Foundation of Supervised Learning

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Learning from data



- What is this animal?
 - You would answer the question in few seconds

- Will you need a zoological (mathematical) definition to distinguish it?
 - Yes or No

We have learned a lot from data (pattern) despite being ignorant of a rigorous definition of a lion

Machine learning problems

Is it a spam mail or not?



Binary classification

Image recognition Multi-class classification

House prices Regression

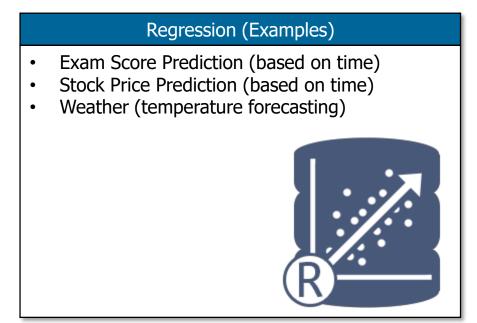


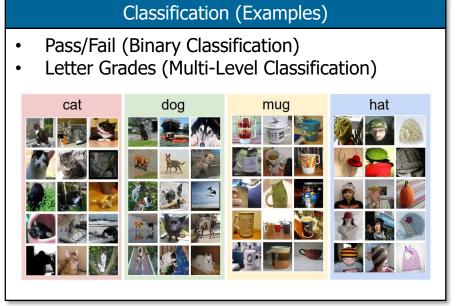
ImageNet Large Scale Visual Recognition Challenge (ILSVRC)



Supervised learning

• Given a set of labeled examples (x^1, y^1) , ..., (x^N, y^N) , learn a mapping function $g: X \to Y$, such that given an unseen sample x', associated output y' is predicted.

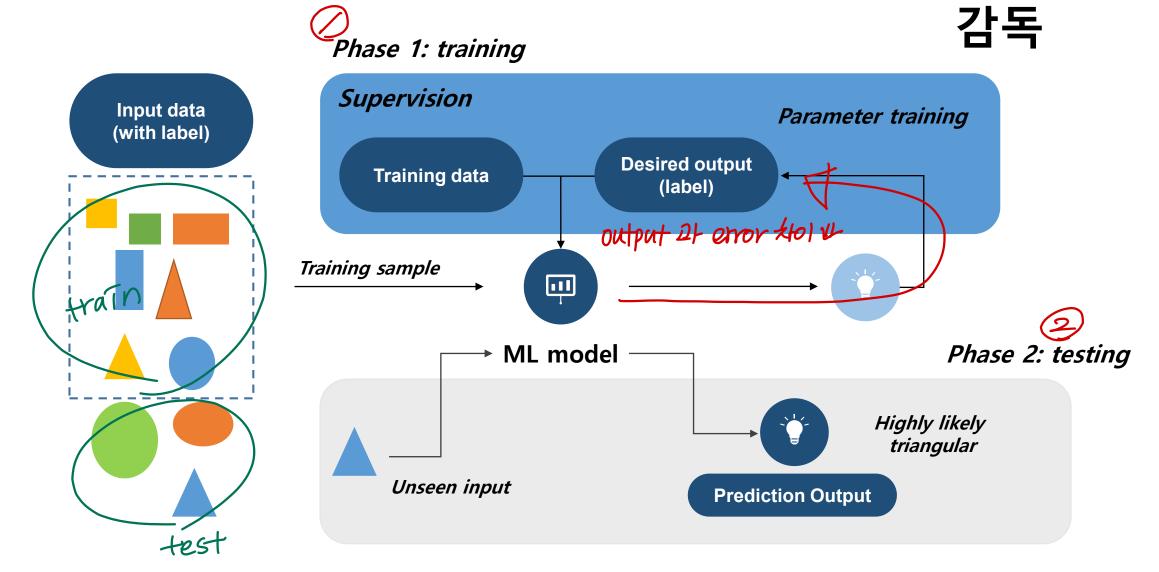




Continuous variables

Discrete variables

Learning pipeline



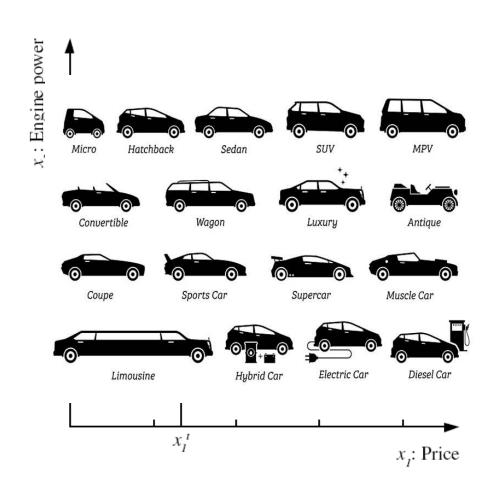
Example: family car

- Class C of a "family car"
 - Prediction: Is this car a family car?
- Output:

