
VHH Plugin Package: Shot Type Classification (vhh_stc)

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The following list give an overview of the folder structure of this python repository:

name of repository: vhh_stc

- **ApiSphinxDocumentation/**: includes all files to generate the documentation as well as the created documentations (html, pdf)
- **config/**: this folder includes the required configuration file
- **stc/**: this folder represents the shot-type-classification module and builds the main part of this repository
- **Demo/**: this folder includes a demo script to demonstrate how the package have to be used in customized applications
- **Develop/**: includes scripts to train and evaluate the pytorch models. Furthermore, a script is included to create the package documentation (pdf, html)
- **README.md**: this file gives a brief description of this repository (e.g. link to this documentation)
- **requirements.txt**: this file holds all python lib dependencies and is needed to install the package in your own virtual environment
- **setup.py**: this script is needed to install the stc package in your own virtual environment

SETUP INSTRUCTIONS

This package includes a `setup.py` script and a `requirements.txt` file which are needed to install this package for custom applications. The following instructions have to be done to use this library in your own application:

Requirements:

- Ubuntu 18.04 LTS
- CUDA 10.1 + cuDNN
- python version 3.6.x

Create a virtual environment:

- create a folder to a specified path (e.g. `/xxx/vhh_stc/`)
- `python3 -m venv /xxx/vhh_stc/`

Activate the environment:

- `source /xxx/vhh_stc/bin/activate`

Checkout `vhh_stc` repository to a specified folder:

- `git clone https://github.com/dahe-cvl/vhh_stc`

Install the `stc` package and all dependencies:

- change to the root directory of the repository (includes `setup.py`)
- `python setup.py install`

Note: You can check the success of the installation by using the command `pip list`. This command should give you a list with all installed python packages and it should include `vhh_stc`

Note: Currently there is an issue in the `setup.py` script. Therefore the pytorch libraries have to be installed manually by running the following command: `pip install torch==1.5.0+cu101 torchvision==0.6.0+cu101 -f https://download.pytorch.org/whl/torch_stable.html`

API DESCRIPTION

This section gives an overview of all classes and modules in *stc* as well as an code description.

2.1 Configuration class

class `stc.Configuration.Configuration` (*config_file: str*)

Bases: `object`

This class is needed to read the configuration parameters specified in the `configuration.yaml` file. The instance of the class is holding all parameters during runtime.

Note: e.g. `./config/config_vhh_test.yaml`

the yaml file is separated in multiple sections `config['Development']` `config['PreProcessing']` `config['StcCore']` `config['Evaluation']`

whereas each section should hold related and meaningful parameters.

loadConfig ()

Method to load configurables from the specified configuration file

2.2 STC class

class `stc.STC.STC` (*config_file: str*)

Bases: `object`

Main class of shot type classification (stc) package.

exportStcResults (*fName, stc_results_np: numpy.ndarray*)

Method to export stc results as csv file.

Parameters

- **fName** – [required] name of result file.
- **stc_results_np** – numpy array holding the shot type classification predictions for each shot of a movie.

loadSbdResults (*sbd_results_path*)

Method for loading shot boundary detection results as numpy array

Note: Only used in debug_mode.

Parameters **sbd_results_path** – [required] path to results file of shot boundary detection module (vhh_sbd)

Returns numpy array holding list of detected shots.

runModel (*model, tensor_l*)

Method to calculate stc predictions of specified model and given list of tensor images (pytorch).

Parameters

- **model** – [required] pytorch model instance
- **tensor_l** – [required] list of tensors representing a list of frames.

Returns predicted class_name for each tensor frame, the number of hits within a shot, frame-based predictions for a whole shot

runOnSingleVideo (*shots_per_vid_np=None, max_recall_id=-1*)

Method to run stc classification on specified video.

Parameters

- **shots_per_vid_np** – [required] numpy array representing all detected shots in a video (e.g. sid | movie_name | start | end)
- **max_recall_id** – [required] integer value holding unique video id from VHH MMSI system

2.3 Video class

class stc.Video.Video

Bases: object

This class is representing a video. Each instance of this class is holding the properties of one Video.

getFrame (*frame_id*)

Method to get one frame of a video on a specified position.

Parameters **frame_id** – [required] integer value with valid frame index

Returns numpy frame (WxHx3)

load (*vidFile: str*)

Method to load video file.

Parameters **vidFile** – [required] string representing path to video file

printVIDInfo ()

Method to a print summary of video properties.

2.4 Models - module

`stc.Models.loadModel(model_arch="", classes=None, pre_trained_path=None)`

This module is used to load specified deep learning model.

Parameters

- **model_arch** – string value [required] - is used to select between various deep learning architectures (Resnet, Vgg, Densenet, Alexnet)
- **classes** – list of strings [required] - is used to hold the class names (e.g. ['ELS', 'LS', 'MS', 'CU'])
- **pre_trained_path** – string [optional] - is used to specify the path to a pre-trained model

Returns the specified instance of the model

2.5 Datasets module

`stc.Datasets.loadDatasetFromFolder(path="", batch_size=64)`

This method is used to load a specified dataset.

Parameters

- **path** – [required] path to dataset folder holding the subfolders “train”, “val” and “test”.
- **batch_size** – [optional] specifies the batchsize used during training process.

Returns instance of trainloader, validloader, testloader as well as the corresponding dataset sizes

2.6 CustomTransforms class

class `stc.CustomTransforms.ToGrayScale`

Bases: `object`

This class is needed to transform rgb numpy frames to grayscale numpys during the training process with pytorch.

2.7 Shot class

class `stc.Shot.Shot(sid, movie_name, start_pos, end_pos)`

Bases: `object`

This class is representing a shot. Each instance of this class is holding the properties of one shot.

convert2String()

Method to convert class member properties in a semicolon separated string.

Returns string holding all properties of one shot.

printShotInfo()

Method to a print summary of shot properties.

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3.1 References

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