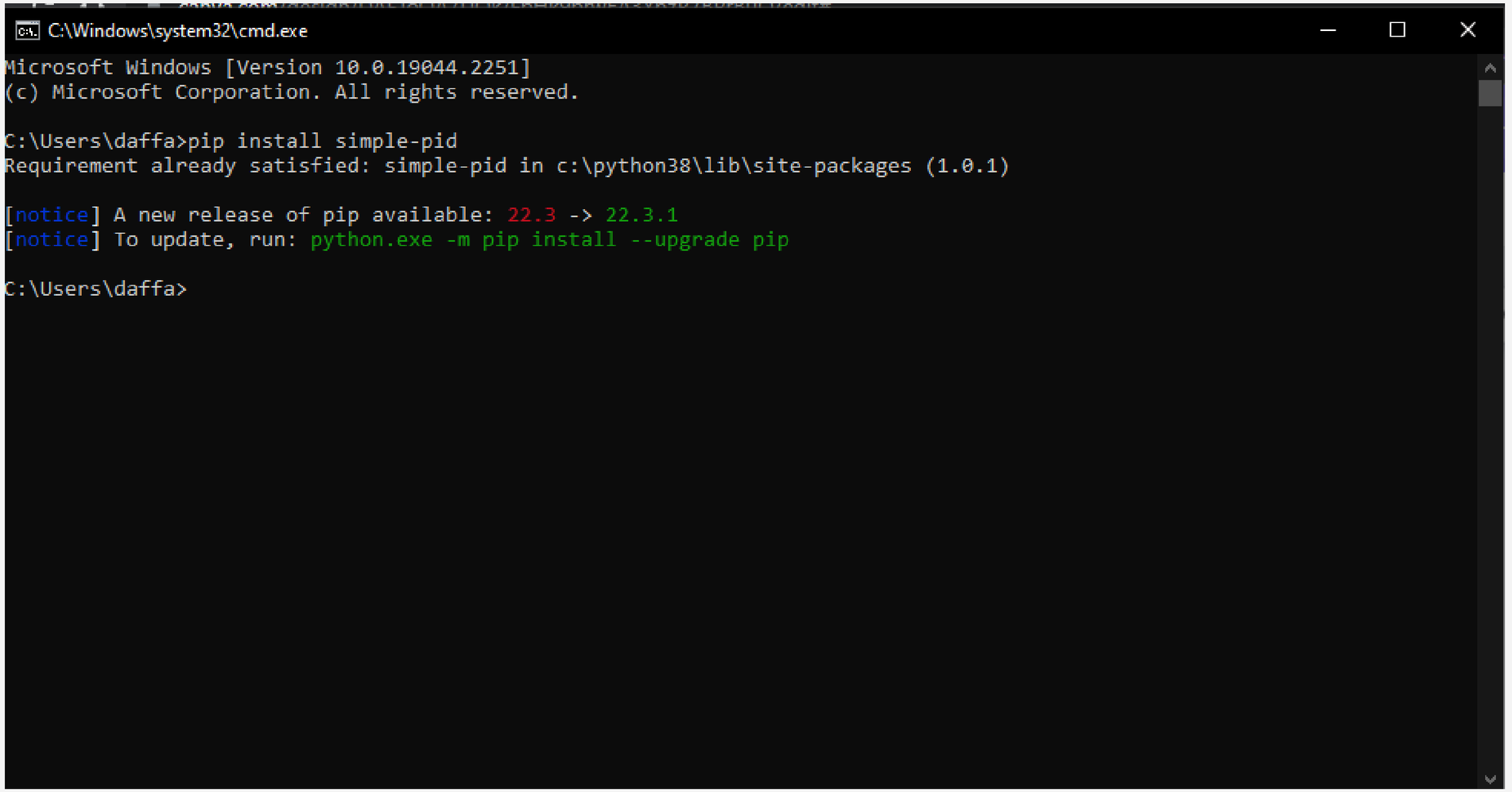
Buka Git Bash lalu Git Clone ke Folder yang sudah kita buat