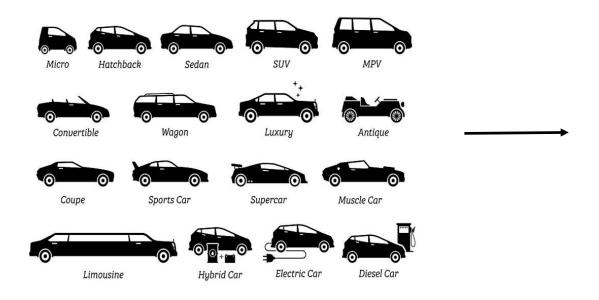
Positive (+) and negative (–) examples, or multi-class examples

Input representation:

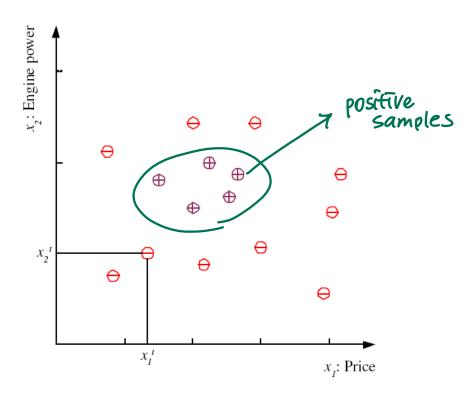
 x_1 : price, x_2 : engine power



Problem formulation



Input representation



Problem formulation

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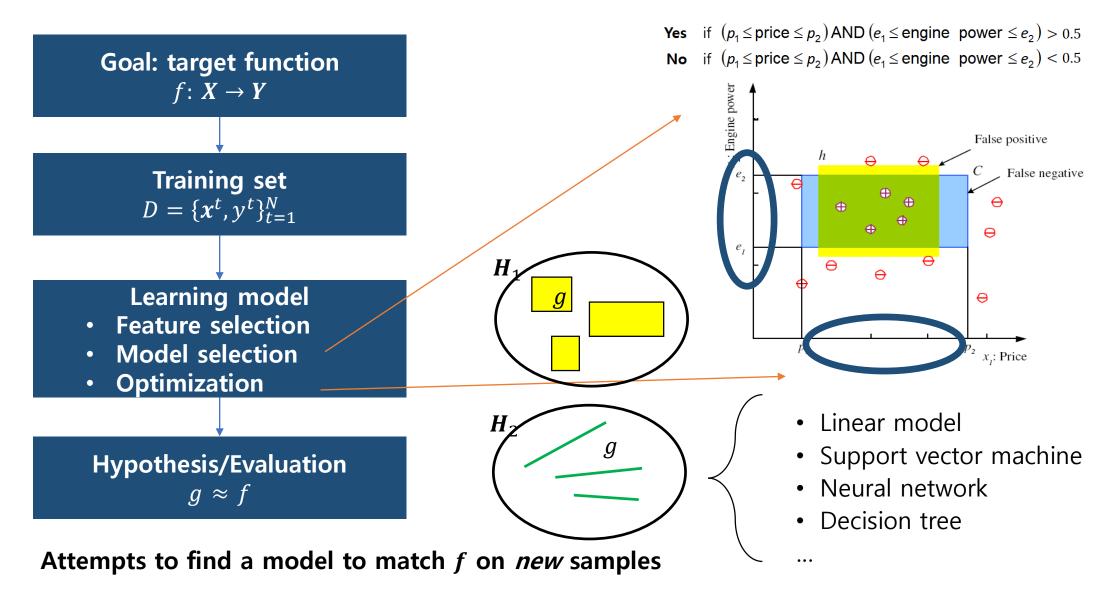
- $X = \mathbb{R}^d$ is an input space
 - \mathbf{R}^d : a *d*-dimensional Euclidean space
 - input vector $x \in X$: $x = (x_1, x_2, ..., x_d)$
- Y is an output space
 - Binary (yes/no) decision

