

# Algebraic Topology Problem Bank

Dahlen Elstran

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## 1 Revised

### 1.1 Homework 1

**Exercise 0.2.** Construct an explicit deformation retraction of  $\mathbb{R}^n - \{0\}$  onto  $S^{n-1}$ .

*Proof.* First note that  $S^{n-1}$  is defined to be all the points  $(x_1, \dots, x_n)$  such that  $\sqrt{x_1^2 + \dots + x_n^2} = 1$ . Let  $f_t(x_1, \dots, x_n) = (1 + t(\frac{1}{\sqrt{x_1^2 + \dots + x_n^2}} - 1))(x_1, \dots, x_n)$ . Note that this is a continuous function because  $(x_1, \dots, x_n) \neq 0$  and it is made up of continuous functions. Then we have

$$\begin{aligned} f_0(x_1, \dots, x_n) &= (1 + 0)(x_1, \dots, x_n) = (x_1, \dots, x_n) \\ f_1(x_1, \dots, x_n) &= (1 + \frac{1}{\sqrt{x_1^2 + \dots + x_n^2}} - 1)(x_1, \dots, x_n) \\ &= (\frac{1}{\sqrt{x_1^2 + \dots + x_n^2}})(x_1, \dots, x_n) \\ &= (\frac{x_1}{\sqrt{x_1^2 + \dots + x_n^2}}, \dots, \frac{x_n}{\sqrt{x_1^2 + \dots + x_n^2}}). \end{aligned}$$

Notice that because

$$\begin{aligned} &\sqrt{(\frac{x_1}{\sqrt{x_1^2 + \dots + x_n^2}})^2 + \dots + (\frac{x_n}{\sqrt{x_1^2 + \dots + x_n^2}})^2} \\ &= \sqrt{\frac{x_1^2}{x_1^2 + \dots + x_n^2} + \dots + \frac{x_n^2}{x_1^2 + \dots + x_n^2}} \\ &= \sqrt{\frac{x_1^2 + \dots + x_n^2}{x_1^2 + \dots + x_n^2}} = 1, \end{aligned}$$

we can conclude that  $f_0(\mathbb{R}^n - \{0\}) = \mathbb{R}^n - \{0\}$  and  $f_1(\mathbb{R}^n - \{0\}) = S^{n-1}$ . Finally, let  $(x_1, \dots, x_n) \in S^{n-1}$ , so that  $\sqrt{x_1^2 + \dots + x_n^2} = 1$ . Then

$$f_t(x_1, \dots, x_n) = (1 + \frac{1}{\sqrt{x_1^2 + \dots + x_n^2}} - 1)(x_1, \dots, x_n) = 1 \cdot (x_1, \dots, x_n) = (x_1, \dots, x_n).$$

So  $f_t(x_1, \dots, x_n)|_{S^{n-1}} = (x_1, \dots, x_n)$ . Thus  $f_t(x)$  is a deformation retraction.  $\square$

**Exercise 0.3.** Before starting Exercise 0.3, let me state the following implications.

*Proof.* First, note that for any continuous map  $h$ ,  $f \cong g \implies h(f) \cong h(g)$ :

Assuming  $f \cong g$ , there exists some continuous  $\theta_t$  such that  $\theta_0 = f$  and  $\theta_1 = g$ . Let  $\theta'_t = h(\theta_t)$ , and note that this is continuous because it is composed of continuous functions. Then  $\theta'_0 = h(\theta_0) = h(f)$ , and similarly,  $\theta'_1 = h(\theta_1) = h(g)$ . Thus  $h(f) \cong h(g)$ .

Next, I aim to show that  $f \cong g \implies f(h) \cong g(h)$ :

Assuming  $f \cong g$ , there exists some continuous  $\theta_t$  such that  $\theta_0 = f$  and  $\theta_1 = g$ . Let  $\theta'_t = \theta_t(h)$ , and note that this is continuous because it is composed of continuous functions. Then  $\theta'_0 = \theta_0(h) = f(h)$ , and similarly,  $\theta'_1 = \theta_1(h) = g(h)$ . Thus  $f(h) \cong g(h)$ .  $\square$

**Exercise 0.3a.** Show that the composition of homotopy equivalences  $X \rightarrow Y$  and  $Y \rightarrow Z$  is a homotopy equivalence  $X \rightarrow Z$ . Deduce that homotopy equivalence is an equivalence relation.

