

# Chapters 7 & 8

## Memory Management

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# Part 0: Introduction

# Review: Multiprogramming

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Multiprogramming: switching Between multiple ready tasks

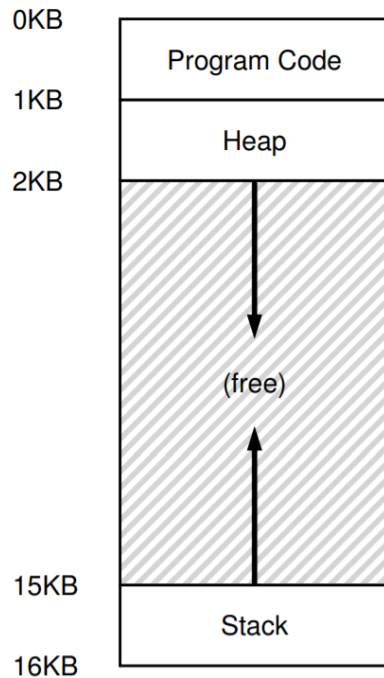
We've discussed:

- Concurrency
- CPU scheduling

And now:

- Memory Management

# Review: Memory Model of a Process



Memory:

1. addresses start at 0
2. both linear and adjacent
3. memory is infinite

The Crux of the Problem: How does the OS provide a private, potentially large address space on top of a single, unified, physical memory?

RAM

# Requirements

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1. **Transparent**: process does not know it is there  
    ↳ memory management
2. **Process Isolation / Protection**: independent processes can not read or write to each others memory  
    ↳ getting both is word
3. **Allow for sharing, when wanted**
4. **Efficiency**

# A First Attempt

Idea: only the OS & the currently running process are in RAM <sup>0KB</sup>

→ all other processes are swapped out to disk <sup>64KB</sup>

multiple processes are in RAM at the same time

Transparent? *meh.*

Protection? ✓

Efficient?

*X - bc disk is really slow  
context switch  
a mil cycles  
will be like*

Sharing? X

Operating System  
(code, data, etc.)

Current Program  
(code, data, etc.)

max

# The Road Ahead

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1. Partitioning

2. segmentation

★  
3. Paging

# Aside: Every Address you see is Virtual

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You've likely printed the address of a variable before...

...this is **never** the *true physical address* in RAM...

=> **virtual address** : address into  
the abstraction

```
int main(int argc, char *argv[]) {  
    printf("location of code : %p\n", main);  
    printf("location of heap : %p\n", malloc(100e6));  
    int x = 3;  
    printf("location of stack: %p\n", &x);  
    return x;  
}
```



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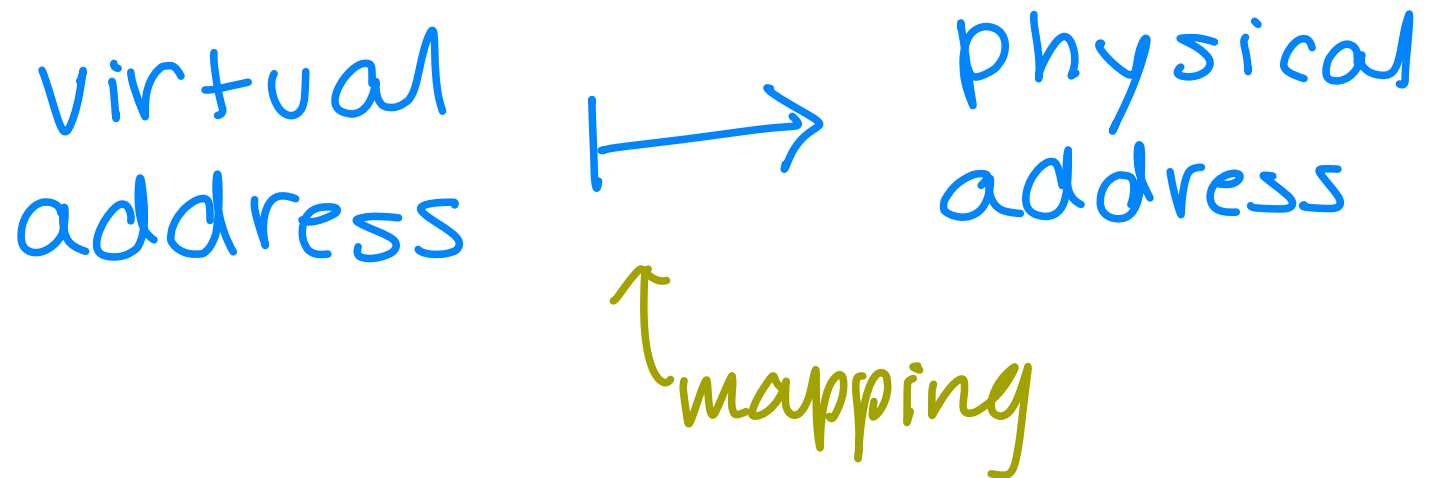
# Part 1: The Basics & Partitioning