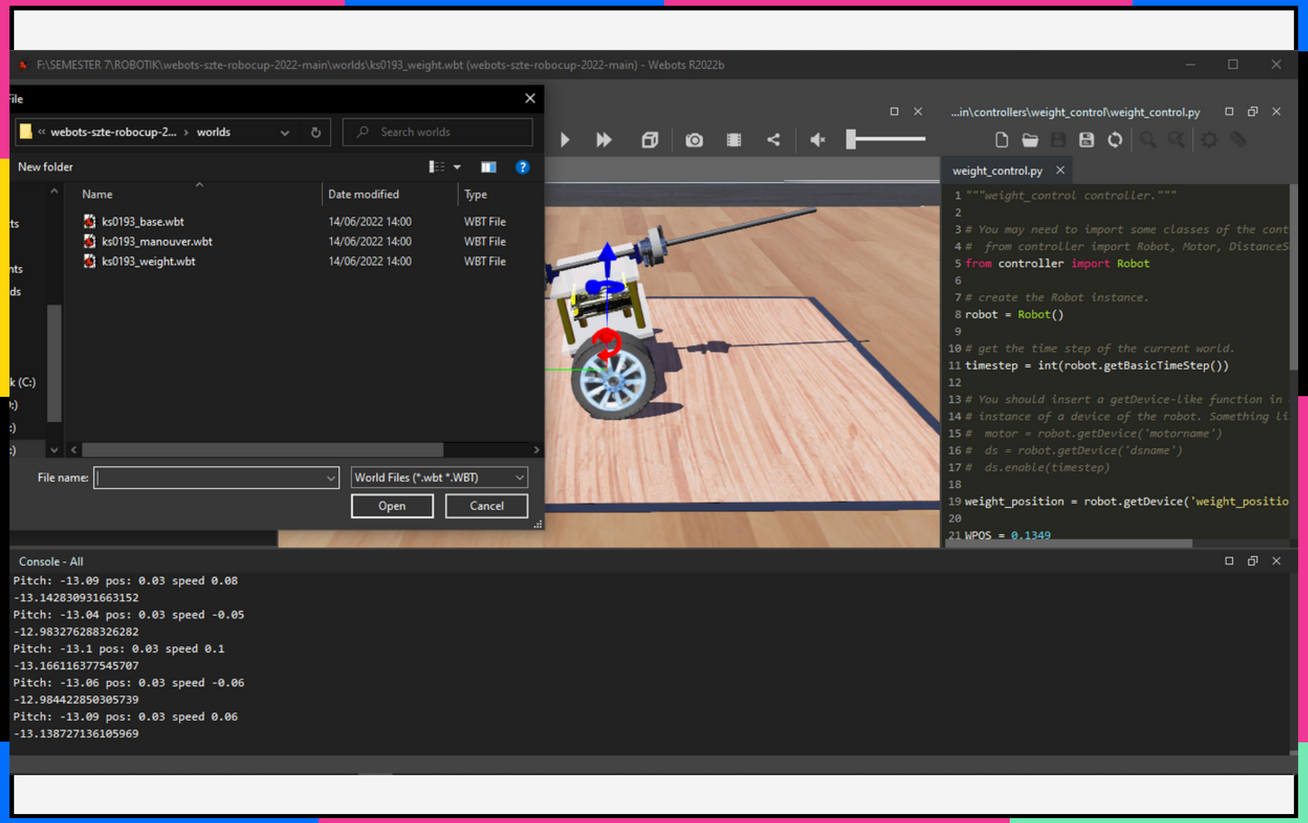
Install simple_pid

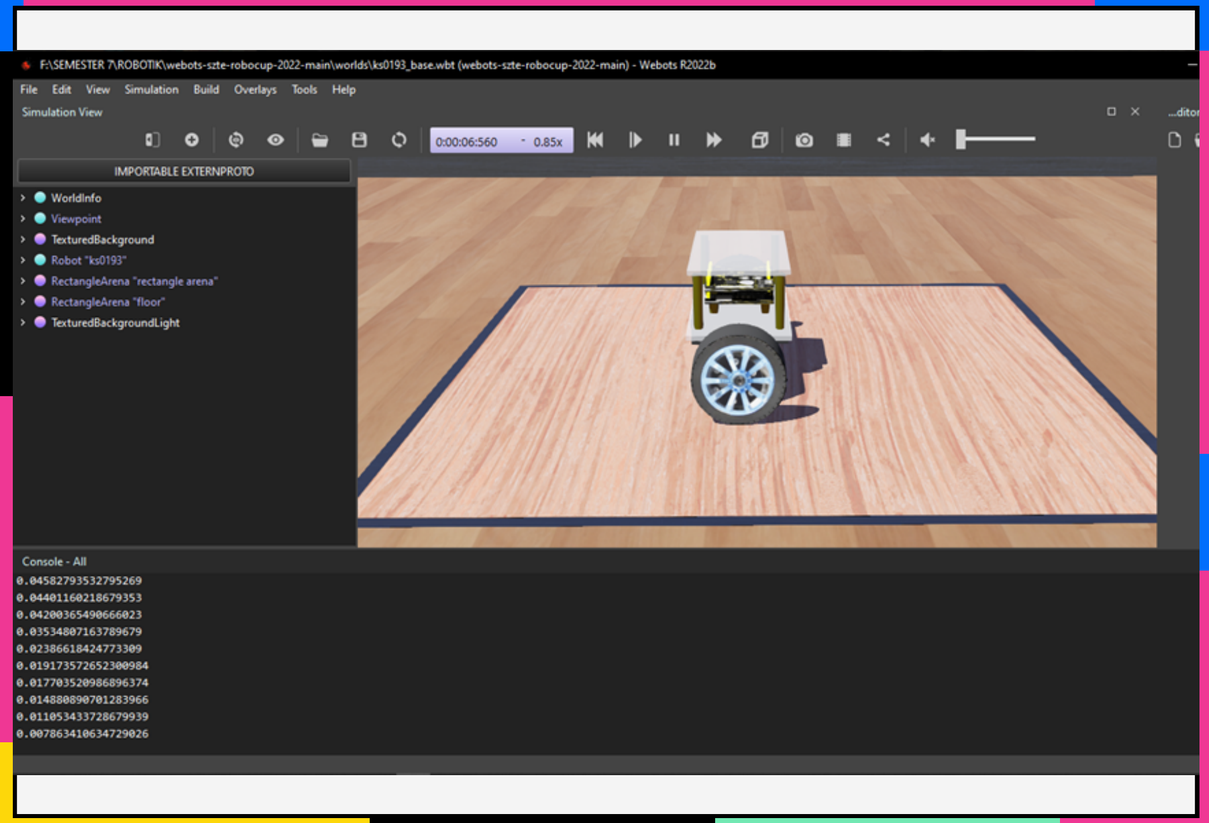
