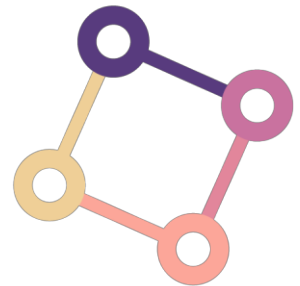


# Training Neural Networks

주재걸 교수

KAIST 김재철AI대학원



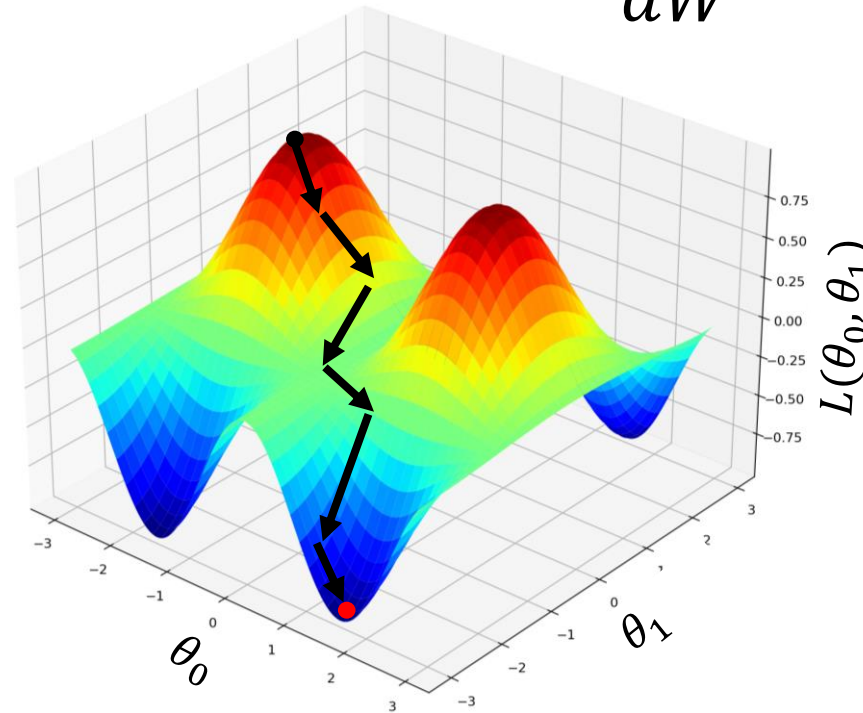
**DAVIAN**

Data and Visual Analytics Lab

# Training Neural Networks via Gradient Descent

Given the optimization problem,  $\min_W L(W)$ , where  $W$  is the neural network parameters, we optimize  $W$  using gradient descent approach:

$$W := W - \alpha \frac{dL(W)}{dW}$$

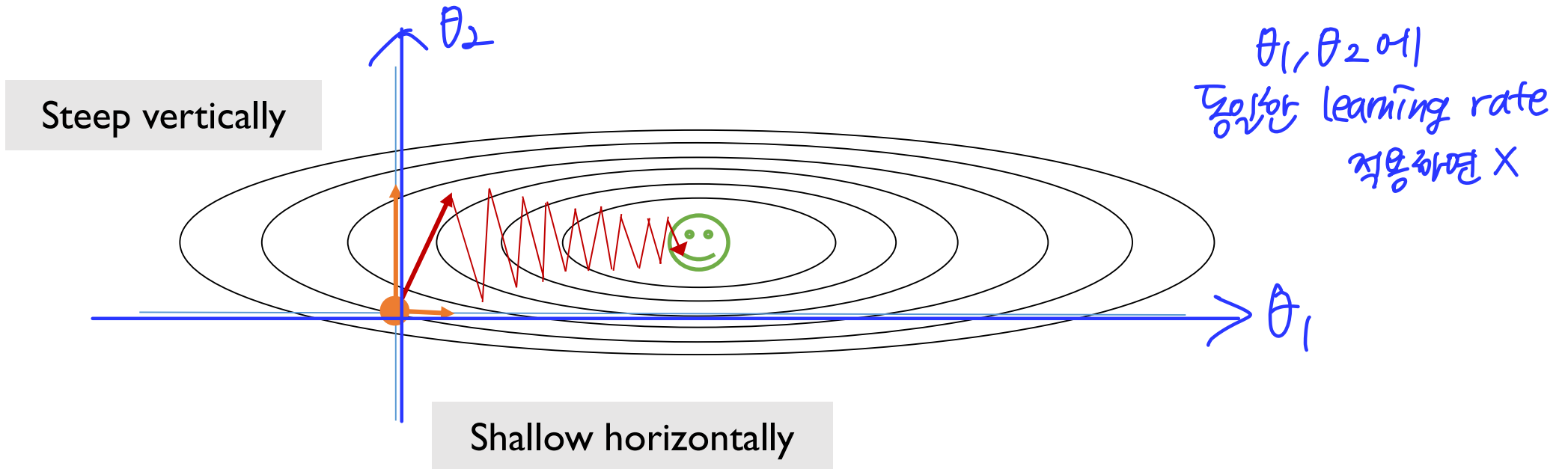


# Poor Convergence Case of Naïve Gradient Descent

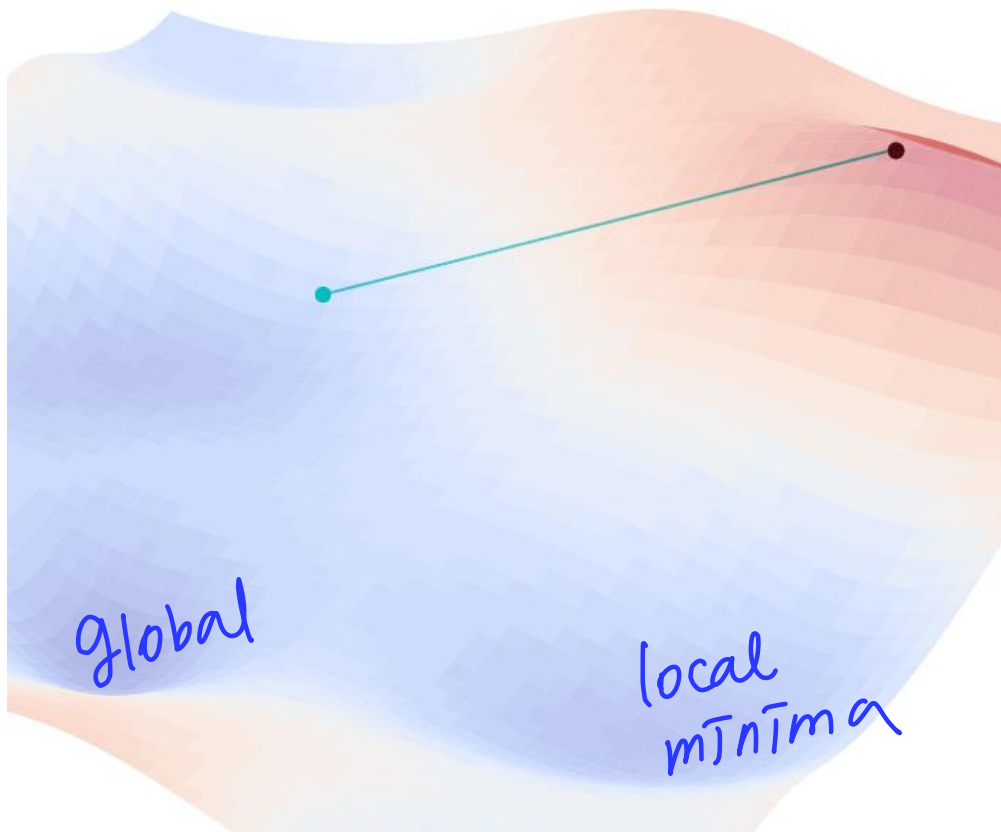
Suppose loss function is steep vertically but shallow horizontally:

Q: What is the trajectory along which we converge towards the minimum with SGD?