# Terms

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Address Space: memory locations that can be accessed by the process

Address Translation:



# Simple Example

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$$X = X + 3$$

Becomes:

128: <sup>lw</sup> movl 0x0(<sup>4</sup>%ebx), %eax ;load 0+ebx into eax

132: <sup>addi</sup> addl \$0x03, %eax ;add 3 to eax register

135: <sup>sw</sup> movl %eax, 0x0(<sup>5</sup>%ebx) ;store eax back to mem

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# Memory Partitioning

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## Basic setup:

1. Divide RAM into "chunks"/partitions
  - static / fixed size
  - dynamic / variable sized
2. load a process into a big enough partition
  - one process per partition
  - one partition per process

# Implementing

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Two registers:

1. **Base Register** → stores start addr of the partition
2. **Bound / limit** → stores the end addr

Address translation:

$$\text{physical address} = \text{virtual address} + \text{Base Register}$$

→ eia proc gets an address space that starts at 0

# Translation Example

A process:

- An address space of 4 KB

- Loaded at physical address 16 KB

$2^{10}$

4096

size

Virtual Address	Physical Address
0	16 KB
1 KB	17 KB
3000	$16 \cdot 1024 + 3000$
4400	FAULT

19384

out of  
Bound

# Fixed vs Dynamic

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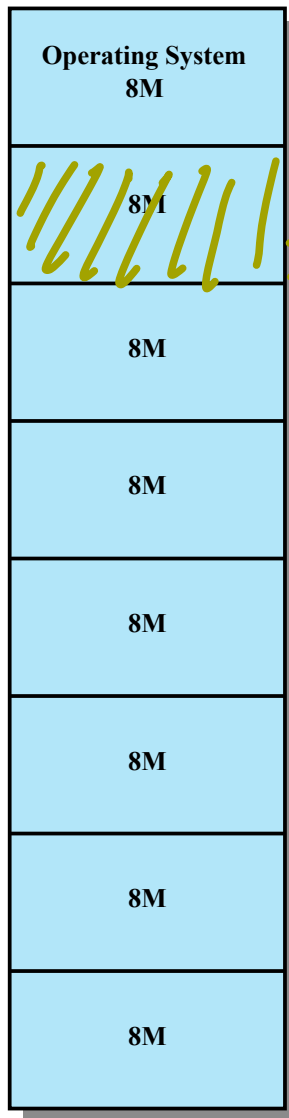
## Fixed Partitioning:

- Partitions cannot change in size or #
- May be of the same or diff size

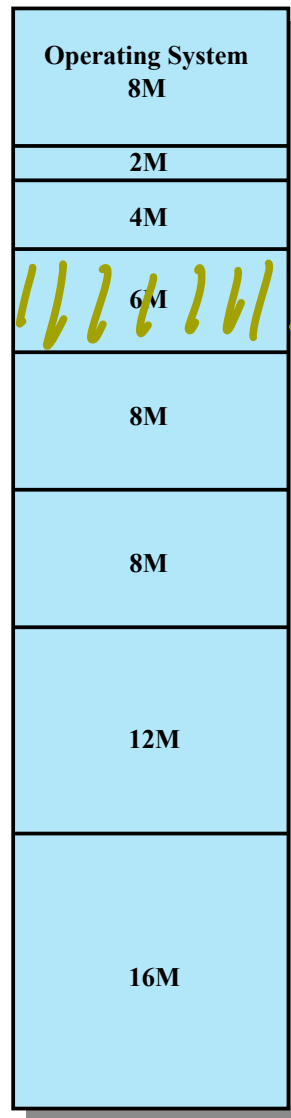
## Dynamic Partitioning:

- Variable size and # of partitions
- Partitions are made on allocation requests

# Example: Fixed Partitioning



(a) Equal-size partitions



(b) Unequal-size partitions

Allocate a 5MB process:

a. Into (a)  
→ 3 MB wasted due to over allocation

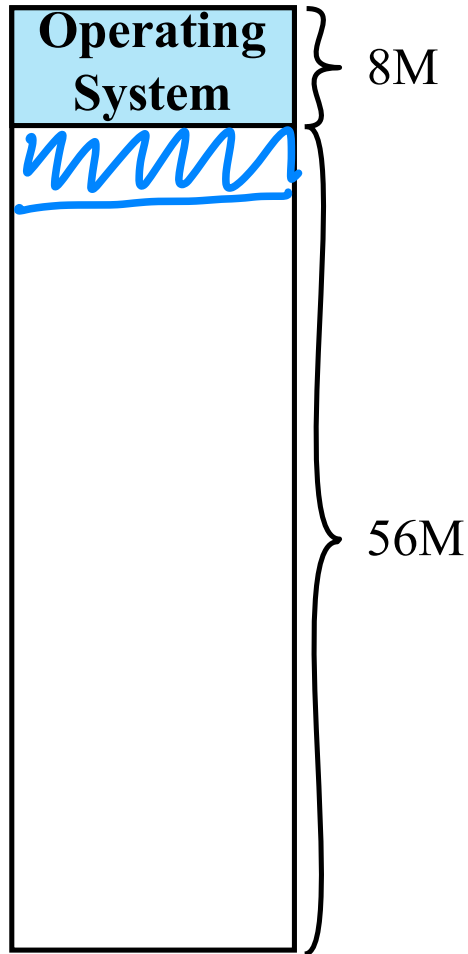
b. Into (b)  
→ 1 MB wasted

Internal fragmentation