for the base environment

ketik "pip install simpel-pid" pada CMD



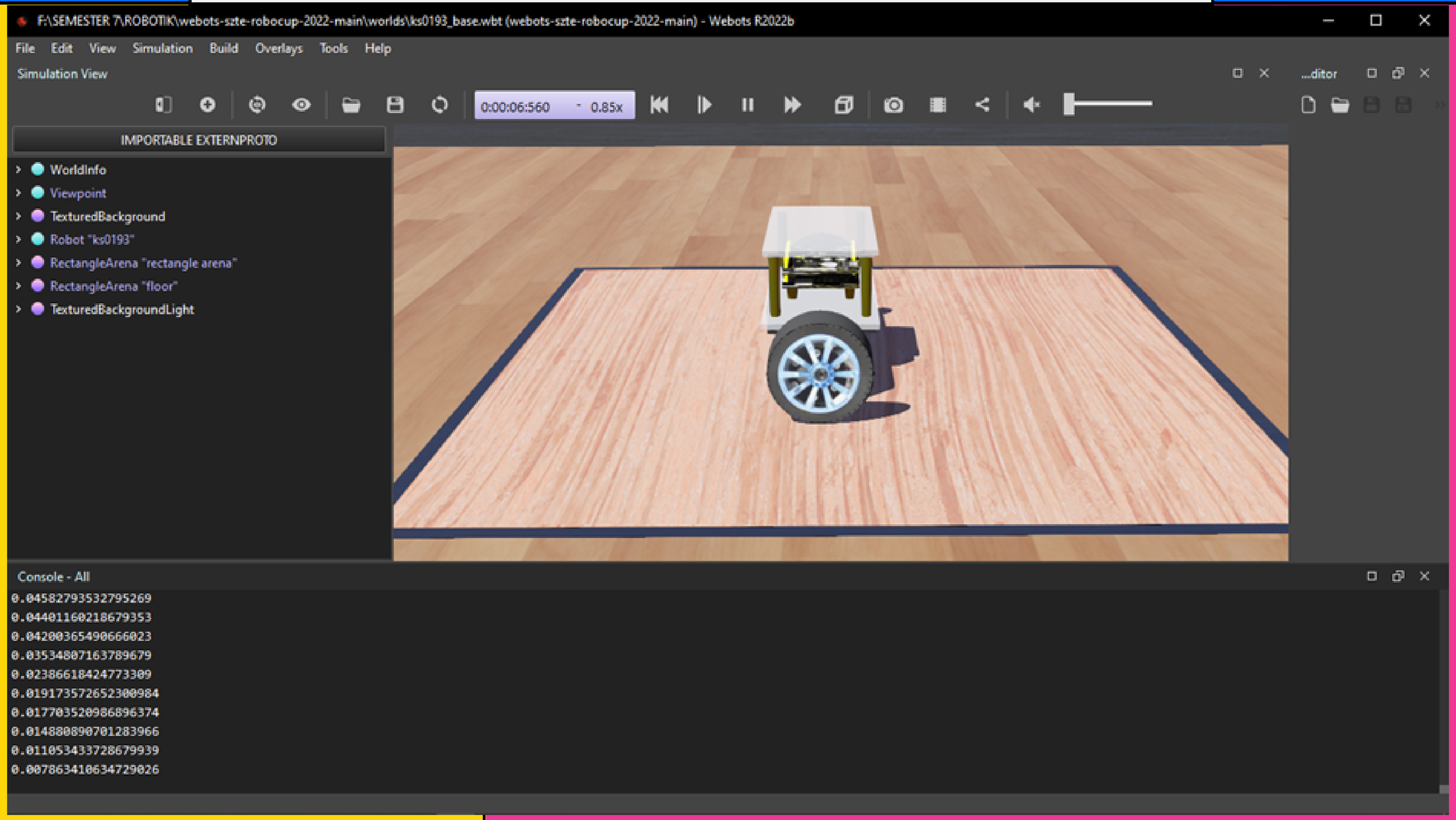
Buka Webots dan open file yang sudah di Git Clone