*Proof.* First, to show the composition holds, assume that there is a homotopy equivalence from  $X \rightarrow Y$ , so there exists a continuous map  $f_1 : X \rightarrow Y$  such that there exists a continuous map  $g_1 : Y \rightarrow X$ , and  $f_1 \circ g_1 \cong \text{id}_y$  and  $g_1 \circ f_1 \cong \text{id}_x$ . Similarly, if there is a homotopy equivalence from  $Y \rightarrow Z$ , there exists a continuous map  $f_2 : Y \rightarrow Z$  such that there exists a continuous map  $g_2 : Z \rightarrow Y$ , and  $f_2 \circ g_2 \cong \text{id}_z$  and  $g_2 \circ f_2 \cong \text{id}_y$ .

Define the following:

$$\begin{aligned} f &= f_2 \circ f_1(x) = f_2(f_1(x)) \\ g &= g_1 \circ g_2(z) = g_1(g_2(z)) \end{aligned}$$

Then  $f$  and  $g$  are continuous maps because they are composed of continuous functions, and

$$\begin{aligned} (f \circ g)(z) &= f(g(z)) \\ &= f_2(f_1(g_1(g_2(z)))) \\ &= f_2(g_2(z)) = z \\ (g \circ f)(x) &= g(f(x)) \\ &= g_1(g_2(f_1(x))) \\ &= g_1(f_1(x)) = x \end{aligned}$$

Thus  $f$  is a homotopy equivalence from  $X \rightarrow Z$ .

Next we show that homotopy equivalence is an equivalence relation.

**Reflexivity:** Let  $f, g : X \rightarrow X$  be the identity map. Then  $f, g$  are continuous,  $f \circ g \cong \text{id}_x$ ,  $g \circ f \cong \text{id}_x$ . Thus  $f$  is a homotopy equivalence, and  $X \cong X$ .

**Symmetry:** Assume  $X \cong Y$ . Then  $f : X \rightarrow Y$  is a homotopy equivalence, so there exists  $g : Y \rightarrow X$  such that  $g \circ f \cong \text{id}_x$  and  $f \circ g \cong \text{id}_y$ . Let  $f_0 = g$  and  $g_0 = f$ , so that  $f_0 : Y \rightarrow X$  is a continuous map, as is  $g_0 : X \rightarrow Y$ ; also,  $g_0 \circ f_0 \cong \text{id}_y$  and  $f_0 \circ g_0 \cong \text{id}_x$ . Thus  $Y \cong X$ .

**Transitivity:** Assume  $X \cong Y$  and  $Y \cong Z$ . Because  $X \cong Y$ , we know there exists  $f_1 : X \rightarrow Y$ ,  $g_1 : Y \rightarrow X$ ,  $f_1 \circ g_1 \cong \text{id}_y$ , and  $g_1 \circ f_1 \cong \text{id}_x$ . Similarly, because  $Y \cong Z$ , we

know there exists  $f_2 : Y \rightarrow Z$ ,  $g_2 : Z \rightarrow Y$ ,  $f_2 \circ g_2 \cong \text{id}_Z$ , and  $g_2 \circ f_2 \cong \text{id}_Y$ . Then define

$$\begin{aligned} f &= f_2 \circ f_1 \\ g &= g_1 \circ g_2, \end{aligned}$$

and note that both are continuous because they are composed of continuous functions.

Then

$$\begin{aligned} (f \circ g)(z) &= f(g(z)) = f_2(f_1(g_2(z))) = f_2(g_2(z)) = z \\ (g \circ f)(x) &= g(f(x)) = g_1(g_2(f_1(x))) = g_1(f_1(x)) = x. \end{aligned}$$

So  $X \cong Z$  with  $f$ , so that transitivity is true, and a homotopy equivalence is an equivalence relation.  $\square$

**Exercise 0.3b.** Show that the relation of homotopy among maps  $X \rightarrow Y$  is an equivalence relation.

*Proof. Reflexivity:* Consider any  $f : X \rightarrow Y$ , and then let  $f_t = f$ , so that  $f_0 = f$  and  $f_1 = f$ . Thus  $f \cong f$ .