# Example: Dynamic Partitioning

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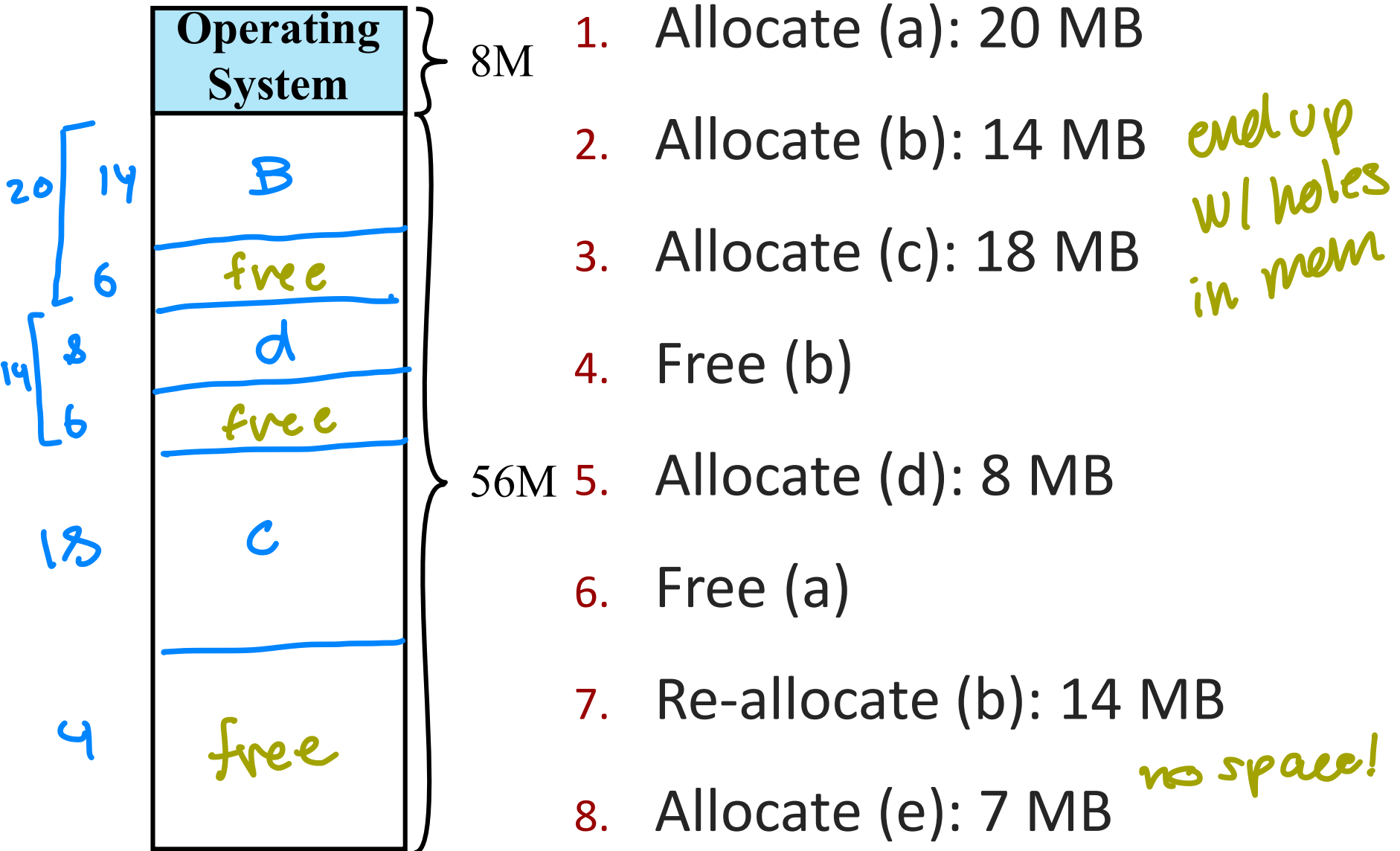


(a)

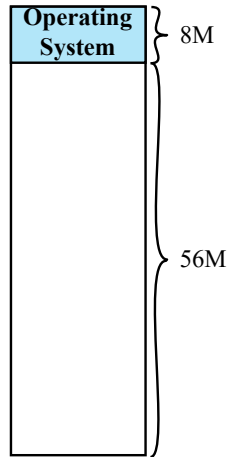
Allocate a 5MB process.

→ the exact size needed  
→ no internal fragmentation

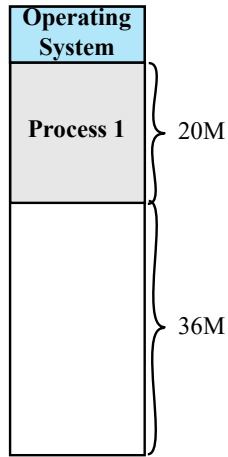
# Why Dynamic Partitioning Isn't So Great



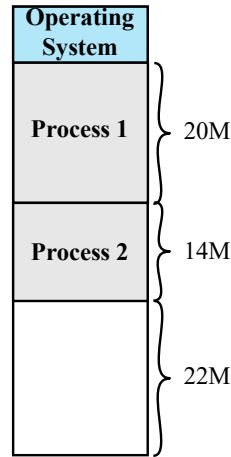
# Computer Graphics Version



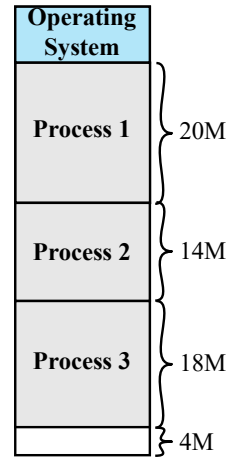
(a)



(b)