Very slow progress along flat direction, jitter along steep one



# Various Gradient Descent Methods



- GD
- Momentum
- Adagrad
- RMSProp
- Adam
- Adadelta<sup>[1]</sup>
- Ftrl<sup>[2]</sup>

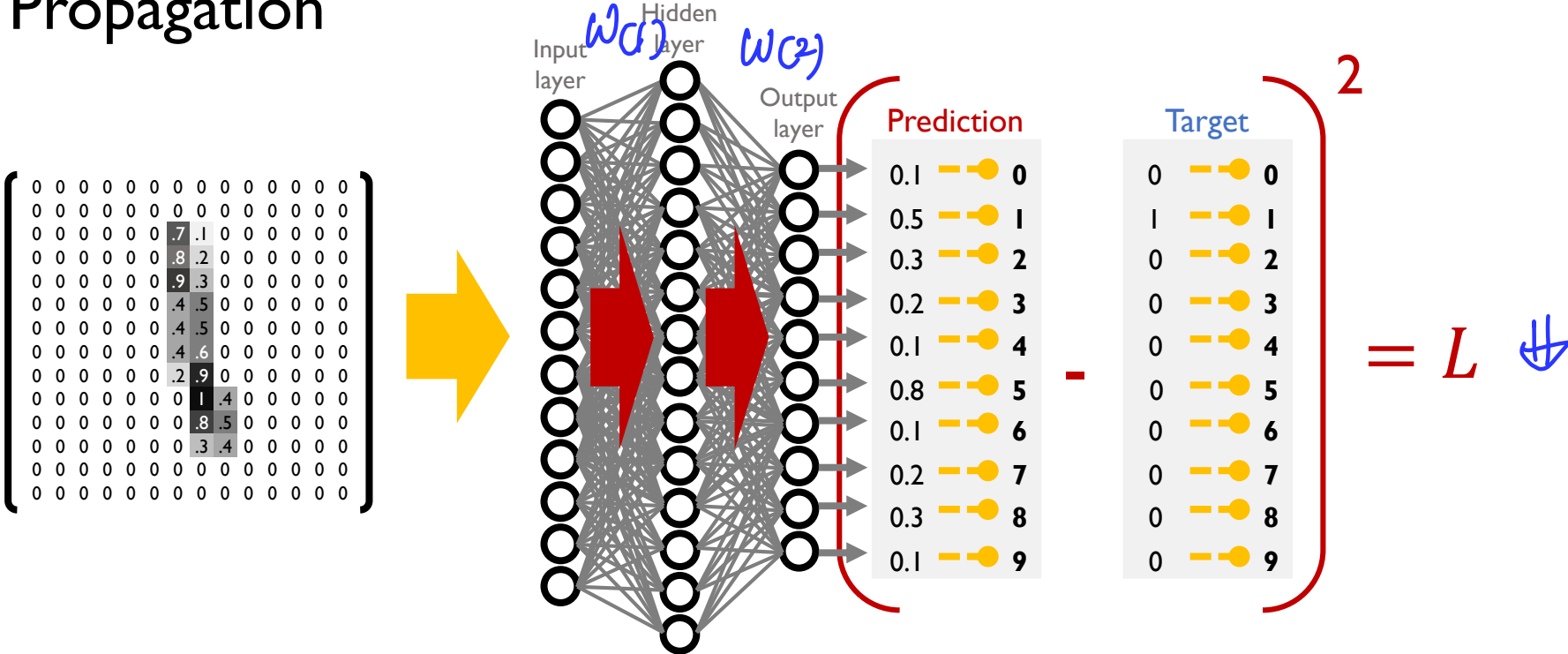
<http://www.denizyuret.com/2015/03/alec-radfords-animations-for.html>

[1] Zeiler, M. D. (2012). ADADELTA: An Adaptive Learning Rate Method. <http://arxiv.org/abs/1212.5701>

[2] H. Brendan McMahan et. al., (2013). Ad Click Prediction: a View from the Trenches, KDD

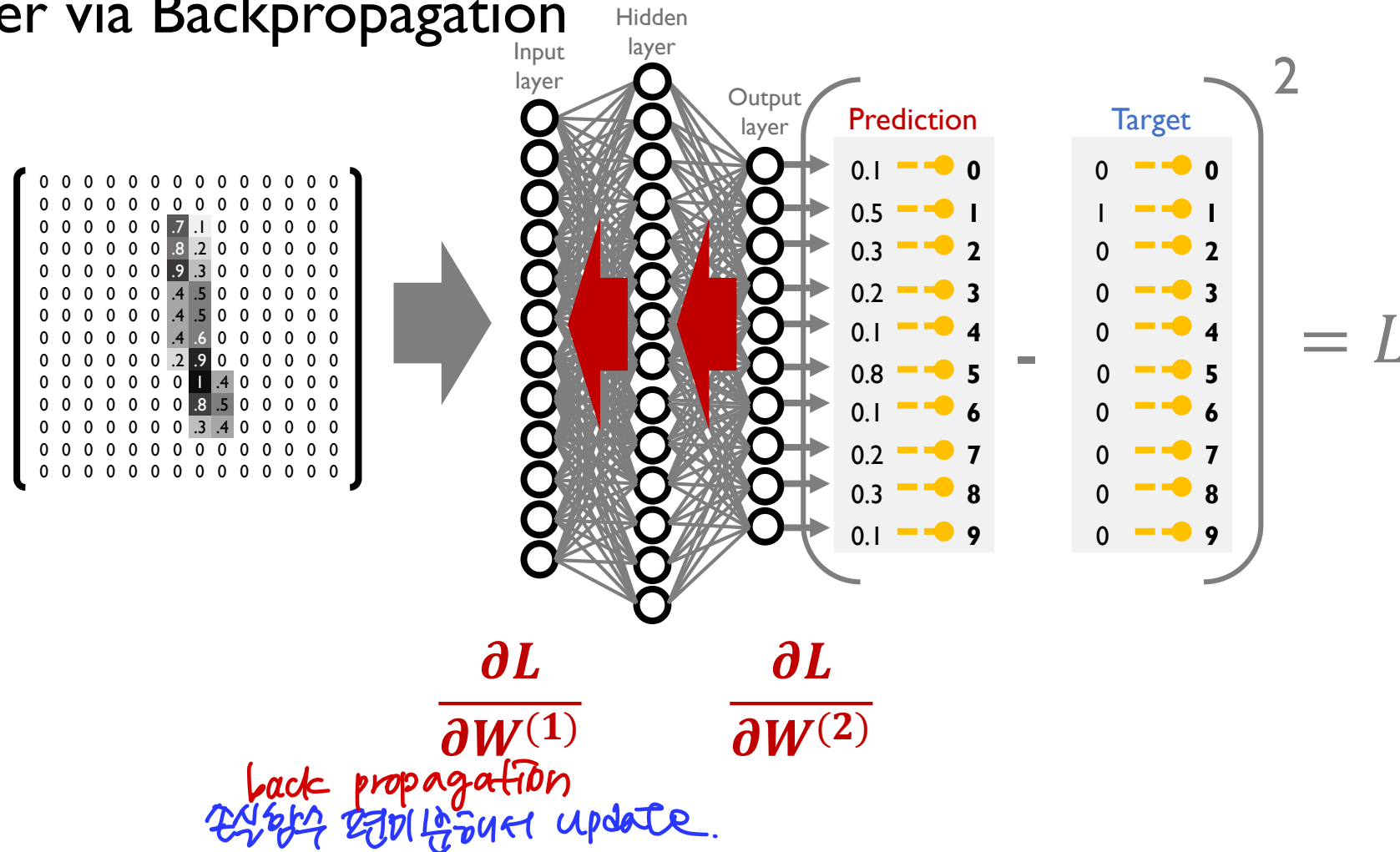
# Backpropagation to Compute Gradient in Neural Networks

First, given an input data item, compute the loss function value via Forward Propagation



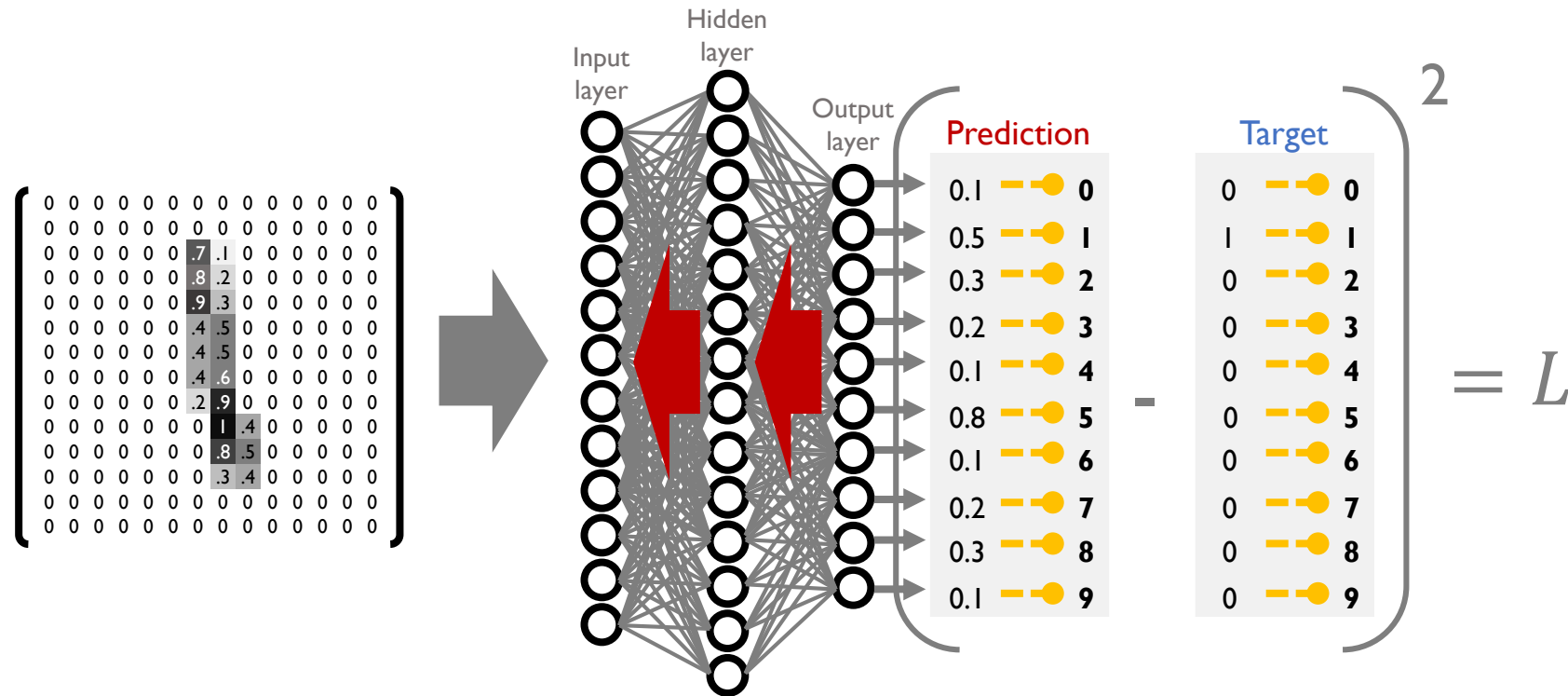
# Backpropagation to Compute Gradient in Neural Networks

