# 2-Dimensional Range Minimum Queries

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#### **Outline**

- Introduction to RMQs
  - Formal Problem Definition
  - Previous Results
- Solution Methods
  - Overview
  - Preprocessing of First Level
  - Other Levels and Microblock-Queries

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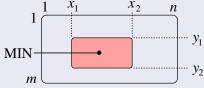
### **Formal Problem Definition**

#### **The Problem**

**given:** matrix A[1..m][1..n] (totally ordered objects)

task: preprocess A to answer "efficiently"

$$RMQ(y_1, y_2, x_1, x_2) = \underset{(y, x) \in [y_1: y_2] \times [x_1: x_2]}{\operatorname{argmin}} A[y][x]$$



### Main Result

#### The Problem

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#### Theorem (2-Dimensional RMQs)

 $O(nm(k + \log^{[k+1]}(mn)))$ -preprocessing using O(kmn) space for O(1)-RMQs, for any k > 1.

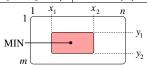
Converges towards  $O(mn \log^*(mn))$  preprocessing time **and** space, and O(1) query time.

### **Our Result in Context**

N := mn

|                            | preprocessing              |                       | query               |
|----------------------------|----------------------------|-----------------------|---------------------|
|                            | time                       | space                 | time                |
| Gabow et al.'84            | $O(N \log N)$              | $O(N \log N)$         | O(log N)            |
| Chazelle-<br>Rosenberg'89  | O(RN)                      | O(RN)                 | $O(\alpha^2(RN,N))$ |
| (with $R = \text{const}$ ) | O(N)                       | <i>O</i> ( <i>N</i> ) | $O(\alpha^2(RN,N))$ |
| Mäkinen'03                 | $O(N \log m)$              | $O(N \log m)$         | <i>O</i> (1)        |
| this paper                 | $O(N(k + \log^{[k+1]} N))$ | O(kN)                 | O(1)                |
| (with $k=2$ )              | $O(N \log \log \log N)$    | O(N)                  | O(1)                |
| this paper                 | $O(N \log^* N)$            | $O(N \log^* N)$       | <i>O</i> (1)        |

 $R \ge 144$ ,  $k \ge 2$  (both not necessarily constants!)



### **Results for 1-Dimensional RMQs**

 Results for O(n) preprocessing time and O(1) query time:

|                                       | space (bits)  |               |
|---------------------------------------|---------------|---------------|
|                                       | final         | peak          |
| Berkman-Vishkin'93                    | $O(n \log n)$ | $O(n \log n)$ |
| Bender-<br>Farach-Colton'00           | $O(n \log n)$ | $O(n \log n)$ |
| Farach-Colton'00<br>Alstrup et al.'02 | $O(n \log n)$ | $O(n \log n)$ |
| Fischer-Heun'06                       | $O(n \log n)$ | $O(n \log n)$ |
| Sadakane'02                           | 4n + o(n)     | $O(n \log n)$ |
| Fischer-Heun'07                       | 2n + o(n)     | 2n + o(n)     |

Cartesian Trees (=treaps) important tool for all!

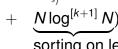
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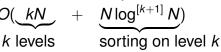
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# Overview of the Algorithm

- impose grids on A (widths  $s_1 \geq s_2 \geq \cdots \geq s_k$ )
- preprocess each "layer" seperately
- level *i*: queries crossing grid  $s_i$ . but no grid  $s_i$ for j < i
- other queries: precompute all possible!
- time:



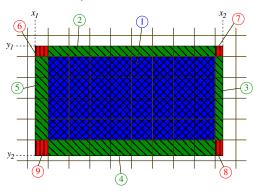




S2

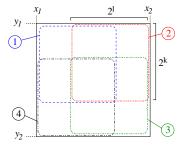
# Preprocessing on Level 1

- assume A is square ( $\Rightarrow n = m, N = n^2$ )
- $s_1 = \log n$ : grid-width on level 1
- decompose RMQ $(y_1, y_2, x_1, x_2)$  into nine sub-queries:
- several blocks
  in both
  directions
- 2-5 several blocks in 1 direction
- 6-9 in-block, but "touches" boundary



### **Precomputation of Queries 1–9**

• Precompute only queries that span  $2^k \times 2^l$  blocks



- Answer all queries by selecting at most four overlapping "power-of-two"-queries
- same idea as for 1D-RMQ!

## **Recursive Partitioning**

perform same preprocessing for grid-widths

$$s_2 = \log \log n, s_3 = \log \log \log n, \dots, s_k = \log^{[k]} n$$

- either stopping at some fixed k > 1...
- ... or until  $s_k = O(1)$  ( $\iff k = \Theta(\log^* n)$ )

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- ... or until  $s_k = O(1)$  ( $\iff k = \Theta(\log^* n)$ )
- naive query-answering would cost O(k) or O(log\* n) time!
- ⇒ store additional structures of size o(n) for selecting the right grid in O(1) time

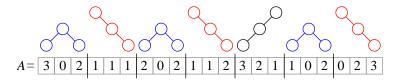




## What to do with microblock-queries?

#### **Key-property for 1D-RMQs**

2 blocks have same answers to all RMQs  $\iff$  they have equal Cartesian Trees



Problem: nothing similar for 2D

#### **Weaker Property**

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- $\Rightarrow$  sort microblocks (e.g. row-wise) to get permutation of [1 : S] (=relative order),  $S = s_k^2$ 
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#### **Weaker Property**

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  - precompute microblock-queries only for different permutations and not for all occurring microblocks
  - space is

$$O(S^2 \times S!) = \cdots = O(N)$$
 (if  $k > 1$ )

• time is  $O(\frac{N}{S} \times S \log S) = O(N \log^{[k+1]} n)$ 

# Summary

- preprocessing-scheme for 2D-RMQs (N: size of input)
  - space O(N)
  - preprocessing time O(N)
  - query time *O*(1)
- generalizes to higher dimensions d: query time O(C<sup>d</sup>), C =const
- open question: can we achieve O(N) preprocessing time and O(1) query time?
  - impossible for slightly more general operations! (Chazelle-Rosenberg'89)