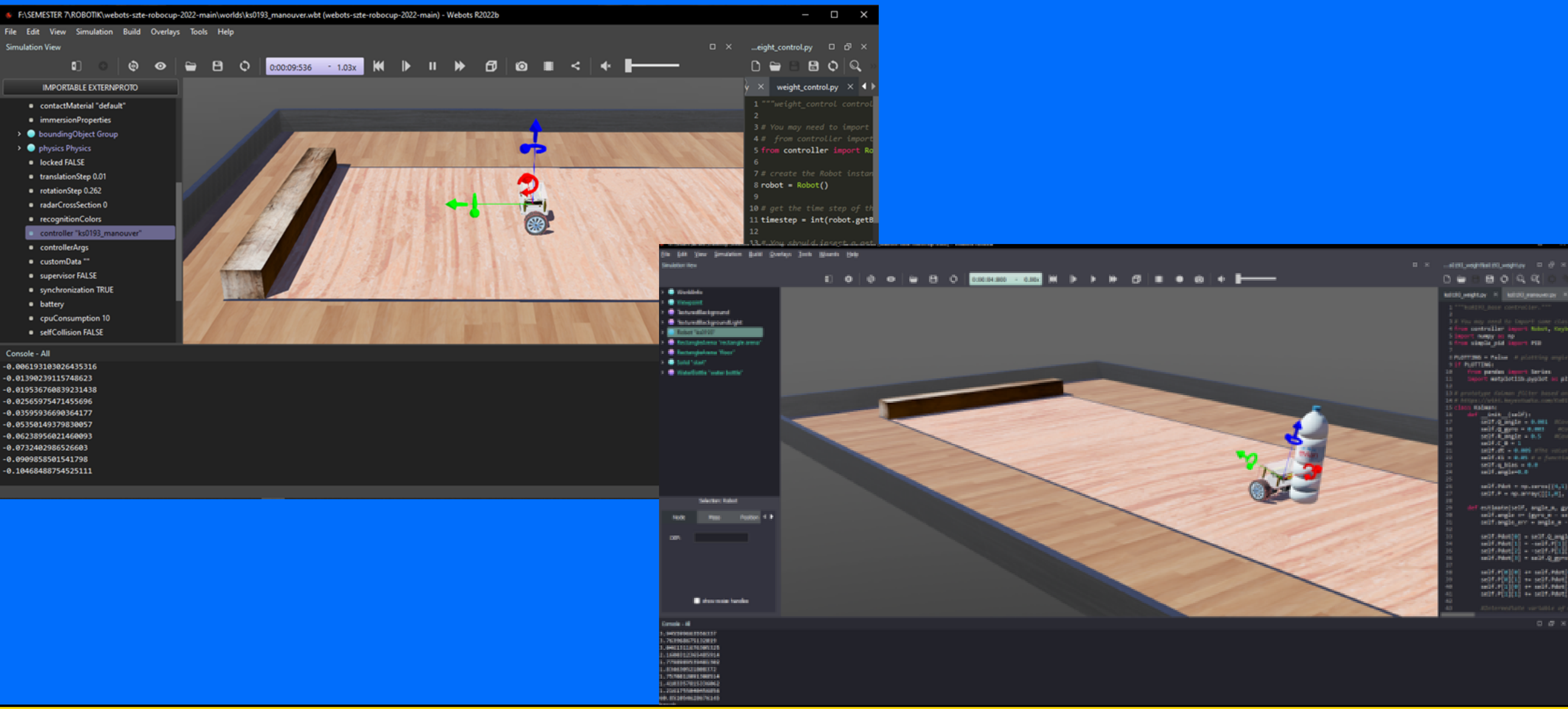
Berikut File World ks0193_base.wbt

Berikut File World ksO193_base.wbt



Ketika robot tersebut dijalankan, Robot tersebut berdirii seimbang dan tidak terjatuh