**Symmetry:** Assume  $f \cong g$ , so that there exists a homotopy  $f_t(x)$  such that  $f_0 = f$  and  $f_1 = g$ . Define  $f'_t(x) = f_{1-t}(x)$ , and note that it is continuous. Then  $f'_0(x) = f_1(x) = g$  and  $f'_1(x) = f_0(x) = f$ . Thus, by  $f'_t(x)$ ,  $g \cong f$ .

**Transitivity:** Assume  $f \cong g$  and  $g \cong h$ , so that there exists  $\psi_t(x)$  such that  $\psi_0 = f$ ,  $\psi_1 = g$ , and  $\theta_t(x)$  such that  $\theta_0 = g$  and  $\theta_1 = h$ . Define  $\phi_t(x)$  as  $\psi_{2t}(x)$  for  $0 \leq t \leq \frac{1}{2}$  and  $\theta_{2t-1}(x)$  for  $\frac{1}{2} < t \leq 1$ . Thus  $\phi_t$  is continuous, because  $\psi$  and  $\theta$  are, and  $\lim_{t \rightarrow \frac{1}{2}^-} \phi_t(x) = \psi_1(x) = g(x) = \theta_0(x) = \lim_{t \rightarrow \frac{1}{2}^+} \phi_t(x)$ . Furthermore,  $\phi_0 = \psi_0 = f$  and  $\phi_1 = \theta_1 = h$ . Thus,  $f \cong h$ .

Thus the relation of homotopy among maps is an equivalence relation.  $\square$

**Exercise 0.3c.** Show that a map homotopic to a homotopy equivalence is a homotopy equivalence.

*Proof.* Let  $f : X \rightarrow Y$  be a homotopy equivalence, and assume it is homotopic to  $g : X \rightarrow Y$ . Because  $f$  is a homotopy equivalence, there exists some continuous  $h : Y \rightarrow X$  such that  $f \circ h \cong \text{id}_Y$  and  $h \circ f \cong \text{id}_X$ . Because  $h$  is continuous, we can use a previous result to say that because  $f \cong g$ , then  $h(f) \cong h(g)$ . Because  $f(h) \cong \text{id}_Y$ , by transitivity proven above,  $h(g) \cong \text{id}_Y$ . Similarly, we can also say that  $f(h) \cong g(h)$ , and so because  $f(h) \cong \text{id}_Y$ , then  $g(h) \cong \text{id}_Y$ . Thus  $g$  is homotopy equivalent.  $\square$

**Exercise 0.10.** Show that a space  $X$  is contractible if and only if every map  $f : X \rightarrow Y$ , for arbitrary  $Y$ , is nullhomotopic. Similarly, show  $X$  is contractible if and only if every map  $f : Y \rightarrow X$  is nullhomotopic.

*Proof.* Assume  $X$  is contractible. Then we know any identity map  $h : X \rightarrow X$  is nullhomotopic. Then we know, because  $h \cong g$  for constant function  $g$ , that  $f(h) \cong f(g)$ , and  $f(h) = h$  and  $f(g) = g_0$ , a constant function. Thus  $f$  is nullhomotopic for any  $Y$ .

Assume every map  $f : X \rightarrow Y$ , for arbitrary  $Y$ , is nullhomotopic. Then the identity map  $f : X \rightarrow X$  is nullhomotopic. Thus, by definition,  $X$  is contractible.

For the more general statement, first assume  $X$  is contractible, so that  $h : X \rightarrow X$ ,  $h \cong g$  (where  $g$  is a constant function). Let  $f : Y \rightarrow X$  be a map with any space  $Y$ . Then there exists  $f_t(x)$  such that  $f_0 = h$ , and  $f_1 = g$ . Let  $f'_t = f_t(f)$  (and note that  $f'_t(x)$  is still continuous), so  $f'_0 = h(f)$ , and  $f'_1 \cong g_1(f)$ . Then  $f \cong g_1(f)$ , and  $g_1(f)$  is a constant function.

