

# CS 615 – Deep Learning

Learning

Slides adapted from material created by E. Alpaydin Prof. Mordohai, Prof. Greenstadt, Pattern Classification (2<sup>nd</sup> Ed.), Pattern Recognition and Machine Learning



# Objectives

- Updating weights
- Gradient descent



### Updating Weights

- Ok fine, we can do forward-backward propagation.
- But how does this help us learn the weights to minimize our objective function?
- When we hit a layer that has weights (for now, that's just the fully-connected layer) we can use the incoming (backcoming?) gradient to update the weights!
- For example, our fully-connected layers have weights, W, and biases, b
- So, we'll want to compute  $\frac{\partial J}{\partial W}$  and  $\frac{\partial J}{\partial b}$  and move/update our weights by going some amount in the direction of the gradient.



- Imagine that our FC layer has a backpropagated gradient  $\frac{\partial J}{\partial h} \in \mathbb{R}^{1 \times K}$  coming into it.
- We then need  $\frac{\partial H}{\partial W}$  and  $\frac{\partial H}{\partial b}$  in order to compute  $\frac{\partial J}{\partial W}$  and  $\frac{\partial J}{\partial b}$
- Let's start with  $\frac{\partial J}{\partial b}$
- $h \in \mathbb{R}^{1 \times K}$  and  $b \in \mathbb{R}^{1 \times K}$ , so what is the size of  $\frac{\partial h}{\partial h}$ ?
  - A  $K \times K$  Jacobian matrix
- What are the elements of  $\frac{\partial h}{\partial h}$ ?
  - Recall that h = xW + b
  - Identity matrix!
- And if we have multiple observations, then  $\frac{\partial H}{\partial b}$  is a  $N \times (K \times K)$  tensor of identity matrices.



# Gradient: Fully Connected Layer (bias)

- So what is  $\frac{\partial J}{\partial b}$  then?
- For a single observation it will be:

$$\frac{\partial J}{\partial b} = \frac{\partial J}{\partial h} \cdot \frac{\partial h}{\partial b} = \frac{\partial J}{\partial h}$$

• If there's multiple observations?

$$\frac{\partial J}{\partial H} \otimes \frac{\partial H}{\partial b} \in \mathbb{R}^{N \times (1 \times K)}$$

• So to get  $\frac{\partial J}{\partial h}$  we just take the average of the N elements (vectors) of this tensor.



# Gradient: Fully Connected Layer (weights)

- How about  $\frac{\partial J}{\partial W}$ ?
- For the single observation case we need  $\frac{\partial h}{\partial W}$ .
- So what is the derivative of a vector with respect to a matrix?
- Since  $h \in \mathbb{R}^{1 \times K}$  and  $W \in \mathbb{R}^{D \times K}$  intuitively this should be  $\in \mathbb{R}^{K \times (D \times K)}$ 
  - And for a particular output  $h_k \in \mathbb{R}^{D \times K}$
- So what are the elements of  $\frac{\partial h_k}{\partial W}$ ?



$$h = xW + b$$

- Let's start with, what is  $\frac{\partial h_k}{\partial W_{ij}}$ ?
  - If k == j

$$\frac{\partial h_k}{\partial W_{ij}} = x_i$$

Otherwise

$$\frac{\partial h_k}{\partial W_{ij}} = 0$$

- How can we interpret this?
- Let's look at a somewhat simple example...



h = xW + b

- Let's look at somewhat simple example...
- Let  $W \in \mathbb{R}^{3 \times 2}$

$$W = \begin{bmatrix} W_{11} & W_{12} \\ W_{21} & W_{22} \\ W_{31} & W_{32} \end{bmatrix}, b = [b_1, b_2]$$

- What is  $\frac{\partial h_1}{\partial W}$ ?
  - $h_1 = x_1 W_{11} + x_2 W_{21} + x_3 W_{31} + b_1$

• 
$$\frac{\partial h_1}{\partial W_{11}} = x_1, \frac{\partial h_1}{\partial W_{12}} = 0, \frac{\partial h_1}{\partial W_{21}} = x_2, \frac{\partial h_1}{\partial W_{22}} = 0, \frac{\partial h_1}{\partial W_{31}} = x_3, \frac{\partial h_1}{\partial W_{32}} = 0$$

$$\bullet \frac{\partial h_1}{\partial W} = \begin{bmatrix} x_1 & 0 \\ x_2 & 0 \\ x_3 & 0 \end{bmatrix}$$



$$h = xW + b$$

$$\frac{\partial h_1}{\partial W} = \begin{bmatrix} x_1 & 0 \\ x_2 & 0 \\ x_3 & 0 \end{bmatrix}$$

- How about  $\frac{\partial h_2}{\partial w}$ ?
  - $h_2 = x_1 W_{12} + x_2 W_{22} + x_3 W_{32} + b_1$

$$\frac{\partial h_2}{\partial W} = \begin{vmatrix} 0 & x_1 \\ 0 & x_2 \\ 0 & x_3 \end{vmatrix}$$