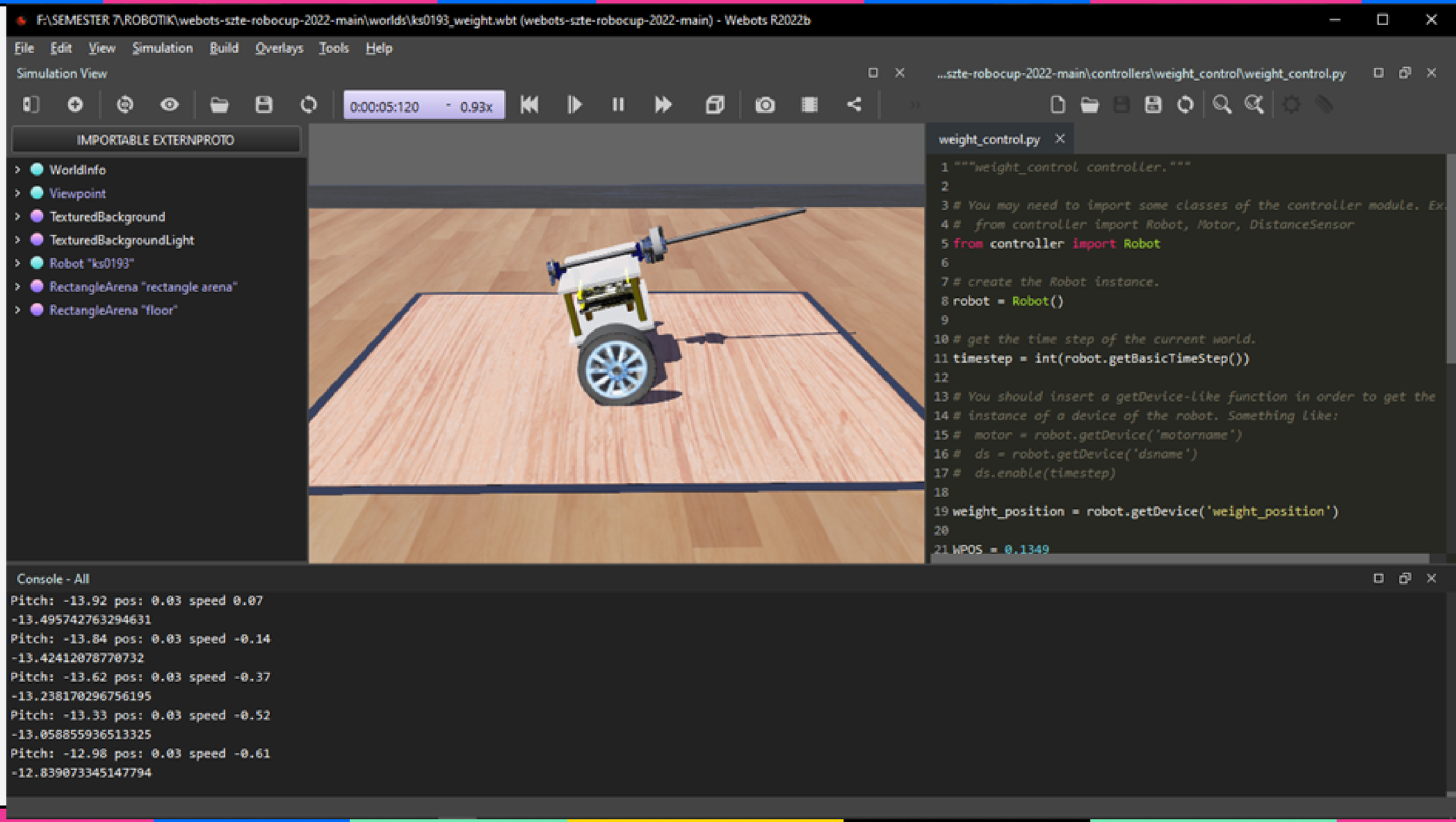
Robot ks0193_manouver.wbt40



Robot tersebut akan berjalan dengan imbang dan akan menabrak sebuah objek yaitu botol