Assume every map  $f : Y \rightarrow X$  is nullhomotopic, then  $f : X \rightarrow X$ , where  $f$  is the identity function, is nullhomotopic, and therefore  $X$  is contractible.  $\square$

**Exercise 0.11.** Show that  $f : X \rightarrow Y$  is a homotopy equivalence if there exist maps  $g, h : Y \rightarrow X$  such that  $fg \cong \text{id}$  and  $hf \cong \text{id}$ . More generally, show that  $f$  is a homotopy equivalence if  $fg$  and  $hf$  are homotopy equivalences.

*Proof.* Assume there exists  $g, h : Y \rightarrow X$  such that  $fg \cong \text{id}_y$ ,  $hf \cong \text{id}_x$ . Then, because  $fg \cong \text{id}_y$ , we know  $fgf \cong f \iff fgf \cong f \circ \text{id}_x$ . Then  $gf \cong \text{id}_x$ , and so for  $f : X \rightarrow Y$ , there exists  $g : Y \rightarrow X$  such that  $fg \cong \text{id}_y$  and  $hf \cong \text{id}_x$ , so  $f : X \rightarrow Y$  is a homotopy equivalence.

Assume that there exists  $h, g : Y \rightarrow X$ , and  $fg$  and  $hf$  are homotopy equivalents. Then we know

$$\begin{aligned} fg \text{ is homotopy equivalent} &\iff \exists g' : Y \rightarrow Y, fg \circ g' \cong \text{id}_y, g' \circ fg \cong \text{id}_y \\ hf \text{ is homotopy equivalent} &\iff \exists h' : X \rightarrow X, hf \circ h' \cong \text{id}_x, h' \circ hf \cong \text{id}_x \end{aligned}$$

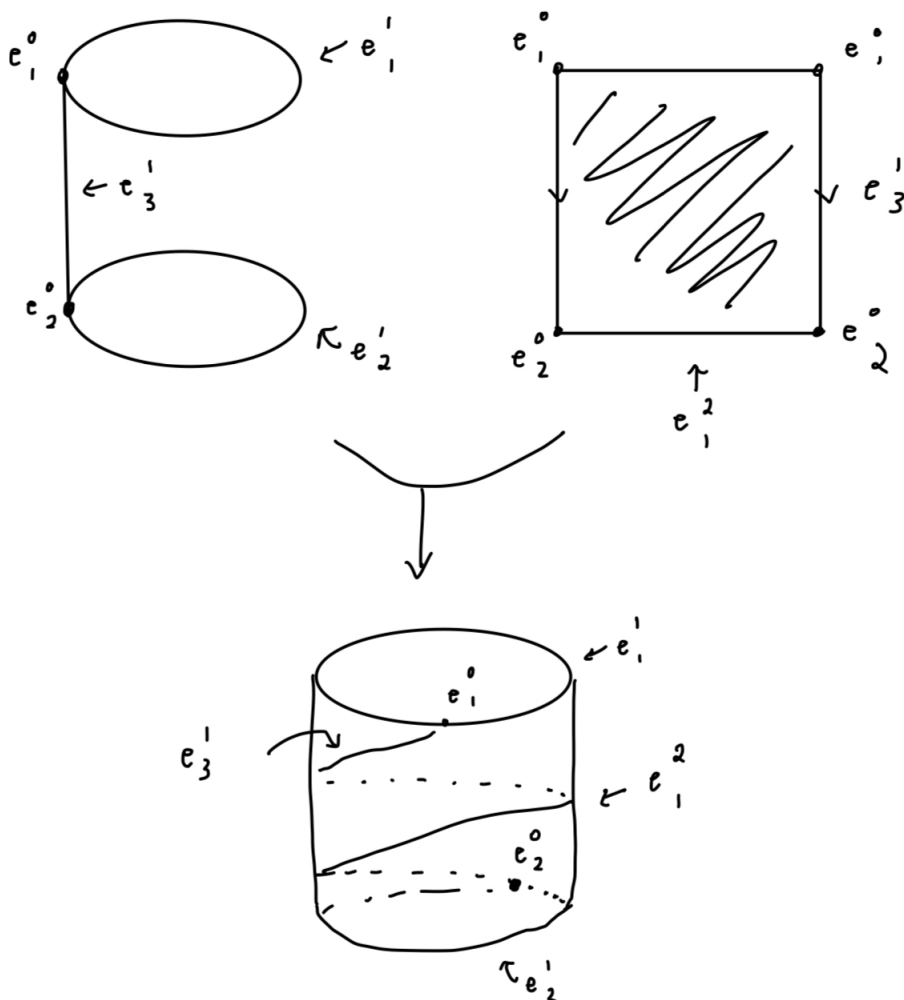
Then we have

$$\begin{aligned} h'hf \cong \text{id}_x &\implies h(fh'h) \cong \text{id}_x \circ h \cong h \cong h \circ \text{id}_x \\ &\implies fh'h \cong \text{id}_x \cong h'hf \end{aligned}$$