- So each matrix  $\frac{\partial h_k}{\partial W}$  is all zeros, except for column k, which has  $x^T$  on it.
- So maybe we just use  $x^T$  somehow?



$$h = xW + b$$

- Let's think about this another way..
- What is  $\frac{\partial J}{\partial W_{ij}}$ ?
- $W_{ij}$  only affects  $h_j$  on the output of the fully-connected layer and  $h_j = xW_{:j} + b_j$
- So what is  $\frac{\partial h_j}{\partial W_{ij}}$ ?
  - $x_i$
- So for  $\frac{\partial J}{\partial W_{ij}}$  we just need:

$$\frac{\partial J}{\partial W_{ij}} = \frac{\partial J}{\partial h_j} x_i$$



$$h = xW + b$$

$$\frac{\partial J}{\partial W_{ij}} = \frac{\partial J}{\partial h_i} x_i$$

• So if  $W \in \mathbb{R}^{3 \times 2}$ , we get:

et:
$$\frac{\partial J}{\partial W} = \begin{bmatrix} \frac{\partial J}{\partial h_1} x_1 & \frac{\partial J}{\partial h_2} x_1 \\ \frac{\partial J}{\partial h_1} x_2 & \frac{\partial J}{\partial h_2} x_2 \\ \frac{\partial J}{\partial h_1} x_3 & \frac{\partial J}{\partial h_2} x_3 \end{bmatrix} = x^T \frac{\partial J}{\partial h}$$

Or in general:

$$\frac{\partial J}{\partial W} = x^T \delta$$



$$h = xW + b$$

$$\frac{\partial J}{\partial W} = x^T \delta$$

- Dimension check?
  - $\delta \in \mathbb{R}^{1 \times K}$ ,  $x^T \in \mathbb{R}^{D \times 1}$ , so  $\frac{\partial J}{\partial W} = x^T \delta \in (\mathbb{R}^{D \times 1})(\mathbb{R}^{1 \times K}) \in \mathbb{R}^{D \times K}$
  - Same dimensions as W!
- What about multiple observations?
- Actually, pre-multiplying the incoming gradient by  $X^T$  will even provide the summation part of the mean of the gradient (so we just need to divide by the number of observations, N)!

$$\frac{\partial J}{\partial W} = \frac{1}{N} X^T \delta$$



# Updating Weights

- Now that we have the gradient of our objective function with regards to its weights, we can update them!
- Since all our objective functions were framed as loss function, we actually want to go some amount in the direction **opposite** the gradient:

$$W = W + \eta \left( -\frac{\partial J}{\partial W} \right)$$

- The variable  $\eta$  is called the *learning rate* and it is a hyperparameter that we can choose.
- More on that in a moment, but as a start, we might set it to be a small value like  $\eta=10^{-4}$



### **Updating Weights**

• Let's add a method to our FullyConnected layer, called updateWeights, that takes an incoming gradient and a learning rate, and updates the layer's weights.

```
def updateWeights(gradIn, eta):
    dJdb = np.sum(gradIn, axis = 0)/gradIn.shape[0]
    dJdW = (self.getPrevIn().T @ gradIn)/gradIn.shape[0]
    self.__weights -= eta*dJdW
    self.__biases -= eta*dJdb
```



#### Backpropagating

- And now our backpropagation looks like
  - Note, that since calling updateWeights updates the weights and biases of the fully-connected layer, I get the pass-through gradient of the fully-connected layer before updating the weights.
    - Otherwise it's like trying to hit a moving target!

```
#backwards!
grad = layers[-1].gradient(Y,h)
for i in range(len(layers)-2,0,-1):
  newgrad = layers[i].backward(grad)

if(isinstance(layers[i],FullyConnected)):
  layers[i].updateWeights(grad,eta)

grad = newgrad
```



#### **Gradient Descent**

- Nice!
- Do we just update the weights once?
  - No!
- We keep doing forward-backwards propagation until we hit some sort of termination criteria.
  - Ideally we detect convergence of the objective function.
  - Worst case we run out of allotted time.

```
while still learning
Perform forward propagation
Perform backwards propagation, updating weights
```



#### **Gradient Descent**

- Each time we update the weights is called an epoch.
- If we're using all the observations for each epoch we call this batch gradient descent.
- If we're using just one observation each time, we call this *online* gradient descent.
- Both have their pros and cons.
- Therefore, it is common to do mini-batch gradient descent.
- If there's random selection involved, then we call this *stochastic* gradient descent.



#### References

- Textbook
  - Section 4.3 : Gradient-Based Optimization
  - Section 5.9: Stochastic Gradient Descent
- Web
  - http://ruder.io/optimizing-gradient-descent/
  - https://www.mathworks.com/help/deeplearning/ref/connectlayers.html;jsessi onid=5a96c52e8efec11d475011b1222f
  - https://deepnotes.io/softmax-crossentropy
  - https://ml-cheatsheet.readthedocs.io/en/latest/index.html