Afterwards, compute the gradient with respect to each neural network parameter via Backpropagation



# Backpropagation to Compute Gradient in Neural Networks

Finally, update the parameters using gradient descent algorithm

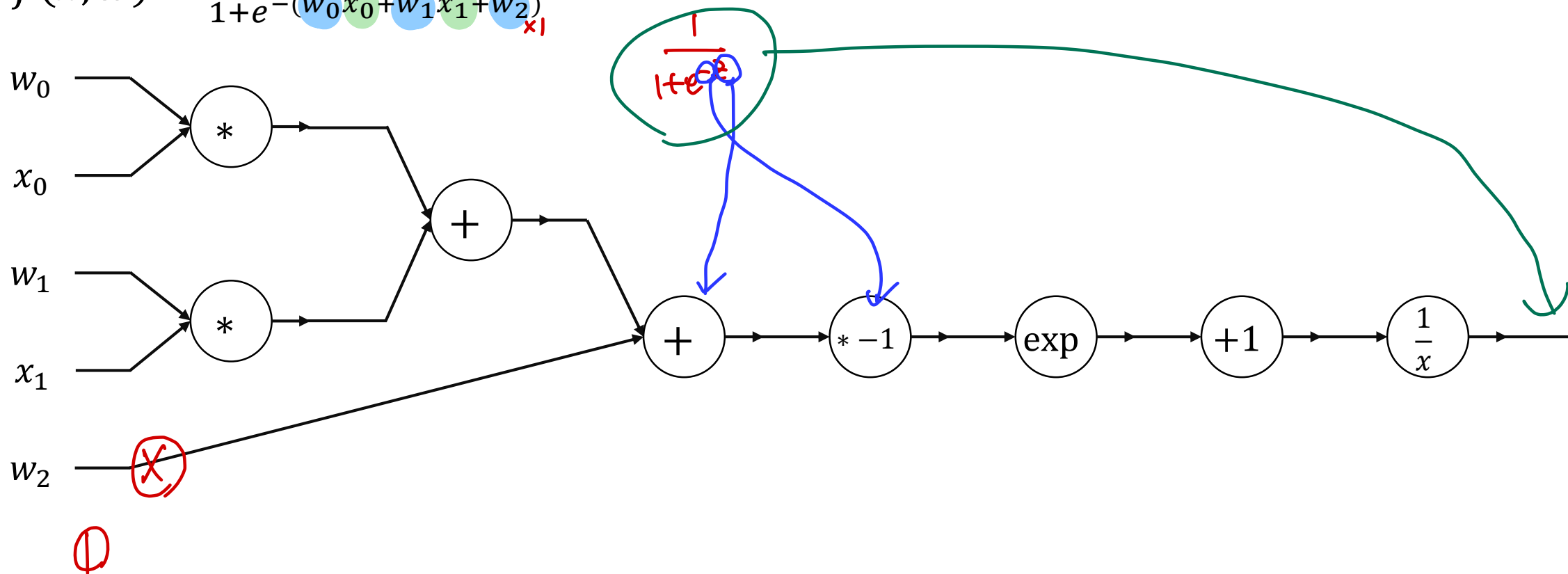


$$W^{(1)} := W^{(1)} - \alpha \frac{\partial L}{\partial W^{(1)}}$$

$$W^{(2)} := W^{(2)} - \alpha \frac{\partial L}{\partial W^{(2)}}$$

# Computational Graph of Logistic Regression

$$f(x, w) = \frac{1}{1 + e^{-(w_0 x_0 + w_1 x_1 + w_2 \times 1)}}$$

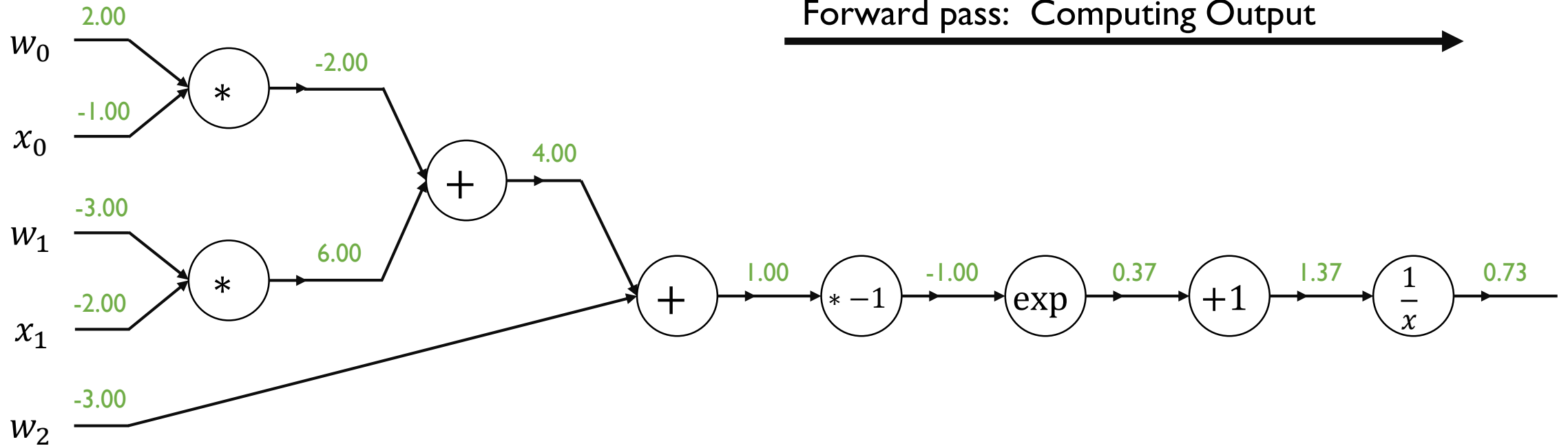