So because of  $h'h$ ,  $f$  is a homotopy equivalence.  $\square$

**Exercise 0.17a.** Show that the mapping cylinder of every map  $f : S^1 \rightarrow S^1$  is a CW complex.

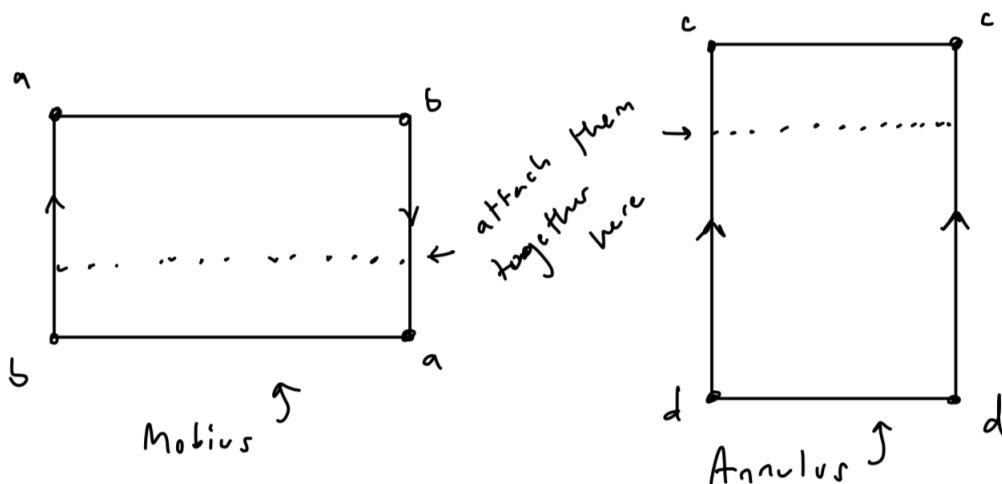
*Proof.* Let  $f : S^1 \rightarrow S^1$  be any arbitrary mapping. To construct the CW complex, start with two 0-cells,  $e_1^0$ , acting as an  $x$  coordinate, and  $e_2^0$ , acting as its  $y$  coordinate. Then add the 1-cell  $e_1^1$  as a circle, where  $e_1^0$  is in this circle, and another 1-cell  $e_2^1$  as another (disjoint) circle, this time with  $e_2^1$  containing  $e_2^0$ . Then add one more 1-cell,  $e_3^1$ , as the graph of  $f$ , effectively going around the cylinder. Finally, attach a 2-cell  $e_1^2$  so that it "closes" the cylinder. An attempted diagram is attached below:



□

**Exercise 0.17b.** Construct a 2-dimensional CW complex that contains both an annulus  $S^1 \times I$  and a Mobius band as deformation retracts.