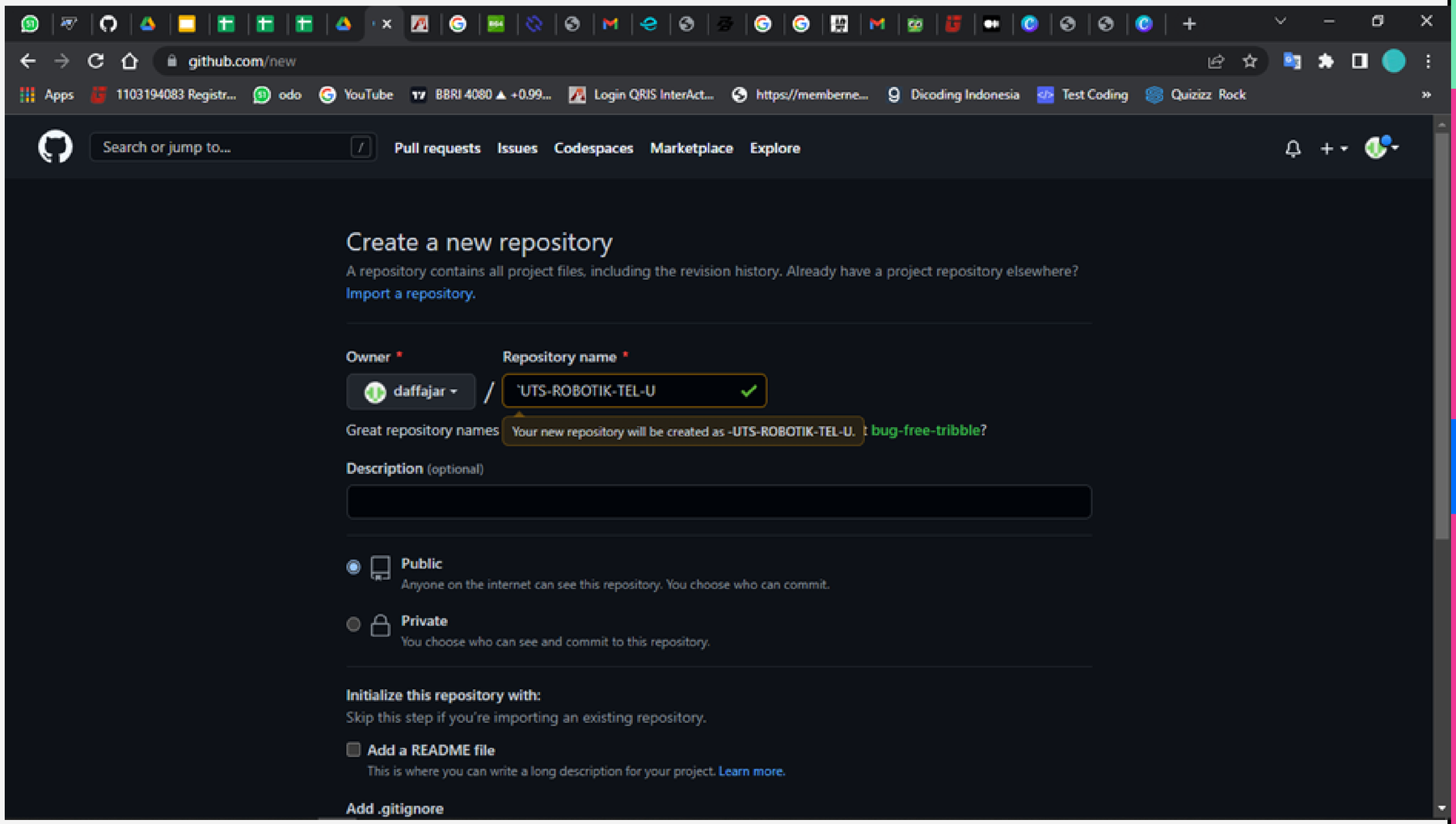
Robot ks0193_weight.wbt

Robot tersebut akan berdiri seimbang dan tidak terjatuh



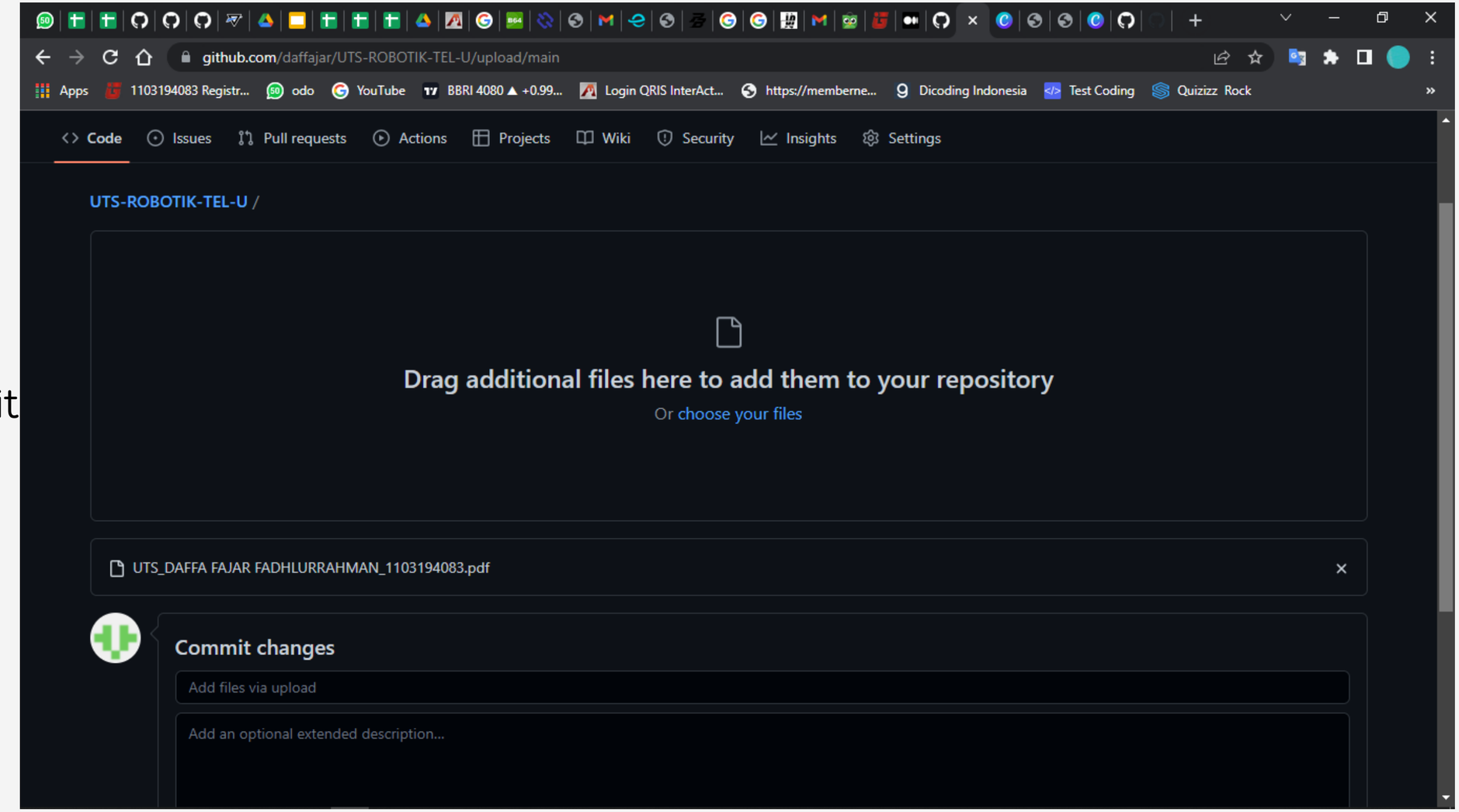
Repository