- Micro Hachback Sedan SUV MPV

 Convertible Wagon Luxury Antique

 Coupe Sports Car Supercar Muscle Car
- $X = \mathbb{R}^d$ is an input space
- R^d: a d-dimensional Euclidean space
- input vector $x \in X$: $x = (x_1, x_2, ..., x_d)$
- Y is an output space
- Binary (yes/no) decision
- Now, we want to approximate a target function f
- f: X → Y (unknown ideal function)
- Data (x^1, y^1) , ..., (x^N, y^N) ; dataset where $y^N = f(x^N)$
- Correct label is ready for a training set
- Hypothesis $g: X \to Y$ (ML model to approximate f): $g \in H$
- \bullet Now, we want to approximate a target function f
 - $f: X \to Y$ (unknown ideal function)
 - Data (x^1, y^1) , ..., (x^N, y^N) ; dataset where $y^N = f(x^N)$
 - Correct label is ready for a training set
 - Hypothesis $g: X \to Y$ (ML model to approximate f): $g \in H$

Learning model Learnable parameters to learn a boundary



Model generalization

- Learning is an ill-posed problem; data is limited to find a unique solution
- Generalization (Goal): a model needs to perform well on unseen data

 emor function আহম কিছেৰ এই মুক্ত
 - Generalization error E_{gen} ; the goal is to minimize this error, but it is impractical to compute in the real world

Learning from data ——— Learning from error (supervision)

Use training/validation/test set errors for the proxy

Errors

- Pointwise error is measured on an each input sample: e(h(x), y)
- Examples:
 - ✓ squared error $e(h(x^i), y^i) = (h(x^i) y^i)^2$
 - ✓ binary error $e(h(x^i), y^i) = \mathbf{1}[h(x^i) \neq y^i]$
- From a pointwise error to overall errors

$$\checkmark E[(h(x^i) - y^i)^2]$$

ENDER loss function (= cost function)

If an input sample is chosen from training, validation, and testing datasets, the errors are called a training error (E_{train}), a validation error (E_{val}), and a testing error (E_{test})

- Training error E_{train} measured on a training set, which may or may not represent E_{gen} ; used for fitting a model
- Testing error E_{test} (not used in training), which can be used for a proxy of E_{qen}
- Split into two objectives:
 - 1. $E_{test} \approx E_{train}$
 - 2. $E_{train} \approx 0$
- Objective 1: make $E_{test} \approx E_{train}$
 - Failure : <u>overfitting</u> → high variance
 Cure: <u>regularization</u>, <u>more</u> data
- Objective 2: make $E_{train} \approx 0 \iff \text{perel of the party of the part$
 - Failure : <u>underfitting</u> → high bias
 - Cure: optimization, more complex model

Goal: $E_{test} \approx E_{gen} \approx 0$

How to achieve the goal in practice?

Bias and Variance

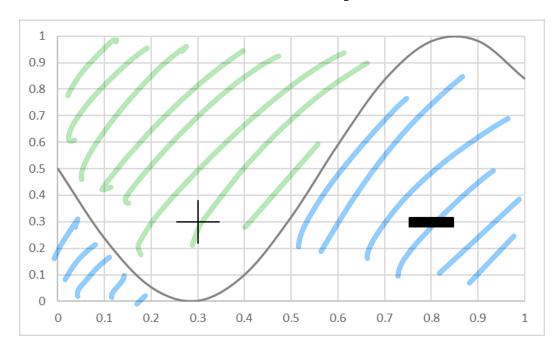
- Bias error because the model can not represent the concept
- Variance error because a model overreacts to small changes (noise) in the training data

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Total Loss = Bias + Variance (+ noise)
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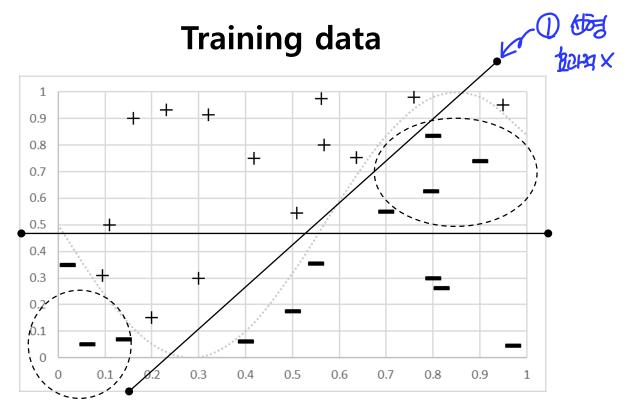
high bias