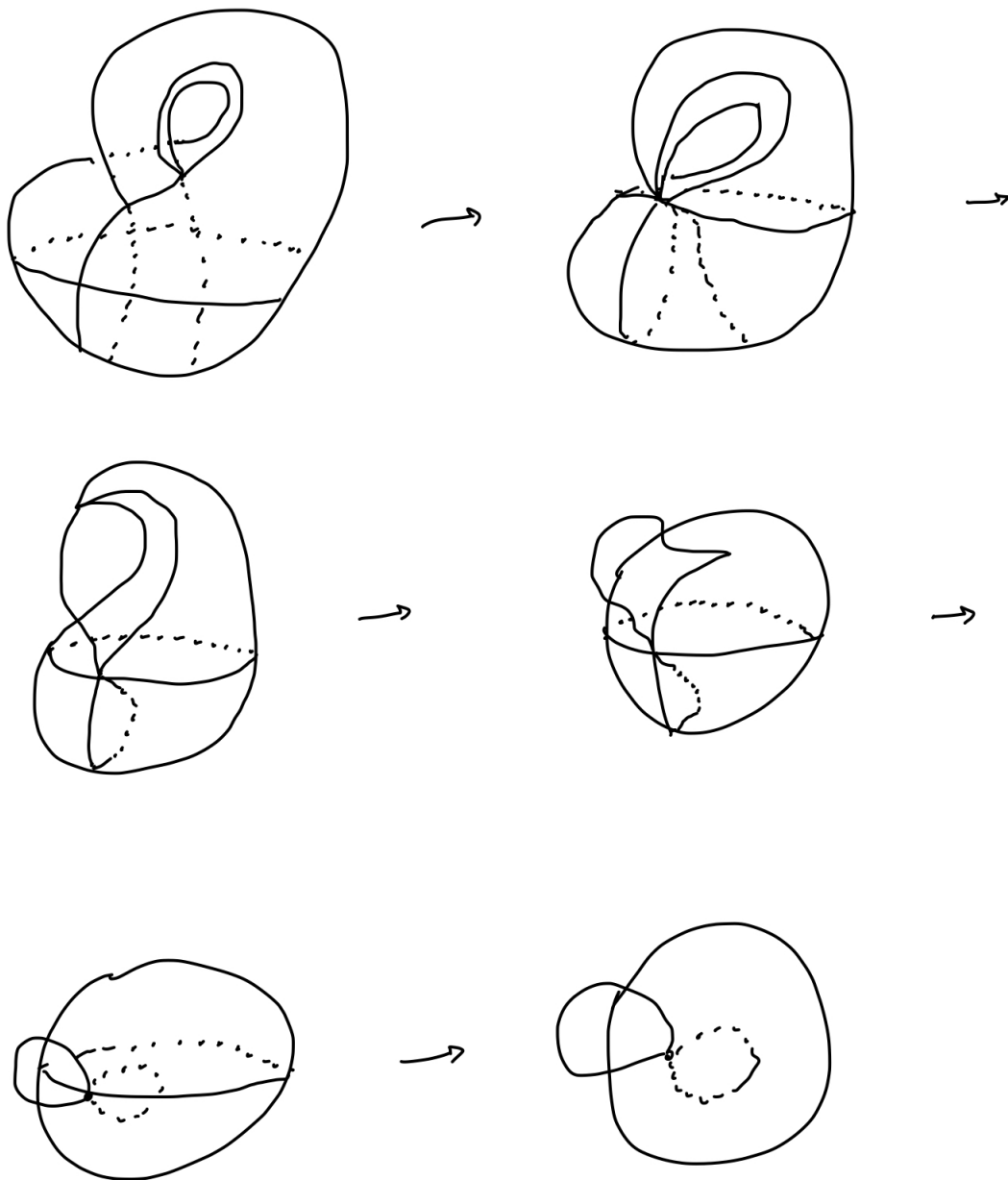
*Proof.* Both the Mobius band and the annulus can deformation retract onto their middle circles, so if we glue the middle circles together, we can get a 2-dimensional CW complex that can deformation retract to both. Image below:



□

**Exercise 0.20.** Show that the subspace  $X \subset \mathbb{R}^3$  formed by a Klein bottle intersecting itself in a circle is homotopy equivalent to  $S^1 \vee S^1 \vee S^1$ .

*Proof.* As shown in the picture below, you can condense there the neck meets the rest of the bottle into one point, extend the neck out so there is only a 1-cell coming from that intersection point, until the neck is pushed all the way into a sphere. Then all that is left is a sphere with a circle on the outside and another circle on the inside, where the circles intersect at exactly one point. Thus  $X \subset \mathbb{R}^3 \cong S^1 \vee S^1 \vee S^1$ .



□

## 1.2 Homework 1 Extra Problems

**Hatcher 0.6.** • Let  $X$  be the subspace of  $\mathbb{R}^2$  consisting of the horizontal segment  $[0, 1] \times \{0\}$  together with all the vertical segments  $\{r\} \times [0, 1 - r]$ .