# Forward Propagation of Logistic Regression

$$f(x, w) = \frac{1}{1 + e^{-(w_0 x_0 + w_1 x_1 + w_2)}}$$

Forward pass: Computing Output

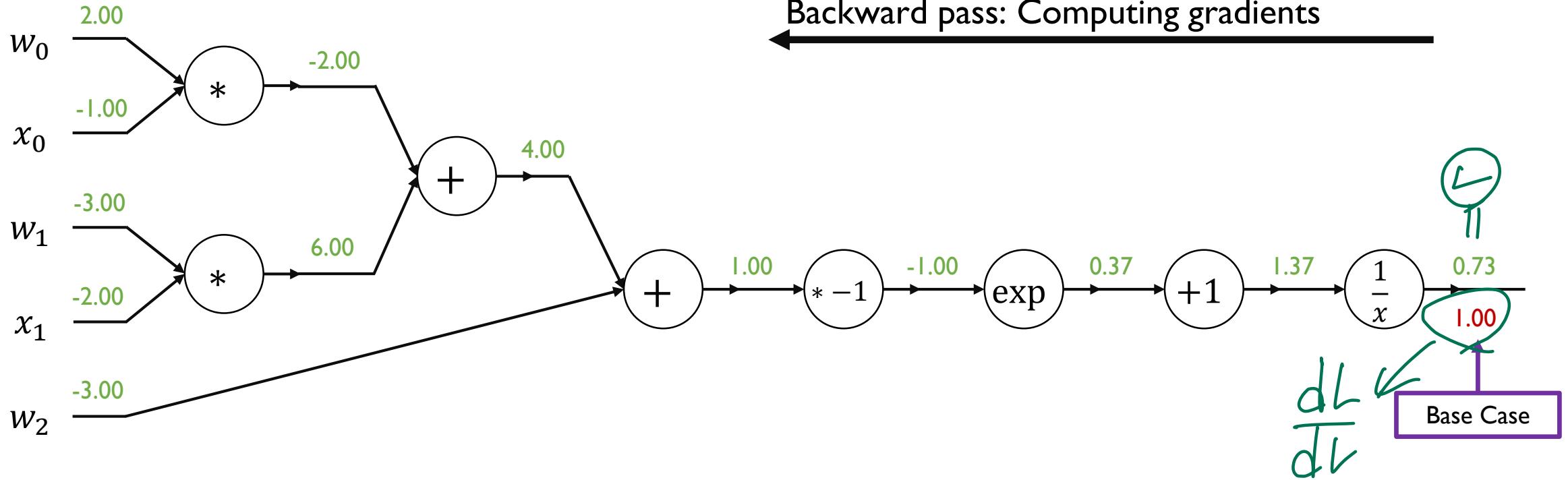


# Backpropagation of Logistic Regression

$$f(x, w) = \frac{1}{1 + e^{-(w_0 x_0 + w_1 x_1 + w_2)}}$$

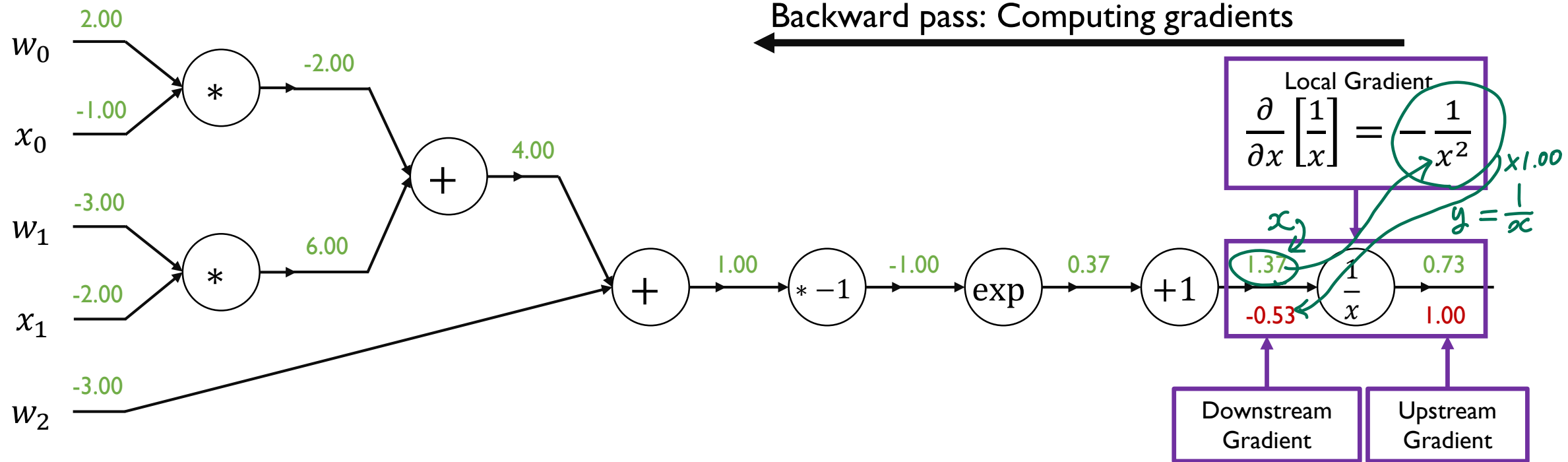
편미분 값 구함.

Backward pass: Computing gradients



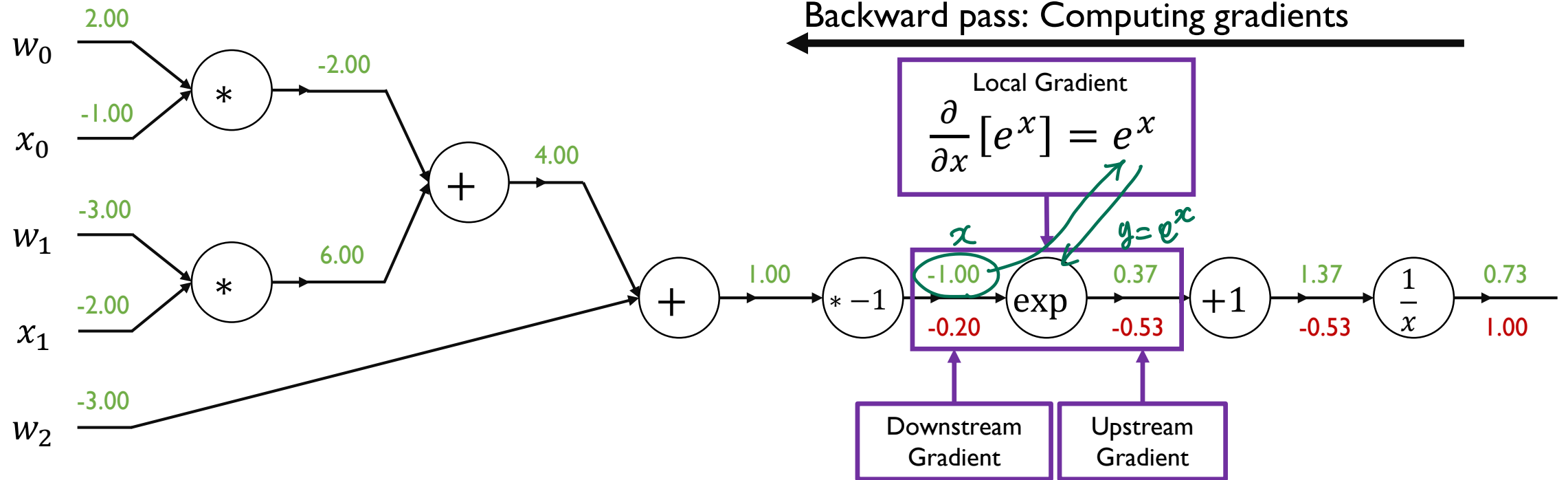
# Backpropagation of Logistic Regression

$$f(x, w) = \frac{1}{1 + e^{-(w_0 x_0 + w_1 x_1 + w_2)}}$$



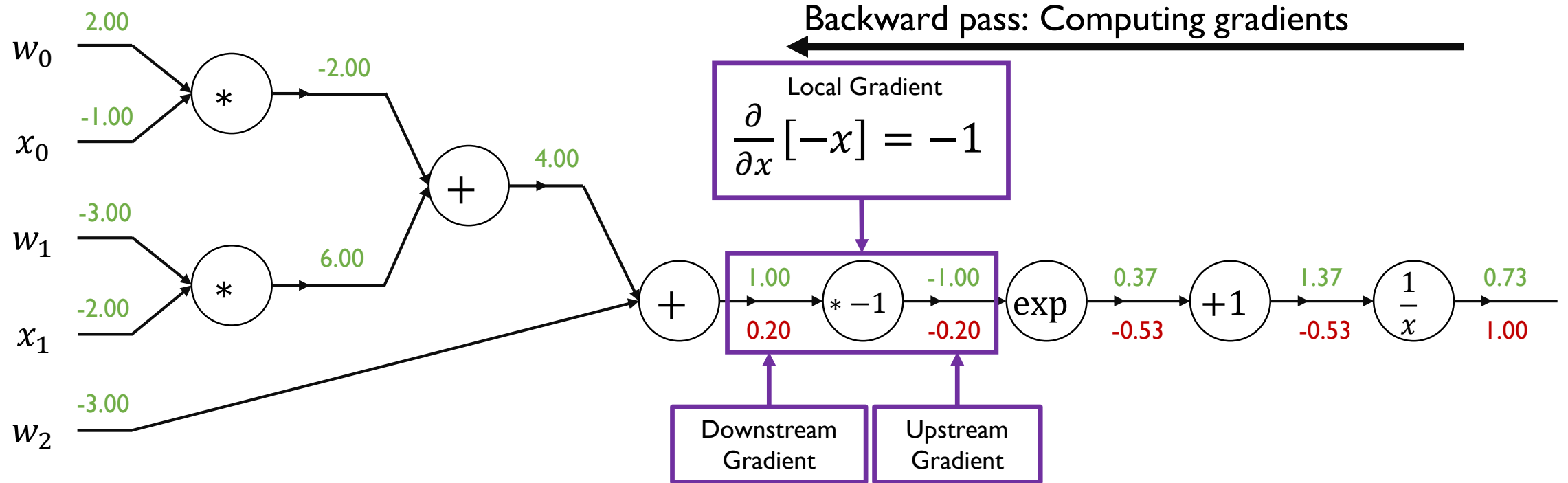
# Backpropagation of Logistic Regression