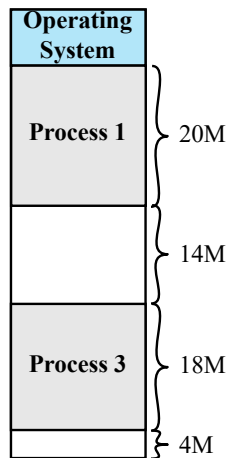
(c)



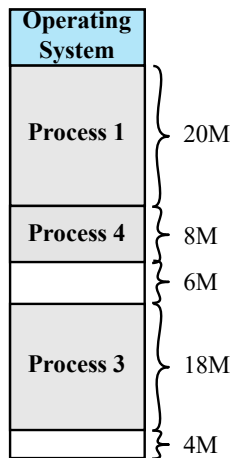
(d)

problem:

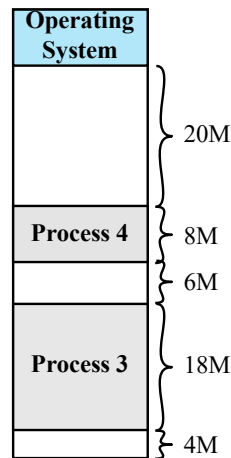
External Fragmentation



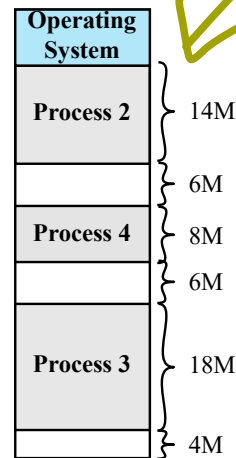
(e)



(f)



(g)



(h)

Allocate (e): 7 MB?

=> Cannot

# More Terms

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Placement Algorithm: where in RAM to allocate a request

Internal Fragmentation: memory w/in a partition is wasted

External Fragmentation: memory between partitions is wasted

solutions:

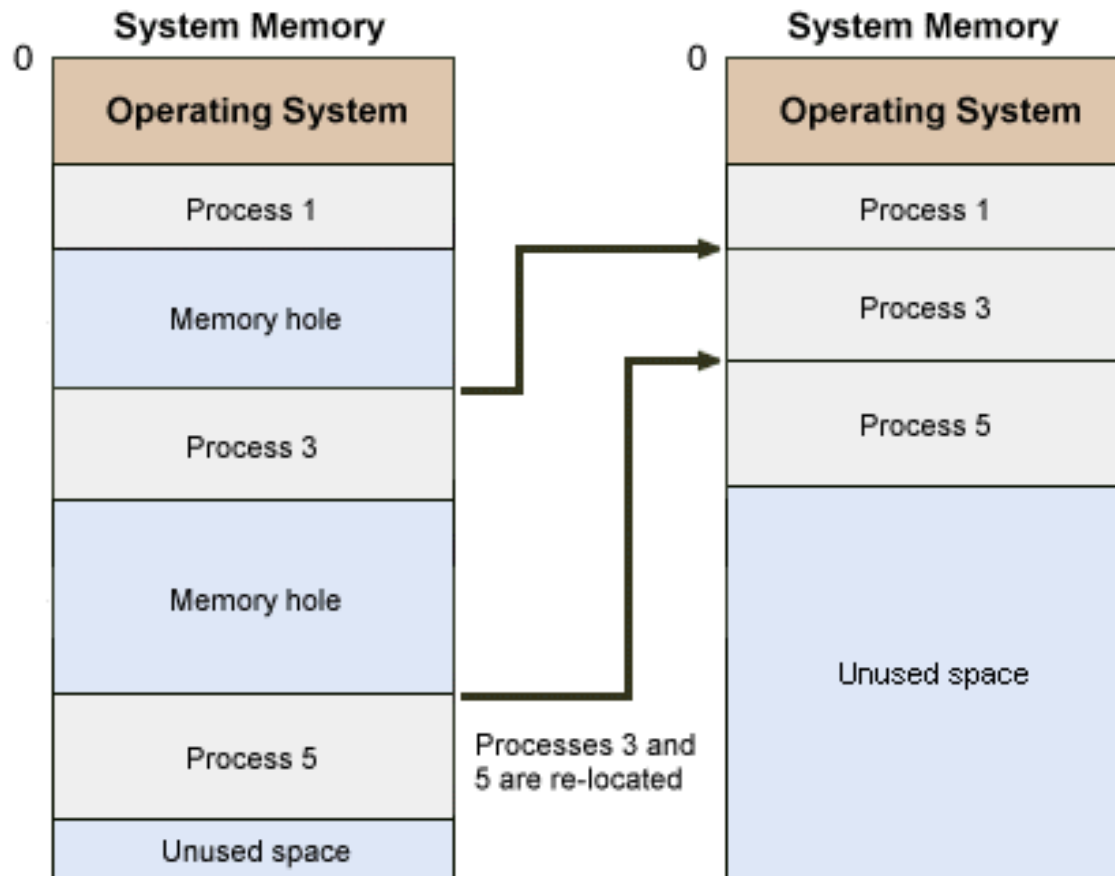
a) compaction

b) use a different placement algorithm

# Compaction Example

Compaction: move partitions in physical mem to make them contiguous

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← slow  
~only 10,000s  
of cycles

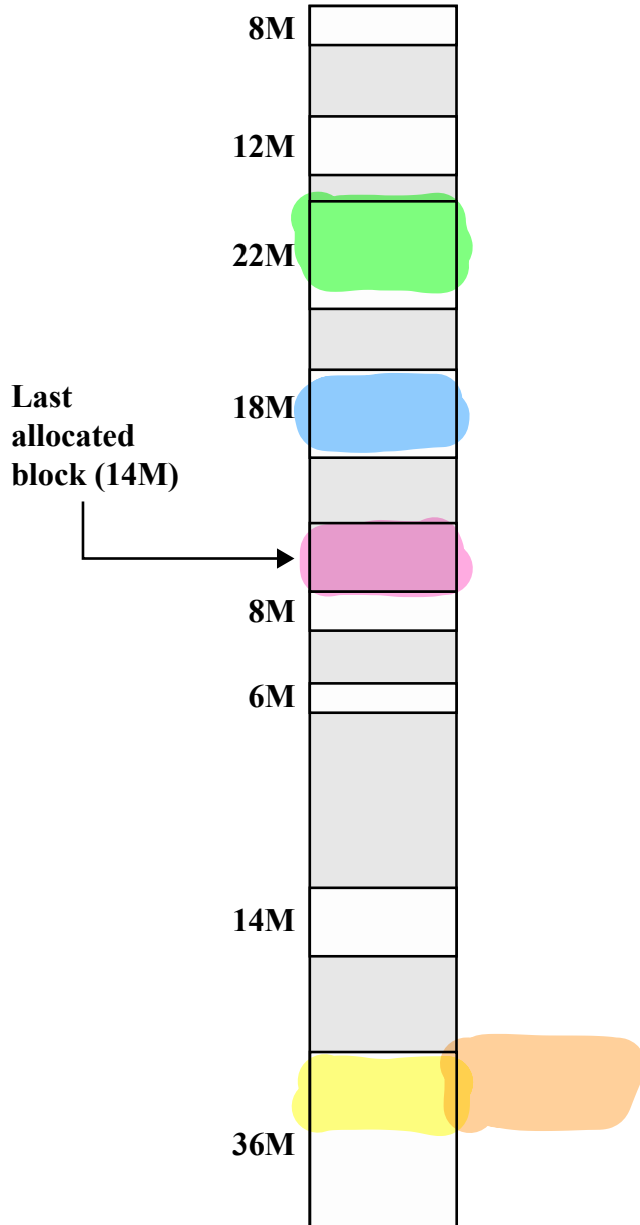
# Basic Placement Schemes

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1. **Best fit**: choose the block closest in size
2. **Worst fit**: choose largest block
3. **First fit**: chooses first block that is big enough
4. **Next fit**: choose the next big enough block



# Placement Example



Allocate a 16M using:

a) Best Fit

b) Worst Fit

c) First Fit

d) Next Fit

*does the same thing*