Underfitting

True concept



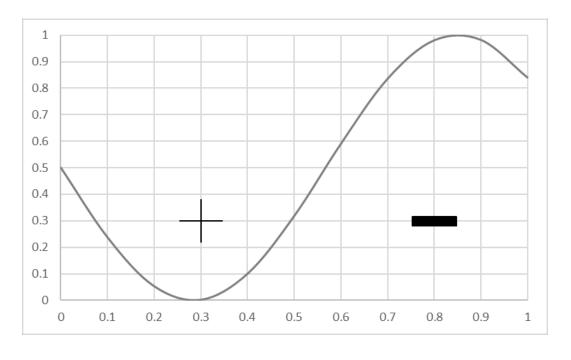
Try a simple model



Underfitting problem because of using too simpler model than actual data distribution (high bias)

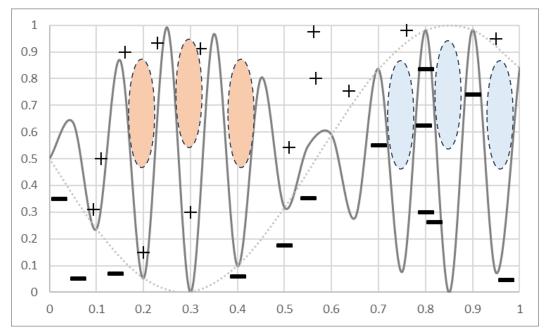
Overfitting

True concept



Try a complex model

Training data



Overfitting problem because of using more complex model than actual data distribution (high variance)

Simple model is better

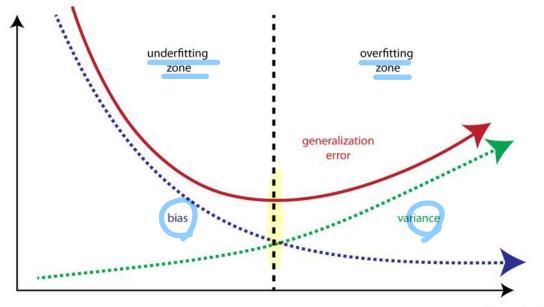
Bias-variance trade-off

 $E_{test} \approx E_{train} \approx 0$ Complex model is better

- Split into two objectives:
 - 1. $E_{test} \approx E_{train}$
 - 2. $E_{train} \approx 0$
- Objective 1: make $E_{test} \approx E_{train}$
 - Failure : <u>overfitting</u> → high variance and low bias
 - If a model is too complex
- Objective 2: make $E_{train} \approx 0$
 - Failure : <u>underfitting</u> → high bias and low variance
 - If a model is too simple

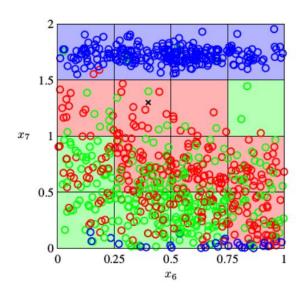
 The two objectives have tradeoff between approximation and generalization w.r.t model complexity

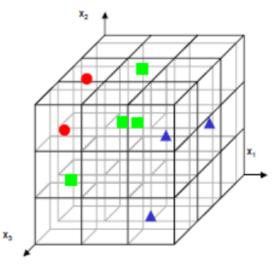
the bias vs. variance trade-off



Avoid overfitting

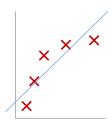
- (Problem) In today's ML problems, a complex model tends to be used to handle high-dimensional data (and relatively insufficient number of data); prone to an overfitting problem
- (Curse of dimension) Will you increase the dimension of the data to improve the performance as well as maintain the density of the examples per bin? If so, you need to increase the data exponentially.