$$f(x, w) = \frac{1}{1 + e^{-(w_0 x_0 + w_1 x_1 + w_2)}}$$



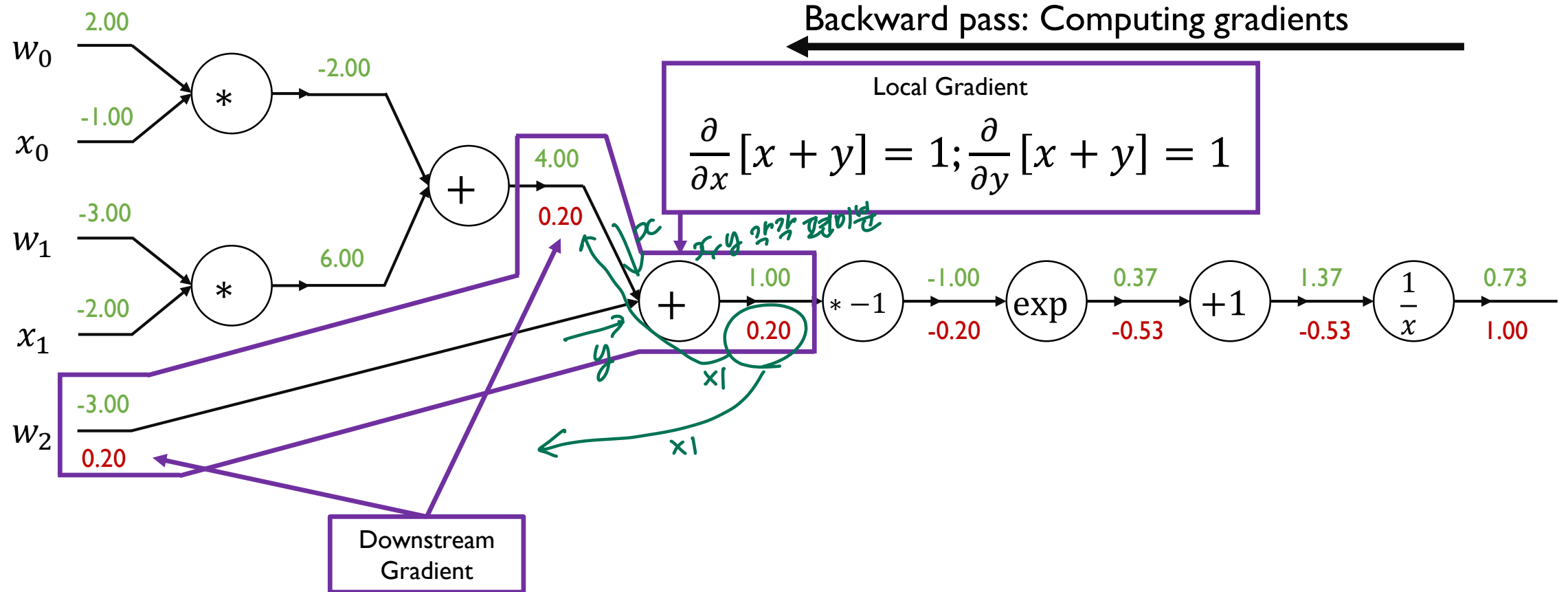
# Backpropagation of Logistic Regression

$$f(x, w) = \frac{1}{1 + e^{-(w_0 x_0 + w_1 x_1 + w_2)}}$$



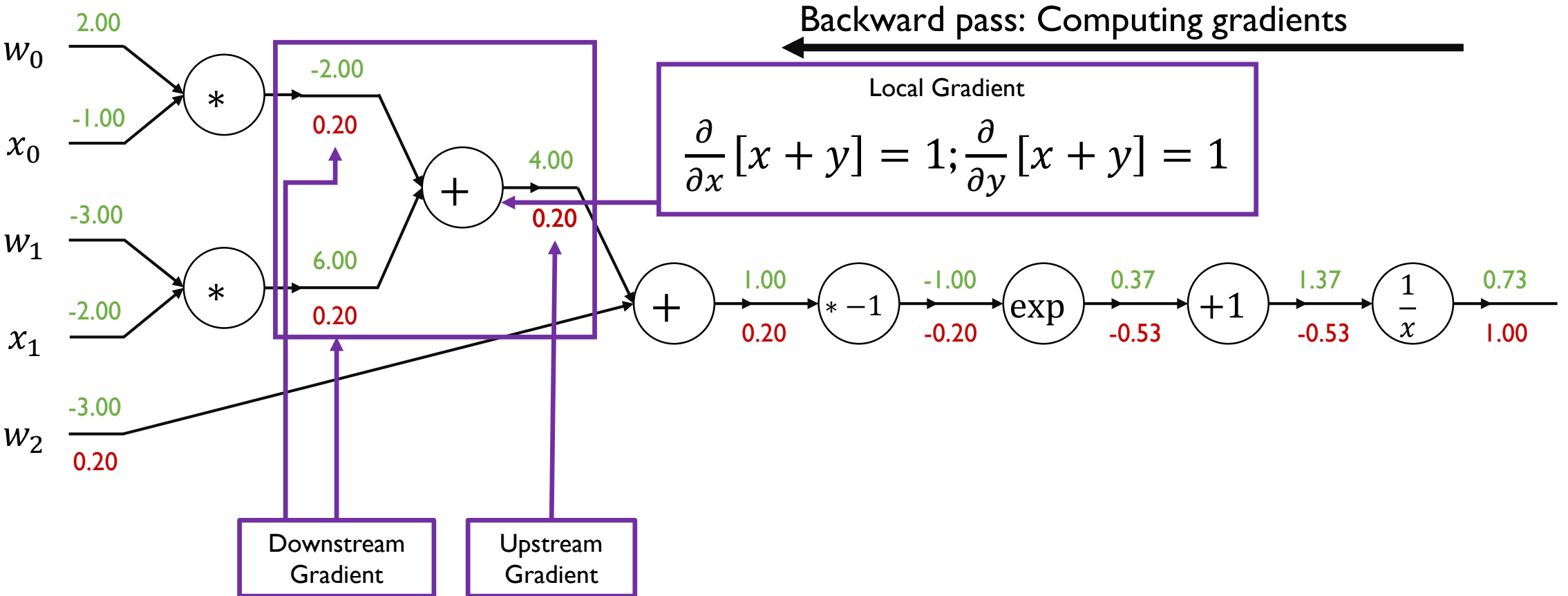
# Backpropagation of Logistic Regression

$$f(x, w) = \frac{1}{1 + e^{-(w_0 x_0 + w_1 x_1 + w_2)}}$$



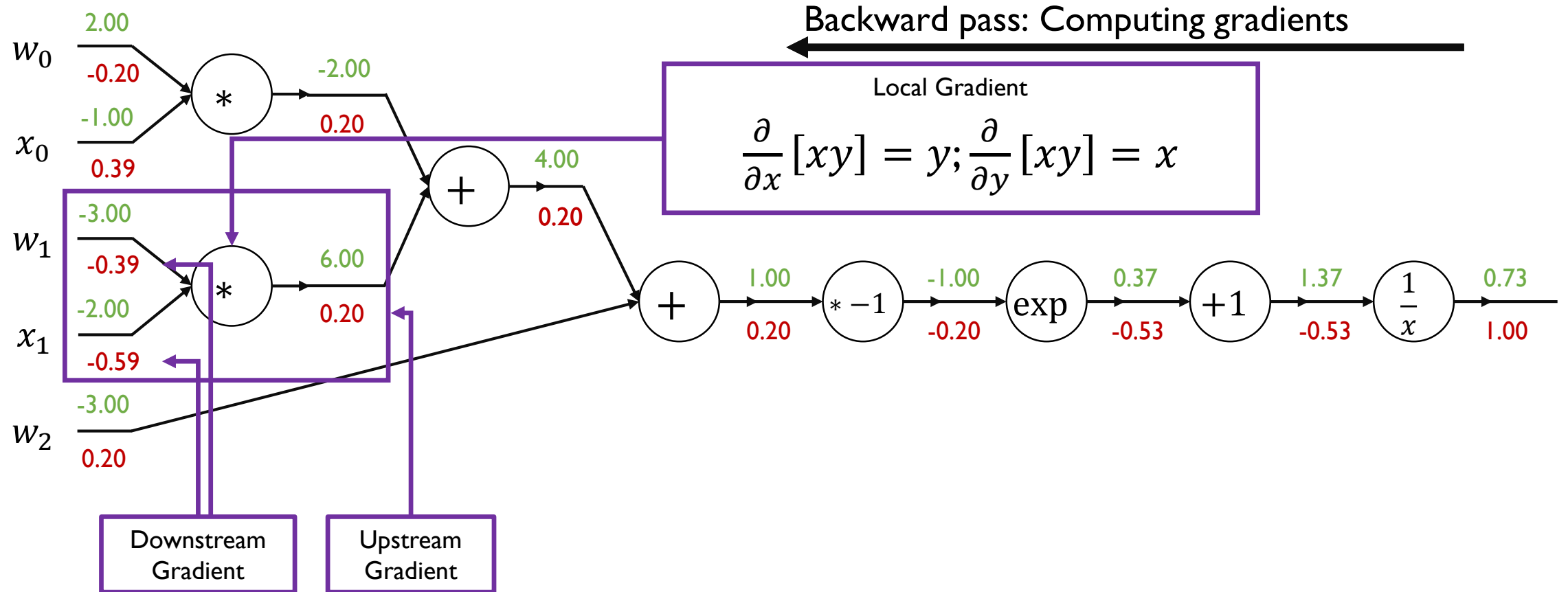
# Backpropagation of Logistic Regression