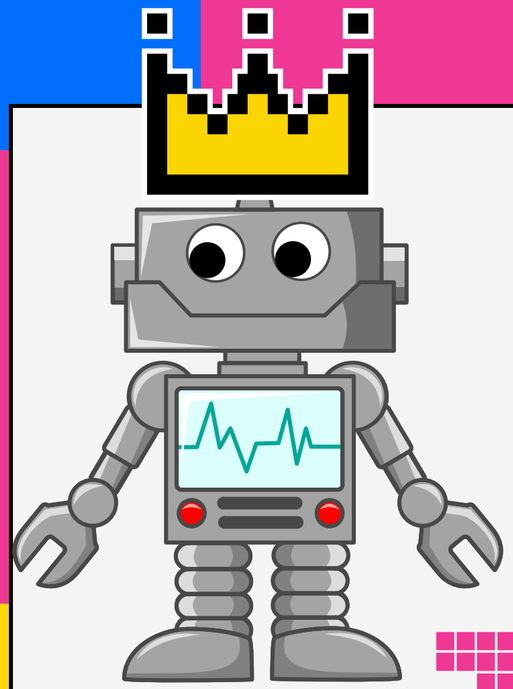
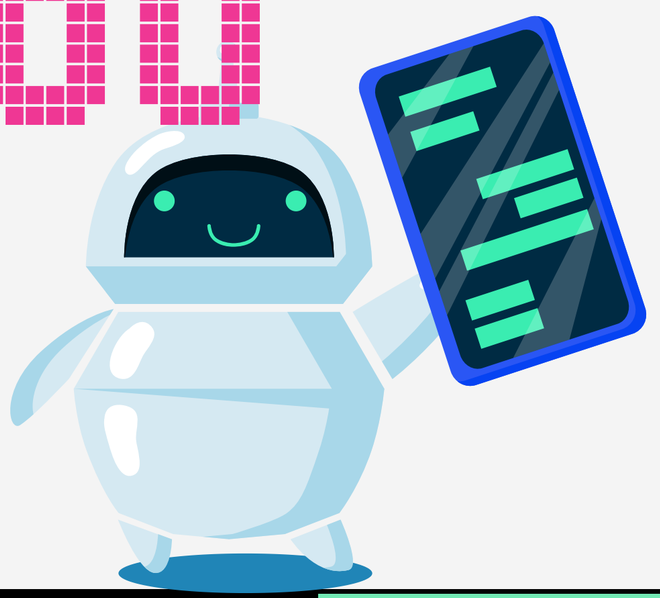
Membuat Repository untuk menyimpan project yang sudah kita kerjakan



Repository

Masukan Project tersebut lalu commit





THANK YOU