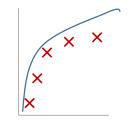


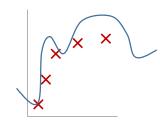


Avoid overfitting

- (Remedy)
 - ✓ Data augmentation
- √ Regularization to penalize complex models (variance reduction); make a model not too sensitive to noise or outliers (e.g. drop-out, LASSO)
- Ensemble: average over a number of







$$\theta_0 + \theta_1 x$$

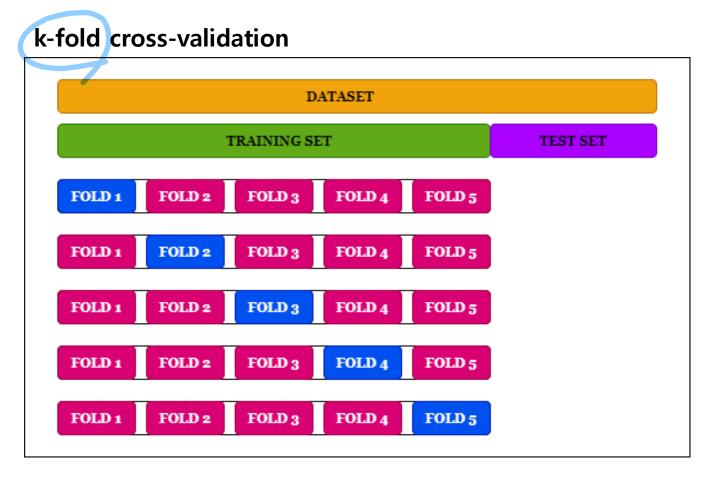
$$\theta_0 + \theta_1 x + \theta_2 x$$

$$\theta_0 + \theta_1 x + \theta_2 x^2$$
 $\theta_0 + \theta_1 x + \theta_2 x^2 + \theta_3 x^3 + \theta_4 x^4$

$$J(\theta) = \frac{1}{2m} \left[\sum_{i=1}^{m} (h_{\theta}(x^{(i)}) - y^{(i)})^2 + \lambda \sum_{j=1}^{n} \theta_j^2 \right]$$

$$\min_{\theta} J(\theta)$$

Cross-validation (CV)



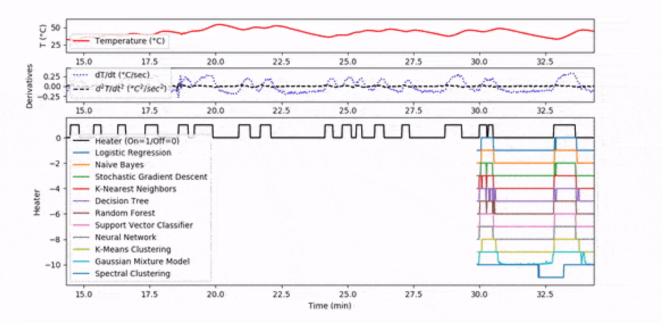
- Training data set used to train a model to fit data
- Validation data set used to provide unbiased evaluation of the model's fitness
- Test data set never been used in the training

a better model to avoid overfitting (but more complexity)

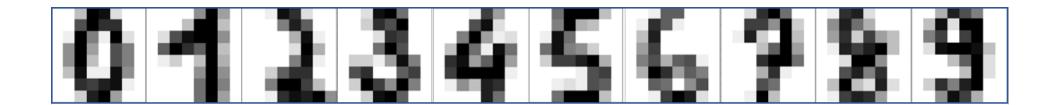
- 1. What are two examples of classification? Select two answers.
- A. Determine when a heater is on or off based on weather data
- **B.** Translate the numbers or letters from a handwritten message to ASCII text
- **C.** Develop a mathematical relationship between heater level (0-100%) and temperature (20-70°C)

- 1. What are two examples of classification? Select two answers.
- A. Determine when a heater is on or off based on weather data

Correct. The classifier distinguishes between on or off with temperature and temperature derivatives as the features.



- 1. What are two examples of classification? Select two answers.
- **B.** Translate the numbers or letters from a handwritten message to ASCII text Correct. The classifier analyzes the pixels of each letter to determine the alpha-numeric value.



- 2. What answers are correct for supervised learning? Select all that apply.
- A. Requires labeled data that reveals the measured or true outcome
- B. Training and test samples can be overlapped

- 2. What answers are correct for supervised learning? Select all that apply.
- **A.** Requires labeled data that reveals the measured or true outcome Correct. Supervised learning uses labeled data to compute an error with a model output.
- B. Training and test samples can be overlapped

False. Training and test samples must not be overlapped

Summary

Introduction to supervised learning

- Regression and classification
- Learning pipeline of a supervised learning
 - Learning from data (error)
- Overfitting VS underfitting (Bias-variance trade-off)
- Model generalization
 - Avoid overfitting and cross validation

Reference

- Book: Pattern Recognition and Machine Learning (by Christopher M. Bishop)
- Book: Machine Learning: a Probabilistic Perspective (by Kevin P. Murphy)
- https://www.andrewng.org/courses/