**다른 예시:**  $f(x, w) = \frac{1}{1+e^{-(w_0x_0+w_1x_1+w_2)}}$



# Backpropagation of Logistic Regression

다른 예시:  $f(x, w) = \frac{1}{1 + e^{-(w_0x_0 + w_1x_1 + w_2x_2)}}$

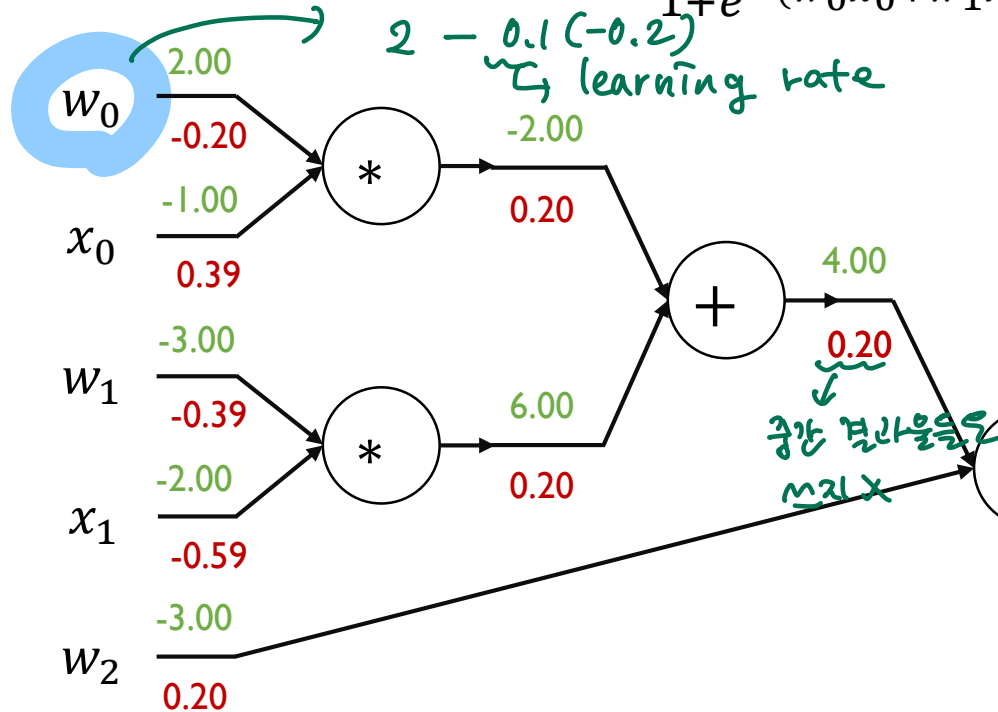




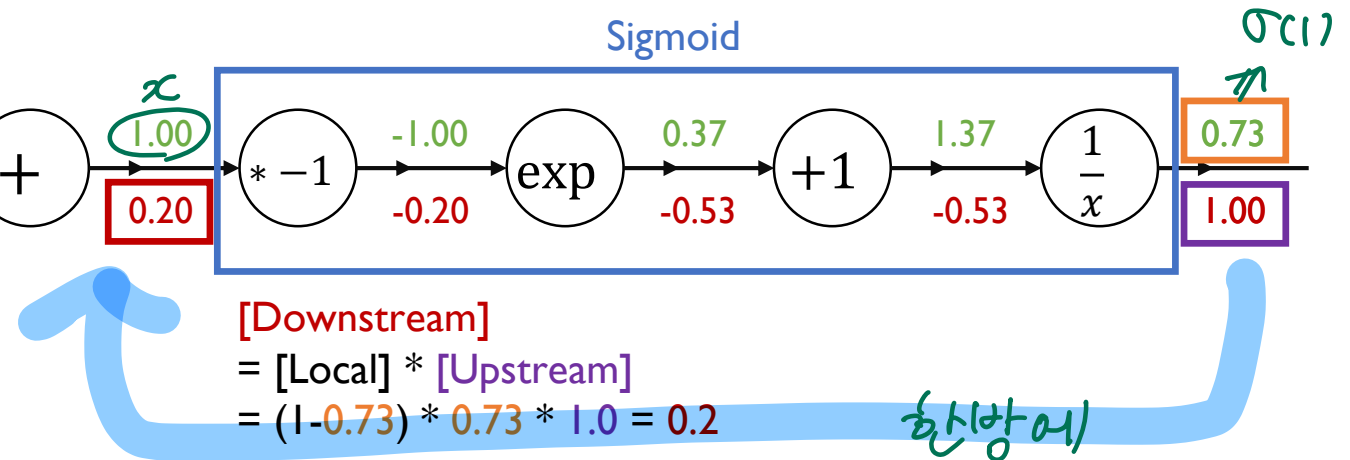
# Backpropagation of Logistic Regression

다른 예시:  $f(x, w) = \frac{1}{1+e^{-(w_0x_0+w_1x_1+w_2)}} = \sigma(w_0x_0 + w_1x_1 + w_2)$

Backward pass: Computing gradients



$\sigma(x) = \frac{1}{1+e^{-x}}$  One can represent multiple computational steps as a single computational module



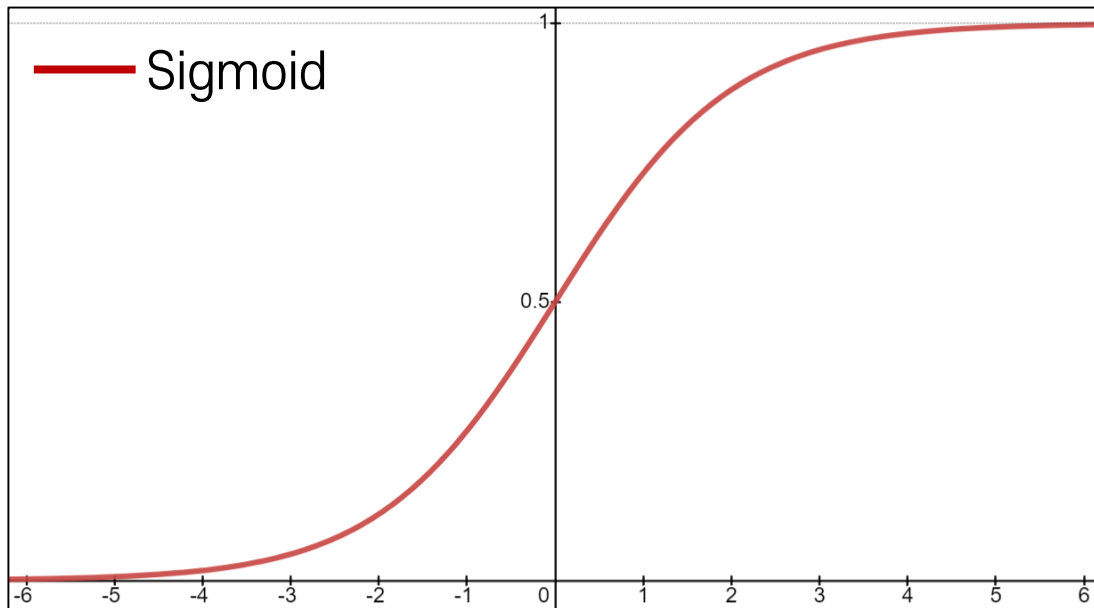
Sigmoid local gradient  $\frac{\partial}{\partial x} [\sigma(x)] = \frac{e^{-x}}{(1+e^{-x})^2} = \left( \frac{1+e^{-x}-1}{1+e^{-x}} \right) \left( \frac{1}{1+e^{-x}} \right) = (1 - \sigma(x))\sigma(x)$

$4(1-0.73)0.73$

# Sigmoid Activation

## Sigmoid

$$\sigma(x) = \frac{e^x}{e^x + 1} = \frac{1}{1 + e^{-x}}$$



- Maps real numbers in  $(-\infty, \infty)$  into a range of  $[0, 1]$
- gives a probabilistic interpretation

확률값을 출력

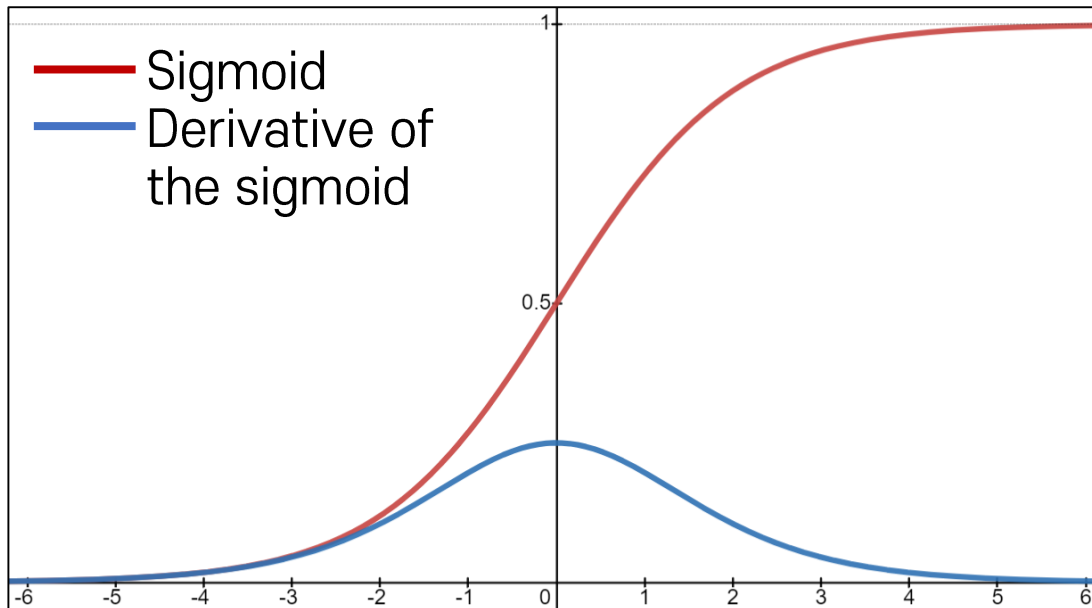
Historically, sigmoid activation function gives nice interpretation of saturating firing rate of a neuron