## 2 Not Revised

### 2.1 Homework 2

**Exercise 1.** Describe a CW complex structure on  $\mathbb{C}P^2 \times \mathbb{R}P^2$  and  $\Sigma T^2$ .

*Proof.* For  $\mathbb{C}P^2 \times \mathbb{R}P^2$ , we know that  $\mathbb{R}P^2$  consists of 1 0-cell, 1 1-cell, and 1 2-cell. Similarly, for  $\mathbb{C}P^2$ , it consists of 1 1-cell, 1 2-cell, and 1 4-cell. Thus the product of these spaces consists of 1 0-cell, 1 1-cell, 2 2-cells, 1 3-cell, 2 4-cells, 1 5-cell, and 1 6-cell. Visually, we're finding the product of a sphere and a 4th dimensional shape.

For  $\Sigma T^2$ , first note that  $T^2 = S^1 \times S^1$ , the torus. In Hatcher, it is stated that  $\Sigma X = X \wedge S^1$ , so in our case,  $\Sigma(S^1 \times S^1) = (S^1 \times S^1) \wedge S^1$ . Also in Hatcher,  $X \wedge Y = X \times Y / X \vee Y$ . So finally, we have  $(S^1 \times S^1) \times S^1 / (S^1 \times S^1) \vee S^1$ . Visually, we can imagine this as a torus crossed with  $S^1$  quotient by a torus touching a circle. Regarding cell complexes, we have  $(e^0 \cup e^1 \cup e^1 \cup e^1 \cup e^2 \cup e^2 \cup e^2 \cup e^3) / (e^0 \cup e^0 \cup e^1 \cup e^1 \cup e^1 \cup e^2)$ . Thus the reduced suspension of a torus has the CW structure of 1 1-cell, 2 2-cells, and 1 3-cell.  $\square$

**Exercise 2.** Let  $X_n$  be the topological space obtained by identifying  $n > 1$  points on  $S^2$  to a single point. Describe a CW decomposition of  $X_n$ .

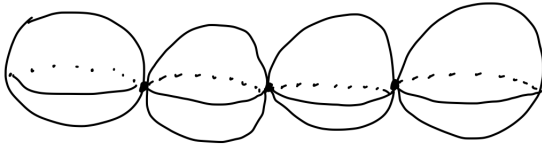
*Proof.* When you identify a point with a singular point, you're pinching the  $S^2$  sphere at that singular point, and it creates a "loop" from where the point originally was to the singular point. This occurs for every point identified, so that there are  $n - 1$  loops (or  $S^1$ 's) added to the space. Note that we need loops, because if we were to do lines, some lines could intersect. Thus we can say  $X_n = S^2 \vee \bigvee_{i=1}^{n-1} S^1$ , which is just stating that  $X_n$  is a sphere with loops added that intersect at a single point (the singular point). When considering CW decomposition, the  $S^2$  has 1 0-cell and 1 2-cell, while each  $S^1$  has a 0-cell and a 1-cell. However, the singular point can be made the 0-cell for the  $S^2$  and the  $S^1$ 's, so in total there is 1 0-cell, 1 2-cell, and  $n - 1$  1-cells.  $\square$

**Exercise 3.** Hatcher Exercise 0.21: If  $X$  is a connected Hausdorff space that is a union of a finite number of 2-spheres, any two of which intersect in at most one point, show that  $X$  is homotopy equivalent to a wedge sum of  $S^1$ 's and  $S^2$ 's.

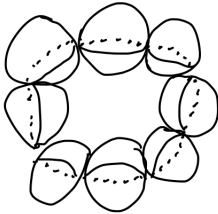
*Proof.* First, because the space is connected, we know that there aren't any disjoint 2-spheres. Then, we can imagine this space made up of  $S^2$ 's which intersect at most 1 point, and because there can't be any disjoint 2-spheres, they must all be in a row like this, or in a loop:



row:

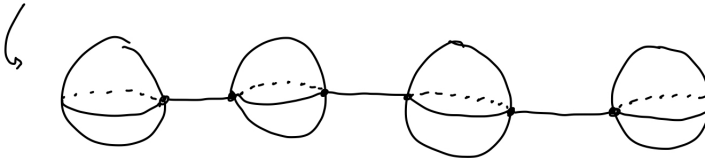
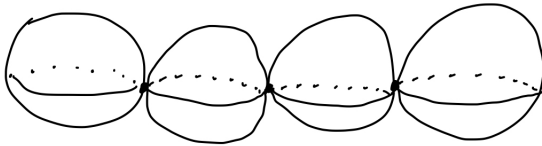


loop:

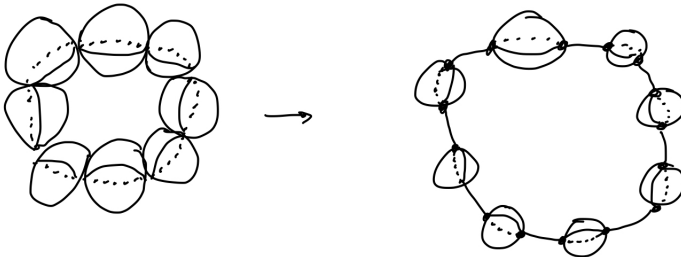


Either way, the intersection points between the spheres can be stretched into lines between them, like this:

row:



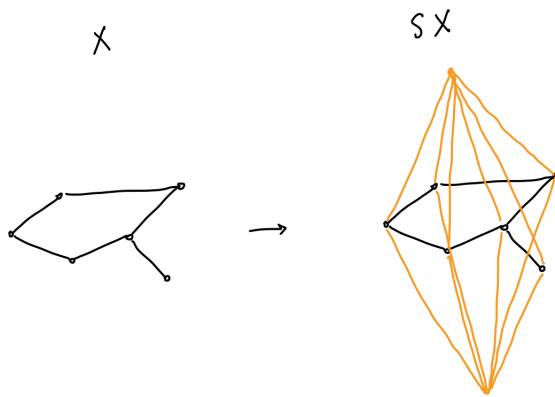
loop:



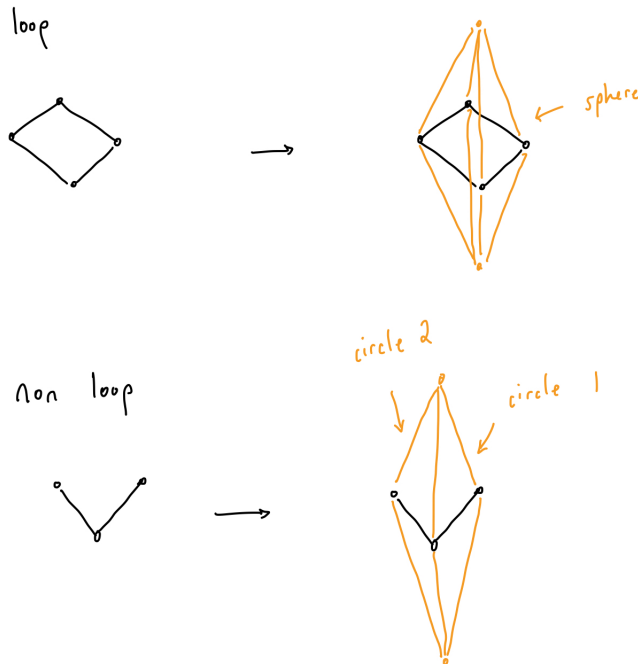
As you can see, the space  $X$  can be stretched (and is therefore homotopically equivalent to) to be  $\bigvee_{i=1}^{n-1} S^1 \vee \bigvee_{i=1}^n S^2$  where  $n$  is the number of 2-sphere's in  $X$ .  $\square$

**Exercise 4.** Hatcher Exercise 0.25: If  $X$  is a CW complex with components  $X_\alpha$ , show that the suspension  $SX$  is homotopy equivalent to  $Y \vee_\alpha SX_\alpha$  for some graph  $Y$ . In the case that  $X$  is a finite graph, show that  $SX$  is homotopy equivalent to a wedge sum of circles and 2-spheres.

*Proof.* If  $X$  is a finite graph, the suspension  $SX$  is just taking all the vertices in the graph and connecting them to a point "above" and "below" the graph. This results in something like this:



Note that when you have a closed loop in a graph, when you do the suspension it results in a sphere, and when there is a non-loop, it just creates circles:



Because everything in a graph is either a loop or a nonloop, this accounts for what makes up any graph  $X$ . Thus if  $X$  is a graph,  $SX$  is just a wedge sum of spheres and circles.  $\square$