# Problems of Sigmoid Activation

$$0 < \sigma(x) \cdot (1 - \sigma(x)) \leq \frac{1}{4}$$

## Sigmoid

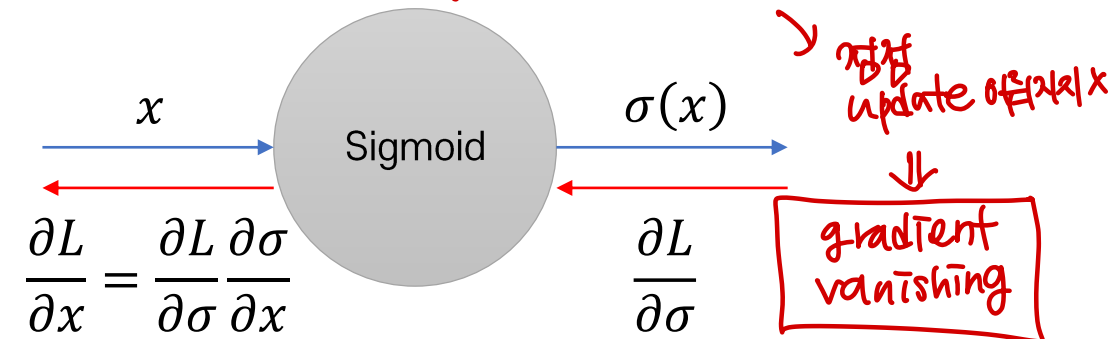
$$\sigma(x) = \frac{e^x}{e^x + 1} = \frac{1}{1 + e^{-x}}$$



- Saturated neurons kills the gradients

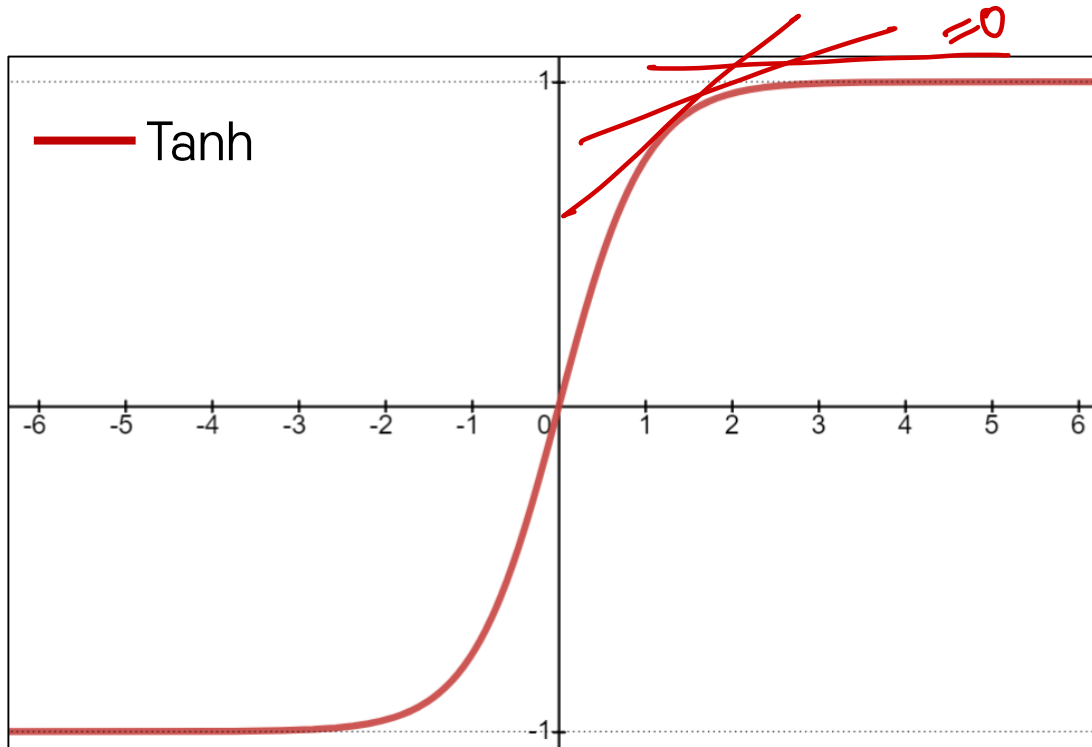
- The gradient value  $\sigma(x) \leq \frac{1}{4}$ , which decreases the gradient during backpropagation, i.e., causing a gradient vanishing problem

back propagation 때(즉) 수렴시  
gradient 점차 작아짐.



# Tanh Activation

$-\infty, \infty \Rightarrow -1, 1$



## Tanh

- $\tanh(x) = 2 \times \text{sigmoid}(x) - 1$
- Squashes numbers to range  $[-1, 1]$

## Strength

- Zero-centered (average is 0)

## Weakness

- Still kills gradients when saturated, i.e., still causing a gradient vanishing problem

$0 \sim \frac{1}{2}$  임.  $\rightarrow$  gradient vanishing 문제 발생.

# ReLU Activation

## ReLU (Rectified Linear Unit)

$$f(x) = \max(0, x)$$

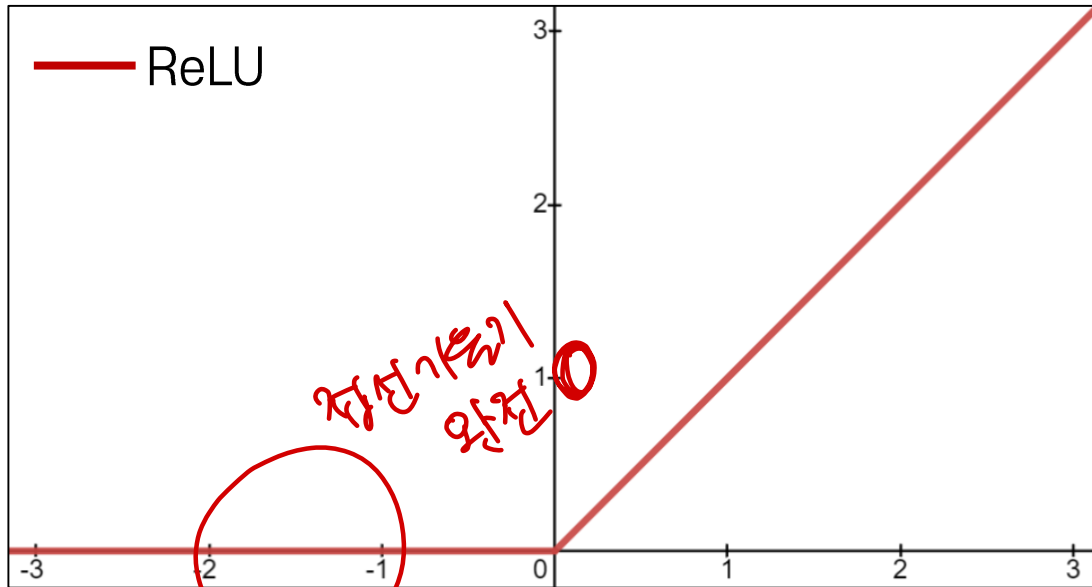
↳ 연산 간단

### Strength

- Does not saturate (in + region)
- Very computationally efficient
- Converge much faster than sigmoid/tanh

### Weakness

- Not zero-centered output
- Gradient is completely zero for  $x < 0$



The slope of the function  
 $x \geq 0$ : 1 (bypass)  
 $x < 0$ : 0 (gating)

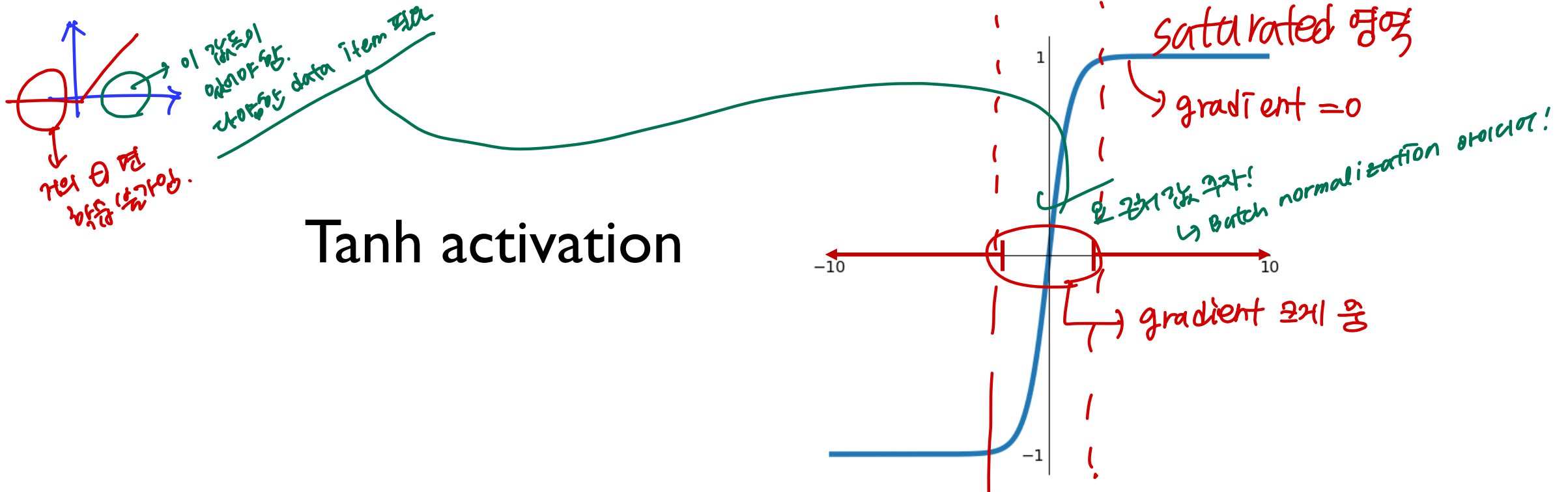
$-\infty, \infty \Rightarrow 0, \infty$

layer 99 더 good?

# Batch Normalization

# Motivation of Batch Normalization

- Saturated gradients when random initialization is done
- The parameters are not updated  $\rightarrow$  Hard to optimize (in red region)

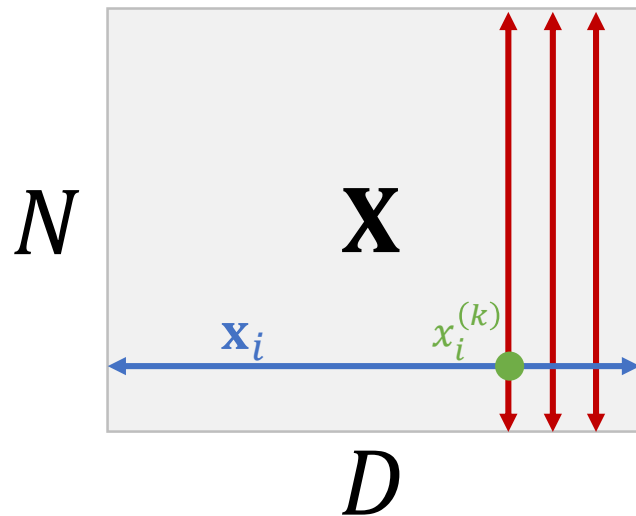


# Definition of Batch Normalization

“You want unit Gaussian activations? just make them so.”

- We consider a batch of activations at some layer to make each dimension unit Gaussian

1. Compute the empirical mean  $\mathbb{E}[x^{(k)}]$  and variance  $\text{Var}[x^{(k)}]$  independently for each dimension  $k$



2. Normalize

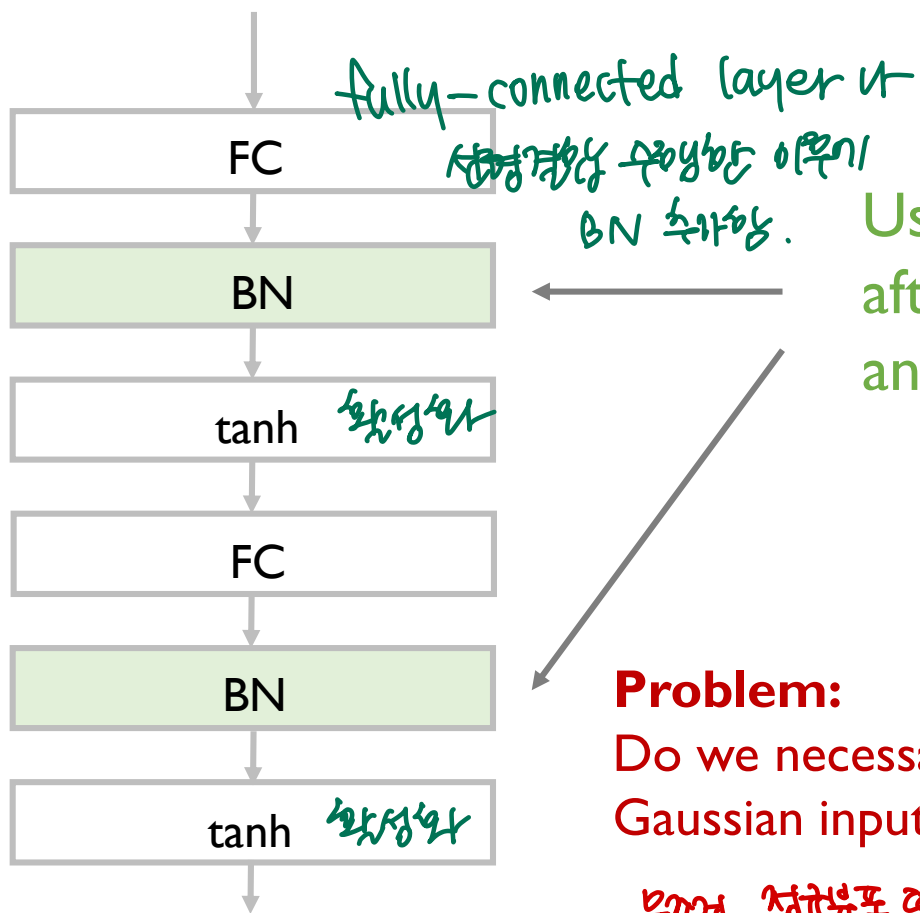
$$\hat{x}_i^{(k)} = \frac{x_i^{(k)} - \mathbb{E}[x^{(k)}]}{\sqrt{\text{Var}[x^{(k)}]}}$$

This is a vanilla differentiable function

~~정규분포~~  $\tanh$   
정규분포 따는게.



# Batch Normalization Process



Usually inserted  
after fully-connected or convolutional layers,  
and before nonlinearity.

## Problem:

Do we necessarily want a unit  
Gaussian input to a tanh layer?

무조건 정규분포 따르게 하느건  
neural network가 잘 추출한 정보  
무시하는 과정일 수 있음.

$$\hat{x}_i^{(k)} = \frac{x_i^{(k)} - \mathbb{E}[x^{(k)}]}{\sqrt{\text{Var}[x^{(k)}]}}$$

# Batch Normalization

↑  
기울기 소실 문제 해결할 수 있는 장치.

Normalize:

$$\hat{x}_i^{(k)} = \frac{x_i^{(k)} - \mathbb{E}[x^{(k)}]}{\sqrt{\text{Var}[x^{(k)}]}}$$

And then allow the network to squash the range if it wants to:

$$y_i^{(k)} = \gamma^{(k)} \hat{x}_i^{(k)} + \beta^{(k)}$$

원하는 범위로 맞춤

→ 평균  $b$ ,

분산  $a^2$  으로 바꿈.

← 평균 분산  
스스로 결정하도록

Note, the network can learn:

$$\gamma^{(k)} = \sqrt{\text{Var}[x^{(k)}]}$$

$$\beta^{(k)} = \mathbb{E}[x^{(k)}]$$

to recover the identity mapping

↙  
원래 평균 분산으로  
복원 가능.

Determined while training neural network

# Batch Normalization

**Input:** Values of  $x$  over a mini-batch:  $B = \{x_1 \dots x_m\}$ ;

Parameters to be learned;  $\gamma, \beta$


**Output:**  $\{y_i = \text{BN}_{\gamma, \beta}(x_i)\}$

$$\mu_B \leftarrow \frac{1}{m} \sum_{i=1}^m x_i \quad // \text{ mini-batch mean}$$

$$\sigma_B^2 \leftarrow \frac{1}{m} \sum_{i=1}^m (x_i - \mu_B)^2 \quad // \text{ mini-batch variance}$$

$$\hat{x}_i \leftarrow \frac{x_i - \mu_B}{\sqrt{\sigma_B^2 + \epsilon}} \quad // \text{ normalize}$$

$$y_i \leftarrow \gamma \hat{x}_i + \beta \equiv \text{BN}_{\gamma, \beta}(x_i) \quad // \text{ scale and shift}$$

  $\gamma$  1  $\beta$  0  $\gamma$  1  $\beta$  0

- Improves gradient flow through the network
- Reduces the strong dependence on initialization

THANK YOU